

LECTURE 11

LECTURE OUTLINE

- Extreme points
 - Extreme points of polyhedral sets
 - Extreme points and linear/integer programming
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Recall some of the facts of polyhedral convexity:

- Polarity relation between polyhedral and finitely generated cones

$$\{x \mid a'_j x \leq 0, j = 1, \dots, r\} = \text{cone}(\{a_1, \dots, a_r\})^*.$$

- Farkas' Lemma

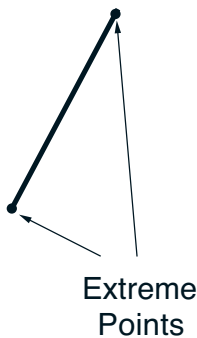
$$\{x \mid a'_j x \leq 0, j = 1, \dots, r\}^* = \text{cone}(\{a_1, \dots, a_r\}).$$

- Minkowski-Weyl Theorem: a cone is polyhedral iff it is finitely generated. A corollary (essentially):

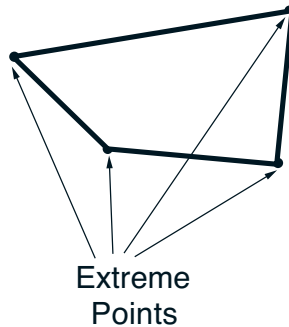
$$\text{Polyhedral set } P = \text{conv}(\{v_1, \dots, v_m\}) + R_P$$

EXTREME POINTS

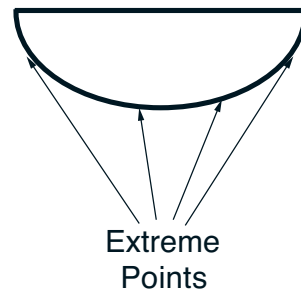
- A vector x is an *extreme point* of a convex set C if $x \in C$ and x cannot be expressed as a convex combination of two vectors of C , both of which are different from x .



(a)

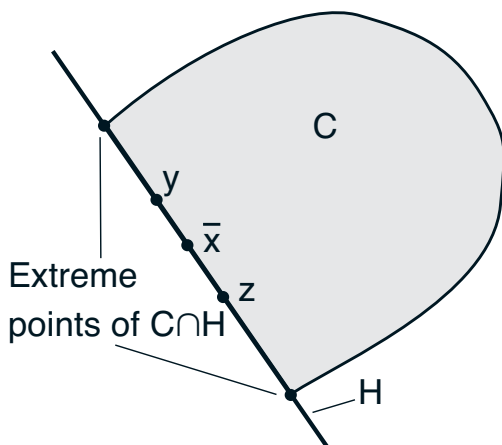


(b)



(c)

Proposition: Let C be closed and convex. If H is a hyperplane that contains C in one of its closed halfspaces, then every extreme point of $C \cap H$ is also an extreme point of C .



Proof: Let $\bar{x} \in C \cap H$ be a nonextreme point of C . Then $\bar{x} = \alpha y + (1 - \alpha)z$ for some $\alpha \in (0, 1)$, $y, z \in C$, with $y \neq \bar{x}$ and $z \neq \bar{x}$. Since $\bar{x} \in H$, the closed halfspace containing C is of the form $\{x \mid a'x \geq a'\bar{x}\}$. Then $a'y \geq a'\bar{x}$ and $a'z \geq a'\bar{x}$, which in view of $\bar{x} = \alpha y + (1 - \alpha)z$, implies that $a'y = a'\bar{x}$ and $a'z = a'\bar{x}$. Thus, $y, z \in C \cap H$, showing that \bar{x} is not an extreme point of $C \cap H$.

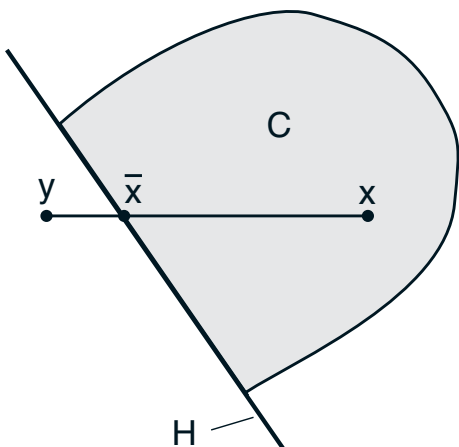
PROPERTIES OF EXTREME POINTS I

Proposition: A closed and convex set has at least one extreme point if and only if it does not contain a line.

