20.GEM GEM4 Summer School: Cell and Molecular Biomechanics in Medicine: Cancer Summer 2007

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GEM⁴ Summer School on Cell and Molecular Mechanics in Biomedicine June 25 - July 6 2007

Molecular mechanics

Lecture 1

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Molecular mechanics: Definition of scales





Protein (molecules) are crucial for cellular functions









Adapted from Alberts, The Cell







Example: Nuclear envelope





Foisner et al., 2001

Courtesy of the Company of Biologists. Used with permission.

Structural: Maintaining Nuclear Shape, Absorbing Mechanical Shock, Organizing Chromatin, etc **Biological:** Regulating Cell Cycle, Controlling DNA replication, Determining Apoptosis, etc Lamina - a mesh network U. Aebi *et al.*



Courtesy of the Company of Biologists. Used with permission.







- Single point mutations in IF structure causes severe diseases such as rapid aging disease progeria – HGPS (*Nature*, 2003; *Nature*, 2006, *PNAS*, 2006)
- Cell nucleus loses stability under cyclic loading
- Failure occurs at heart (fatigue)



Courtesy of National Academy of Sciences, U. S. A. Used with permission. Source: Dahl, et al. "Distinct Structural and Mechanical Properties of the Nuclear Lamina in Hutchinson–Gilford Progeria Syndrome." *PNAS* 103 (2006): 10271-10276. Copyright 2006 National Academy of Sciences, U.S.A.

Substitution of a single DNA base: Amino acid guanine is switched to adenine

Experiment suggests that mechanical properties of nucleus change (Dahl *et al.*, *PNAS*, 2006)

HGPS cells wt LA











- Many cancer cells have abnormal expression of lamin: For example, HL-60 cells (type of leukemic cells) shows a change expression level of lamin A/C and B and changes in nuclear shape.
- Changes in lamin structure can lead to abnormal expression of genes in cancer cells
- A key step of **apoptosis** is the disassembly of lamina and detachment of chromatin: Mutation in Lamin A/C can make the cleavage site of lamina uncleavable, thus hinder apoptosis
- Understanding of molecular mechanics e.g. assembly, stability, for instance under chemical / enzymatic signals – is vital to understand these processes rigorously





- Mechanics describes the relationship between the deformation state of a material or system as a function of the applied load and boundary conditions
- Mechanical properties are crucial for biological processes:
 - □ **Functioning of biological systems passive role** (structural materials such as bone, skin, tendon,...)
 - Mechanical stimulation is utilized to facilitate signaling in biological processes (in cells, e.g. via mechanosensation) – passive role
 - Active mechanical stimulation (protein motors) active role
- Change in mechanical properties may interfere with biological processes and lead to diseases
- Pathological condition may in turn change mechanical behavior, e.g. cells become stiffer (RBCs in malaria)





- Molecular mechanics with focus on biomolecules (proteins)
- Topics covered:
 - □ Chemical bonding in molecules & theory
 - Characterization of molecular properties (tensile stiffness, persistence length, adhesion..)
 - Application of continuum mechanical concepts to molecular mechanics
 - □ Link of molecular properties to tissue properties (collective behavior of many molecules, elasticity, fracture,..)
 - Molecular defects and consequence for diseases: Certain mutation may induce changes in mechanical properties, e.g. molecular defects, mutations; leads to pathological consequence (too soft, too stiff,..)
- Multi-scale modeling
- Emphasis on developing a sensitivity for the significance of molecular mechanics in biology and how atomistic and continuum viewpoints can be coupled

M. Buehler & T. Ackbarow, *Materials Today, in press*



Significance of molecular mechanics from a material scientist's perspective





M. Buehler & T. Ackbarow, *Materials Today, in press*





From electrons to molecules A brief review of chemical concepts





- Atoms are composed of electrons, protons, and neutrons. Electron and protons are negative and positive charges of the same magnitude, 1.6 × 10-19 Coulombs
- Chemical bonds between atoms by interactions of the electrons of different atoms (e.g. sharing of electrons)



"Point" representation



From electrons to atoms



Governed by laws of quantum mechanics: Numerical solution by Density Functional Theory (DFT), for example





Primary bonds ("strong")

