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Coarse-Grained Modeling of Cytoskeletal Dynamics

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Spectrin-Net Level, Whole Red Blood Cell model (Discher, Boal, Boey, 1998)



+ total volume constraint + total area constraint

Small Cell Simulation of Volume Deflation



2562 vertices

Full-sized cell with bending energy E_{bend} only Canham (1970) Helfrich (1973)



OT stretching simulation with bending + in-plane energies



Courtesy of the Biophysical Society. Used with permission.



Li, Dao, Lim & Suresh, *Biophys*. *J.* **88** (2005) 3707.



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Why is biconcave the stable equilibrium shape?



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$$E_{\text{bend}} \sim 8\pi\kappa: \kappa \sim 2 \times 10^{-19} \text{ J} \rightarrow E_{\text{bend}} \sim 30 \text{ eV}$$

$$E_{\text{shear}} \sim \mu \epsilon^2 A: \ \mu \sim 8\mu \text{N/m}, \ \epsilon \sim 0.1, A \sim 140\mu \text{m}^2$$
$$\rightarrow E_{\text{shear}} \sim 70 \text{ eV}$$

Material Concept Hypothesis

Li, Dao, Lim & Suresh, Biophys. J. 88 (2005) 3707.

• In an ideal limit, for any RBC shape, the cytoskeleton will always undergo remodeling in topological connectivity at a slow rate to relax its in-plane *shear* elastic energy to *zero*.

"liquefaction", "slow-flowing glass"

• At the timescale of optical tweezers stretching, the above relaxation is not significant, so large shear energy can be injected temporarily.

Stillinger-Weber liquid on curved surface:



no shear energy can survive long!

RBC cytoskeleton at reduced spectrin density



very large holes start to percolate ...

Extreme Statistics of Cytoskeletal Defects in RBC

	actin#	spectrin#	largest polygon hole
normal	28673	81718	6
degree-4.5	26880	57523	8
degree-4	24372	48012	11
degree-3.5	21504	37416	22
degree-3	18637	26837	35

But this is basically from a "geometrical" simulation. No biophysical basis yet.

Intermediate Summary

- Spectrin-level and continuum FEM analyses indicate our optical tweezers experiments give approximately the same in-plane shear modulus as micropipette aspiration experiments: $\mu = 5$ to 10×10^{-6} N/m.
- Stabilization of biconcave equilibrium shape strongly suggests the cytoskeleton undergoes slow but constant remodeling topologically to always relax the in-plane shear elastic energy to zero.
- Connection to single-molecule stretching experiments ("intermolecular potential development").

CGMD model with *breakable* actin-spectrin junction







We also put soft $(0.1k_{BB})$ confinement potential on A and B in z to mimic interaction with the membrane without actually simulating the membrane.







Pure shear deformation at 300K and strain rate 3×10^{5} /s



Stress-strain curve at 300K and no ATP



Defect statistics at 300K with no ATP



A broken link 5-fold defect





Corrugation due to buckling: elevated / depressed in height

Now add ATP (0.5eV random kinetic energy to green ball): hit rate = $100/\mu s$ per spectrin end

Defect statistics at 300K, ATP hit rate 100/µs



Now turn off ATP hits, "anneal" at 300K...



Miraculously, the system recovers, within CGMD simulation timescale.

A more reasonable ATP hit rate: 10/µs. Simultaneously, also shear deform.



ATP hit rate = $10/\mu s$



ATP hit rate = $1/\mu s$:



ATP hit rate = $1/\mu s$



ATP hit rate = $2/\mu$ s: two plastic displacements... also longer



ATP hit rate = $5/\mu$ s: large-strain resistance collapses, manifest global yield



Summary

- A minimal CGMD model with *breakable* actinspectrin junction has been developed, with physically reasonable parameters and behavior.
- ATP hydrolysis is modeled as stochastic kinetic energy transfer. As ATP hit rate rises, we see initiation of plastic displacement excursions, followed by macroscopic yield, and eventually, complete fluidization.
- Practical timescale of CGMD able to simulate recovery. J. Li, G. Lykotrafitis, M. Dao and S. Suresh, *Proc. Natl. Acad. Sci. USA* 104 (2007) 4937.

A preview:

Vector Fluids: A Coarse-Grained 2D Fluid Membrane Model

The simplest potential that allows discrete agents to self-assemble into a 2D monolayer, and diffuse around as a 2D fluid.

Each agent has five degrees of freedom $\{\mathbf{x}_i, \mathbf{n}_i\}$, with constraint $|\mathbf{n}_i| = 1$. Define

$$\mathbf{x}_{ji} \equiv \mathbf{x}_j - \mathbf{x}_i, \quad r_{ji} \equiv |\mathbf{x}_{ji}|, \quad \hat{\mathbf{x}}_{ji} \equiv \frac{\mathbf{x}_{ji}}{r_{ji}}$$

The total potential is pairwise additive

$$V = \sum_{i < j} v_{ij}$$

with

 $a(\mathbf{n}_i, \mathbf{n}_j, \hat{\mathbf{x}}_{ji}) = (\mathbf{n}_i \times \hat{\mathbf{x}}_{ji}) \cdot (\mathbf{n}_j \times \hat{\mathbf{x}}_{ji}) = \mathbf{n}_i \cdot \mathbf{n}_j - (\mathbf{n}_i \cdot \hat{\mathbf{x}}_{ji})(\mathbf{n}_j \cdot \hat{\mathbf{x}}_{ji})$

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