Proof: If C contains a line, then this line translated to pass through an extreme point is fully contained in C - impossible.

Conversely, we use induction on the dimension of the space to show that if C does not contain a line, it must have an extreme point. True in \mathbb{R} , so assume it is true in \mathbb{R}^{n-1} , where $n \geq 2$. We will show it is true in \mathbb{R}^n .

Since C does not contain a line, there must exist points $x \in C$ and $y \notin C$. Consider the relative boundary point \bar{x} .



The set $C \cap H$ lies in an $(n-1)$ -dimensional space and does not contain a line, so it contains an extreme point. By the preceding proposition, this extreme point must also be an extreme point of C .

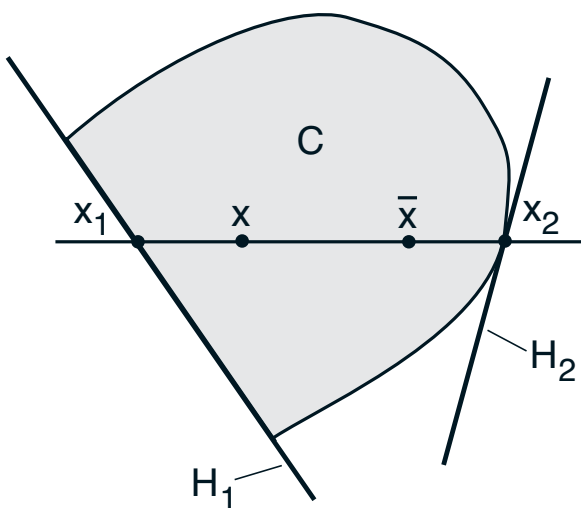
PROPERTIES OF EXTREME POINTS II

Krein-Milman Theorem: A convex and compact set is equal to the convex hull of its extreme points.

Proof: By convexity, the given set contains the convex hull of its extreme points.

Next show the reverse, i.e, every x in a compact and convex set C can be represented as a convex combination of extreme points of C .

Use induction on the dimension of the space. The result is true in \mathfrak{R} . Assume it is true for all convex and compact sets in \mathfrak{R}^{n-1} . Let $C \subset \mathfrak{R}^n$ and $x \in C$.



If \bar{x} is another point in C , the points x_1 and x_2 shown can be represented as convex combinations of extreme points of the lower dimensional convex and compact sets $C \cap H_1$ and $C \cap H_2$, which are also extreme points of C .

EXTREME POINTS OF POLYHEDRAL SETS

- Let P be a polyhedral subset of \mathfrak{R}^n . If the set of extreme points of P is nonempty, then it is finite.

Proof: Consider the representation $P = \hat{P} + C$, where

$$\hat{P} = \text{conv}(\{v_1, \dots, v_m\})$$

and C is a finitely generated cone.

- An extreme point \bar{x} of P cannot be of the form $\bar{x} = \hat{x} + y$, where $\hat{x} \in \hat{P}$ and $y \neq 0$, $y \in C$, since in this case \bar{x} would be the midpoint of the line segment connecting the distinct vectors \hat{x} and $\hat{x} + 2y$. Therefore, an extreme point of P must belong to \hat{P} , and since $\hat{P} \subset P$, it must also be an extreme point of \hat{P} .
- An extreme point of \hat{P} must be one of the vectors v_1, \dots, v_m , since otherwise this point would be expressible as a convex combination of v_1, \dots, v_m . Thus the extreme points of P belong to the finite set $\{v_1, \dots, v_m\}$. **Q.E.D.**

