

## Problem Set IX Solutions

1. § 21.1 4.

- (a) Since  $r = \sqrt{u^2 + v^2}$ ,  $0 \leq r \leq 2$ . Clearly,  $0 \leq \theta \leq 2\pi$ . Since  $u = r \cos \theta$  and  $v = r \sin \theta$ , it follows that

$$\vec{R}(u, v) = \vec{R}(r, \theta) = r \cos \theta \hat{i} + r \sin \theta \hat{j} + 2r^2 \hat{k}$$

- (b) We take  $z = 2(u^2 + v^2)$ , so  $0 \leq z \leq 8$ ,  $0 \leq \theta \leq 2\pi$ , and  $u = \sqrt{\frac{z}{2}} \cos \theta$ ,  $v = \sqrt{\frac{z}{2}} \sin \theta$ . Hence we have that

$$\vec{R}(\theta, z) = \sqrt{\frac{z}{2}} \cos \theta \hat{i} + \sqrt{\frac{z}{2}} \sin \theta \hat{j} + z \hat{k}$$

2. § 21.1 6.

- (a) The domain  $\hat{D}$  is the disk of radius  $a$  centered at the origin, and the parametrization is

$$\vec{R}(x, y) = x \hat{i} + y \hat{j} + \sqrt{a^2 - x^2 - y^2} \hat{k}$$

- (b) The domain is the rectangle given by  $0 \leq r \leq a$  and  $0 \leq \theta \leq 2\pi$ . The parametrization is

$$\vec{R}(r, \theta) = r \cos \theta \hat{i} + r \sin \theta \hat{j} + \sqrt{a^2 - r^2} \hat{k}$$

3. § 21.3 1ab.

- (a) The parametrization is  $\vec{R}(u, v) = u \hat{i} + v \hat{j} + v \hat{k}$ , where the domain  $\hat{D}$  is the triangle of vertices  $(0,0)$ ,  $(1,0)$ , and  $(1,1)$ . Hence the parametric normal vector is

$$\vec{w}(u, v) = \frac{\partial \vec{R}}{\partial u} \times \frac{\partial \vec{R}}{\partial v} = \hat{i} \times (\hat{j} + \hat{k}) = -\hat{j} + \hat{k}$$

- (b) The parametrization is  $\vec{R}(\theta, z) = \frac{z}{2} \cos \theta \hat{i} + \frac{z}{2} \sin \theta \hat{j} + z \hat{k}$ , with  $0 \leq z \leq 6$  and  $0 \leq \theta \leq 2\pi$ . Hence

$$\frac{\partial \vec{R}}{\partial \theta} = -\frac{z}{2} \sin \theta \hat{i} + \frac{z}{2} \cos \theta \hat{j},$$

$$\frac{\partial \vec{R}}{\partial z} = \frac{\cos \theta}{2} \hat{i} + \frac{\sin \theta}{2} \hat{j} + \hat{k}$$

Hence the parametric normal vector is

$$\vec{w}(\theta, z) = \frac{\partial \vec{R}}{\partial \theta} \times \frac{\partial \vec{R}}{\partial z} = \frac{z}{4} (\cos \theta \hat{i} + \sin \theta \hat{j} - \hat{k})$$

4. § 21.4 1dg.

- (d) The parametrization is  $\vec{R}(\theta, z) = \sqrt{z^2 + 1} \cos \theta \hat{i} + \sqrt{z^2 + 1} \sin \theta \hat{j} + z \hat{k}$ , with  $0 \leq \theta \leq 2\pi$  and  $-2 \leq z \leq 2$ . Then

$$\frac{\partial \vec{R}}{\partial \theta} = -\sqrt{z^2 + 1} \sin \theta \hat{i} + \sqrt{z^2 + 1} \cos \theta \hat{j},$$

$$\frac{\partial \vec{R}}{\partial z} = \frac{z}{\sqrt{z^2 + 1}} \cos \theta \hat{i} + \frac{z}{\sqrt{z^2 + 1}} \sin \theta \hat{j} + \hat{k}$$