- Ionic,
- □ Covalent,
- Metallic (high melting point, 1000-5000K)

Secondary bonds ("weak")

- □ Van der Waals,
- Hydrogen bonds (melting point 100-500K)
- Ionic: Non-directional
- Covalent: Directional (angles, torsions)
- Metallic: Non-directional

Strength: several nN

Strength: 10..100 pN

M. Buehler, J. Comput. Theoretical Nanoscience, 2006





M. Buehler J. Mat. Science, in press



Proteins often include a variety of atomic interactions





Covalent bonds

Between differently charged species:

Electrostatic interactions

Hydrogen bonds

vdW interactions





Protein unfolding

Image removed due to copyright restrictions.

Please see Figure 3(a) in Marszalek, Piotr E., et al. "Mechanical unfolding intermediates in titin modules." Nature 402 (1999): 100-103. Images removed due to copyright restrictions.

Please see Figures 1(f) and 2 in Tskhovrebova, L., J. Trinick, J. A. Sleep and R. M. Simmons. "Elasticity and unfolding of single molecules of the giant muscle protein titin." Nature 387 (1997): 308-312.

Stretching of tropocollagen molecules



Figure by MIT OpenCourseWare. After Sun, 2004.



$$V(R) = E_{bonded} + E_{non-bonded}$$
$$E_{bonded} = E_{bond-stretch} + E_{angle-bend} + E_{rotate-along-bond}$$

Bonding between atoms described as combination of various terms, describing the angular, stretching etc. contributions

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Images created for the CHARMM tutorial by Dr. Dmitry Kuznetsov (Swiss Institute of Bioinformatics) for the EMBnet Education & Training committee (http://www.embnet.org)







Model for covalent bonds



$$E_{\text{rotate-along-bond}} = \sum_{1.4 \text{ pairs}} K_{\text{pl}} \left(1 - \cos(n\phi) \right)$$

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Images created for the CHARMM tutorial by Dr. Dmitry Kuznetsov (Swiss Institute of Bioinformatics) for the EMBnet Education & Training committee (http://www.embnet.org)

http://www.ch.embnet.org/MD_tutorial/pages/MD.Part2.html





Chemical type	K _{bond}	b _o
С-С	100 kcal/mole/Å ²	1.5 Å
C=C	200 kcal/mole/Å ²	1.3 Å
C≡C	400 kcal/mole/Å ²	1.2 Å

Bond Energy versus Bond length

Different types of C-C bonding represented by different choices of b_0 and k_b ;

Need to retype when chemical environment changes



$$V_{bond} = K_b \left(b - b_o \right)^2$$

Courtesy of the EMBnet Education & Training Committee. Used with permission.

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http://www.ch.embnet.org/MD_tutorial/pages/MD.Part2.html http://www.pharmacy.umaryland.edu/faculty/amackere/force_fields.htm



Review: CHARMM potential



Courtesy of the EMBnet Education & Training Committee. Used with permission.

Images created for the CHARMM tutorial by Dr. Dmitry Kuznetsov (Swiss Institute of Bioinformatics) for the EMBnet Education & Training committee (http://www.embnet.org)

http://www.ch.embnet.org/MD tutorial/pages/MD.Part2.html





Molecular dynamics Numerical simulation of stretching experiments





System of coupled 2nd order nonlinear differential equations

Solve by discretizing in time (spatial discretization given by "atom size") M. Buehler, J. Comput. Theoretical Nanoscience, 2006





Solve those equations: Discretize in time (*n* steps), Δt time step:

 $r_i(t_0) \rightarrow r_i(t_0 + \Delta t) \rightarrow r_i(t_0 + 2\Delta t) \rightarrow r_i(t_0 + 3\Delta t) \rightarrow \dots \rightarrow r_i(t_0 + n\Delta t)$

Taylor series expansion

$$r_i(t_0 + \Delta t) = r_i(t_0) + v_i(t_0)\Delta t + \frac{1}{2}a_i(t_0)(\Delta t)^2 + \dots$$

Adding this expansion together with one for $r_i(t_0 - \Delta t)$:

$$r_i(t_0 - \Delta t) = r_i(t_0) - v_i(t_0)\Delta t + \frac{1}{2}a_i(t_0)(\Delta t)^2 + \dots$$

M. Buehler, J. Comput. Theoretical Nanoscience, 2006



 $F = k(v \cdot t - x)$

Image removed due to copyright restrictions.

