

16.060 - Principles of Automatic Control (F'02)
Final Exam

Part C

C-1) You are given

$$G(s) = \frac{100(10s+1)}{s(s+1)(1s+1)}$$

- a) Sketch the $\log |G|$ vs $\log \omega$
- b) Sketch the $\angle G$ vs. $\log \omega$. What is the value at $\omega=10$ r/s ?

C-2) For the open loop system

$$G(s) = \frac{k(s+4)}{(s+2)(s-4)(s^2+8s+32)}$$

figure (a) is the pole zero diagram and figure (b) is the Nyquist diagram showing 3 regions of interest: A, B & C

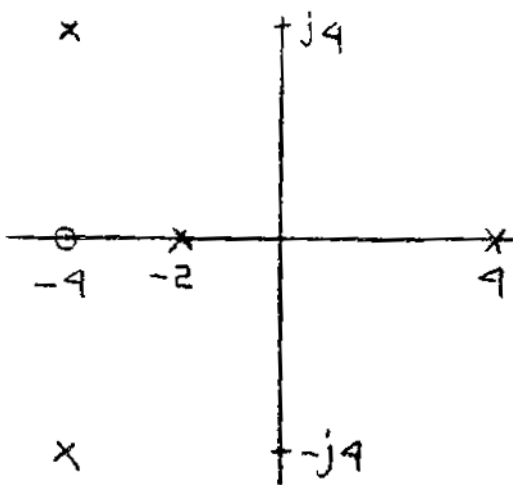


Figure (a)

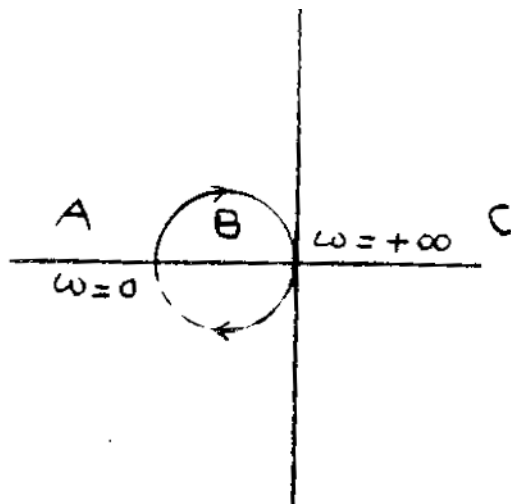


Figure (b)

- a) Fill in table C-2
- b) Sketch the branches which correspond to region C, the root locus

C-3) Figure C-3 is the Bode diagram of a certain $G(s)$. What is the expression for $G(s)$?

C-4) Given

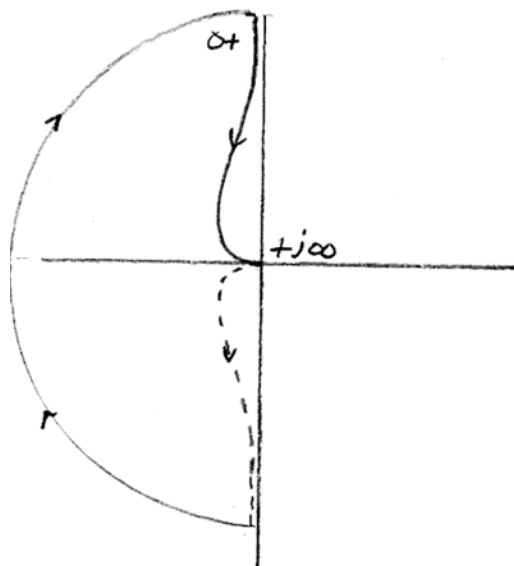
$$G(s) = \frac{K(1+s)^2}{(1-s)^2}$$

- Sketch the Nyquist plot and the root locus for $k>0$ and $k<0$.
For the Nyquist plot use $G(s)/k$. Clearly show $0+$, $+j\infty$, $-j\infty$, $0-$ and the direction of increasing frequency.
- There will be four regions of interest (A,B,C,D left to right) in the Nyquist plot. Mark them.
- Show the $r-\lambda$ branches which correspond to regions B and D.

C-5) Estimate the phase margin and crossover frequency specifications to which a loop gain function must be designed if the closed-loop system must meet the following set of requirements:

A step response with an overshoot of 15% and a settling time of .5 sec.

- C6) a) In doing a Nyquist stability analysis for a system which has, among other things, a pole at the origin and one zero in the r.h.p. the control engineer modifies the D contour by going around the pole at the origin in a clockwise sense. Now what is the correct equation for the Nyquist Stability Criterion?
- b) The following is the Nyquist diagram for a certain $G(s)$ which does not have poles or zeros in the r.h.p. What is a generic expression for $G(s)$?
Use as few poles and zeros as possible.



d) In old textbooks it is possible to find the following statement:

“In applying the Nyquist stability criterion, the closed loop system will be stable if there are no encirclements of the 1 point.”

Is this true or false?