

## Problem set # 2 - SOLUTION

## Problem 1 - Microtubule structure

- Flexural rigidity  $\kappa_f = Y \cdot I$ , where  $\begin{cases} Y \text{ is the microtubule's Young modulus} \\ \text{take } Y = 10^3 \text{ J.m}^{-3} \text{ (Boal p. 53)} \\ I \text{ moment of inertia} \end{cases}$

$$\left. \begin{array}{l} \text{- hollow tube } R = 14 \text{ nm} \\ \quad R_i = 11.5 \text{ nm} \end{array} \right\} I_h = \frac{\pi}{4} (R^4 - R_i^4) = 1.64 \cdot 10^{-32} \text{ m}^4 \quad \left. \begin{array}{l} \text{- solid tube } R = 14 \text{ nm} \\ \quad R_i = 0 \text{ nm} \end{array} \right\} I_s = \frac{\pi}{4} R^4 = 3.02 \cdot 10^{-32} \text{ m}^4 \quad \left. \begin{array}{l} \frac{I_s}{I_h} = 1.84 \end{array} \right.$$

- Mass ratio of a microtubule of density  $\rho_m = 10^3 \text{ kg m}^{-3}$  and length L
- hollow tube  $m_h = \rho_m \cdot \pi \cdot (R^2 - R_i^2) \cdot L$
- solid tube  $m_s = \rho_m \cdot \pi \cdot R^2 \cdot L$

$$\frac{m_s}{m_h} = \frac{1}{1 - \frac{R_i^2}{R^2}} = 3.07$$

While a hollow microtubule has only around one third of the mass of a solid microtubule, it has over half its rigidity. The most efficient way for a cell to gain rigidity is to use many hollow microtubules rather than one solid one, it makes better use of the number of proteins required, of its resources in proteins.

## Problem 3 - Properties of ideal chains

From Boal's chapter 2 p. 44-45, we have, for an ideal chain in 3-D:

$$p^*(r) = 4\pi r^2 (2\pi\sigma^2)^{-3/2} \exp\left(-\frac{r^2}{2\sigma^2}\right) \quad \text{with } \sigma^2 = \frac{Nb^2}{3}$$

$$\langle r_{ee} \rangle = \frac{\int_{r_{ee}=0}^{+\infty} r_{ee} p^*(r_{ee}) dr_{ee}}{\int_{r_{ee}=0}^{+\infty} p^*(r_{ee}) dr_{ee}} ; \quad \text{let's momentarily write 'r' instead of 'r_{ee}' for the sake of clarity.}$$

$$\bullet \int_0^{+\infty} r p^*(r) dr = 4\pi (2\pi\sigma^2)^{-3/2} \int_0^{+\infty} r^3 \exp\left(-\frac{r^2}{2\sigma^2}\right) dr, \quad \text{which we integrate by parts:}$$

$$= 4\pi (2\pi\sigma^2)^{-3/2} \left\{ \left[ -\sigma^2 r^2 \exp\left(-\frac{r^2}{2\sigma^2}\right) \right]_0^{+\infty} + 2\sigma^2 \int_0^{+\infty} r \exp\left(-\frac{r^2}{2\sigma^2}\right) dr \right\}$$

$$= 4\pi (2\pi\sigma^2)^{-3/2} \left[ -2\sigma^4 \exp\left(\frac{-r^2}{2\sigma^2}\right) \right]_0^{+\infty} = \left(\frac{8}{\pi}\right)^{1/2} \sigma^{5/2}$$

$$\bullet \int_0^{+\infty} p^*(r) dr = 4\pi (2\pi\sigma^2)^{-3/2} \int_0^{+\infty} r^2 \exp\left(-\frac{r^2}{2\sigma^2}\right) dr = 4\pi (2\pi\sigma^2)^{-3/2} \left\{ \left[ -r\sigma^2 \exp\left(\frac{-r^2}{2\sigma^2}\right) \right]_0^{+\infty} + \sigma^2 \int_0^{+\infty} \exp\left(\frac{-r^2}{2\sigma^2}\right) dr \right\}$$

$$= 4\pi (2\pi\sigma^2)^{-3/2} \sigma^2 \cdot \frac{\sigma}{2} \sqrt{2\pi} = \sigma^{3/2}$$

$$\langle r_{ee} \rangle = \left(\frac{8}{\pi}\right)^{1/2} \sigma^{5/2} \cdot \sigma^{-3/2} = \left(\frac{8\sigma^2}{\pi}\right)^{1/2} = \underline{\underline{\left(\frac{8}{3\pi}\right)^{1/2} N^{1/2} b}}$$

