

10.34: Numerical Methods Applied to Chemical Engineering

Lecture 5:
Eigenvalues and eigenvectors

Permutation

- Reordering through use of permutation matrices:
 - Consider the operation of swapping two rows. This can be done through matrix multiplication.

$$P = \begin{pmatrix} 0 & 1 & 0 & \dots & 0 \\ 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix}$$

swap row 1 and 2

identity

- For example:

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_2 \\ x_1 \\ x_3 \end{pmatrix}$$

Permutation

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← swap row 1 and 2

← identity

$$PA = \left(PA_1^C \quad PA_2^C \quad \dots \quad PA_N^C \right) = \begin{pmatrix} A_2^R \\ A_1^R \\ A_3^R \\ \vdots \\ A_N^R \end{pmatrix}$$

Permutation

- Reordering through use of permutation matrices:
 - How do I swap columns?

$$AP^T = (PA^T)^T$$

- Permutation matrices are unitary:

$$\begin{aligned} \mathbf{P}\mathbf{P}^T &= \mathbf{I} \\ \mathbf{P}^T &= \mathbf{P}^{-1} \end{aligned}$$

- Reordering a system of equations:

$$(P_1AP_2^T)(P_2x) = P_1b$$

- Reordering is a form of preconditioning!
- Reordering can be used for pivoting!

Recap

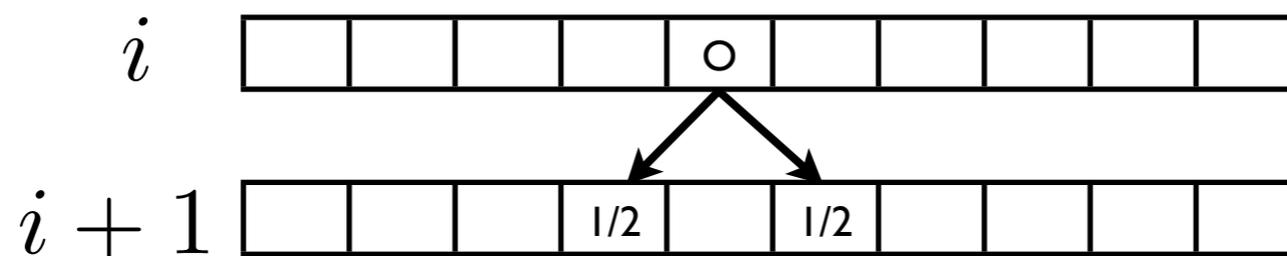
- Gaussian elimination
- Sparse matrices
- Permutation and reordering

Recap

- Example: Plinko:



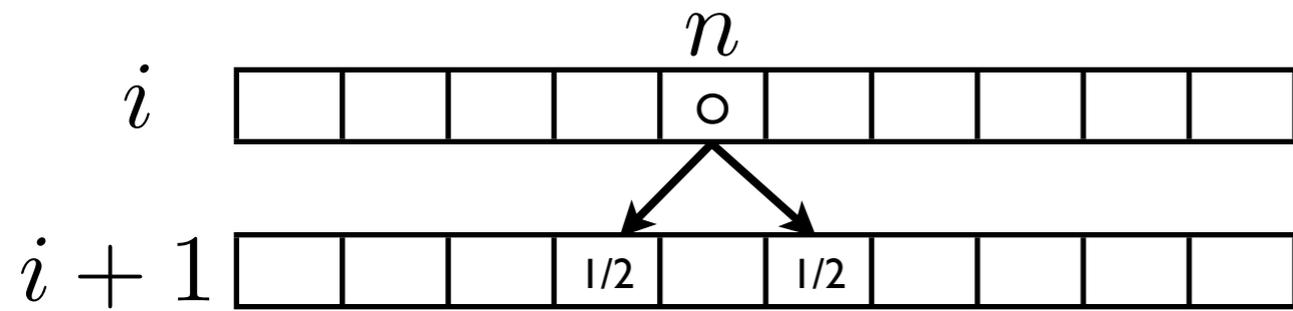
¥ 'gci fW'i b_bck b"5''f][\hg'fYgYfj YX''H\]g'Vt̂bhYbh'i]g'YI W XYX'Zfca 'ci f'7fYUH]j Y
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- Derive a sparse matrix model that maps the probability of the chip location from one level to the next.