CHARACTERIZATION OF EXTREME POINTS

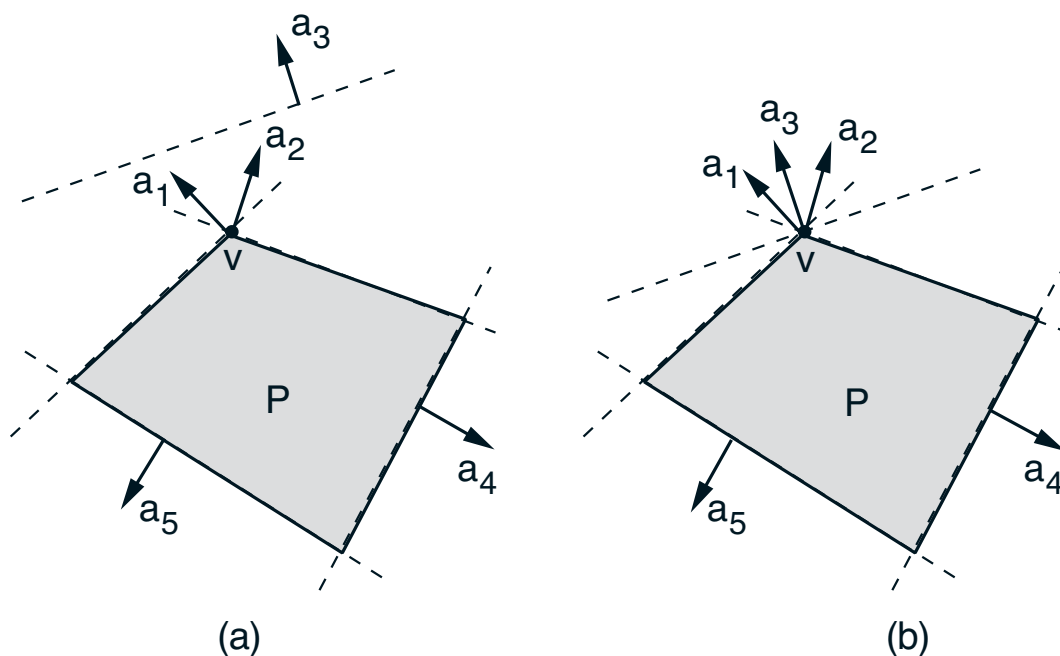
Proposition: Let P be a polyhedral subset of \mathbb{R}^n . If P has the form

$$P = \{x \mid a'_j x \leq b_j, j = 1, \dots, r\},$$

where a_j and b_j are given vectors and scalars, respectively, then a vector $v \in P$ is an extreme point of P if and only if the set

$$A_v = \{a_j \mid a'_j v = b_j, j \in \{1, \dots, r\}\}$$

contains n linearly independent vectors.



PROOF OUTLINE

If the set A_v contains fewer than n linearly independent vectors, then the system of equations

$$a'_j w = 0, \quad \forall a_j \in A_v$$

has a nonzero solution \bar{w} . For small $\gamma > 0$, we have $v + \gamma\bar{w} \in P$ and $v - \gamma\bar{w} \in P$, thus showing that v is not extreme. Thus, if v is extreme, A_v must contain n linearly independent vectors.

Conversely, assume that A_v contains a subset \bar{A}_v of n linearly independent vectors. Suppose that for some $y \in P$, $z \in P$, and $\alpha \in (0, 1)$, we have $v = \alpha y + (1 - \alpha)z$. Then, for all $a_j \in \bar{A}_v$,

$$b_j = a'_j v = \alpha a'_j y + (1 - \alpha) a'_j z \leq \alpha b_j + (1 - \alpha) b_j = b_j.$$

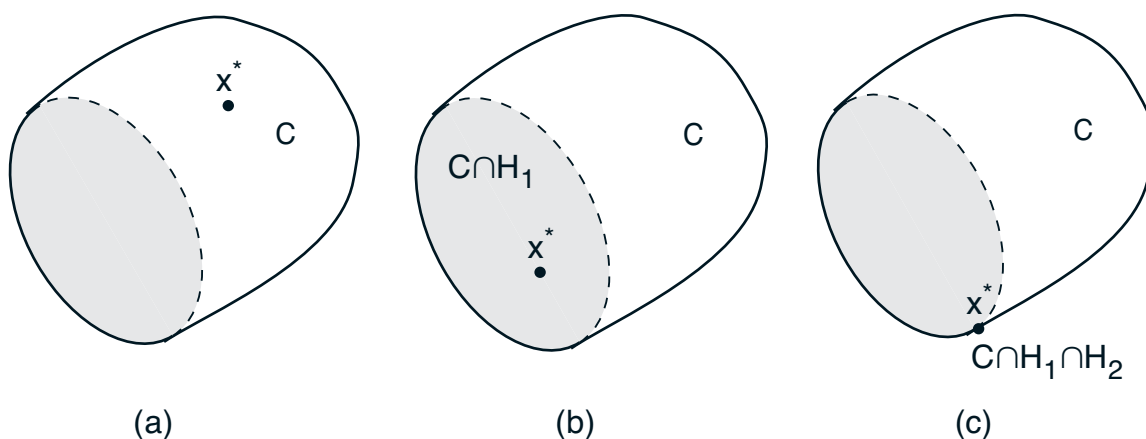
Thus, v , y , and z are all solutions of the system of n linearly independent equations

$$a'_j w = b_j, \quad \forall a_j \in \bar{A}_v.$$

Hence, $v = y = z$, implying that v is an extreme point of P .