## Problem set # 2 - SOLUTION

## Problem 2 - Entropic elasticity of a 1-D polymer chain model

Freely jointed chain model in 1D

a) Probability of a given conformation  $p(\sigma_1, \dots, \sigma_N) = \frac{1}{Q} \exp\left(\frac{-U(\sigma_1, \dots, \sigma_N)}{kT}\right) \exp\left(\frac{f \cdot z \underline{\sigma}}{kT}\right)$

where  $U(\sigma_1, \dots, \sigma_N)$  is the internal energy of the system in the  $\{\sigma_1, \dots, \sigma_N\}$  configuration

$$\left\{ \begin{array}{l} U(\sigma_1, \dots, \sigma_N) = 0 \text{ in the FJC model} \\ \underline{\sigma} \text{ is the unit vector of the 1-D space} \end{array} \right.$$

$f$  and  $z\underline{\sigma}$  are colinear in a 1-D space, thus  $f \cdot z\underline{\sigma} = fz = fb \sum_{i=1}^N \sigma_i$

and where  $Q' = \int_{\text{phase space}} \exp\left(\frac{fb \sum_{i=1}^N \sigma_i}{kT}\right)$ , under the assumption that  $U_{\text{any microstate}} = 0$ .

Here, the phase space is the ensemble of all possible arrangements of  $\sigma_i$ ,  $i \in [1, N]$ , each of the  $\sigma_i$ 's being either 1 or -1

$$Q' = \int_{\forall i \in [1, N], \sigma_i = -1 \text{ or } 1} \exp\left(\frac{fb}{kT} \sigma_1\right) \exp\left(\frac{fb}{kT} \sigma_2\right) \dots \exp\left(\frac{fb}{kT} \sigma_N\right)$$

Each exponential factor is actually identical, for no correlation exists from one segment to another one

$$\begin{aligned} Q' &= \left[ \exp\left(\frac{fb}{kT}\right) + \exp\left(-\frac{fb}{kT}\right) \right] \cdot \left[ \exp\left(\frac{fb}{kT}\right) + \exp\left(-\frac{fb}{kT}\right) \right] \dots \left[ \exp\left(\frac{fb}{kT}\right) + \exp\left(-\frac{fb}{kT}\right) \right] \\ &= \left[ \exp\left(\frac{fb}{kT}\right) + \exp\left(-\frac{fb}{kT}\right) \right]^N \end{aligned}$$

$$p(\sigma_1, \dots, \sigma_N) = \frac{1}{\left[ \exp\left(\frac{fb}{kT}\right) + \exp\left(-\frac{fb}{kT}\right) \right]^N} \cdot \exp\left(\frac{fb}{kT} \sum_{i=1}^N \sigma_i\right)$$

## b) Force / extension behavior of a 1-D FJC

$$\langle z \rangle = \frac{1}{Q'} \int_{\substack{\text{phase} \\ \text{space}}} z(\sigma_1, \dots, \sigma_N) p(\sigma_1, \dots, \sigma_N) = kT \frac{\partial}{\partial f} \ln Q' \quad \text{, where } z(\sigma_1, \dots, \sigma_N) = b \sum_{i=1}^N \sigma_i$$

