### I 6 The Origin and Development of Laboratory Models and Analogues of the Ocean Circulation

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# 16.1 A Brief Philosophy of Laboratory Experimentation

"No one believes a theory, except the theorist. Everyone believes an experiment—except the experimenter." This often used adage, although not aways accurate in detail, carries a certain element of truth. Here we consider certain experiments—analogs, models, or fundamental studies of basic fluid dynamics—that are intended to be relevant to one or another aspect of the ocean circulation. These are physical, fluid models—as opposed to numerical, analytical, abstract, or conceptual models—that make use of a *real* fluid. When the fluid in a container is subjected to some driving force, the fluid moves. It is observed by the experimenter. It is there. It is a real fluid circulation. Apart from its relevance, why should it not be believed?

The experienced experimenter is well aware of the pitfalls of his trade. Aside from the accuracy of his reported observations there are many questions. Were the boundary conditions well controlled? Were the physical properties of the materials and their variations during the experiment known? Did the methods of observation (probes, dyes, tracers, lighting) influence the results? Were the reported observations complete, or at least representative? or were they filtered, massaged, interpreted, selectively reported, etc.? In fact there is always an element of judgment, selectivity, and interpretation concerning what to observe, and having observed, what to record, and what to report. Thus, despite the apparent confidence that may be exuded in publication, the cautious experimenter maintains a restraint born of continual reflection on the extensive preparations necessary for an apparently simple experiment and the many opportunities for error and misinterpretation.

We can broadly classify experiments into four categories, according to their intent, under these headings: (1) simulation, (2) abstraction, (3) verification, and (4) extension. In the first category the experimenter attempts to represent nature in miniature in so far as possible. An effort is made to include all of the relevant driving mechanisms, and the geometry is scaled as in nature, although some distortion may be necessary. Using theoretical guides such as the matching of the appropriate nondimensional ratios, the intent is to learn by trial and error to what extent the ocean circulation can be reproduced as a scale model. If it were possible to reproduce known features of the North Atlantic circulation, for example, such a model could be used to predict similarly scaled features of the ocean circulation in less accessible regions of the world. The predictions would serve as a guide to further exploration and would be compared with observations as they became available. The simulation mode of experimen-

tation is appealing to the eye of the layman who can rather easily be convinced of its possible application and relevance.

The second mode of experimentation is rather like abstract art. The artist draws out (abstracts) from some natural subject those features that he imagines to be of significance, and he displays his interpretation of those features on canvas or in stone for the reaction of his peers and his public. The experimental scientist conceptually isolates one or more processes that he believes to be significant in nature, and he displays and tests them in the form of an operational laboratory experiment. Just as it may be difficult for the artist to persuade his lay audience of the sincerity of his efforts (although his fellow artists understand), so also the scientist may have difficulty convincing his nonprofessional audience that his experiment is relevant to the grand scheme of things past, present, and future.

Abstract experiments may be particularly successful in systems that can be decomposed linearly without doing violence to the essential dynamics, i.e., systems in which the abstracted phenomenon can be isolated by virtue of a lack of coupling with other processes. This may be possible because of a smallness of amplitude of potentially interactive processes, or because of mismatch in the temporal and spatial scales of the various processes. But even in those situations where decomposition is not warranted, one can say, "If .... Perhaps a planet will be found where these conditions prevail; or perhaps some machinery in a chemical plant, somewhere, generates the conditions that I am studying; or perhaps I can build upon this experiment to incorporate the interactive processes necessary for a more realistic representation of the oceanic circulation (simulation?). In any case I will publish my abstract results for the benefit of posterity."

Abstraction experiments, in contrast to direct simulation, are more readily subject to a posteriori mathematical analysis because of their relative simplicity. They may more directly lead to the advancement of theoretical aspects of the problem. Either mode may be regarded as exploratory, for it is likely that certain new aspects of the fluid circulations will emerge that were not anticipated and that will require rationalization. Here again the abstract experiment has the advantage of its simplicity, for deviations from the anticipated behavior will be more clearly recognized. The simulation experiment, however, will generally pose a larger variety of unanticipated phenomena because of its inherently greater complexity.

The verification mode of laboratory experiment implies an apparatus designed to test (and verify) a specific analytical or numerical model. A certain theoretical model predicts a steady-state circulation, the temporal development of a flow, or perhaps an instability. Apparatus is designed to match the conditions of the theory in so far as possible, and, as often as not, the theory is modified to conform to the limitations of the experiment. But in all cases under this category there is a detailed theory capable of a priori predictions and the physical conditions of the theory and of the experiment are closely matched. If this matching is sufficiently precise, the experiment will exactly verify the predictions. From this viewpoint the situation may at first appear to be rather sterile, but this is not the case at all. For following the adage, "No one believes a theory . . . ; everyone believes an experiment . . . ," we find that the theorist has arrived. For now everyone believes the theory, and rightly so, because it is confirmed by the experiment! The verification mode of laboratory experiment is widely endorsed by theorists.

The fourth type of experiment is the extension mode. The experimenter, having set up the theorist by collaboration and verification of his theory, now attempts to do him in by varying the parameters of the experiments,  $\epsilon$  and  $\delta$ , until they lie outside the range of validity of the theory. It is then incumbent upon the theorist to expand everything in powers of  $\epsilon$  and  $\delta$  to take into account the nonlinear aspects of the flow, but here the experimenter always has the upper hand and can easily keep one step ahead of the theorist. It is only necessary to do this in a manner in keeping with accepted scientific and engineering practice, expressing the experimental results in terms of the minimum number of nondimensional ratios appropriate to the case at hand. Oftentimes, of course, the experimenter and the theorist are one and the same person.

This short excursion into the philosophy of laboratory experimentation may be found useful in the interpretation of the remainder of this chapter. Perhaps not all experimental studies are cleary motivated and can be identified as belonging exclusively to one or the other of the categories discussed above, but such a classification seems to be by and large appropriate.

#### **16.2 Introduction**

Perhaps the first rotating laboratory experiment specifically directed toward understanding some aspect of the ocean circulation was that of C. A. Bjerknes in 1902, as reported by Ekman (1905). Because this report is not well known and because a discussion of its results will have later application, I have reproduced it here:

The late Prof. C. A. Bjerknes at Kristiania, whose vivid interest seems to have been bestowed on every extension of knowledge in his branch, also made in the autumn of 1902, some experiments with the object of verifying some of the results to be found in Section 1 of this paper. His apparatus consisted of a low cylinder (12 or 17 cm. high and 36 or 44 cm. wide) made of metal or glass, and resting on a table which could be put into uniform rotation (about 7 turns a minute against the sun) by means of a water-turbine. To the upper edge of the rotating cylinder was attached a jet having a horizontal split, 10 cm. long and 1 mm. broad; and through this a stream of air was forced from a pump to produce a wind diametrically across the cylinder over a 10 cm. broad belt.

The motion of the water was observed by means of small balls which just floated in it. As a result of the rotation of the cylinder the current always swept towards the right and thus formed a large whirl-pool occupying, when seen in the wind's direction, the middle as well as the right half of the cylinder.

The direction of motion at different depths was observed at the centre of the cylinder, on a sensitive vane (4 cm. long and 1 mm. high) which could be raised and lowered during the experiment without disturbing the motion. The direction of the vane was read against a glass square divided into radians and laid on top of the cylinder. The following table taken from Prof. Bjerknes' note-book kept in his laboratory gives as an example a series of measurements made during such an experiment. The first column gives the depth in cm. below the surface, the second column the deviation of the current to the right or left of the wind's direction.

Surface (cm)	<b>20–25°</b> :	right
0.5	45-50°	"
1	45-50°	"
1.5	25-30°	"
2	0-10°	"
2.5	0°	"
3	5–10° ]	left
3.5	5-10°	"
4	5-10°	"
4.5	10°	"
5	10-15°	"
5.5	15-20°	"
6	20°	"
6.5	20°	"
7	20-25°	"

The circumstances under which these experiments were made were in any case such as to satisfy the conditions for stationary motion but very roughly; and an exact interpretation may furthermore be difficult owing to the shape of the vessel, etc. It is certain however that their real object was to obtain merely qualitative verification of the reality of the phenomena considered, and as such they are very striking and instructive. Both the deflection of the surface-current and the increase of the angle of deflection increases only in the very uppermost layer; and this is explained as a result of the rapid rotation of the vessel. Indeed a value of  $\mu = 0.3$  (which would not appear to be too small for motion on such a small scale) would give  $D_{\rm Ek} = 2$  cm only. [Author's note: Here I have used  $\overline{D}_{\rm Ek}$ in place of D to avoid later confusion. As used here and in other recent literature  $D = D_{\rm Ek}/\pi$  is the mathematically more convenient measure of boundary-layer thickness.] The directions of motion below this level have very much the appearance of a "midwater-current" produced by a pressure-gradient.

