Magnetically Induced Strain In FePd

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Format

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 - Shape memory phenomenon
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Shape Memory Effect (SME)

- Parent phase austenite (FCC)
- Cool to form martensite (FCT)
- Twinned structure is energetically favorable
- Stress/magnetic field moves twin/phase boundaries
- Heat to recover strain

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FePd Phases



Twinning

- Minimizing strain energy
 - Slip
 - Breaks more bonds Image removed due to copyright considerations. See reference [2].
 - Twinning
 - Breaks less bonds

Magnetic Field Induced SME

• Magnetic field can move twin and phase boundaries

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Energetics

- Exchange: Neglect
- Magnetic anisotropy:
 - Uniaxial (FCT): $\mathbf{u}_{\mathbf{a}} = \mathbf{K}_{\mathbf{u}} \operatorname{Sin}^{2}[\boldsymbol{\theta}]$

- Cubic (FCC):
$$\mathbf{u}_{\mathbf{a}} = \mathbf{K}_{\mathbf{1}} \left(\alpha_{\mathbf{1}}^{2} \alpha_{\mathbf{2}}^{2} + \alpha_{\mathbf{2}}^{2} \alpha_{\mathbf{3}}^{2} + \alpha_{\mathbf{1}}^{2} \alpha_{\mathbf{3}}^{2} \right)$$

- Magnetoelastic: Insignificant
- Zeeman: $\mathbf{u}_{\mathbf{z}} = -\mathbf{M}_{\mathbf{s}} \cdot \mathbf{H}$
- Elastic strain: $U_e = \frac{1}{2} C_{eff} e_{ij}^2$

• Latent Heat:
$$u_{L} = 10.79 \left(\frac{erg}{cm^{3}}\right)$$

Variants for FePd

• 6 martensitic variants, 3 Austenite

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$$\mathbf{E}_{1} = \begin{bmatrix} \epsilon_{2} & & \\ & \epsilon_{1} & \\ & & \epsilon_{1} \end{bmatrix}, \quad \mathbf{m}_{1}^{a} = m_{s}(010), \quad \mathbf{m}_{1}^{b} = m_{s}(001),$$

$$\mathbf{E}_{2} = \begin{bmatrix} \epsilon_{1} & & \\ & \epsilon_{2} & \\ & & \epsilon_{1} \end{bmatrix}, \quad \mathbf{m}_{2}^{a} = m_{s}(100), \quad \mathbf{m}_{2}^{b} = m_{s}(001),$$
Image removed due to copyright considerations. See reference [5].
$$\mathbf{E}_{3} = \begin{bmatrix} \epsilon_{1} & & \\ & \epsilon_{2} & \\ & & \epsilon_{2} \end{bmatrix}, \quad \mathbf{m}_{3}^{a} = m_{s}(100), \quad \mathbf{m}_{3}^{b} = m_{s}(010).$$
Ref. [4]

• Quadratic programming problem of 9 variables

2D Simplification



• Magnetic anisotropy: $U_a = K_u \left(\frac{M_{sm} H}{2 K_u}\right)^2 f2 + K_1 \left(\frac{M_{sa} H}{2 K_1}\right)^2 fa$

• Zeeman:
$$U_z = -M_{sa} H fa - M_{sm} H f1$$

• Elastic strain:
$$U_e = \frac{1}{2} C_{eff} (e_x^2 + e_y^2)$$

- Latent Heat: $U_L = u_L$ (fa fao)
- Total: $\mathbf{U} = \mathbf{U}_{\mathbf{a}} + \mathbf{U}_{\mathbf{z}} + \mathbf{U}_{\mathbf{e}} + \mathbf{U}_{\mathbf{L}}$

• Volume Fraction vs. Magnetic Field (Low Field)



• Volume Fraction vs. Magnetic Field (High Field)



• Strain vs. Magnetic Field (Low Field)



• Strain vs. Magnetic Field (High Field)



Conclusion

- Low field (H ~ 1 kOe)
 - Twin boundary motion
 - Linear strain response (e ~ 1.5%)
 - Negligible phase transformation
- High Field (H \sim 1000 kOe)
 - Phase boundary motion
 - Nonlinear strain response (e ~ 3.0%)
 - Full phase transformation

References

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