Please see Fig. 6 in Buehler, M., and T. Ackbarow. "Fracture Mechanics of Protein Materials." Materials Today 10 (2007): 46-58.

M. Buehler & T. Ackbarow, *Materials Today, in press*





Unfolding of a titin molecule





M. Buehler, J. Mat. Science, in press





Experimental techniques have progressed very much over the past decade – covering more time- and length-scales ...



Experimental techniques







- Development of quantitative, predictive theoretical models

 utilizing large-scale molecular dynamics simulation &
 multi-scale integration is in reach
- Predict behavior of complex biological materials across many hierarchies and many time- and length scales



M. Buehler & T. Ackbarow, *Materials Today, in press*





Energy approach to elasticity Linking atomistic scales to 'meso'-scale

Elasticity: Reversible deformation

Stretching of tropocollagen molecules



Figure by MIT OpenCourseWare. After Sun, 2004.









1st law of TD

$$\frac{\mathrm{d}U}{\mathrm{d}t} = \delta W + \delta Q_{t}$$

External work rate

$$W = \dot{x}F_e$$
 Applied force

2nd law

 $\frac{\mathrm{d}S}{\mathrm{d}t} \geq \frac{\delta Q}{T} \quad \begin{array}{l} \text{Change in entropy is always greater or equal than the} \\ \text{entropy supplied in form of heat; difference is due to} \\ \text{internal dissipation} \end{array}$

$$rac{\mathrm{d}D}{\mathrm{d}t} = Trac{\mathrm{d}S}{\mathrm{d}t} - \delta Q \ge 0$$
 $\delta Q = \mathrm{d}U/\mathrm{d}t - \delta W$
Dissipation rate

δ

Dissipation rate after consider 1^{st} law of TD:

$$\frac{\mathrm{d}D}{\mathrm{d}t} = \delta W - \frac{\mathrm{d}}{\mathrm{d}t} \left(U - TS \right)$$

Dissipation rate=External work rate -change in usable energy U-TS

F = U - TS is defined as free energy or Helmholtz energy,




Elastic deformation (no dissipation by definition):

$$\frac{\mathrm{d}D}{\mathrm{d}t} = 0 \qquad \qquad \delta W - \frac{\mathrm{d}F}{\mathrm{d}t} = 0 \qquad \text{Assume only internal energy change} \\ \delta W = \dot{x}F_e \qquad \qquad \begin{array}{l} \text{Expand equation} \\ \mathrm{d}U/\mathrm{d}t = \mathrm{d}U/\mathrm{d}x \,\mathrm{d}x/\mathrm{d}t \quad \dot{x}F_e - \frac{\mathrm{d}F}{\mathrm{d}x} \frac{\mathrm{d}x}{\mathrm{d}t} = 0 \\ \dot{x}\left(F_e - \frac{\mathrm{d}F}{\mathrm{d}x}\right) = 0. \end{array}$$

Therefore: If applied force equals change in free energy of the system, have elastic deformation

$$F_e = \frac{\mathrm{d}F}{\mathrm{d}x} \qquad F_e = \frac{\mathrm{d}U}{\mathrm{d}x}$$

With strain energy density: $\Psi = F/V$ $\Psi = U/V$

$$\sigma_{ij} = \frac{\mathrm{d}\Psi}{\mathrm{d}\varepsilon_{ij}} \quad c_{ijkl} = \frac{\mathrm{d}^2\Psi}{\mathrm{d}\varepsilon_{ij}\mathrm{d}\varepsilon_{kl}}$$



The equations

$$\sigma_{ij} = \frac{\mathrm{d}\Psi}{\mathrm{d}\varepsilon_{ij}} \quad c_{ijkl} = \frac{\mathrm{d}^2\Psi}{\mathrm{d}\varepsilon_{ij}\mathrm{d}\varepsilon_{kl}}$$

are significant since they provide a direct link between energy state and elasticity (stress & moduli)

Physics of deformation:

How does free energy state change when the deformation changes?