From the expression for  $Q'$  in a), we have  $\langle z \rangle = kT \frac{\partial}{\partial f} \ln \left\{ \left[ \exp\left(\frac{fb}{kT}\right) + \exp\left(-\frac{fb}{kT}\right) \right]^N \right\}$

$$\begin{aligned} \langle z \rangle &= NkT \cdot \frac{1}{e^x + e^{-x}} \cdot \frac{\partial}{\partial f} (e^x + e^{-x}) \quad \text{where } x = \frac{fb}{kT} \\ &= NkT \cdot \frac{b}{kT} \cdot \frac{e^x - e^{-x}}{e^x + e^{-x}}, \text{ which we can write again} \end{aligned}$$

$$\frac{\langle z \rangle}{Nb} = \tanh\left(\frac{fb}{kT}\right)$$

c) Small force limit : for  $f \ll \frac{kT}{b}$  and  $x = \frac{fb}{kT}$ ,

$$e^x \sim 1 + x$$

$$\langle z \rangle \sim Nb \cdot \frac{(1+x) - (1-x)}{(1+x) + (1-x)} = Nb x$$

$$1\text{D-} \langle z \rangle \rightarrow \frac{fb}{kT} Nb$$

A spring constant (defined through entropic reasoning) would be defined as  $k_{1D} = \frac{f}{\langle z \rangle}$ .

$$k_{1D} = \frac{kT}{Nb^2} = \frac{1}{3} k_{3D}$$

(see class notes where in 3D  $\langle z \rangle \rightarrow \frac{1}{3} \frac{fb}{kT} Nb$ )

d) One could anticipate the spring constant for the small force limit of a 2D FJC model to be  $k_{2D} = 2 \frac{kT}{Nb^2}$ .

## Problem set # 2 - SOLUTION

## Problem 4 - DNA folding

## a) Free energy variations

From class notes, the free energy  $A$  can be expressed in terms of the partition function  $Q$ :

$$A = -k_B T \ln Q$$

Consider the two macrostates "hairpin" & "random"

$$\text{Hence } \frac{P_{\text{hairpin}}}{P_{\text{random}}} = \frac{Q_{\text{hairpin}}}{Q_{\text{random}}}$$

$$= \exp \left( \frac{-(A_{\text{hairpin}} - A_{\text{random}})}{k_B T} \right)$$

$$\begin{cases} P_{\text{hairpin}} = \frac{Q_{\text{hairpin}}}{Q} \\ P_{\text{random}} = \frac{Q_{\text{random}}}{Q} \end{cases}$$

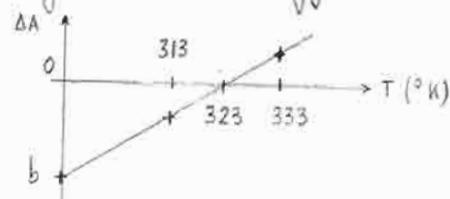
$$A_{\text{hairpin}} - A_{\text{random}} = -k_B T \ln \left( \frac{P_{\text{hairpin}}}{P_{\text{random}}} \right)$$

Temperature (°C)	$P_{\text{hairpin}}$	$\frac{P_{\text{hairpin}}}{P_{\text{random}}}$	$A_{\text{hairpin}} - A_{\text{random}}$ (J)	
40	0.37	6.69	$-8.2 \cdot 10^{-21} \text{ J}$	( $\approx -2 k_B T$ )
50	0.5	1	0	
60	0.13	0.15	$+8.7 \cdot 10^{-21} \text{ J}$	( $\approx +2 k_B T$ )

b) When  $T$  increases by  $10^{\circ}\text{K}$  ( $= 10^{\circ}\text{C}$ ),  $\Delta A$  increases by  $2 k_B T$  (or  $\approx 50 \text{ kJ/mol}^{-1}$ ).

$$\left. \begin{array}{l} A_{\text{hairpin}} = U_{\text{hairpin}} - TS_{\text{hairpin}} \\ A_{\text{random}} = U_{\text{random}} - TS_{\text{random}} \end{array} \right\} \Delta A = \underbrace{(U_{\text{hairpin}} - U_{\text{random}})}_{(i)} - T \underbrace{(S_{\text{hairpin}} - S_{\text{random}})}_{(ii)}$$

