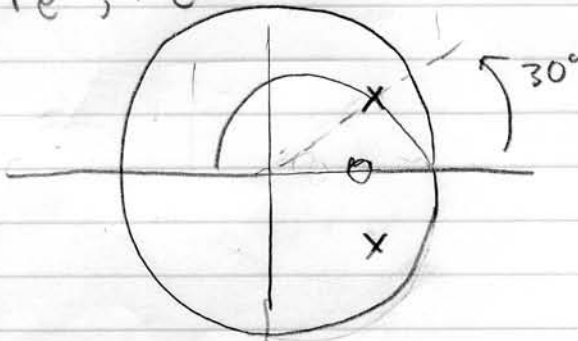


4.19 2nd order system

$$\zeta = 0.5$$

poles at $\theta = 30^\circ$

$$z = re^{i\theta}, r = e^{-\zeta\omega_n T}$$



$$Y(z) = \frac{z - 0.6}{z^2 - 2r\cos\theta z + r^2}$$

Solving for parameters using table 4.2 in FPW...

$$\theta = \omega_n T \sqrt{1 - \zeta^2} = \frac{1}{6} \pi = \omega_n T \sqrt{1 - .5^2}$$

$$\omega_n T = .6046$$

$$r = \exp(-\zeta\omega_n T) = \exp(-.5 \cdot .6046) = 0.7391$$

$$G = 1/1.5036 \text{ (for unity gain at DC)}$$

The overshoot should be approximately 30-40% according to Figure 4.30 in FPW.

The discrete bode plot and the step response are attached,

$$4.28 \quad G(s) = \frac{10(s+1)}{s^2+s+10}$$

$$T = 0.01 \text{ sec}$$

$$\begin{aligned} \frac{G(s)}{s} &= \frac{10(s+1)}{s(s^2+s+10)} = \frac{10}{s^2+s+10} + \frac{10}{s(s^2+s+10)} \\ &= \frac{10}{s^2+s+10} + \frac{A}{s} + \frac{B}{s^2+s+10} \end{aligned}$$

$$A(s^2+s+10) + Bs = 10$$

$$A=1, B=-(s+1)$$

$$\begin{aligned} \frac{G(s)}{s} &= \frac{10}{s^2+s+10} + \frac{1}{s} - \frac{s+1}{s^2+s+10} \\ &= \frac{-s+9}{(s+0.5)^2+9.75} + \frac{1}{s} = -\frac{s+0.5}{(s+0.5)^2+9.75} + \frac{9.5}{(s+0.5)^2+9.75} + \frac{1}{s} \end{aligned}$$

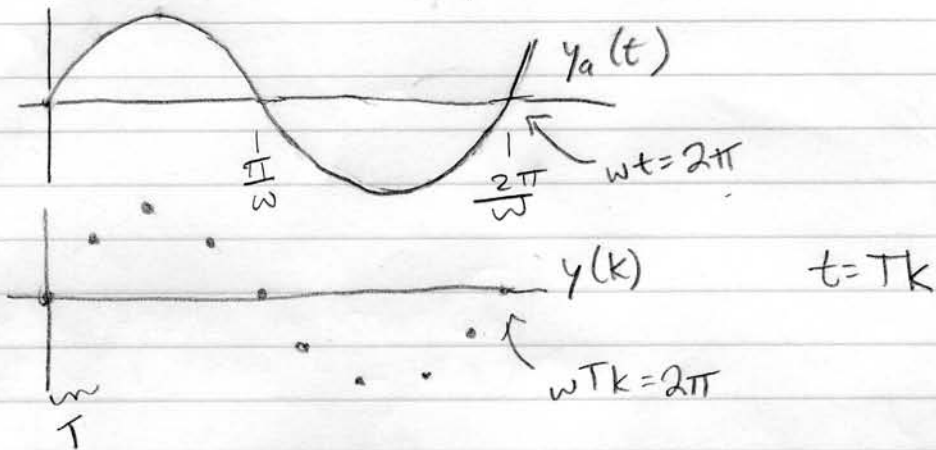
$$\begin{aligned} Z\left\{\frac{G(s)}{s}\right\} &= \frac{z}{z-1} - \frac{z(z-e^{-0.5T} \cos(\sqrt{9.75}T))}{z^2-2e^{-0.5T} \cos(\sqrt{9.75}T)z+e^{-T}} \\ &\quad + \frac{9.5}{\sqrt{9.75}} \frac{ze^{-0.5T} \sin(\sqrt{9.75}T)}{z^2-2e^{-0.5T} \cos(\sqrt{9.75}T)z+e^{-T}} \end{aligned}$$