F = U - TS





Change of free energy as a function of deformation provides an intimate link between atomistic/molecular scales and 'continuum' (average)





High entropy



Low entropy

F = U - TS



- Bending deformation (R=radius, EI=flexural rigidity of the rod) - energy $E_{bend} = EI \frac{L}{2R^2}$
- Thermal (kinetic) energy per molecule (kinetic theory of gases)
 energy 3

$$E_{kin,mol} = \frac{3}{2}kT$$

- Example: *kT*~4E-21 J at body temperature
- If El is very small, thermal energy may be enough to bend the molecule

$$F = U - TS$$





The length at which a filament is capable of bending significantly in independent directions, at a given temperature.

This is defined by a autocorrelation function which gives the characteristic distance along the contour over which the tangent vectors **t(s)** become uncorrelated



Bending stiffness given by

$$EI = \frac{F_{appl}L^3}{48d}$$

$$EI = 9.71 \times 10^{-29} \text{ Nm}^2$$

(5,5) CNT: ~ 1,000 times stiffer $EI = 6.65 \times 10^{-26} \text{ Nm}^2$



Figure by MIT OpenCourseWare.

M.J. Buehler, J. Mater. Res., Vol. 21(8), 2006





- The contour length of a molecule is the total length in the stretched configuration, denoted as L
- When $L << \xi_p$

a filament appears relatively straight.

• When $L >> \xi_p$

a filament adopts more convoluted shapes



M. Buehler, J. Comput. Theoretical Nanoscience, 2006



To pull a highly convoluted molecule apart, a force is necessary; define effective spring constant

 $L >> \xi_n$

No energetic interactions!





Figure by MIT OpenCourseWare.



 $F \sim k_{sp} x$ $x \ll L$



Note: No change in elastic energy of molecules



Figure by MIT OpenCourseWare.

Needed to understand elasticity: Expression of free energy as a function of the applied strain!

Entropic elasticity – therefore change in entropy



Freely jointed Gaussian chain with *n* links and length *l* each (same for all chains in rubber)



Figure by MIT OpenCourseWare.





For SED: Free energy

$$F = -T\Delta S = \frac{1}{2}N_{b}kT(\lambda_{1}^{2} + \lambda_{2}^{2} + \lambda_{3}^{2} - 3)$$

$$C = E/6$$
Predictions:

$$E = 3N^{*}kT \quad N^{*} = N_{b}/V$$

Stiffness is proportional to temperature

$$E \sim T$$

Stiffness is proportional to degree of cross-linking (for ideal network, N^* equals twice the cross-link density) $E \sim N^*$

Entropic change as a function of stretch



Figure by MIT OpenCourseWare.





Freely-jointed rigid rods



Image removed due to copyright restrictions.

DNA 4-plat electron micrograph (Cozzarelli; Berkeley)

Continuously flexible ropes

Worm like chain model







This spring constant is only valid for small deformations from a highly convoluted molecule, with length far from its contour length

$$x \ll L$$

- A more accurate model (without derivation) is the Worm-like chain model (WLC) that can be derived from the Kratky-Porod energy expression
- A numerical, approximate solution of the WLC model:

$$F = \frac{kT}{\xi_p} \left(\frac{1}{4} \frac{1}{(1 - x/L)^2} - \frac{1}{4} + x/L \right)$$

Marko and Siggia, 1995





Figure by MIT OpenCourseWare. After Sun, 2004.





Summary and review Lecture 1



Molecular mechanics: Definition of scales







- Molecular mechanics with focus on biomolecules (proteins)
- Topics covered:
 - □ Chemical bonding in molecules & theory
 - Characterization of molecular properties (tensile stiffness, persistence length, adhesion..)
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M. Buehler & T. Ackbarow, *Materials Today, in press*



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Molecular mechanics

Lecture 2

Markus J. Buehler



Massachusetts Institute of Technology Laboratory for Atomistic and Molecular Mechanics





- Proteins are made up of amino acids
- 20 amino acids carrying different side groups (R)
- Amino acids linked by the amide bond via condensation; formation of proteins controlled by genes
- Proteins have four levels of structural organization: primary, secondary, tertiary and quaternary

Fascinating for a material scientist:

Understand structure-function relationship for protein materials 20 building blocks; machinery of material synthesis from DNA molecular scale control of structure, multi-functionality, ...