## (i) change in internal energy



From base-pairing number of accessible configurations changes

$$\text{intersect } \Delta U = -T_{\Delta A=0} \cdot \text{slope} = -(273 + 50) \frac{8.2 \cdot 10^{-21}}{10} = -2.65 \cdot 10^{-19} \text{ J}$$

and corresponds to the formation of 14 base pairs

$$\text{Therefore } \Delta U_{\text{base-pairing}} = \frac{-2.65 \cdot 10^{-19}}{14} = -1.9 \cdot 10^{-21} \text{ J} = -4.4 \text{ } k_B T$$

## (ii) Ratio of accessible configurations

$$S_{\text{hairpin}} - S_{\text{random}} = -\text{slope} = -8.2 \cdot 10^{-22} \text{ J.K}^{-1} = k_B (\ln W_{\text{hairpin}} - \ln W_{\text{random}}) = k_B \ln \frac{W_{\text{hairpin}}}{W_{\text{random}}}$$

$$\frac{W_{\text{hairpin}}}{W_{\text{random}}} = \exp \frac{-\text{slope}}{k_B} = 1.6 \cdot 10^{-26}$$

The Hairpin configuration allows much fewer arrangements than the random one, but is favored energetically.

## Problem set # 2 . SOLUTION

## Problem 5- Dynamics of actin polymerization

## a) Three regimes of growth for the filament

$$\left\{ \begin{array}{l} \frac{dn^+}{dt} = k_{on}^+ [M] - k_{off}^+ \\ \frac{dn^-}{dt} = k_{on}^- [M] - k_{off}^- \end{array} \right.$$

$$\frac{dL}{dt} = \frac{dn^+}{dt} + \frac{dn^-}{dt}$$

One can choose to define

o regimes ①, ② and ③

$$\left. \begin{array}{l} ① 0 < [M] < [M]_1, \\ \frac{dn^+}{dt} < 0 \text{ and } \frac{dn^-}{dt} < 0 \end{array} \right\} \text{shrinkage at both ends}$$

$$\left. \begin{array}{l} ② [M]_1 < [M] < [M]_3, \\ \frac{dn^+}{dt} > 0 \text{ and } \frac{dn^-}{dt} < 0 \end{array} \right\} \text{growth at } +\text{ end, collapse at } -\text{ end}$$

depending on the relative velocities, the length of the filament can increase, decrease or remain constant ( $\frac{dL}{dt} = 0$  at  $[M] = [M]_2$ )

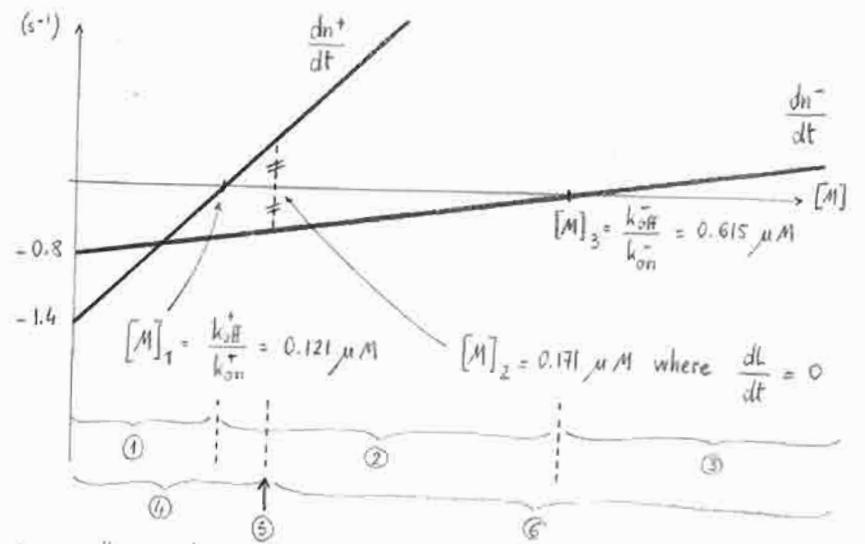
$$\left. \begin{array}{l} ③ [M] > [M]_3, \\ \frac{dn^+}{dt} > 0 \text{ and } \frac{dn^-}{dt} > 0 \end{array} \right\} \text{elongation at both ends}$$

o or regimes ④, ⑤, ⑥

$$\left. \begin{array}{l} ④ \frac{dL}{dt} < 0 \\ \text{shrinkage of filament} \end{array} \right.$$

$$\left. \begin{array}{l} ⑤ \frac{dL}{dt} > 0 \\ \text{elongation " " } \end{array} \right.$$

$$\left. \begin{array}{l} ⑥ \frac{dL}{dt} = 0 \\ \text{stationary regime, constant length for the actin filament} \end{array} \right.$$