$$\mathbf{P}^{i+1} = \mathbf{A}\mathbf{P}^i$$

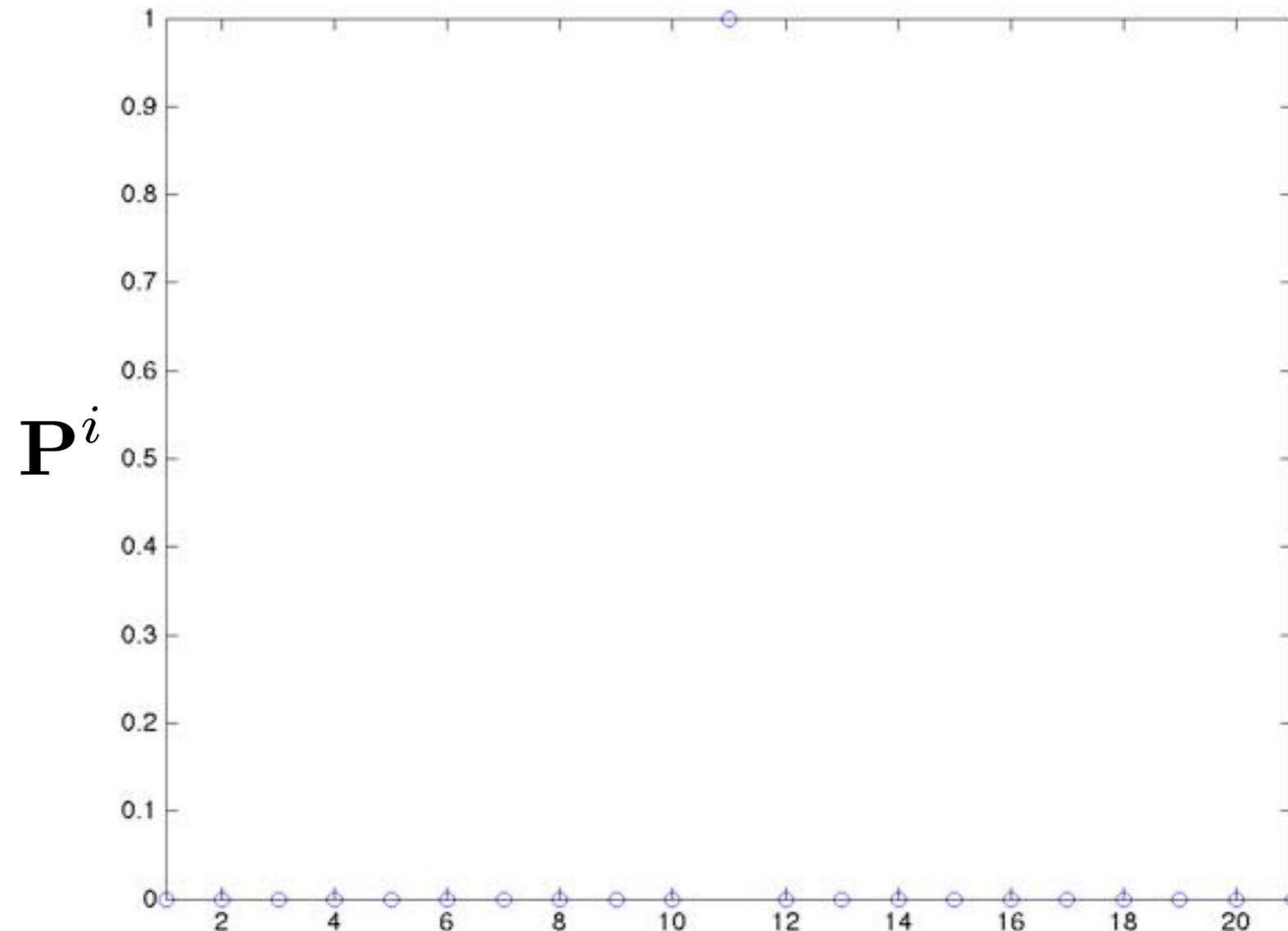
Recap



$$P_n^{i+1} = P_{n-1}^i / 2 + P_{n+1}^i / 2$$

$$\mathbf{P}^{i+1} = \mathbf{A}\mathbf{P}^i$$

- $A = \text{spdiags}(\text{ones}(N, 2) / 2, [-1 \ 1], N, N);$
- $A(1, 2) = 1; \ A(N, N-1) = 1;$