Apparently Ekman determined the effective viscosity  $\mu = 0.3$  indirectly from his estimate  $D_{\rm Ek} = 2$  cm, for with a rotation rate  $\Omega = 0.73 \, {\rm s}^{-1}$  and with the viscosity of water  $\mu = 0.01$  we find  $D_{\rm Ek} = 0.37$  cm and D = 0.117 cm. Thus the laminar Ekman depth would be considerably shallower than that inferred from the experimental data, as Ekman must have recognized. Departing temporarily from the historical development to consider this question, these early results possibly may be explained in the light of recent laboratory experiments and numerical calculations on the stability of the Ekman boundary layer.

Laboratory studies have mostly been confined to flow over a rigid boundary (Faller, 1963; Faller and Kaylor, 1967; Tatro and Mollo-Christensen, 1967; Caldwell and van Atta, 1970; Cerasoli, 1975), and most comparative theoretical studies also have been concerned with the rigid-boundary case.

The Reynolds number for the Ekman layer is defined as  $Re = UD/\nu$ , where U is the difference between the speed at the boundary and the speed of the interior flow. Over a rigid boundary the critical value for instability is approximately  $Re_c = 55$ . For the Ekman layer with a free boundary, the profile of flow is exactly the same, but potential instabilities are not constrained by a no-slip boundary condition. A preliminary estimate given by Faller and Kaylor (1967) was  $Re_c =$  $12 \pm 3$  for the first onset of instability. This result has recently been confirmed with a more accurate calculation by Iooss, Nielsen, and True (1978), who found  $Re_c = 11.816$ . In C. A. Bjerknes's experiment the corresponding critical surface water speed would be approximately  $U = 1 \text{ cm s}^{-1}$ , and the corresponding critical wind stress would be  $\tau_c = 0.12 \text{ dyn cm}^{-2}$ . Still another possibility is that of Langmuir circulations, a subject that will be touched upon briefly later, in section 16.6.10 and in this connection it would be interesting to know whether the air jet had sufficient speed to raise capillary waves. Unfortunately Ekman's account gives no means of estimating the air or water speeds, but it seems likely that the surface Ekman layer was unstable, thus accounting for the approximate  $D_{\rm Ek} = 2$  cm and the lack of an idealized spiral.

In determining the scope of this chapter it has been found necessary to restrict the material arbitrarily to laboratory experiments rather directly concerned with large-scale oceanic circulations, and a number of significant developments and important areas of research have been omitted from consideration. With one exception we shall be concerned exclusively with rotating experiments, omitting laboratory studies of the generation and interaction of surface and internal waves, thermohaline (double-diffusive) phenomena,

thermal convection, turbulence, and other fundamental fluid dynamic studies that may be directly related to oceanic processes. Even in the realm of rotating fluids it is not possible to consider all studies of interest in as much detail as may be warranted, and there will be those overlooked in the literature. Moreover, the author confesses to a certain prejudice, which will be evident, in emphasizing his own contributions and those with which he is most intimately familiar.

After the experiments of C. A. Bjerknes, the first serious attempt at the isolation of an oceanic circulation in a rotating laboratory experiment appears to have been that of Spilhaus (1937). C. G. Rossby had proposed that the Gulf Stream might be similar to an inertial jet emerging from the Straits of Florida. Differences between the Gulf Stream and the usual laboratory jet might be expected from the effects of the earth's rotation (with the consequent adjustment to geostrophic balance) and the stratification of the ocean.

Spilhaus's attempts to verify certain aspects of Rossby's concepts consisted of (1) some preliminary trial experiments in a small cylindrical tank with a jet of water injected from a slot in the wall, (2) more elaborate uniform-fluid experiments in a 6-ft-diameter tank with the jet emerging from an axial tube in the center and with excess water overflowing at the rim, and (3) experiments with a two-layer system (immiscible fluids) in a 4-ft-diameter tank with a central jet confined to the upper layer. The resulting circulations were more complex than anticipated and could not be interpreted satisfactorily in terms of Rossby's theoretical work. Nevertheless it is interesting to read Spilhaus's account of the experiments in the light of our present understanding of source-sink flow in rotating experiments.

#### 16.3 The Experiments of W. S. von Arx

Serious and sustained efforts at modeling the ocean circulation began with von Arx circa 1950. At about the same time, and quite independently, major laboratory efforts were being initiated by D. Fultz and R. Long at the University of Chicago, who were primarily interested in atmospheric circulations, and by R. Hide at King's College, the University of Newcastle, who was attempting to understand the fundamentals of circulation in the molten interior of the earth. The eventual collaboration and interchange of information between these investigators and their students became part of the rapid development of the field of study that today we refer to as geophysical fluid dynamics. The rather bold initiatives of these scientists eventually led to the realization by a broader base of theoretically oriented meteorologists and oceanographers that it was indeed possible to simulate certain features of complex geophysical circulations in the laboratory.

The first major experiments reported by von Arx (1952) were conducted in a paraboloidal basin in which the northern hemisphere continental boundaries were modeled in sponge rubber. The trade winds were derived from the relative motion of the air in the laboratory at the rotation rate  $\Omega = 3.18 \text{ s}^{-1}$ , and the midlatitude westerlies were generated by three stationary vacuum cleaner blowers with appropriately directed nozzles. With this basic system it was possible to generate many of the essential features of the northern ocean circulations that were then known to exist. These and subsequent experiments had certain shortcomings, but their role in the stimulation and development of further laboratory studies should be recognized.

The paraboloidal models were not entirely satisfactory in several ways: geometrical distortion was inevitable; the wind fields could not be precisely controlled or measured; at wind speeds of about 2 m s<sup>-1</sup> the water surface was wavy and it is likely that the surface Ekman layer was unstable; and with the complex geometry a slight tilt of the rotation axis produced large undesirable oscillations. Moreover, a severe critic might argue that in attempting to approach the complexity of nature, the ability to achieve understanding of fundamental processes was sacrificed. Nevertheless, in the developing field of oceanography there was still at that time what seemed to be a residual dichotomy of opinion between advocates of the wind-generation theory of ocean currents and advocates of the thermalgeneration theories, which tended to divide theoretical and observational oceanographers; von Arx's experiments were a convincing verification of the theories of Stommel, Munk, and others with respect to wind generation of the primary ocean circulation.

The von Arx experiments helped stimulate further laboratory studies in various ways. First, there was the development of experimental techniques for use with rotating laboratory models. Second, the rotating apparatus that he built was used in later experiments by this author and a succession of others, and the basic rotating system is today still available for use at the Woods Hole Oceanographic Institution. Third, through a paradox that was observed in the early studies with the paraboloid, the possibility of simulating the  $\beta$ -effect by a radial variation of depth was first realized.

Von Arx originally employed his carefully constructed paraboloidal basin at the equilibrium rotation rate, i.e., the rotation rate at which the water surface had the same paraboloidal shape as the container. Strangely, at this speed no western boundary current could be found. But at higher speeds, the western intensification was obviously present and at lower speeds there was eastern itensification! This behavior was explained by C. G. Rossby (von Arx, 1952) and eventually led to the proposition, by the present writer, that the paraboloidal shape was unnecessary—that a flat tank with a paraboloidal free surface, produced by a suitable rotation rate, would work equally well.

Further experiments using a flat-bottomed tank (von Arx, 1957) allowed lower rotation rates and a generally better overall experimental control. Studies of the southern hemisphere were undertaken and the representation of natural circulations was somewhat better than in the paraboloidal basin.

Success with the flat geometry encouraged von Arx to build a much larger apparatus, a floating cylinder with a working area having a diameter of 4 m and driven by impeller blades beneath the tank. A photograph and description of this apparatus appear in von Arx (1957). In an effort to improve the analogy with nature, infrared heaters were installed above the tank with the intention of heating the surface layers of water in the lower latitudes, thus simulating solar heating of the upper layers of the ocean. Unfortunately, the production of a warm surface layer essentially destroyed the induced  $\beta$ -effect associated with the paraboloidal depth variation and eliminated the western intensification!

Although this mammoth rotating tank did not improve significantly the ability to reproduce nature in miniature, the availability of this large apparatus encouraged this author to undertake experiments on the instability of the Ekman boundary layer (Faller, 1963). With the large-diameter tank the Reynolds numbers necessary for instability of the Ekman layer could be achieved at much lower Rossby numbers, i.e., with a more nearly geostrophic, as opposed to gradient, circulation.