Hence the parametric normal vector is

$$\vec{w}(\theta, z) = \frac{z}{\sqrt{z^2 + 1}} \cos \theta \hat{i} + \frac{z}{\sqrt{z^2 + 1}} \sin \theta \hat{j} - \hat{k}$$

So the surface area is given by

$$\int_{-2}^2 \int_0^{2\pi} |\vec{w}(\theta, z)| d\theta dz = \int_{-2}^2 \int_0^{2\pi} \sqrt{2z^2 + 1} d\theta dz =$$

$$= 4\pi \int_0^2 \sqrt{2z^2 + 1} dz = 12\pi + \sqrt{2}\pi \ln(3 + 2\sqrt{2})$$

- (g) The parametrization is  $\vec{R}(\varphi, \theta) = a \sin \varphi \cos \theta \hat{i} + b \sin \varphi \sin \theta \hat{j} + c \cos \varphi \hat{k}$ , with  $0 \leq \varphi \leq \frac{\pi}{2}$ ,  $0 \leq \theta \leq 2\pi$ . Hence

$$\frac{\partial \vec{R}}{\partial \varphi} = a \cos \varphi \cos \theta \hat{i} + b \cos \varphi \sin \theta \hat{j} - c \sin \varphi \hat{k},$$

$$\frac{\partial \vec{R}}{\partial \theta} = -a \sin \varphi \sin \theta \hat{i} + b \sin \varphi \cos \theta \hat{j}$$

So  $\vec{w}(u, v) = bc \sin^2 \varphi \cos \theta \hat{i} + ac \sin^2 \varphi \sin \theta \hat{j} + ab \sin \varphi \cos \varphi \hat{k}$ . The surface area is given by the integral

$$\int_0^{\frac{\pi}{2}} \int_0^{2\pi} abc \sin \varphi \sqrt{\frac{\sin^2 \varphi \cos^2 \theta}{a^2} + \frac{a^2 c^2 \sin^2 \varphi \sin^2 \theta}{b^2} + \frac{\cos^2 \varphi}{c^2}} d\theta d\varphi$$

5. § 21.7 1.

In both cases,  $C$  is a loop, i.e. a simple closed curve. For (b) this is obvious, for (a) it is easily verifiable. To obtain a two-sided surface, choose a point  $P$  on  $C$  and start moving points  $P'(t)$  and  $P''(t)$  on  $C$  away from  $P$  in opposite directions. Because  $C$  is a loop,  $P'$  and  $P''$  will meet again at a point distinct from  $P$ . The union of all segments  $P'(t)P''(t)$  is a two-sided surface.

6. § 22.3 2. Because of symmetry between  $x$  and  $y$ ,

$$\int \int_S x^2 z d\sigma = \int \int_S y^2 z d\sigma = \frac{1}{2} \int \int_S (x^2 + y^2) z d\sigma$$

Let  $S_1$  be the top of the cylinder and let  $S_2$  be the vertical part of  $S$ . Then

$$\frac{1}{2} \int \int_S (x^2 + y^2) z d\sigma = \frac{1}{2} \int \int_{S_1} r^2 d\sigma + \frac{1}{2} \int \int_{S_2} z d\sigma$$

Let  $t = z - \frac{1}{2}$  and consider the cylinder  $S'$  in  $x, y, t$  coordinates with function  $f(x, y, t) = t$ . For  $P(x, y, t)$  on  $S'$ ,  $P'(x, y, -t)$  is on  $S'$  as well, and  $f(P) = -f(P')$ . Hence  $\int \int_{S'} f d\sigma = 0$ , so  $\int \int_{S_2} z d\sigma = \frac{1}{2} \int \int_{S_2} d\sigma$ . If we divide  $S_2$  into  $n$  equal cylinders, the Riemann Sum of  $\int \int_{S_2} d\sigma$  corresponding to this division is  $2\pi$ . Hence  $\int \int_{S_2} d\sigma = 2\pi$ , so

$$\frac{1}{2} \int \int_{S_2} z d\sigma = \frac{1}{4} \int \int_{S_2} d\sigma = \frac{\pi}{2}$$

So the integral we are evaluating is

$$\begin{aligned} \int \int_S x^2 z d\sigma &= \frac{1}{2} \int \int_{S_1} r^2 d\sigma + \frac{\pi}{2} = \\ &= \pi \int_0^1 r^3 dr + \frac{\pi}{2} = \frac{\pi}{4} + \frac{\pi}{2} = \frac{3\pi}{4} \end{aligned}$$

7. § 22.3 3.