$$G(z) = 1 - (z-1) \left(z - e^{-0.5T} \cos(\sqrt{9.75}T) + \frac{9.5}{\sqrt{9.75}} e^{-0.5T} \sin(\sqrt{9.75}T) \right) \frac{1}{z^2 - 2e^{-0.5T} \cos(\sqrt{9.75}T)z + e^{-T}}$$

$$\text{MATLAB Answer: } G(z) = \frac{0.09998z - 0.09899}{z^2 - 1.989z + 0.99}$$

$$G(z) = \frac{0.9998z - 0.09899}{z^2 - 1.989z + 0.99} \text{ given } T=0.01$$

Problem 4: (a)

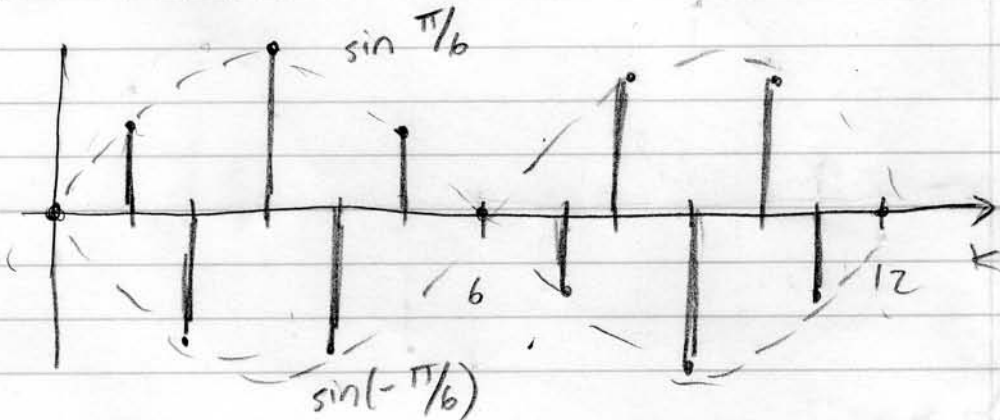


$$y(k) = \sin \Omega k, \quad \Omega = \omega T$$

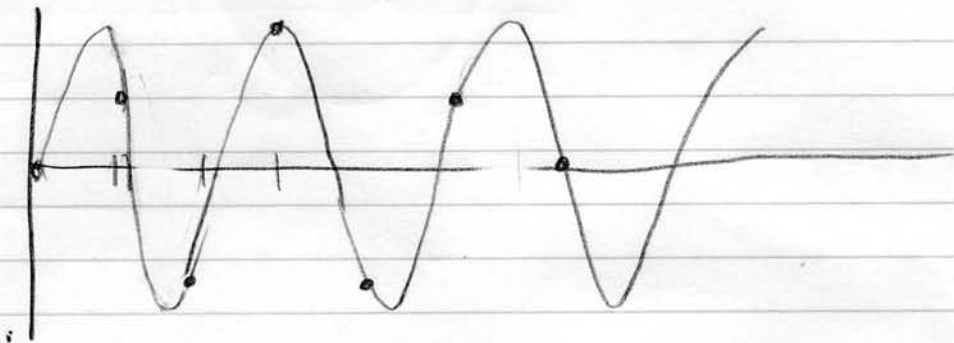
$$(b) \sin \Omega k = \frac{1}{2} [\sin \Omega k + \sin (\Omega - 2\pi)k]$$

$$\begin{aligned} \sin \Omega k &= \frac{1}{2} \sin(ak) \sin(bk), \text{ where } a = \Omega \text{ and } b = \Omega - 2\pi \\ &= \frac{1}{2} [\sin(A+B)k + \sin(A-B)k] \text{ where } A = \frac{a+b}{2} = \Omega - \pi, B = \frac{a-b}{2} = \pi \\ &= \sin(Ak) \cos(Bk) \\ &= \sin((\Omega - \pi)k) \cos(\pi k) \\ &= \sin(\Delta k) \cos(\pi k) \end{aligned}$$