As an aside, to this author's knowledge the Ekman number, which figures prominently in all rotating laboratory experiments, was first introduced by H. Lettau in a turbulence course at MIT in 1953 that was attended by both von Arx and this writer. Lettau's definition was E = D/H, the geometric ratio of the depth of an Ekman layer to the total depth of fluid. This definition was introduced into the literature by Faller and von Arx (1958) and by Bryan (1960) although the ratio L/D, where L is an arbitrary characteristic length, was defined as the Ekman number by von Arx (1957). The ratio D/H is, of course, also the inverse of the fourth root of the Taylor number; and Fultz (1953) referred to  $L^2/D^2$  as a rotation Reynolds number. Stern (1960b) used Ekman number  $E = \Omega H^2 / \nu = (H/D)^2$ , but it appears that now the generally accepted definition is  $E = \nu/\Omega H^2 = (D/H)^2$  or a definition in which H is replaced by some characteristic horizontal scale. This writer prefers the definition E = D/H as originally given

by Lettau because of its simple geometric significance and because the scaled Ekman depth is then proportional simply to E rather than  $E^{1/2}$ , although other definitions may sometimes be mathematically more convenient.

#### 16.4 The SAF Model

In reviewing theories of the ocean circulation, Stommel (1957b) recognized the essential analogy between the precipitation theories of Hough and Goldsborough and more recent theories of the wind-driven ocean circulation. In brief, each mechanism may be considered in terms of distributed sources and sinks of fluid at or near the ocean surface. Moreover, isolating the deep ocean, one could imagine this layer as being driven by the sinking of cold water in selected Arctic and Antarctic regions with more or less uniformly rising motion out of the top of this layer to satisfy the continuity of mass.

At that time this writer was engaged in the study of laboratory models of the atmospheric circulation, using the rotating turntable of von Arx. At the suggestion of H. Stommel and A. B. Arons it was a relatively straightforward matter to arrange a simple source-sink experiment in analogy with the precipitation mechanism. It was predicted that with distributed precipitation over a portion of the interior of a bounded basin and with the  $\beta$ -effect simulation found by von Arx, the geostrophic constraint in the interior of the basin would require some rather bizarre flow patterns. In particular, with the geostrophic condition as the overriding constraint on the interior flow, continuity would have to be satisfied by a combination of east-west geostrophic currents along contours of constant depth and frictionally balanced western boundary currents, unspecified in detail.

Figure 16.1 shows the very first experiment of the series eventually presented in SAF, that is, Stommel, Arons, and Faller (1958), and in F, that is, Faller (1960). In this initial trial the depth variation was provided in part by a spherical-cap polar dome (built of wood) that was 5 cm high in the center, tapering to zero height at the radius r = 91.4 cm in a tank of total radius r = 106.7 cm. An additional depth variation was provided by the counterclockwise rotation rate of  $\Omega = 0.84$  s<sup>-1</sup>. The average water depth was h = 10 cm at  $\Omega = 0$ , measured above the flat portion of the tank bottom near the rim.

The side walls of the 30° sector were carved to fit the polar dome and were puttied in place with a small gap between the two sides at the apex to allow water to escape into the remainder of the circular tank as necessary to balance the source. An area of precipitation was arranged by dribbling dyed water (from a supply vessel) through a perforated coffee can at a flow rate of



Figure 16.1 The original experiment of Stommel, Arons, and Faller (1958). The black area on the right shows a portion of a spherical-cap polar dome that was 5 cm high at the center and tapered to zero depth at 91.4-cm radius. This dome was painted white within the 30° sector (on the left) that was formed by radial side walls shaped to fit the bottom boundary and puttied in place. The entire circular tank contained water approximately 3 cm deep at the center and 11 cm deep at the rim at the rotation rate  $\Omega = 0.84 \, \text{s}^{-1}$ , counterclockwise as viewed from above. Dyed water from the bucket on the right drained through a tube into a perforated coffee can and "precipitated" at the rate of 200 cm<sup>3</sup>min<sup>-1</sup> into the sector, near the rim. A small gap between the side walls at the apex allowed flow out of the sector. The western boundary current is clearly evident as a dark band of dyed water. (See figure 5.3).

approximately 200 cm<sup>3</sup> min<sup>-1</sup>. The experimental conditions were not precisely controlled, and figure 16.1 shows an area of disturbance near the precipitation source. Similar disturbances occurred near the apex, but these are obscured in figure 16.1 by a partial masonite cover. Nevertheless, the predicted western boundary current was obvious, thus confirming the theoretical prediction and leading to an extended series of controlled experiments.

The SAF experiments established the validity of the following basic concepts for slow, steady motion of a uniform fluid in a bounded basin without closed depth contours:

(1) If there is no local source (sink) of fluid and the local depth remains constant, the interior geostrophic flow is constrained to follow contours of constant depth.

(2) If there is a local source (sink) of fluid or if there is a gradual decrease (increase) in the local fluid depth, a column of fluid moves toward greater (lesser) depths satisfying the geostrophic condition of zero horizontal divergence.

(3) Failure of the interior motion to satisfy an overall mass balance produces a frictional western boundary current, the interior flow moving along lines of constant depth to the western boundary as required for overall continuity.

Perhaps the most striking result of these experiments was the verification of the recirculation phenomenon illustrated in figure 16.2. With a source of strength  $S_0$ at the apex of the sector and a distributed sink (represented by the gradual rise of the free surface), the predicted western boundary current flow was twice the source strength! In the laboratory experiment this current was composed half from the colored source water and half from the recirculated clear water.

Elaboration of the SAF experiments (Faller, 1960) demonstrated several additional features of the flow:

(1) In east-west currents (along contours of constant depth) the effect of bottom friction causes westwardmoving currents to diverge in a laminar and geostrophic Gaussian plume. This divergence is forced by bottom Ekman layer suction (and pumping) together with the effect of the radial depth variation. More sur-



Figure 16.2 An example of the partial radial-barrier experiments of Faller (1960) for a source at the apex and a uniformly rising free surface. The source  $S_0$  is joined by recirculated interior water to give a total western boundary current of  $2S_0$ . At the radius of the inner end of the partial radial barrier the WBC divides, one  $S_0$  continuing along the boundary and one  $S_0$  separating. Of the latter,  $0.25S_0$  reaches the radial barrier and participates in the WBC there, while  $0.75S_0$  moves northward as the required interior flow. A transport of  $0.75S_0$  from the southwest basin joins in the eastward-moving jet to complete the source water for the transport of one  $S_0$  along the radial barrier.

prisingly, the theory, being linear and reversible, predicts that an eastward-moving current of constant mass flux should converge into a narrower and more intense jet. As shown in the experiments, catastrophy is avoided in the converging jet because the flow spreads out in the western boundary current to whatever extent is necessary for its eventual convergence as it flows eastward.

(2) With an interior source (or sink) there was an intense recirculation analogous to the effects of the windspun vortex described by Munk (1950). The intensity of this recirculation phenomenon was found to be in excellent agreement with a theoretical analysis.

(3) The concepts predicted and verified in SAF were extended to somewhat more complex geometries involving partial radial barriers. An example of such a flow, qualitatively verified by experiment, is shown in figure 16.2, where the indicated transports are the theoretical predictions. Further application to an Antarctic-type geometry illustrated the important role of the radial barriers in allowing the buildup of pressure gradients essential to the maintenance of the geostrophic flow.

(4) In certain source-sink experiments with closed contours of constant fluid depth, it is not possible to construct purely geostrophic regimes of flow. In such cases, lacking resolution of the problem by western boundary currents, the effects of bottom friction dominate the flow. Examples of the complex set of spiral flow patterns necessary in order to transport fluid from an interior source to an interior sink illustrated the dominance of frictional effects.

(5) One feature that would not stand the test of time was the observation of an eastern boundary current when the flow was injected through the eastern boundary of the sector. In later experiments (Faller and Porter, 1976) it was found that this current was probably a density-driven flow due to incomplete thermal control of the injected water.

The analogy between these laboratory experiments and theoretical models of steady wind-driven ocean circulation may be illustrated most clearly by a comparison of the governing equations from three studies. These equations are

Stommel (1948)  $\alpha \frac{\partial \psi}{\partial x} + \nabla^2 \psi = \gamma \sin \pi y/b,$  (16.1)

Munk (1950) 
$$\beta \frac{\partial \psi'}{\partial x} - A \nabla^4 \psi' = \operatorname{curl}_z \tau,$$
 (16.2)

Faller (1960) 
$$\frac{\partial h}{\partial r} \left( \frac{1}{r} \frac{\partial \psi}{\partial \theta} \right) + \frac{D}{2} \nabla^2 \psi$$
  
=  $Q - \frac{\partial h}{\partial t}$ . (16.3)

In (16.1)  $\alpha = (H^*/R)(\partial f/\partial y)$ , where  $H^*$  is a constant effective ocean depth and R a linear drag coefficient;

and  $\gamma = F\pi/(Rb)$ , where F is the magnitude of the maximum wind stress per unit mass and b the northsouth dimension of the model. In (16.2) A is a horizontal Austausch coefficient,  $\tau$  the wind stress per unit mass, and  $\psi'$  the mass transport stream function. In (16.3) h is the variable fluid depth and Q an internal or surface source of fluid per unit horizontal area.

