

6.641 Quiz 2 Solutions

4/21/04

$$1. a) K_x = \frac{i}{D} \Rightarrow H_z = -K_x = -\frac{i}{D}$$

$$\Phi = -\mu_0 H_z S \hat{z} = \frac{\mu_0 S i}{D} \hat{z}$$

$$L(\hat{z}) = \frac{\Phi}{i} = \frac{\mu_0 S \hat{z}}{D}$$

$$b) \Phi_0 = L(\hat{z}_0) I_0 = \frac{\mu_0 S \hat{z}_0}{D} I_0 = \frac{\mu_0 S \frac{I_0}{2} \hat{z}}{D} \Rightarrow i = 2I_0, \Phi_0 = \frac{\mu_0 S \hat{z}_0 I_0}{D}$$

$$c) f_x(\hat{z}) = -\frac{1}{2} \Phi_0^2 \frac{d}{d\hat{z}} \left(\frac{1}{L(\hat{z})} \right) = -\frac{1}{2} \frac{\Phi_0^2 D}{\mu_0 S} \frac{d}{d\hat{z}} \left(\frac{1}{\hat{z}} \right) = +\frac{1}{2} \frac{\Phi_0^2 D}{\mu_0 S \hat{z}^2}$$

$$d) f_T = -K \hat{z} + \frac{1}{2} \frac{\Phi_0^2 D}{\mu_0 S \hat{z}^2}$$

$$e) f_{\hat{z}} = f_T = 0 = -K \hat{z}_0 + \frac{1}{2} \frac{\Phi_0^2 D}{\mu_0 S \hat{z}_0^2} \Rightarrow \hat{z}_0^3 = \frac{1}{2} \frac{\Phi_0^2 D}{\mu_0 S K}$$

$$\hat{z}_0 = \left[\frac{1}{2} \frac{\Phi_0^2 D}{\mu_0 S K} \right]^{1/3}$$

$$f) \left. \frac{\partial f_T}{\partial \hat{z}} \right|_{\hat{z}_0} = -K - \frac{\Phi_0^2 D}{\mu_0 S \hat{z}_0^3} = -3K < 0 \Rightarrow \text{stable}$$

$$g) M \frac{d^2 \hat{z}'}{dt^2} = f_T(\hat{z}_0 + \hat{z}') \approx f_T(\hat{z}_0) + \left. \frac{\partial f_T}{\partial \hat{z}} \right|_{\hat{z}_0} \hat{z}' + f_0(t) = -3K \hat{z}' + f_0(t-T)$$

$$\frac{d^2 \hat{z}'}{dt^2} + \omega_0^2 \hat{z}' = \frac{f_0(t-T)}{M}, \omega_0^2 = \frac{3K}{M}$$

$$\hat{z}'(t) = \frac{f_0}{M\omega_0^2} + A_1 \sin \omega_0(t-T) + A_2 \cos \omega_0(t-T) \quad t > T$$

$$\left. \begin{aligned} \hat{z}'(t=T) = 0 &= \frac{f_0}{M\omega_0^2} + A_2 \Rightarrow A_2 = -\frac{f_0}{M\omega_0^2} \\ \left. \frac{d\hat{z}'}{dt} \right|_{t=T} = 0 &= \omega_0 A_1 \Rightarrow A_1 = 0 \end{aligned} \right\} \Rightarrow \hat{z}'(t) = \frac{f_0}{M\omega_0^2} (1 - \cos \omega_0(t-T)) \quad t > T$$

$$= \frac{f_0}{3K} (1 - \cos \omega_0(t-T))$$

$$z. a) B_y = \frac{\mu N i}{h}, \quad \vec{B} = B_y \vec{e}_y$$

$$b) \lambda = N B_y \omega D = \frac{4N^2 \omega D}{h} i \Rightarrow L = \frac{\lambda}{i} = \frac{4N^2 \omega D}{h}$$

$$c) J_x = \frac{i}{\omega D} = \nabla (E_x - V B_y) \quad (J = \nabla (\vec{E} + \vec{v} \times \vec{B}))$$

$$E_x = \frac{L}{\omega D} + V B_y$$

$$v_{\text{MHD}} = E_x \omega = \frac{i \omega}{\omega D} + \frac{V i N \omega}{h} = i \left[\frac{\omega}{\omega D} + \frac{4N \omega V}{h} \right]$$

$$d) v_{\text{MHD}} + v_c + v_L = 0 \Rightarrow i \left[\frac{\omega}{\omega D} + \frac{4N \omega V}{h} \right] + \frac{L}{C} \left(i \frac{di}{dt} + L \frac{di}{dt} \right) = 0$$

$$L \frac{d^2 i}{dt^2} + \left[\frac{\omega}{\omega D} + \frac{4N \omega V}{h} \right] \frac{di}{dt} + \frac{i}{C} = 0$$

$$e) \omega_0^2 = \frac{1}{LC}, \quad R = \frac{\omega}{\omega D}, \quad G = \frac{4N \omega V}{h}$$

$$\frac{d^2 i}{dt^2} + \frac{1}{L} [R + GV] \frac{di}{dt} + \omega_0^2 i = 0$$

$$i = A e^{st}$$

$$s^2 + s \frac{[R + GV]}{L} + \omega_0^2 = 0$$

$$s = \frac{-[R + GV]}{2L} \pm \left[\left[\frac{R + GV}{2L} \right]^2 - \omega_0^2 \right]^{1/2}$$

For self-excitation: $R + GV < 0 \Rightarrow V < -\frac{R}{G} \Rightarrow V < -\frac{1}{\mu N D}$

$|V| > \frac{1}{\mu N D}$ with direction in $-z$ direction

$$f) \omega_0^2 > \left[\frac{R + GV}{2L} \right]^2 \Rightarrow C < \frac{4N^2 D h}{\omega \left[\frac{1}{\omega D} + 4NV \right]^2}$$