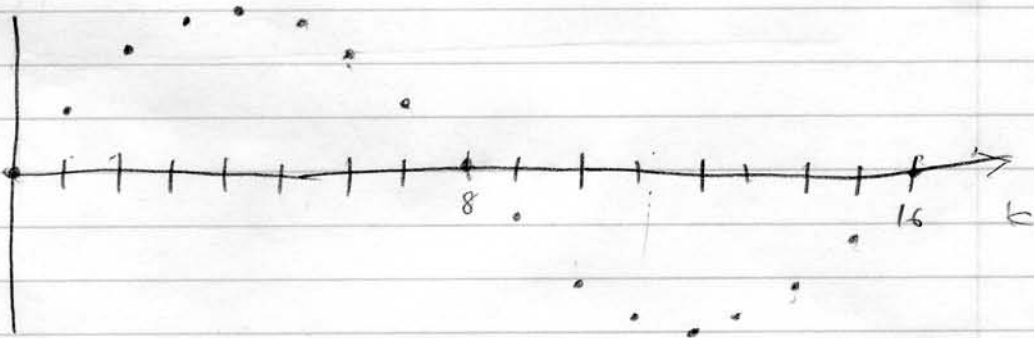
$$(c) y(k) = \sin\left(\frac{5\pi}{6}k\right)$$



(d) $y_a(t) = \sin\left(\frac{5\pi}{6} t\right)$

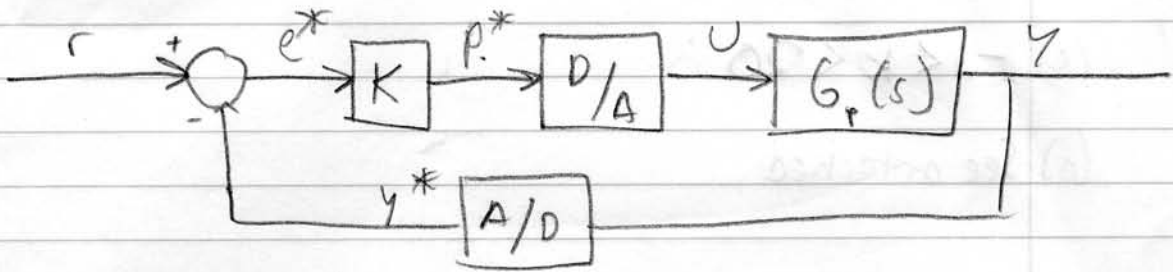


(e) Assume $y(k) = \sin\left(\frac{\pi}{8} k\right)$



The "beat" frequency is high so the beating envelope is not visible

Problem 5



$$G_p(s) = \frac{10(s+1)}{s^2 + s + 10}$$

$$T = 10 \text{ msec}$$

$$(a) G(z) = \frac{0.9998z - 0.09899}{z^2 - 1.989z + 0.99}$$

$$e^* = r^* - y^*$$

$$p^* = K e^*$$

$$u = p^* \left[\frac{1 - e^{-Ts}}{s} \right]$$

$$y = G_p(s) u$$

$$y^* = [G u]^*$$

$$y^* = [G p^* \left[\frac{1 - e^{-Ts}}{s} \right]]^* = (1 - e^{-Ts}) p^* \left(\frac{G}{s} \right)^*$$

$$y^* = (1 - e^{-Ts}) K e^* \left(\frac{G}{s} \right)^*$$

$$y^* = (1 - e^{-Ts}) K (r^* - y^*) \left(\frac{G}{s} \right)^*$$

$$(1 - e^{-Ts}) K \left(\frac{G}{s} \right)^* = H^*$$

$$Y^* = \frac{H^*}{1 + H^*} r^*$$

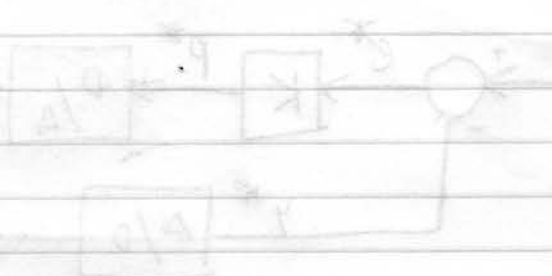
$$\frac{Y^*}{r^*} = \frac{Y(z)}{R(z)} = \frac{K(0.9998z - 0.09899)}{z^2 - (1.989 - 0.9998K)z + 0.99 - 0.09899K}$$