To illustrate the close correspondence of these equations we may multiply (16.1) by  $R/H^*$  and convert the right-hand side to the derivative of a cosine; introduce  $\psi = \psi'/H$  as the velocity streamfunction in (16.2), Hbeing the ocean depth; and multiply (16.3) by f/h, reorient the coordinate axes with  $r d\theta = dx$  and dy = -dr, and add the horizontal viscous term. The three equations then become

$$\frac{\partial f}{\partial y}\frac{\partial \psi}{\partial x} + \frac{R}{H^*}\nabla^2\psi = -\frac{1}{H^*}\frac{\partial F\cos\pi y/b}{\partial y},$$
(16.4)

$$\beta \frac{\partial \psi}{\partial x} \qquad -A \nabla^4 \psi = \frac{1}{H} \operatorname{curl}_z \tau,$$

$$\left(-\frac{f}{h}\frac{\partial h}{\partial y}\right)\frac{\partial \psi}{\partial x} + \frac{fD}{2h}\nabla^2\psi - \nu\nabla^4\psi = -\frac{f}{h}Q + \frac{f\partial h}{h\partial t}.$$
(16.6)

Equations (16.4)-(16.6) clearly demonstrate the analogy between the laboratory experiment and the basic theories of the steady wind-driven ocean circulation. In particular,  $\beta = \partial f/\partial y$  is modeled by  $-fh^{-1}\partial h/\partial y$ , Stommel's linear drag law corresponds to the Ekman layer effect with  $R/H^*$  the equivalent of fD/2h, and a positive curl of the wind stress in (16.4) or (16.5) is represented in (16.6) by either an internal (or surface) sink of fluid -fQ/h or by a local rate of increase of depth  $(f/h)\partial h/\partial t$ . Note also that with the addition of the lateral viscous term to (16.6) this equation is capable of describing steady, linear western boundary currents analogous to those of Munk.

#### 16.5 Experiments with Rotating Covers

The source-sink experiments were more controlled than the wind-driven experiments, and the regular boundary conditions of the 60° sector allowed a clear distinction between the interior flow and the western boundary current (WBC); turbulence was essentially eliminated and the interior flow could be guaranteed to be essentially geostrophic by controlling the flow rates. The introduction of a rotating cover (rotating lid) as the driving mechanism produced a certain degree of additional control by completely enclosing the fluid, by eliminating the possibility of density differences in

the source flow, and by allowing the parameters of the problem to be more easily varied. For example, transient circulations due to an impulsive start of the cover or due to a periodic oscillation of the cover could be easily controlled. Such experiments would be difficult with the sources and sinks of the SAF studies.

Bryan (1960) was perhaps the first to use a rotating lid in an experiment directed toward the understanding of oceanic circulations. Having in mind the planetary waves of the atmosphere and the Gulf Stream meanders, he investigated the baroclinic stability of a twolayer system of salt and fresh water in a 34-cm-diameter cylindrical vessel, the driving force being a slowly rotating lid. He successfully produced symmetric flow, one to three regular waves, and an irregular wave regime, more or less in agreement with a corresponding theory of baroclinic instability. These experiments, of course, had a great deal in common with the annulus experiments of Hide (1958) and with the annulus, open dishpan, and two-fluid experiments of Fultz (1953).

Rotating-lid experiments that turned out to be analogous in many ways to the SAF studies were introduced by Beardsley (1969) in connection with the theories of Pedlosky and Greenspan (1967), the so-called sliced-cylinder model of the wind-driven ocean circulation. The steady-state sliced-cylinder circulation can be described and understood by a relatively simple theoretical analysis, and the following section, through equation (16.18), develops the theory of this model in terms borrowed from the theory of the SAF experiments. This short section will be of particular interest to those directly concerned with the theory of such experiments but may be passed over by the more casual reader. In either case figures 16.3 and 16.4 illustrate the model geometry and circulation.

The radial transport per unit of circumference in the upper Ekman layer due to a differential rotation  $\epsilon \Omega$  is simply  $T_{\text{Ek}}(r) = \epsilon \Omega r D/2$ , and the corresponding source strength per unit area for the interior due to Ekman layer divergence is  $Q = -\epsilon \Omega d$ , independent of radius. For positive  $\epsilon$  this source is the equivalent of a uniform rise of the free surface in the SAF studies.

At the rim, r = a, the Ekman transport  $T_{Ek}(a)$  feeds into a Stewartson boundary layer at the circular wall. Since the interior flow is quite slow for large  $\alpha$ , little of the flow into the Stewartson layer from above can be taken up by the slow bottom Ekman layer, and we ignore this effect. The Stewartson layer then feeds uniformly into the interior, giving an average flow normal to the wall:

$$U_{\rm n} = \epsilon \Omega a D/2h. \tag{16.7}$$

The interior geostrophic flow is governed by equation (16.6) omitting the lateral and bottom friction



Figure 16.3 A schematic N-S cross section of the circulation in a sliced-cylinder model. The circulation is driven by the divergent Ekman layer of the rotating lid with the induced suction velocity  $Q = -\epsilon \Omega D$ . The Ekman flow at the rim of the rotating lid turns into the Stewartson layer and feeds the interior as a velocity component normal to the wall  $U_n$ . The geostrophic S-N interior flow  $v_i$  is independent of x and y and is given by  $v_i = -Q/\tan \alpha$ . Global continuity of mass is satisfied by geostrophic east-west interior flows and the western boundary current (not shown).



Figure 16.4 Streamlines of the theoretical, linear, steady-state circulation in the sliced-cylinder experiment of Pedlosky and Greenspan (1967) and Beardsley (1969) for a bottom slope angle  $\alpha = 30^{\circ}$ . For large  $\alpha$  the flow away from the eastern boundary becomes evident in the streamline pattern because of the reduction of  $v_i$  in comparison to  $U_n$  (figure 16.3). The variation in width of the western boundary current is schematically illustrated.

terms. The resultant equation for the south-to-north interior flow is

$$v_i = -Q/\tan \alpha = \epsilon \Omega D/\tan \alpha, \qquad (16.8)$$

where  $v_1 = \partial \psi / \partial x$  and  $\tan \alpha = -\partial h / \partial y$ . Thus for  $\epsilon > 0$ , as in the case considered by Pedlosky and Greenspan (1967), Q < 0 (Ekman suction) and it follows that  $v_1 >$ 0. Later experiments of Beardsley used  $\epsilon < 0$ .

The interior velocity component  $u_1$  is determined by continuity. For a cell in the interior mass continuity is given by

$$\left[v_{1}h - \left(v_{1}h + \frac{\partial v_{1}h}{\partial y} dy\right)\right] dx$$
$$+ \left[u_{1}h - \left(u_{1}h + \frac{\partial u_{1}h}{\partial x} dx\right)\right] dy + Q dx dy = 0.$$

Using equation (16.8) and  $\partial h/\partial x = 0$  it is readily found that  $\partial u_1/\partial x = 0$ . Following the assertion made in SAF that there can be no geostrophic flow component normal to the eastern boundary, but that unlimited flow into or out of the western boundary layer is permitted, the value of  $u_1$  is determined by  $u_e$ , the westeast flow at the eastern boundary. This in turn is composed of two parts: the source flow from the Stewartson layer is  $u_{e1} = -U_n/\cos\theta = -\epsilon\Omega Da/2h\cos\theta$ ; and from the constraint that there be no geostrophic flow normal to the boundary we obtain  $u_{e2} = -v_1 \tan \theta$ . The total west-east interior flow is then

$$u_{i} = -\epsilon \Omega D \left( \frac{a}{2h\cos\theta} + \frac{\tan\theta}{\tan\alpha} \right) . \tag{16.9}$$

Integrating (16.8) and (16.9) to obtain an interior streamfunction defined by  $v_i = \partial \psi / \partial x$  and  $u_i = -\partial \psi / \partial y$  gives

$$\psi' = \frac{\psi}{\epsilon \Omega D a} = \frac{a}{\overline{h}} \frac{\sin^{-1} y'}{2} + \left[ \left( \frac{a}{\overline{h}} \right)^2 \frac{\tan \alpha}{2} + \frac{1}{\tan \alpha} \right] \left[ 1 - (1 - y'^2)^{1/2} \right] + \frac{x'}{\tan \alpha}, \qquad (16.10)$$

where y' = y/a, x' = x/a, and  $\psi' = 0$  at x' = 0, y' = 0. In this integration I have used the approximation

$$h = \overline{h} - y \tan \alpha \cong \overline{h} \left( 1 + \frac{y \tan \alpha}{\overline{h}} \right)^{-1},$$

and as a result (16.10) differs slightly from Beardsley's (1969) equation for pressure.