EXTREME POINTS AND CONCAVE MINIMIZATION

- Let C be a closed and convex set that has at least one extreme point. A concave function $f : C \mapsto \mathfrak{R}$ that attains a minimum over C attains the minimum at some extreme point of C .



Proof (abbreviated): If $x^* \in \text{ri}(C)$ [see (a)], f must be constant over C , so it attains a minimum at an extreme point of C . If $x^* \notin \text{ri}(C)$, there is a hyperplane H_1 that supports C and contains x^* .

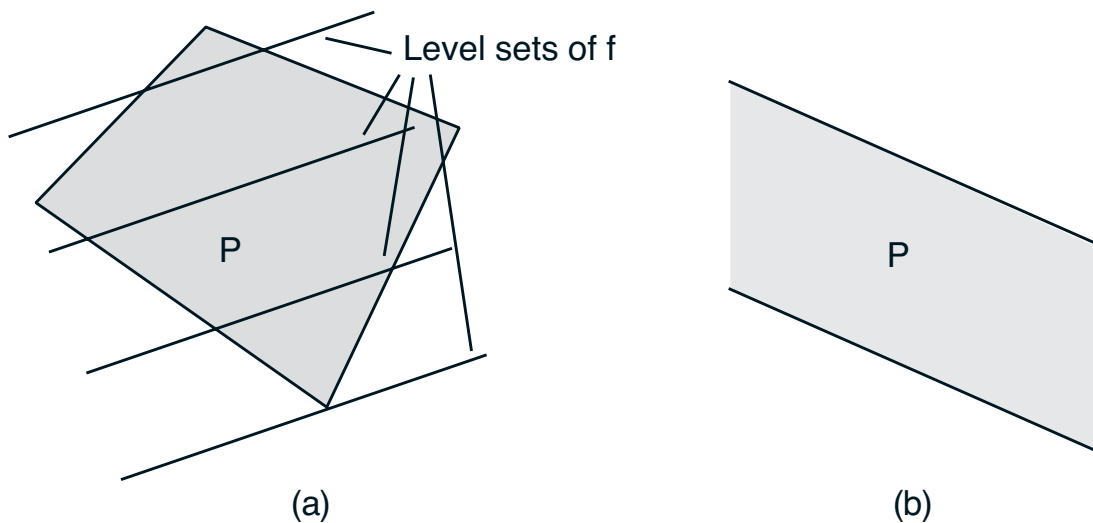
If $x^* \in \text{ri}(C \cap H_1)$ [see (b)], then f must be constant over $C \cap H_1$, so it attains a minimum at an extreme point $C \cap H_1$. This optimal extreme point is also an extreme point of C . If $x^* \notin \text{ri}(C \cap H_1)$, there is a hyperplane H_2 supporting $C \cap H_1$ through x^* . Continue until an optimal extreme point is obtained (which must also be an extreme point of C).

FUNDAMENTAL THEOREM OF LP

- Let P be a polyhedral set that has at least one extreme point. Then, if a linear function is bounded below over P , it attains a minimum at some extreme point of P .

Proof: Since the cost function is bounded below over P , it attains a minimum. The result now follows from the preceding theorem. **Q.E.D.**

- Two possible cases in LP: In (a) there is an extreme point; in (b) there is none.



EXTREME POINTS AND INTEGER PROGRAMMING

- Consider a polyhedral set

$$P = \{x \mid Ax = b, c \leq x \leq d\},$$

where A is $m \times n$, $b \in \mathbb{R}^m$, and $c, d \in \mathbb{R}^n$. Assume that all components of A and b, c , and d are integer.

- Question: Under what conditions do the extreme points of P have integer components?

Definition: A square matrix with integer components is *unimodular* if its determinant is 0, 1, or -1. A rectangular matrix with integer components is *totally unimodular* if each of its square submatrices is unimodular.

Theorem: If A is totally unimodular, all the extreme points of P have integer components.

- Most important special case: Linear network optimization problems (with “single commodity” and no “side constraints”), where A is the, so-called, *arc incidence matrix* of a given directed graph.