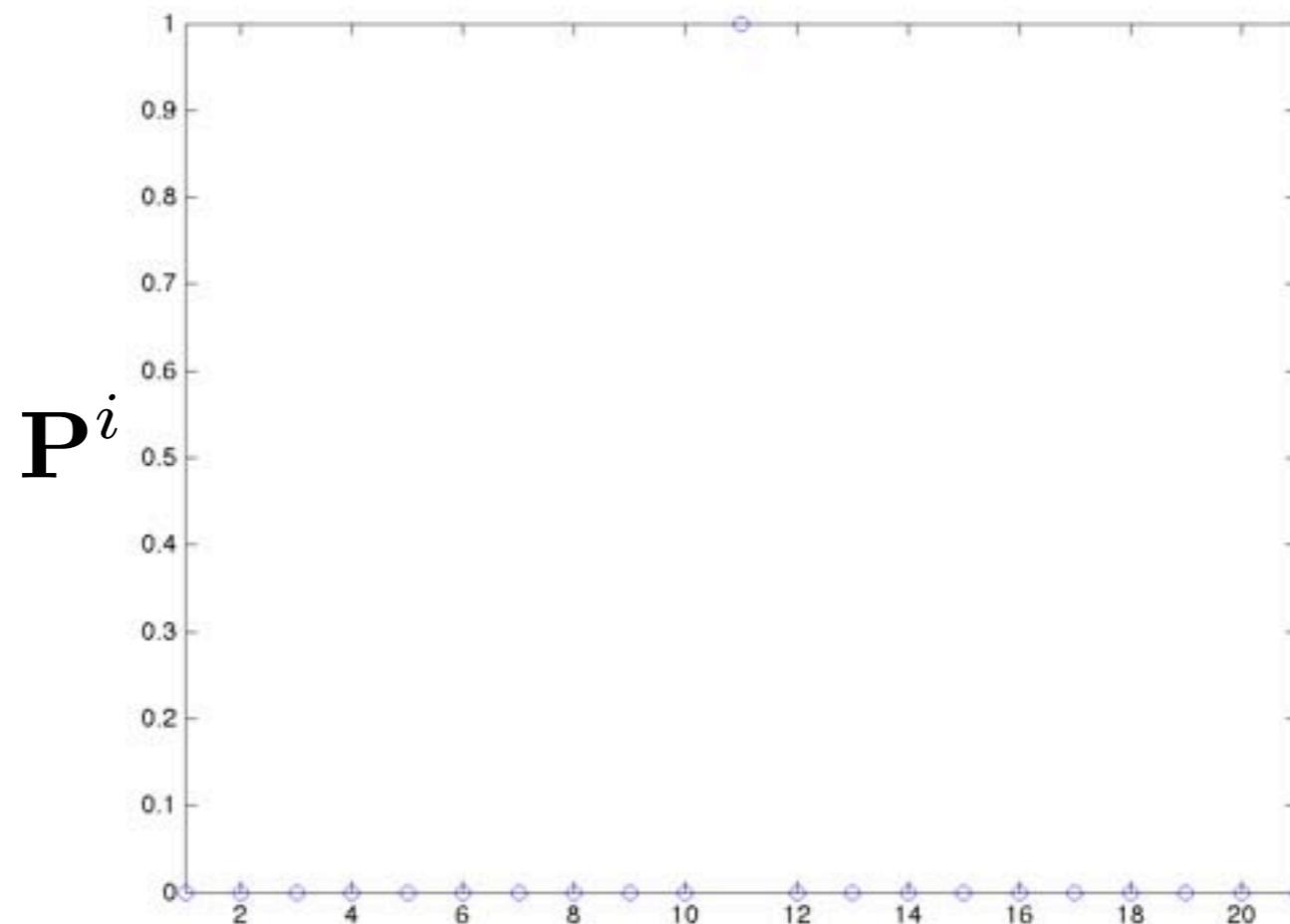


Recap

- Notice that after many cycles, the probability distribution becomes “constant.” $\mathbf{A}\mathbf{A}\mathbf{A}\mathbf{A}\dots\mathbf{A}\mathbf{P}_0$
- In fact there are special distributions such that:

$$(\mathbf{A}\mathbf{A})\mathbf{P} = \mathbf{P}$$

- What are examples of those distributions?
- They are called eigenvectors of the matrix: $\mathbf{B} = \mathbf{A}\mathbf{A}$