Figure 16.4 illustrates the pattern of  $\psi'$  for  $\alpha = 30^{\circ}$ . With this large slope  $v_1$  is small and the effect of the source at the rim is made conspicuous [compare Pedlosky and Greenspan (1967, figure 5)]. Since the rim source does not directly contribute to the north-south (N-S) transport, it is easily seen, as pointed out by Beardsley (1969), that the WBC transport  $T_w$  is determined solely by the value of  $v_1$  integrated over x. By continuity

$$T_{w}(N-S) = -\int_{-X(y)}^{X(y)} hv_{i} dx = -2hv_{i} X(y).$$
(16.11)

The WBC transport parallel to the boundary, however, requires that the result in (16.11) be divided by  $\cos \theta$ . Dividing also by  $\epsilon \Omega Dah$ , the nondimensional transport per unit depth and parallel to the boundary is

$$T'_{w}(||) = \mp 2 \tan \alpha, \qquad (16.12)$$

the upper sign corresponding to  $\epsilon > 0$ .

But although  $T'_w(||)$  is constant, the current sees different variations of depth  $\partial h/\partial s$  along its axis s, and the width of the current must change. For positive y (and  $\epsilon > 0$  as in figure 16.3) the current narrows as it moves south toward y = 0, and it is also fed from the interior flow. For y < 0 the current feeds the interior and at the same time broadens because  $\partial h/\partial s$  decreases along the direction of flow. By the time the flow reaches  $\theta = -\pi/2$  the WBC must completely disperse, and under these circumstances it is not surprising that an instability occurs for sufficiently large  $\epsilon$ .

The steady-state, linear analysis given above cannot take into account transients, instabilities of the flow, details of the boundary layer flow, or the range of validity of the theory. These aspects of the problem were the principal focal points of the analytic, numerical, and experimental sliced-cylinder studies cited above. Nevertheless, the simplified treatment given here reveals the essential physical mechanisms without mathematical obfuscation. In this spirit we continue with an elementary treatment of the WBC to illustrate certain principles analyzed by Beardsley (1969) and later disucssed also by Kuo and Veronis (1971).

Beardsley noted that when the angle  $\alpha$  is small, the WBC is dominated by bottom Ekman-layer pumping, rather than by lateral friction. Except very close to the wall, the boundary current then is essentially that found by Stommel (1948) with friction entering the problem through a constant drag coefficient  $R/H^*$ , as in (16.4).

Figure 16.5 illustrates a WBC profile, the crossstream Ekman transport beneath the current, and the vertical flux from the Ekman layer. The WBC is normally much wider than D, and in the case where lateral friction dominates the boundary layer, the ratio of its width W' to D is W'/D =  $(h/D)^{1/3}(4/\tan \alpha)^{1/3}$  (see below). Thus, in the Ekman layer the usual boundary-layer assumption applies, namely, that lateral variations of the flow can be neglected in comparison to variations normal to the boundary. Under the simplifying as-



Figure 16.5 The nondimensional velocity component  $v' = e^{-x^*} \sin \sqrt{3x^*}$  for the Munk boundary layer in which lateral friction dominates the vorticity balance. (b) The Ekman transport beneath the boundary layer in (a). (c) Flux into or out of the western boundary current by Ekman layer convergence or divergence. (d) The nondimensional velocity  $v^* = x^*e^{-x^*}$  at the transition between the Munk and the Stommel boundary layer regimes.

sumptions given below it can also be shown that the Ekman layer transport is proportional to the local value of v above the Ekman layer. An inconsistency, apparent in figure 16.5, is that the maximum Ekman layer pumping occurs at x = 0 and the no-slip condition at the wall is not satisfied. To completely justify the approximate analysis given below, a more complete boundary-layer scaling and analysis including the sidewall Stewartson layers, as given by Beardsley (1969) and Kuo and Veronis (1971), is required.

Here we specify a total northward transport of the WBC,  $T_w$ , a straight N-S boundary, a linear depth variation  $-\partial h/\partial y = +\tan \alpha$ , and a locally constant depth, where h appears as a coefficient in the final differential equation; and we neglect variations of the current with y, i.e., along the boundary. Then (16.6) is appropriate, and after dividing by  $\nu$  it reduces to the third-order, ordinary linear differential equation with constant coefficients

$$\frac{d^3v}{dx^3} - \left(\frac{1}{Dh}\right)\frac{dv}{dx} - \left(\frac{2\tan\alpha}{D^2h}\right)v = 0$$
(16.13)

subject to the conditions v = 0 at x' = 0, v = 0 at  $x' = \infty$ , and  $T_w = \int_0^\infty vh \, dx$ . It is convenient to define a

nondimensional coordinate x' = x/W', where  $W' = [8 hD^2/(2 \tan \alpha)]^{1/3}$  will be seen to be the characteristic width of the WBC. Then, temporarily neglecting the Ekman layer effect by setting D = 0, (16.13) reduces to

$$\frac{d^3v}{dx'^3} - 8v = 0. \tag{16.14}$$

After applying the boundary conditions the solution to (16.14) is the exponentially-damped sine profile

$$v = \left(\frac{4}{3^{1/2}} \frac{T_{w}}{hW'}\right) e^{-x'} \sin \sqrt{3}x',$$
 (16.15)

which corresponds to the oscillatory solution of Munk (1950). A nondimensional v' for this result is plotted in figure 16.5.

The WBC in the absence of lateral friction has been called the *Stommel boundary layer* (Kuo and Veronis, (1971), and from (16.13) this is given by the solution to

$$\frac{dv}{dx} + \frac{2\tan\alpha}{D}v = 0.$$
(16.16)

Here the condition v = 0 at x = 0 must be relinquished, and the condition at infinity will be satisfied automatically. Applying the transport condition, the solution is the exponential profile

$$v = \frac{T_{w}}{hW''} e^{-x'}$$

where

$$x'' = x/W''$$
 and  $W'' = (D/(2 \tan \alpha))$ .

In terms of a simulated  $\beta$ -effect, being given  $\beta^* = (-2\Omega/h)(\partial h/\partial y)$  it follows that  $W'' = \Omega D/h\beta^*$ .

With the scaled coordinate x', the full equation is

$$\frac{d^3v}{dx'^3} - B\frac{dv}{dx'} - 8v = 0, \qquad (16.17)$$

where  $B = 4(D/h)^{1/3}(2 \tan \alpha)^{-2/3}$ . Substituting the trial solution  $v = e^{kx}$ , the characteristic equation is

$$k^{3} + ak + b = 0$$
, where  $a = -B$  and  $b = -8$ .

Complex values of k correspond to oscillatory solutions, and nonoscillatory boundary layers occur only for  $(b^2/4) + (a^3/27) \le 0$ , or  $D/h \ge 27 \tan^2 \alpha$ . Accordingly, the condition  $D/h = 27 \tan^2 \alpha$  may be defined as the transition point between the Munk and Stommel boundary layer regimes. In the SAF and F experiments where  $\tan \alpha = \Omega^2 r/g$  this transition took place at approximately r = 23 cm in a tank of radius a = 100 cm.

The solution at this transition is the product of linear and exponential functions as given by

 $v = \left(\frac{T_{w}}{hW^{*}}\right) x^{*}e^{-x^{*}},$  (16.18)

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where  $x^* = x/W^*$  and  $W^* = (3hD/4)^{1/2}$ . The slope  $\tan \alpha$  is implicit in this expression for  $W^*$  through  $D/h = 27 \tan^2 \alpha$ .

The theoretical studies of Pedlosky and Greenspan (1967) for the sliced-cylinder geometry emphasized the transient Rossby-wave character of the spin-up problem, i.e., the development of the steady-state flow by the accumulated effect of westward-propagating Rossby waves in response to the spin-up of the lid. Owing to the need for a more detailed examination of the steady-state flow and because of the discovery of an instability of the WBC, Beardsley's original experiments were temporarily diverted from the goal of studying the transient response. The instability was analyzed in detail by Beardsley and Robbins (1975), who described it as a "local breakdown of the finiteamplitude topographic Rossby wave embedded in the western boundary current transition region." This general description would seem to fit almost any reasonable theory of the observed instability, but it is noteworthy that a plausible analytical theory was presented and that numerical calculations of the flow showed similar instabilities and good agreement with the experiments.

In a companion paper Beardsley (1975) experimentally and theoretically examined the transient response of the flow to an oscillatory rotation of the lid. He again found good agreement between theory and experiment in the resonant response of topographic Rossby wave modes. In addition he found that the Stokes drift associated with the Rossby waves partially offset the mean Eulerian flow, a consideration of possible importance for the interpretation of oceanic processes (the result generally agrees with the theory of Moore, 1970). In a short series of trial experiments, Beardsley (1974) also changed the geometry of his experiment by replacing the planar sloping bottom with an axisymmetric conical bottom and introduced partial radial barriers, analogous to those of F (1960), to simulate certain aspects of the Antarctic circulation regime. These experiments again clearly illustrated the anticipated steady-state interior and boundary-layer flows.