(b) Zeros: $z = 0.0992$

$$\text{Poles: } z = \frac{(1.989 - 0.9998K) \pm \sqrt{(1.989 - 0.9998K)^2 - 4(0.99 - 0.09899K)}}{2}$$

(c) $-1 < k < 20$

(d) See attached



$$G(s) = \frac{K}{s(s+1)}$$

$$T = 10 \text{ msec}$$

$$G_c(s) = \frac{0.1}{s} = \frac{1}{10s}$$

$$G_c(s) = \frac{1}{10s}$$

$$G_c(s) = \frac{1}{10s}$$

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$$G_c(s) = \frac{1}{10s}$$

$$G_c(s) = \frac{1}{10s}$$

Problem 6 $H(z) = \frac{0.5z^5 - 0.5}{z^6 + 0.5z^5}$

(a) $H(z) = \frac{v(z)}{e(z)}$

$$(z^6 + 0.5z^5)v(z) = (0.5z^5 - 0.5)e(z)$$

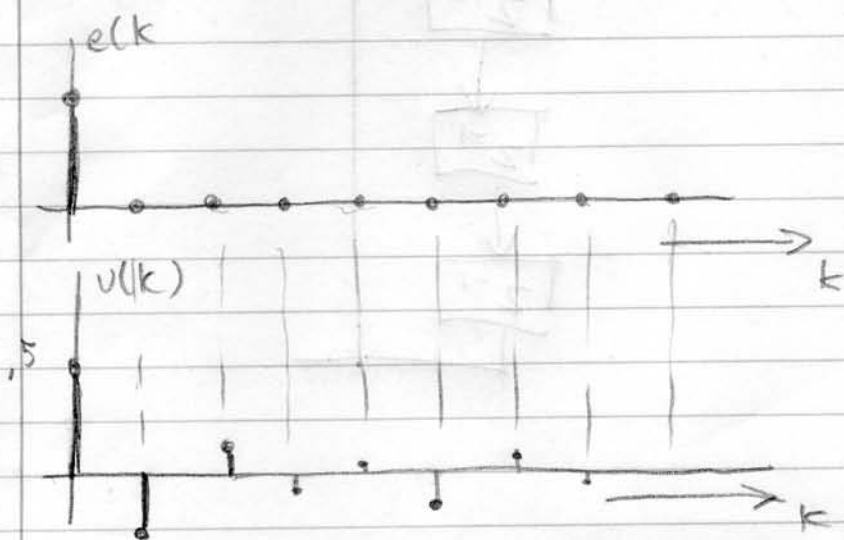
$$v(k+6) + 0.5v(k+5) = 0.5e(k+5) - 0.5e(k)$$