Eigenvalues and Eigenvectors

- The eigenvectors of a matrix are special vectors that are “stretched” on multiplication by the matrix:

$$\mathbf{A}\mathbf{w} = \lambda\mathbf{w}$$

$$\mathbf{A} \in \mathbb{R}^{N \times N} \quad \mathbf{w} \in \mathbb{C}^N \quad \lambda \in \mathbb{C}$$

- The amount of stretch λ is called the eigenvalue
- Finding an eigenvector/eigenvalue involves solving:
 - N equations
 - which are nonlinear ($\lambda\mathbf{w}$)
 - for $N + 1$ unknowns
- Eigenvectors are not unique:
 - If \mathbf{w} is an eigenvector, so is $c\mathbf{w}$

Eigenvalues

- Finding eigenvalues:

$$\mathbf{A}\mathbf{w} = \lambda\mathbf{w} \Rightarrow (\mathbf{A} - \lambda\mathbf{I})\mathbf{w} = 0$$

- either $\mathbf{w} = 0$
 - or $\mathbf{w} \in \mathcal{N}(\mathbf{A} - \lambda\mathbf{I})$ and $\det(\mathbf{A} - \lambda\mathbf{I}) = 0$
-
- For the right values of λ , $\mathbf{A} - \lambda\mathbf{I}$ is singular!
 - $\det(\mathbf{A} - \lambda\mathbf{I}) = 0 = p^N(\lambda)$
 - $p^N(\lambda)$ is called the characteristic polynomial.
 - The N roots of $p^N(\lambda)$ are the eigenvalues of
 - $p^N(\lambda) = c(\lambda_1 - \lambda)(\lambda_2 - \lambda) \dots (\lambda_N - \lambda)$

Eigenvalues

- Examples:

- $\mathbf{A} = \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$

$$\mathbf{A} - \lambda\mathbf{I} = \begin{pmatrix} -2 - \lambda & 0 & 0 \\ 0 & 1 - \lambda & 0 \\ 0 & 0 & 3 - \lambda \end{pmatrix}$$

$$\det(\mathbf{A} - \lambda\mathbf{I}) = (-2 - \lambda)(1 - \lambda)(3 - \lambda) = 0$$

$$\lambda = -2, 1, 3$$

- The elements of a diagonal matrix are eigenvalues

- $\mathbf{A} = \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix}$

Eigenvalues

- Examples:
- The elements of a diagonal matrix are eigenvalues:

$$0 = \det \begin{pmatrix} A_{11} - \lambda & 0 & \dots & 0 \\ 0 & A_{22} - \lambda & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & A_{NN} - \lambda \end{pmatrix} \\ = (A_{11} - \lambda)(A_{22} - \lambda) \dots (A_{NN} - \lambda).$$

- The diagonal elements of a triangular matrix are eigenvalues too:

$$0 = \det \begin{pmatrix} A_{11} - \lambda & A_{12} & \dots & A_{1N} \\ 0 & A_{22} - \lambda & \dots & A_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & A_{NN} - \lambda \end{pmatrix} \\ = (A_{11} - \lambda)(A_{22} - \lambda) \dots (A_{NN} - \lambda).$$

Eigenvalues

- Properties of eigenvalues: $\mathbf{A} \in \mathbb{R}^{N \times N}$
 - Inferred from the properties of polynomial equations!
 - $p^N(\lambda)$ is a polynomial of degree N and has no more than N roots. \mathbf{A} has up to N distinct eigenvalues.
 - The eigenvalues, like the factors of a polynomial need not be distinct. Multiple roots are possible, e.g.
$$p^N(\lambda) = c(\lambda - \lambda_1)^2(\lambda - \lambda_2) \dots (\lambda - \lambda_{N-1})$$
 - Eigenvalues may be real or complex. Complex eigenvalues appear in conjugate pairs: $\lambda, \bar{\lambda}$
 - $\det(\mathbf{A}) = \lambda_1 \lambda_2 \dots \lambda_N$
 - $\text{tr}(\mathbf{A}) = \lambda_1 + \lambda_2 + \dots + \lambda_N$