Another interesting class of rotating-lid experiments was introduced by D. J. Baker. Baker and Robinson (1969) have presented a comprehensive theoretical and experimental analysis of the results and Baker (1970) has given a more pictorial and descriptive account of this research for popular consumption. The fluid (a solution of thymol blue) was contained, top and bottom, between spherical boundaries ground from plastic blocks. The lateral boundary was a circular cylinder, and the lower boundary was rotated to generate the flow. The confined fluid was meant to represent a circular ocean of uniform fluid on a spherical earth. This ingenious apparatus was mounted on a rotating table in such a way that the center of the model ocean could be set for any latitude from the equator to the pole. Indeed, the primary purpose of this experiment was a study of equatorial dynamics in the hope of obtaining a uniform-fluid analogue of the equatorial undercurrent.

Baker (1966) had introduced an important new quantitative method for the measurement of slow flows in the interior of liquids, the thymol-blue-indicator technique. A slightly acidic solution of thymol blue is used as the working fluid, and platinum wires are strung through the interior. When a current is passed through the wires the indicator immediately adjacent to the wires turns to a bluish-brown color and serves as a tracer for the subsequent flow. Baker and Robinson (1969) used an extensive rectangular array of wires to illustrate and measure the overall pattern of flow for a considerable range of flow speeds.

In the range of Rossby numbers where steady laminar flow would be expected, the basic interior and boundary-layer circulations were as would be anticipated from elementary theory. At higher values of the Rossby number, however, interesting asymmetries and irregularities of the flow, attributable to inertial effects, were observed.

When the latitude of the center of the model ocean was sufficiently close to the equator that a large equatorial zone was present, an interior zonal current opposite to the direction of driving of the cover was observed, and this current was tentatively identified as a uniform fluid analogue of the equatorial undercurrent.

#### 16.6 A Variety of Interesting Experiments

#### 16.6.1 Further Source-Sink Experiments

Kuo and Veronis (1971) reinvestigated many of the SAF and F experiments with a similar configuration of the apparatus but with a number of interesting variations and with a more exacting theoretical analysis of the boundary-layer flow. Their principal observational tool was the thymol-blue technique of Baker (1966) except that the platinum wires were alternately coated and exposed in short strips so that a pulse of electric current gave a dashed line of dye. This method allowed more accurate measurements of the flow components and improved the flow visualization.

As in the studies of Beardsley (see section 16.5) their experimental conditions covered both the Munk and Stommel WBC regimes and their experimentally observed current profiles were in excellent agreement with theory.

In addition to the effect of the paraboloidal free water surface, depth variation was controlled by a sloping bottom, and in one case by a partially sloping bottom in the SW corner of the  $60^{\circ}$  sector. The latter experiment was used to confirm certain basic theories about the effect of bottom topography on the separation of the boundary current from the coast. Concentrated sources and sinks in the interior, similar to the source used in F (1960) and to the effect of the wind-spun vortex of Munk (1950), also illustrated separation of the boundary current because of the source-sink distribution.

Veronis and Yang (1972) extended the uniform fluid WBC theory and experiments to cases with significantly nonlinear flow. Once again, the theoretical predictions, including both lateral viscous and Ekman layer effects, were accurately verified in the experiments. Some unsuccessful attempts were made to produce a sufficiently rapid and narrow western boundary current for barotropic instability.

#### 16.6.2 A Two-Layered Model

A major innovation and advance in laboratory modeling has recently been achieved by Krishnamurti (Krishnamurti and Na, 1978; Krishnamurti, 1978) by the introduction of controlled rotating-lid experiments with a two-layer system having no closed contours of depth. Using a conical bottom and a rotating conical lid, radial depth variations are produced in both the upper and lower layers. Under conditions that would be stable for a uniform-fluid experiment, the two-fluid experiment produces baroclinic instability and a number of interesting features associated with the deformation of the interface of the two fluids. Perhaps the most striking of these features is the upwelling of the lower fluid to the "surface" at the western boundary and the concurrent separation of the WBC, a phenomenon predicted by Parsons (1969) (see chapter 5).

Together with the laboratory experiments, Krishnamurti (1978) has theoretically evaluated the comparative spin-up times of the ocean and laboratory models in terms of the Rossby radius of deformation in relation to the fluid depth. These considerations suggest that the two-fluid experiments will have a number of interesting applications.

#### 16.6.3 Flow over Sills and Weirs and through Straits

Smith (1973, 1977) was concerned with the flow of cold bottom water after it had passed through the Denmark Strait from the Norwegian Sea. This is a problem concerning effects of friction and sloping bottom on the modification of a baroclinic current system. To accompany a theoretical model of bottom frictional effects, Smith developed a laboratory experiment in which denser fluid was drained slowly through a source tube onto the sloping bottom of a rotating tank. He observed a variety of systematic wavelike and eddy-like oscillations of the flow that were found to be consistent with appropriate theories of baroclinic instability. In the 1977 paper he compared his experimental results with observations of the pulsed flow over the sill in the Denmark Strait, and he concluded on the basis of the significant nondimensional numbers that the natural case should correspond to what he described as "the meandering jet, vortex train variety (Class I)." Experiments of this type indeed represent a sophisticated application of laboratory experiments to our understanding of detailed oceanic phenomena.

Flows through straits and over sills have been of great interest in a wide variety of nonrotating systems, and engineering data characterizing these flows have long been available. In oceanic applications, however, the Coriolis force must play an important role in modifying or controlling the flow, and from experience with topographic  $\beta$ -effects one might also expect the detailed geometry to be of great significance in many cases. An obvious oceanographic example of restricted flow is that through the Straits of Gibraltar, but many other examples may also be mentioned, such as the seepage of Antarctic Bottom Water through small gaps in the Mid-Atlantic Ridge.

The experiments of Whitehead, Leetmaa, and Knox (1974) and of Sambuco and Whitehead (1976) have been concerned with problems of this type, approaching them experimentally beginning with the nonrotating system and gradually increasing the effect of rotation. Their studies may be characterized as being concerned chiefly with the restriction of the volume transport of the lower fluid through the strait, or over the sill, at relatively high Rossby numbers. Smith's studies, in contrast, have been concerned primarily with very low Rossby numbers, and with frictional effects on sloping boundaries after the flow has left the constriction.

16.6.4 The Generation of Mean Flows by Turbulence One of the more elaborate and more significant recent laboratory studies has been that of Colin de Verdière (1977), who examined the response of a rotating fluid in various geometries to Rossby waves generated by a complex pattern of oscillatory sources and sinks of fluid introduced through holes in the bottom of the tank. He considered three cases: an *f*-plane model (constant depth); a polar  $\beta$ -plane model with a depth variation from the paraboloidal shape of the free surface and with closed height contours; and a sliced-cylinder model. Comparing turbulence and wave theory with the complex flow patterns of his experiments, he included in his studies the interaction of two-dimensional turbulent eddies for a fluid with energy sources and sinks, the evolution of the flow toward statistical equilibrium, and the interaction of Rossby waves with a mean flow.

The extent and variety of the experiments covered by Colin de Verdière preclude a detailed exposition of all his results, but in general it may be said that the theoretical expectations, based upon the theories of potential vorticity mixing of Rhines (1977), were experimentally verified. By way of example, we mention here the results of a polar  $\beta$ -plane experiment in which the flow was driven by alternating sources and sinks of fluid at the outer boundary. This complex system was arranged to produce a westward-moving Rossby wave. Through the preferential inward (northward) diffusion of anticyclonic vorticity, the Rossby wave in effect transferred energy to a westward mean flow north of its region of generation. When the forcing was turned off and the flow was allowed to decay, measurements of the mean flow and of the perturbation kinetic energy indicated that the eddies continued to feed energy into the mean flow.

The particular results given above concerning the generation of mean flows by turbulence in a  $\beta$ -plane model were anticipated by the experiments of Whitehead (1975), who excited turbulent motions in a somewhat different manner. Whitehead used a 2-m-diameter cylindrical tank and vertically oscillated a circular horizontal plastic disk within the fluid, the disk being 20 cm in diameter and centered at 66 cm radius. By thus driving turbulence and Rossby waves with no direct input of angular momentum, it was clear that the observed mean flow [eastward at the latitude (radius) of the oscillator, and westward to the north and south] was due to the lateral redistribution of angular momentum by the waves and turbulence. In such experiments, however, it is difficult to be certain that the mechanical apparatus is not partially forcing the mean flow. Suppose, for example, that the vertical axis of the oscillating plate were tilted by 1° one way or the other. Would this have an influence upon the generation of the mean flow, and if so, how much? The experiments of Colin de Verdière, using sources and sinks parallel to the rotating axis, do not seem to be subject to the same possible difficulties, but one must be very cautious in experiments of this type.

It is interesting to note that the late Professor V. P. Starr (of Chicago and MIT) probably had a significant influence upon these studies, for Whitehead acknowledges many interesting conversations with Starr and his students. I note this fact particularly because it was at the suggestions of Professors Starr and Rossby that Fultz began his experimental studies at the University of Chicago, and one of the original intentions of those studies was an examination of exactly the problem discussed above. The experiments of Fultz eventually centered upon thermally driven circulations in a hemispherical shell, but Starr (personal communication, circa 1952) always kept in mind the possibility of locally pulsing one of the spherical shells to generate purely mechanically driven circulations without the direct introduction of a mean flow.