(a) As in the previous problem, if we shift the cylinder vertically by half its altitude, we get that  $\int \int_{S'} z d\sigma = 0$ , by symmetry with respect to the  $xy$  plane. Hence

$$\int \int_S z d\sigma = \frac{3}{2} \int \int_S d\sigma = \frac{3}{2} (2\pi \cdot 2 \cdot 3 + 2\pi \cdot 2^2) = 30\pi,$$

since by looking at the Riemann sum we can see that  $\int \int_S d\sigma$  is equal to the area of the closed cylinder.

(b) Because the cylinder is symmetrical with respect to the  $x$  axis,

$$\int \int_S x d\sigma = 0$$

(c) Because the cylinder is symmetrical with respect to the  $yz$  plane,

$$\int \int_S xyz d\sigma = 0$$

(d)

$$\int \int_S x^2 d\sigma = \int \int_S y^2 d\sigma = \frac{1}{2} \int \int_S (x^2 + y^2) d\sigma$$

Let  $S_1$  be the bottom of the cylinder and let  $S_2$  be the vertical part of  $S$ . Then

$$\begin{aligned} \frac{1}{2} \int \int_S (x^2 + y^2) d\sigma &= \int \int_{S_1} r^2 d\sigma + \frac{1}{2} \int \int_{S_2} 4 d\sigma = \\ &= 2\pi \int_0^2 r^3 dr + 2(2\pi \cdot 2 \cdot 3) = 32\pi \end{aligned}$$

8. § 22.5 3abc.

Let  $S_1$  be the bottom of  $S$ , let  $S_2$  be the vertical part of  $S$ , and let  $S_3$  be the top of  $S$ .

(a)

$$\begin{aligned} \int \int_S (z\hat{k}) \cdot d\vec{\sigma} &= 3 \int \int_{S_3} (\hat{k} \cdot \hat{k}) dr d\theta + \int \int_{S_2} (z\hat{k} \cdot 2\hat{r}) d\theta dz = \\ &= 3 \int \int_{S_3} dr d\theta = 12\pi \end{aligned}$$

(b)

$$\begin{aligned} \int \int_S (x\hat{i} + y\hat{j}) \cdot d\vec{\sigma} &= \int \int_S (r\hat{r}) \cdot d\vec{\sigma} = \\ &= \int \int_{S_1} (-r\hat{r} \cdot \hat{k}) dr d\theta + \int \int_{S_3} (r\hat{r} \cdot \hat{k}) dr d\theta + \int \int_{S_2} (2\hat{r} \cdot 2\hat{r}) d\theta dz = \\ &= 4 \int \int_{S_2} d\theta dz = 48\pi \end{aligned}$$

(c)

$$\begin{aligned} \int \int_S (-y\hat{i} + x\hat{j}) \cdot d\vec{\sigma} &= \int \int_S (r\hat{\theta}) \cdot d\vec{\sigma} = \\ &= \int \int_{S_1} (-r\hat{\theta} \cdot \hat{k}) dr d\theta + \int \int_{S_3} (r\hat{\theta} \cdot \hat{k}) dr d\theta + \int \int_{S_2} (2\hat{\theta} \cdot 2\hat{r}) d\theta dz = 0 \end{aligned}$$

9. § 22.5 3de.

Let  $S_1$  be the bottom of  $S$ , let  $S_2$  be the vertical part of  $S$ , and let  $S_3$  be the top of  $S$ .

(d)

$$\begin{aligned} & \int_S (x^2 \hat{i}) \cdot d\vec{\sigma} = \\ &= \int \int_{S_1} (x^2 \hat{i}) \cdot \hat{k} dr d\theta + \int \int_{S_3} (-x \hat{i} \cdot \hat{k}) dr d\theta + \int \int_{S_2} (x^2 \hat{i} \cdot 2\hat{r}) d\theta dz = \\ &= \int \int_{S_2} x^3 d\theta dz = 0, \end{aligned}$$

since  $S_2$  is symmetrical with respect to the  $x$  axis, and  $(-x)^3 = -x^3$ .