Eigenvalues

- Example:



- Conservation equation:

$$\frac{d}{dt} \begin{pmatrix} [A] \\ [B] \\ [C] \\ [D] \end{pmatrix} = \begin{pmatrix} -k_1 & 0 & 0 & 0 \\ k_1 & -k_2 & k_3 & 0 \\ 0 & k_2 & -k_3 - k_4 & k_5 \\ 0 & 0 & k_4 & -k_5 \end{pmatrix} \begin{pmatrix} [A] \\ [B] \\ [C] \\ [D] \end{pmatrix}.$$

- Find the characteristic polynomial of the rate matrix:

$$0 = \det \begin{pmatrix} -k_1 - \lambda & 0 & 0 & 0 \\ k_1 & -k_2 - \lambda & k_3 & 0 \\ 0 & k_2 & -k_3 - k_4 - \lambda & k_5 \\ 0 & 0 & k_4 & -k_5 - \lambda \end{pmatrix}$$

$$\det(\mathbf{A}) = \sum_{j=1}^N (-1)^{i+j} A_{ij} M_{ij}(\mathbf{A})$$

- What are the eigenvalues of the rate matrix?

- What are they physically?

Eigenvalues

- Example:



- Conservation equation:

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$$= \lambda(\lambda + k_1) \left[\lambda^2 + (k_2 + k_3 + k_4 + k_4) \lambda + k_2k_4 + k_2k_5 + k_3k_5 \right]$$

- What are the eigenvalues of the rate matrix?

- What are they physically?

Eigenvectors

- Finding eigenvectors:
 - Given an eigenvalue: λ_i , what is the corresponding eigenvector: \mathbf{w}_i ?
 - The eigenvector belongs to the null space of $\mathbf{A} - \lambda_i \mathbf{I}$
 - The eigenvector is not unique: $\mathbf{A}(c\mathbf{w}_i) = \lambda_i(c\mathbf{w}_i)$
 - One option: do Gaussian elimination on $[\mathbf{A} - \lambda_i \mathbf{I} | \mathbf{0}]$

- At some point the eliminated matrix will look like:

$$\left(\begin{array}{cccc|ccc} U_{11} & U_{12} & \dots & U_{1r} & U_{1(r+1)} & \dots & U_{1M} \\ 0 & U_{22} & \dots & U_{2r} & U_{2(r+1)} & \dots & U_{2M} \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & U_{rr} & U_{r(r+1)} & \dots & U_{rM} \\ \hline 0 & 0 & \dots & 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 & 0 & \dots & 0 \end{array} \right)$$

- **These** $r - N$ components of \mathbf{w}_i are arbitrary
- # of all zero rows = multiplicity of eigenvalue

Eigenvectors

- Examples:

- Find the eigenvectors of: $\mathbf{A} = \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$

$$\lambda_1 = -2, \lambda_2 = 1, \lambda_3 = 3$$

$$[\mathbf{A} + 2\mathbf{I} | \mathbf{0}] = \left[\begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 5 & 0 \end{array} \right]$$

$$\mathbf{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \mathbf{A} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 \\ 0 \\ 0 \end{pmatrix}$$

- What are the others?

Eigenvectors

- Example:



- Conservation equation:

$$\frac{d}{dt} \begin{pmatrix} [A] \\ [B] \\ [C] \\ [D] \end{pmatrix} = \begin{pmatrix} -k_1 & 0 & 0 & 0 \\ k_1 & -k_2 & k_3 & 0 \\ 0 & k_2 & -k_3 - k_4 & k_5 \\ 0 & 0 & k_4 & -k_5 \end{pmatrix} \begin{pmatrix} [A] \\ [B] \\ [C] \\ [D] \end{pmatrix}.$$

- Find the eigenvector of the rate matrix with eigenvalue 0:

$$\left[\begin{array}{cccc|c} -k_1 & 0 & 0 & 0 & 0 \\ k_1 & -k_2 & k_3 & 0 & 0 \\ 0 & k_2 & -k_3 - k_4 & k_5 & 0 \\ 0 & 0 & k_4 & -k_5 & 0 \end{array} \right]$$

- What does this eigenvector represent?