The experiments discussed above appear to be contradicted by an experiment of Firing and Beardsley (1976), who generated an isolated eddy in a sliced-cylinder experiment. It was found that the total nonlinear effect of the eddy was the generation of cyclonic vorticity in the northern portion of the basin and anticyclonic vorticity to the south. The net effect was explained as the result of the competition between two opposing tendencies:

Potential vorticity conservation which imparts negative vorticity to northward moving water columns and positive vorticity to southward moving columns, and relative vorticity segregation which gives water columns with positive relative vorticity a tendency to move north and those with negative vorticity a tendency to move south. Thus the positive circulation induced in the northern half of the basin by the dispersing eddy indicated the dominance of the vorticity segregation mechanism in this flow.

There is need for further theoretical and experimental studies to rationalize the apparent differences between these results and those of Colin de Verdière (1977) and Whitehead (1975). The experiment of Firing and Beardsley was conducted in a system with no closed geostrophic contours and with an isolated eddy as the disturbance. The other experiments had continuous sources of Rossby waves or turbulence in an open circular tank without meridional barriers and therefore without the possibility of western boundary current and Rossby-wave reflection from meridional barriers.

## 16.6.5 The Generation, Propagation, and Reflection of Rossby Waves

Topographically generated Rossby waves were studied in detail by Long (1951) for the flow between hemispherical shells. Since that time many experimenters have generated stationary Rossby-wave patterns by the flow over a ridge or obstacle, using the radial depth variation to produce the simulated  $\beta$ -effect. Stationary Rossby waves have also appeared in a variety of experiments where the flow was obliged to separate from the western boundary and the boundary current was sufficiently nonlinear.

Ibbetson and Phillips (1967), however, were the first to investigate the generation, propagation, and reflection of Rossby waves specifically in an oceanographic context. In their classic paper they experimentally studied the free propagation and dissipation of Rossby waves from an oscillating-paddle wave generator (figure 16.6). Moreover, they developed a simple theory and a companion experiment for damped oscillatory flow in the closed region between their oscillating paddle and a radial barrier to the west. For a specific paddle frequency their theoretical solution consisted of the sum of two waves of the same frequency that could be identified as the one generated in the east by the paddle



Figure 16.6 A schematic representation of the Ibbetson and Phillips (1967) experiment for the limiting case of zero frequency of the oscillator. The interior currents are then purely zonal with speeds  $v_1$  equal to the speed of the eastern boundary  $u_e$ . The steady-state western boundary current transport is determined by continuity as in the SAF (1958) experiments.

and its reflection from the western boundary. Since the reflected wave was of high wavenumber and large amplitude, its energy was subject to rapid dissipation as it progressed eastward from the boundary. The net result was a strong concentration of radial motions in the vicinity of the western boundary.

The application of these results to steady-state ocean-circulation theory, as well as to the transient oscillations, becomes evident when one lets the driving frequency of the paddle approach zero. This condition is illustrated in figure 16.6. From section 16.5, because there are no interior sources and sinks of fluid, the interior radial velocity is  $v_1 = 0$ . It also follows that  $u_1 = u_e$ , where  $u_e$  is the zonal velocity of the eastern boundary, which in this case is the velocity of the paddle. The wave generated by the paddle thus degenerates to purely east-west currents, and the reflected wave, with very high longitudinal wavenumber and very large radial flow, in the limit becomes the western boundary current.

#### 16.6.6 Simulation of the American Mediterranean

An account of laboratory models of ocean circulation would not be complete without a brief discussion of Ichiye's (1972) laboratory studies of flow in the Gulf of Mexico and the Caribbean Sea. These were attempts to reproduce the known circulations insofar as is possible with a uniform fluid, by detailed scaling of the complex coastlines and bottom topography. The avowed purpose was "to understand the effects of bottom and coastal configuration of the two seas on the geostrophic current of barotropic mode. The vertical structure of the flow and the details of the horizontal current patterns are not a subject of this study."

Two separate model systems were constructed: one for the Gulf of Mexico, driven by a source of forced inflow through the Yucatan Straits, and outflow through the Straits of Florida; the other, of the Caribbean Sea and adjacent portions of the Gulf and the Atlantic Ocean, driven by a pattern of winds from fans. Rossby numbers and Reynolds numbers of the flow were varied to discover how the overall patterns of flow and the various cyclonic and anticyclonic vortices would respond to different values of these parameters.

In summary it may be said that many realistic features of the natural circulations were reasonably well reproduced, for example, the distribution of geostrophic mass transport in the Caribbean; but other features, notably the major current systems in the Gulf, were unacceptable. Of course, one of the values of experiments of this type lies in failure, for we are then directed to inquire about the specific sources of error. In this study it is likely that density stratification, or at least a two-layer system, may be necessary for greater realism of the model circulations. With the strong topographic effects that must be important in these nearly enclosed basins, the normal  $\beta$ -effect may be negligible, and a stratified-fluid experiment may be practical.

#### 16.6.7 A Laboratory Study of Open-Ocean Barotropic Response

The above title is that of Brink (1978), who studied the *f*-plane and  $\beta$ -plane response of a rotating fluid with a free surface to applied surface-pressure oscillations. A problem of direct interest is the response of the world oceans to atmospheric pressure fluctuations of all scales (see chapter 11). In the absence of the planetary and topographic  $\beta$ -effects, the *f*-plane response should follow the inverse barometric effect except for frequencies close to resonance with inertia-gravity waves. When near resonance occurs there may be significant overshoot, i.e., excess amplitude response compared to the inverse barometer effect. With the  $\beta$ -effect there can be significant undershoot because of the propagation of Rossby waves, although if the scale and frequency of the pressure fluctuations should correspond to one of the normal modes of oscillation of the basin, there again could be significant overshoot.

In his  $\beta$ -plane experiments, Brink oscillated the air pressure over an enclosed region bounded by circular arcs at 15.2- and 30.5-cm radius and by radial walls separated by 120° of azimuth. With the tank radius of 42 cm, the area of forced-pressure oscillation comprised about 13% of the total surface area. The pressure vessel was designed to just touch the water surface with the intent of not seriously interfering with the water circulation or the propagation of waves. Measurements of the water-level response were obtained with capacitance height gauges.

Approximate theoretical solutions for the response of the water level were compared with the amplitudes and phases of the observed height variations at several sites. Reasonable agreement was found in many cases. The most serious lack of agreement occurred at the higher frequencies, and this was tentatively attributed to the use of a primitive (steady-state) Ekman-layer model for viscous damping, rather than one that took into account transients in the Ekman layer. Brink concluded that departures from the inverse barometer effect are to be expected due to propagating free modes of oscillation as predicted by theory.

#### 16.6.8 Gulf Stream Rings

A laboratory study that may have direct analogy to the ocean was that of Saunders (1973), who experimentally tested the stability of a two-layer baroclinic vortex. While this experiment was similar in certain respects to the baroclinic instability studies of Fultz (1953), Hide (1958), Bryan (1960), Hart (1972), and others, Saunders pursued an interesting analogy with the stability of Gulf Stream Rings and other isolated oceanic vortices.

A cylindrical column of denser fluid was released within a lighter fluid, the entire system being initially in solid-body rotation. The lower part of the denser fluid spread out rapidly, leading to a low-level anticyclonic vortex and an upper-level cyclonic vortex. The increase in radius at the bottom  $R - R_0$  from the initial radius of the cylindrical column  $R_0$  was approximately equal to  $\lambda = (g'H)^{1/2}/f$ , the Rossby radius of deformation, where  $g' = g \Delta \rho / \rho$ ,  $\Delta \rho$  is the difference in fluid densities, H the fluid depth, and f the Coriolis parameter.

Defining the parameter  $\theta = \lambda^2/R_0^2$ , it was found that for  $\theta < 1$  the initial circular vortex was unstable and would break up into a number of smaller vortices, each having  $\theta > 1$ .

Calculation of an equivalent value of  $\theta$  for two stable Gulf Stream rings gave  $\theta \approx 2$ . Thus the stability or instability of the laboratory vortices and the corresponding stability characteristics of Gulf Stream rings, or other nearly circular oceanic vortices, may represent one of the most unambiguous tests of baroclinic instability in the ocean.

Two items that may be of historical interest in connection with these experiments are the following. First, in studies designed to test the bubble theory of cumulus convection Saunders used a small, hemispherical volume of buoyant fluid released at the bottom of a large and deep tank of water. Turned upside down, a small volume of dense fluid was released and allowed to fall, expanding as an entraining spherical-cap bubble. Saunders noticed that when the falling dense fluid impinged upon a rigid boundary it spread out somewhat analogously to an atmospheric squall line, and a series of experiments in a shallow fluid were undertaken. Since von Arx's old rotating turntable was available in the same laboratory, extension of these experiments to the rotating system was quite practical without the construction of new elaborate apparatus. Saunders first performed these rotating experiments in 1963 and the critical parameter for the stability of this type of vortex in fact was determined well before the extent and significance of Gulf Stream rings were fully appreciated.