(e) In the same manner as in (d), we get

$$\begin{aligned} & \int \int_S (x^3 \hat{i}) \cdot d\vec{\sigma} = \int \int_S x^4 d\theta dz = 48 \int_0^{2\pi} \cos^4 \theta d\theta = \\ &= 24 \int_0^{2\pi} (1 - 2 \cos^2 \theta \sin^2 \theta) d\theta = 48\pi - 12 \int_0^{2\pi} \sin^2(2\theta) d\theta = \\ &= 48\pi - 6 \int_0^{4\pi} \sin^2 \theta d\theta = 48\pi - 3 \int_0^{4\pi} d\theta = 36\pi \end{aligned}$$

10. § 22.6 3.

Since  $d\vec{\sigma} = \hat{n} d\sigma$ , if we denote  $\vec{F} = f\hat{n}$ , it follows that

$$\int \int_S f d\vec{\sigma} = \int \int_S f \hat{n} d\sigma = \int \int_S \vec{F} d\sigma$$

This last integral can be evaluated by definition with the help of Riemann sums.

11. § 23.1 2.

- (a) Not elementary, not regular.
- (b) Elementary, therefore regular.
- (c) Regular, not elementary.
- (d) Regular, not elementary.

12. § 23.2 1.

- (a) The perimeter of  $R$  is not a measure. Suppose we divide  $R$  in regular subregions  $R_1$  and  $R_2$ . Then if  $R_1$  and  $R_2$  have a common boundary of positive length, this length is equal to  $\mu(R_1) + \mu(R_2) - \mu(R)$ , so  $\mu(R) \neq \mu(R_1) + \mu(R_2)$ .
- (b)  $\mu(R) = 5 \text{ area}(R)$  is a measure. If regular  $R_1$  and  $R_2$  form a subdivision of  $R$ , then  $R_1 \cap R_2$  doesn't have positive area, so  $\mu(R) = \mu(R_1) + \mu(R_2)$ .  $\mu(R)$  is also an integral measure:

$$\mu(R) = \int \int_R 5dA$$

- (c)  $\mu(R) = [\text{area}(R)]^2$  is not a measure. Since  $\text{area}(R) = \text{area}(R_1) + \text{area}(R_2)$ , if  $\text{area}(R_1) \neq 0$  and  $\text{area}(R_2) \neq 0$ , then  $\mu(R) \neq \mu(R_1) + \mu(R_2)$ .
- (d)  $\mu(R) = \text{area}(R \cap H_1) - \text{area}(R \cap H_2)$  is a measure. Let  $f$  be a map  $f$  on  $\mathbf{E}^2$ , such that  $f(P) = 1$  for  $P \in H_1 - H_2$ ,  $f(P) = 0$  for  $P \in H_1 \cap H_2$ , and  $f(P) = -1$  for  $P \in H_2 - H_1$ . Then  $\mu(R) = \int \int_R f dA$ . Hence  $\mu(R)$  is an integral measure.

13. § 23.2 2.

- (a)  $\mu(R) = -2 \text{ volume}(R)$  is a measure. In fact, it is an integral measure:  

$$\mu(R) = \int \int \int_R -2dV.$$
- (b)  $\mu(R) = \text{volume}(R \cap H_1) - \text{volume}(R \cap H_2)$  is a measure. It is an integral measure. We define map  $f$  such that  $f(P) = 1$  for  $P \in H_1 - H_2$ ,  $f(P) = 0$  for  $P \in H_1 \cap H_2$ , and  $f(P) = -1$  for  $P \in H_2 - H_1$ . Then  $\mu(R) = \int \int \int_R f dV$ .
- (c)  $\mu(R) = \text{volume}(R \cap T) - \text{volume}(R \cap T_0)$  is a measure. It is an integral measure. We define map  $f$  such that  $f(P) = 1$  for  $P \in T - T_0$ ,  $f(P) = 0$  for  $P$  on the surface of  $T$ , and  $f(P) = -1$  for  $P \in T_0 - T$ . Then  $\mu(R) = \int \int \int_R f dV$ .