## b) Treadmilling

Total length of filament constant in time if  $\frac{dn^+}{dt} = -\frac{dn^-}{dt}$  (or  $\frac{dL}{dt} = 0$ )

$$[M]_{\text{treadmilling}} = \frac{k_{off}^+ + k_{off}^-}{k_{on}^+ + k_{on}^-} = 0.171 \mu\text{mol. L}^{-1}$$



## c) Velocity of treadmilling

$$\left. \frac{dn^+}{dt} \right|_{\text{treadmilling}} = k_{on}^+ [M]_{\text{treadmilling}} - k_{off}^+ = 0.578 \text{ actin monomer per second}$$

Adding one actin monomer increases the length of the F-actin by  $\frac{5.5}{2} = 2.75 \text{ nm}$ , thus the leading edge moves forward at  $0.578 * 2.75 = 1.59 \text{ nm.s}^{-1} \ll 100 \text{ nm.s}^{-1}$  for keratocytes

## Problem set # 2. SOLUTION

## Problem 5 (cont'd)

d) Taking into account severing proteins

Severing proteins can increase  $k_{off}$  by 2 orders of magnitude. Take  $k_{off} = 100 k_{off/\text{initial}} = 80 \text{ s}^{-1}$ , and let the other constants remain the same.

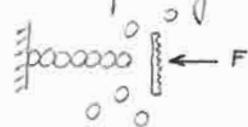
Now  $[M]_{\text{treadmilling with severing proteins}} = 6.31 \mu\text{M}$  and  $\frac{dn^+}{dt}_{\text{treadmilling with severing proteins}} = 71.8 \text{ s}^{-1}$  or  $197 \text{ nm. s}^{-1}$

Severing proteins increase the velocity of treadmilling.

e) In class we have derived two relations:

$$\boxed{F_{eq} = \frac{kT}{\delta} \ln \left( \frac{[M]}{K_c} \right)} \quad (1) \quad \text{where } \begin{cases} \delta : \text{length change in the filament when monomer added} \\ [M] : \text{concentration of monomers} \\ K_c : \text{critical dissociation constant} \end{cases}$$

(1) describes the following situation:



$F$  is the force required to stall the growth of the filament

(1) describes an equilibrium

$$\boxed{v = \frac{2D}{\delta}} \quad \text{where } D \text{ is the diffusion coefficient of monomers}$$

(2) describes the same process, from a kinetic point of view.

(1) would give us information about the ratio of states A & B

(filament with  $n$  &  $n+1$  monomers respectively), while (2) provides information about the energy barrier the 2 states (information given by reaction rates).

For actin pushing a particle

$$\begin{cases} D = \frac{kT}{\zeta} \\ \zeta = 6\pi \mu a \end{cases}$$

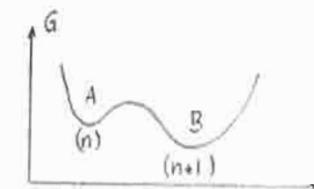
radius of particle

$$\text{take } \begin{cases} k = 1.38 \cdot 10^{-23} \text{ J.K}^{-1} \\ T = 310^\circ \text{ K (human body)} \\ \mu = 800 \cdot 10^{-6} \text{ N.s.m}^{-2} \\ \delta = 2.75 \text{ nm} \end{cases}$$

viscosity of medium (take water)

$$v = \frac{2D}{\delta} = \frac{2kT}{6\pi \mu a \delta} = \frac{kT}{3\pi \mu a \delta}$$

for $a = 10 \mu\text{m}$ ,	$v \approx 20 \mu\text{m.s}^{-1}$
$a = 100 \mu\text{m}$ ,	$v \approx 2 \mu\text{m.s}^{-1}$



$n$  = number of monomers in a filament