The second item of interest is that in the late summer of 1954, when this author was first using von Arx's apparatus for atmospheric model studies, H. Stommel and W. V. R. Malkus one day suddenly appeared in the laboratory equipped with huge jugs of xylene and carbon tetrachloride (which at that time were not known to be so dangerous). Their intention was almost exactly the experiment later performed by Saunders, namely, to release a cylindrical column of a dense mixture of their two fluids in the center of a rotating tank full of water. They were specifically interested in relating the radial spread of this column of dense fluid to the Rossby radius of deformation, which had recently been recognized as an important parameter. Unfortunately this combination of liquids would have dissolved the sealer cementing together the base and rim of the tank. How might the history of laboratory studies have been altered in its course had this author allowed them to proceed with their experiment?

#### 16.6.9 Spin-Up

Laboratory experiments and the theory of spin-up of a rotating fluid began with the work of Stern (1959, 1960b). In the former (unpublished) paper he presented the basic theory of spin-up and a description of laboratory experiments that accurately verified the predicted spin-up times as well as the integrated radial and tangential displacements of floating tracer particles. In the latter paper an instability of Ekman flow was postulated as the source of disagreement between the experiments and laminar theory in certain cases. In more recent experiments, also with a uniform fluid, Fowlis and Martin (1975) used a laser Doppler velocimeter and found clear evidence of the elastoid-inertia oscillations to be expected from transients in the Ekman layer owing to the abrupt change in rotation rate (Greenspan and Howard, 1963). In the wind-driven ocean, however, the stratification may drastically alter the spin-up characteristics from what would be anticipated for a uniform fluid.

Stratified spin-up experiments (e.g., Buzyna and Veronis, 1971; Saunders and Beardsley, 1975) generally have been conducted in the same manner as the classical uniform fluid cases—with an abrupt change in the rotation rate. In such a case, all natural modes of oscillation can be excited, and as a result it has been difficult to match satisfactorily theory and experiment. In recent studies by Beardsley, Saunders, Warn-Varnas, and Harding (1979), however, the spin-up was made

gradually, thus avoiding the excitation of high-frequency oscillations. As a result, substantially better agreement than in previous experiments was found between a simple quasi-geostrophic numerical model and observations of the response of the interior temperatures and the azimuthal velocities.

#### 16.6.10 Langmuir Circulations

One of the areas of research in which H. Stommel played an early role was the study of windrows-slicks on a natural water surface oriented in streaks along the wind direction. In a series of approximately 200 observations on Ashumet Pond, Cape Cod, Massachusetts, over the 7-month period May-November 1950, Stommel (1952) observed the presence or absence of surface streakiness parallel to the wind, and he attempted to relate the occurrence of streaks to various meteorological factors including the wind, cloudiness, humidity, and the air-water temperature difference as a measure of the thermal stability. The single parameter that seemed to be related to the occurrence of streaks was the wind speed, and table 16.1 is a summary of Stommel's data. The occurrence of streaks is clearly seen to be dependent upon the wind speed, and streaks often were observed at speeds much less than what is now generally considered to be the critical value, about  $3 \text{ m s}^{-1}$  (Walther, 1966).

These data do not seem to indicate a sharply defined critical speed, and the apparent critical speed given by other observers should perhaps be questioned in view of the facts that the observation of streakiness is a subjective one, the amount of surface material present may be a factor, and parameters such as the steadiness of the wind measured just above the water surface may be relevant.

Because of the obvious presence of surface films and because "if the wind changes its direction abruptly the streaks themselves are quickly reoriented (in a matter of one or two minutes only)," Stommel (1952) postulated that the phenomenon was essentially a shallow surface-layer effect and that the action of the film in damping capillary waves might be of importance for

Table	16.	1
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Wind speed (mph)	Number o		
	Streaks	No streaks	% streaks
<1.5	3	42	7
1.5-2.5	9	19	32
2.5-3.5	11	8	58
3.5-4.5	14	5	74
4.5-5.5	13	8	62
>5.5	54	3	95

organizing the film into streaks. This postulate was taken up and explored by other authors, but it is now known that the windrows are the result of Langmuir circulations (LCs), organized longitudinal rolls with their axes parallel to the wind, and that surface films are not an integral part of the mechanism.

Since several scales of LCs may exist at any time (Faller and Caponi, 1978) the apparent rapid response of the windrows to wind variations may be presumed to be due primarily to the smaller scales, which are close to the surface and which respond more rapidly to changes in the wind. For example, in recent laboratory experiments with light wind Faller (1978) has found a characteristic growth rate of only 12 s for cells with a cross-wind wavelength of 44 cm. For larger scales one would certainly expect slower response times, but it now appears that reorganization of the pattern of surface streaks in a minute or two by the reformation of the LCs is not unreasonable.

I would now like to report some preliminary qualitative results on the generation of LCs in the presence of surface films. Figure 16.7 illustrates the wind-wave tank in which a regular pattern of crossed waves is generated and in which a wind is blown over the waves. In the absence of a finite-amplitude crossed-wave pattern and at low wind speeds there are virtually no wind waves generated over the working section of the tank, a length of about 5 m. In the presence of finite-amplitude crossed waves, however, the same air speed causes wind-generated waves of significant amplitude. From preliminary estimates it now appears that the large crossed waves and the smaller wind-generated waves both contribute to the growth of the observed LCs whose scale is determined by the crossed-wave pattern.

In previous papers (Faller, 1969; Faller and Caponi, 1978), it was reported that surface films completely prevented the formation of LCs, but this assertion must now be qualified on the basis of recent experiments. Of particular importance here is the effect of the finite length of the wind-wave tank, for this restricts the possible motion of the film. In light-wind conditions the wind stress will compress the surface film against the end of the tank, and a steady state is achieved when the internal film-pressure effect balances the wind stress. This condition can be avoided, at least temporarily, by introducing a surface film onto a clean water surface at the upwind end of the tank, for the film can then move downwind in response to the wind stress.

The effects of surface films under certain laboratory conditions can now be summarized as follows:

(1) Application of a surface film-forming material, in this case dodedyl alcohol, always damps wind-generated waves. Thus, whether moving or stationary, a film always destroys the contribution of small wind-generated waves to the LCs.



Figure 16.7 Apparatus used for the generation of Langmuir circulations. The vertically oscillating wedges generate a crossed pattern of large waves that propagate along the length of the tank and are absorbed at the right-hand end. Wind is

drawn in by an exhaust fan at the right-hand end to produce a shear flow in the water and small superimposed wind-generated waves.

(2) With the large, mechanically generated crossed waves present, LCs are not generated as long as the film is prevented from moving by compression against the end of the tank.

(3) With the same large waves present, LCs *are* generated if the surface film can move in response to the wind stress. In such a case, however, the wind-generated small waves are damped and do not contribute.

These observations lend additional support to the Craik-Leibovich theory of Langmuir circulations (Craik and Leibovich, 1976), which describes the action of essentially irrotational waves in twisting the vorticity of the wind-generated shear flow into the vorticity of the longitudinal rolls. Apparently the moving surface film can transmit the tangential wind stress to the water whereas the stationary film obviously cannot.

#### 16.7 Concluding Remarks

From time to time one may have the impression that laboratory-model experiments have reached the limit

of their usefulness—that all of the interesting and productive experiments have been performed, and that further experimentation will only be repetitious. Then too, many theories that formerly could only be tested in a physical-laboratory experiment can now be tested reliably with computer calculations. But from the extensive list of studies discussed above we perceive a gradual increase in the variety, sophistication, and application of laboratory experiments as novel experimental techniques are developed and as new theories emerge that isolate (abstract) interesting phenomena and require verification.

The laboratory experiments discussed in this review represent a necessarily restricted class of studies. Within this class, however, two progressions in style are evident: the first, from the attempts by von Arx to represent nature in detail insofar as possible, to experiments carefully matched to the corresponding theories and in which all aspects of the flow are analyzed in excruciating detail; the second, from the steady-state SAF experiments, through the transient spin-up, Rossby-wave, and oscillating-lid experiments, to the

interaction of turbulence and the mean flow. The recent two-fluid experiments of Smith, Saunders, Whitehead, and Krishnamurti now seem to indicate a gradual progression from uniform-fluid models into the theoretically and technically more difficult realm of baroclinic models, and clearly it would be premature to conclude that there is no longer a role for laboratory studies. Indeed, as long as "no one believes a theory, except the theorist, and everyone believes an experiment—except the experimenter," the role of laboratory experiments in oceanographic research remains secure.