Images removed due to copyright restrictions.

Table of amino acid chemical structures. See similar image: http://web.mit.edu/esgbio/www/lm/proteins/aa/aminoacids.gif



Protein structure



- Primary structure: Sequence of amino acids
- Secondary structure: Protein secondary structure refers to certain common repeating structures found in proteins. There are two types of secondary structures: <u>alpha-helix</u> and <u>beta-pleated</u> sheet.
- Tertiary structure: Tertiary structure is the full 3-dimensional folded structure of the polypeptide chain.
- Quartenary Structure: Quartenary structure is only present if there is more than one polypeptide chain. With multiple polypeptide chains, quartenary structure is their interconnections and organization.

A A S X D X S L V E V H X X



Image courtesy of NIH.



Despite the existence of a GREAT variety of protein materials, observe dominance of 'universal building blocks'







Images courtesy of Wikimedia Commons and NIH.



Hydrogen bonding

e.g. between O and H in H_2O Between N and O in proteins...

Formation of AH induced due to hydrophobic character of side chains

Image removed due to copyright restrictions.

Alpha helix

For an image of the classic hydrogen bond example, hydrogen bonds in water, please see http://upload.wikimedia.org/wikipedia/commons/f/f9/3D_model_hydrogen_bonds_in_water.jpg.

Pleated sheet Tertiary protein structure occurs when certain attractions are present between alpha helices and pleated sheets.



Beta-sheets (BS)







Case study: Intermediate filament proteins









Fluorescent staining for different protein networks









Courtesy of Rockefeller University Press via CC BY-NC-SA license.

Plectin cross-linking of diverse cytoskeletal elements. Plectin (green) makes cross-links from intermediate filaments (blue) to other intermediate filaments, to microtubules (red), and to myosin thick filaments. In this electron micrograph, the dots (yellow) are gold particles linked to anti-plectin antibodies. The entire actin filament network was removed to reveal these proteins.

(From T.M. Svitkina and G.G.Borisy, *J. Cell Biol.* 135:991–1007, 1996)



Stage I: Uncoiling of each alpha helixStage II: Uncoiling of coiled-coilStage III: Stretching of protein backbone







A: Cross-sectional area of molecule

Ackbarow and Buehler, MRS Proc. 2006; JMS, in press (to appear 2007)

Figure by MIT OpenCourseWare. After Ackbarow and Buehler, 2006.







Larger pulling speed leads to larger resistance against unfolding

M. Buehler & T. Ackbarow, *Materials Today, 2007*







Figure by MIT OpenCourseWare. After Ackbarow and Buehler, 2008.

'Skips' are insertions of one residue into the heptad pattern

'Stammers' result through an insertion of three additional residues

'Stutters' appear if four additional residues interrupt the heptad sequence: Presence of a stutter results in an almost parallel run of both AHs without interrupting the CC geometry.

Ackbarow and Buehler, Experimental Mechanics, 2008





Probability for bond rupture

"off rate"

$$p = \exp\left[-\frac{E_b - Fx_B}{k_B T}\right] \qquad \qquad \chi = \omega_0 \cdot \exp\left(-\frac{(E_b - F \cdot x_b)}{k_b \cdot T}\right)$$

$$p = \tau^{-1} \omega^{-1} \qquad \omega = 1 \times 10^{13} / \text{sec}$$



Bell, 1978; M. Buehler & T. Ackbarow, Materials Today, 2007





Pulling velocity

$$v = \omega_0 \cdot x_b \cdot \exp\left(-\frac{(E_b - F \cdot x_b)}{k_b \cdot T}\right)$$

Rupture force

$$F(v) = \frac{k_b \cdot T}{x_b} \cdot \ln v - \frac{k_b \cdot T}{x_b} \cdot \ln v_0 = a \cdot \ln v + b$$

Energy barrier: $E_b \approx 5.6$ kcal/mol pul $x_b \approx 0.17$ Å: Suggests rupture of single H-bond



Ackbarow and Buehler, JMS, 2007)









Figure by MIT OpenCourseWare. After Ackbarow and Buehler, 2006.