(b) The DC gain is found by setting $z=1$

$$H(1) = \frac{0.5 - 0.5}{1 + 0.5} = 0$$

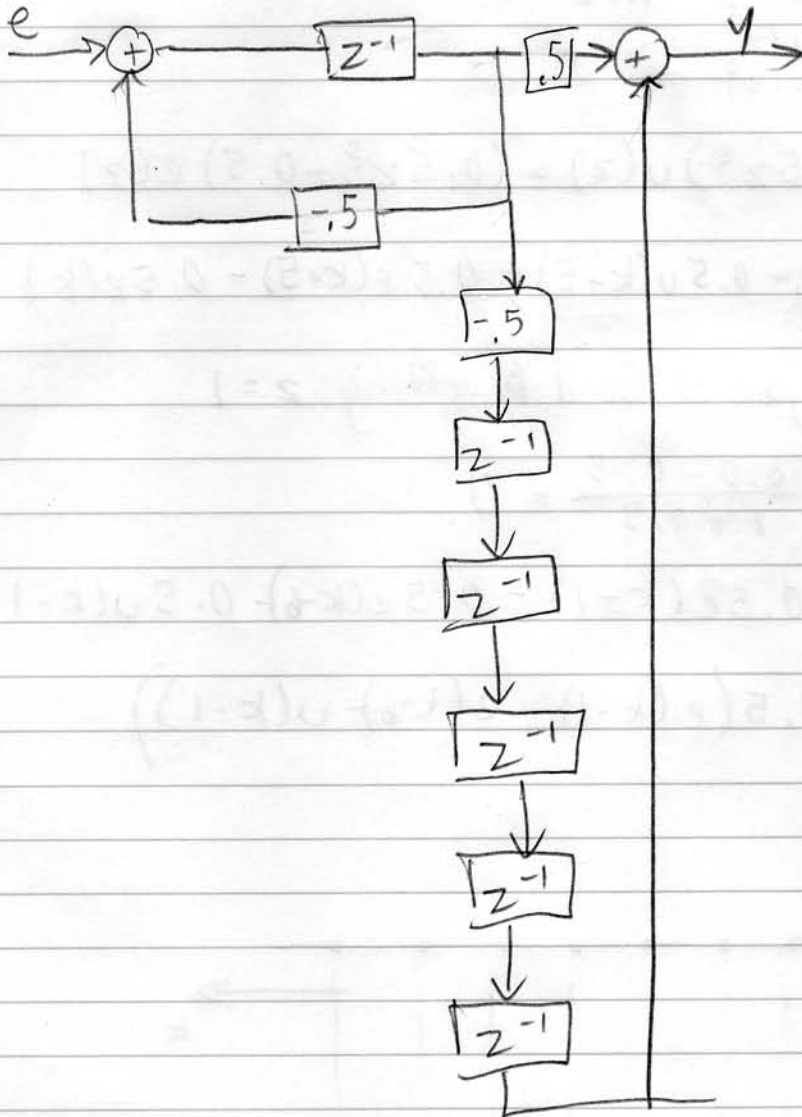
(c) $v(k) = 0.5e(k-1) - 0.5e(k-6) + 0.5v(k-1)$

$$v(k) = 0.5(e(k-1) - e(k-6) + v(k-1))$$

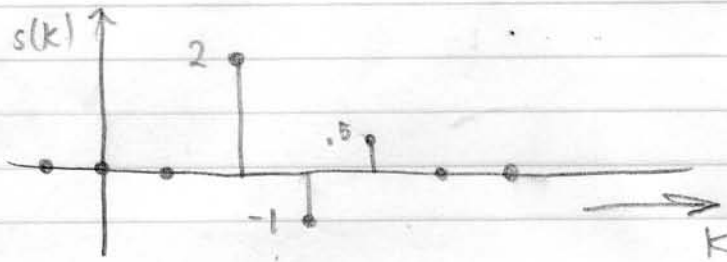


k	e(k)	v(k)	e(k-1)	e(k-6)	v(k-1)
0	1	0	0	0	0
1	0	.5	1	0	0
2	0	-.25	0	0	.5
3	0	.125	0	0	-.25
4	0	-.6125	0	0	.125
5	0	.306125	0	0	-.6125
6	0	-.65	0	1	.306125
7	0	.325	0	0	-.65
8	0	-.6125	0	0	.306125

(b)



Problem 7



$$(a) s(k) = 2u(k-2) - 3u(k-3) + 1.5u(k-4) - 0.5u(k-5)$$

$$(b) \alpha_0$$

$$\alpha_1$$

$$\alpha_2$$

$$\alpha_3$$

$$y(0) = \alpha_0 = 2$$

$$y(1) = \alpha_1 = -3$$

$$y(2) = \alpha_2 = 1.5$$

$$y(3) = \alpha_3 = -0.5$$

$$(c) S(z) = 2z^{-2} - z^{-3} + 0.5z^{-4} = \frac{2z^2 - z + 0.5}{z^4}$$

$$H(z) = 2z^{-2} - 3z^{-3} + 1.5z^{-4} - 0.5z^{-5}$$

$$= \frac{2z^3 - 3z^2 + 1.5z - 0.5}{z^5}$$

$$S(z) = H(z) \cdot \frac{z}{z-1}$$

The step response is given by the impulse response multiplied by a unit step.