Linke et al., Journal of Structural Biology, 2002; Schulten, Science, 2007



Change in deformation mechanism



Figure by MIT OpenCourseWare. After Ackbarow and Buehler, 2006.



Figure by MIT OpenCourseWare.



Slower rates – deformation 'wave' vanishes





Figure by MIT OpenCourseWare. After Ackbarow and Buehler, 2006.

Predict: Strain distribution homogeneous below v_0 , no localization

Ackbarow and Buehler, MRS Proc. 2006; JMS, 2007





$$s_1 = c_5 \cdot v + c_6$$
, $s_2 = \max(c_7 \cdot v + c_8; 0)$, $F_a = c_1 \cdot \ln(v) + c_2$, and $x_a = F_a / s_1$

$$F_s = c_3 \cdot x_s + c_4,$$

$$s_3 = c_9 \cdot v^2 + c_{10} \cdot v + c_{11}$$
 and $x_s = \left(F_a \cdot (1 - \frac{s_2}{s_1}) - c_4\right) / (c_3 - s_2)$

Numerical parameters and its units										
C_1	<i>c</i> ₂	C ₃	\mathcal{C}_4	C ₅	C ₆	<i>C</i> ₇	C ₈	C ₉	C_{10}	<i>c</i> ₁₁
220	3,604	237	-19,65	723,894	59.6	173,519	-6.3	2.4E7	-4.55	2.7
pN	pN	pN/Å	pN	$pN \cdot fs/Å^2$	pN/Å	$pN \cdot fs/Å^2$	pN/A	$pN \cdot fs^2/Å^3$	$pN \cdot fs/Å^2$	pN/Å

Ackbarow and Buehler, MRS Proc. 2006; JMS, 2007





Ackbarow and Buehler, MRS Proc. 2006; JMS, 2007







Figure by MIT OpenCourseWare. After Buehler and Ackbarow.

Superelastic material

High impact resistance

- Coiled-coil: Enables large superelastic strains (low forces, since H-bonds break easily) – scale ~ 10..100 nm
- Different mechanisms: Breaking of single H-bond leads to large slope of AP w.r.t. strain rate (significant strengthening at large deformation rates)

At small deformation rates: strengthening not as strong, as three H-bonds break simultaneously

Refolding possible, since sequence has not been destroyed (if forces below rupture of covalent bonds)

Ackbarow and Buehler, JMS, in press



F, $x_b \in$





θ



$$\chi = \omega_0 \cdot \exp\left(-\frac{\left(E_b - F \cdot x_b \cdot \cos(\theta)\right)}{k_b \cdot T}\right)$$

F,
$$x_b$$
 $v = \chi \cdot x_b$

$$v = \chi \cdot x_b$$

$$v = \omega_0 \cdot x_b \cdot \exp\left(-\frac{\left(E_b - F \cdot x_b \cdot \cos(\theta)\right)}{k_b \cdot T}\right)$$

Rupture force

$$F(v) = \frac{k_b \cdot T}{x_b \cdot \cos(\theta)} \cdot \ln v - \frac{k_b \cdot T}{x_b \cdot \cos(\theta)} \cdot \ln v_0 = a \cdot \ln v + b$$

M. Buehler & T. Ackbarow, Materials Today, in press



Figure by MIT OpenCourseWare. After Ackbarow and Buehler, 2008.

'Skips' are insertions of one residue into the heptad pattern

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Ackbarow and Buehler, Experimental Mechanics, 2008





Ackbarow and Buehler, Experimental Mechanics, 2008



• Renders the molecular structures softer, that is, unfolding occurs at lower tensile forces,

- Introduces predefined locations of unfolding, and
- Thus leads to a more homogeneous distribution of plastic strains throughout the molecular geometry.







- Significance of protein mechanics for biological processes (signaling, cancer, mechanical integrity..)
- Chemical bonds within protein & theoretical description (force field)
- Free energy source of elasticity: Link atomistic/molecular concepts with continuum theory (rubber elasticity, WLC model)
- Case study: Vimentin dimer response to mechanical cue (stretching, unfolding, rate dependence)

Bell model – statistical concept to predict unfolding force 'onset of plasticity' – permanent deformation

Structure-function relationship to describe role of molecular defects in protein mechanics (example: stutter defect)