Eigenvectors

- Example:



- Conservation equation:

$$\frac{d}{dt} \begin{pmatrix} [A] \\ [B] \\ [C] \\ [D] \end{pmatrix} = \begin{pmatrix} -k_1 & 0 & 0 & 0 \\ k_1 & -k_2 & k_3 & 0 \\ 0 & k_2 & -k_3 - k_4 & k_5 \\ 0 & 0 & k_4 & -k_5 \end{pmatrix} \begin{pmatrix} [A] \\ [B] \\ [C] \\ [D] \end{pmatrix}.$$

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- What does this eigenvector represent?

Eigenvectors

- Example:
 - Find the eigenvalues and linearly ind. eigenvectors:

$$\mathbf{A} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

- Find the eigenvalues and linearly ind. eigenvectors:

$$\mathbf{A} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

Eigenvectors

- Example:
- Find the eigenvalues and linearly ind. eigenvectors:

$$\mathbf{A} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \quad p(\lambda) = \lambda^2 \quad \mathbf{w} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$\lambda = 0, 0$

algebraic multiplicity = 2 geometric multiplicity = 2

- Find the eigenvalues and linearly ind. eigenvectors:

$$\mathbf{A} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad p(\lambda) = \lambda^2 \quad \mathbf{w} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$\lambda = 0, 0$

algebraic multiplicity = 2 geometric multiplicity = 1

Eigenvectors

- Example:
 - Find the eigenvalues and linearly ind. eigenvectors:

$$\mathbf{A} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Eigenvectors

- Properties of eigenvectors:
 - If an eigenvalue is distinct (algebraic multiplicity 1):
 - $\dim \mathcal{N}(\mathbf{A} - \lambda_i \mathbf{I}) = 1$
 - There is only one corresponding eigenvector
 - If an eigenvalue has algebraic multiplicity M :
 - $1 \leq \dim \mathcal{N}(\mathbf{A} - \lambda_i \mathbf{I}) \leq M$
 - There could be as many as M linearly independent eigenvectors.
 - Geometric multiplicity is the number of linear independent eigenvectors for an eigenvalue:
 - When geometric and algebraic multiplicity are the same, the matrix is said to have a “complete set” of eigenvectors.

$$\dim \mathcal{N}(\mathbf{A} - \lambda_i \mathbf{I})$$

Eigendecomposition

- For a matrix with a complete set of eigenvectors one can write:

$$\mathbf{A}\mathbf{W} = \mathbf{W}\mathbf{\Lambda}$$

- where $\mathbf{W} = (\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_N)$

- and
$$\mathbf{\Lambda} = \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_N \end{pmatrix}$$

- equivalently: $\mathbf{\Lambda} = \mathbf{W}^{-1}\mathbf{A}\mathbf{W}$

- the matrix can be diagonalized

- equivalently: $\mathbf{A} = \mathbf{W}\mathbf{\Lambda}\mathbf{W}^{-1}$

- the matrix can be easily reconstructed

Eigendecomposition

- Solving systems of equations is easy when a complete set of eigenvectors and eigenvalues are known:

$$\mathbf{A}\mathbf{x} = \mathbf{b} \Rightarrow \mathbf{W}\mathbf{\Lambda}\mathbf{W}^{-1}\mathbf{x} = \mathbf{b}$$

- step 1: $\mathbf{\Lambda}(\mathbf{W}^{-1}\mathbf{x}) = \mathbf{W}^{-1}\mathbf{b} \Rightarrow \mathbf{\Lambda}\mathbf{y} = \mathbf{c}$

- step 2: $\mathbf{y} = \mathbf{\Lambda}^{-1}\mathbf{c} \Rightarrow \mathbf{W}^{-1}\mathbf{x}\mathbf{\Lambda}^{-1}\mathbf{W}^{-1}\mathbf{b}$

- step 3: $\mathbf{x} = \mathbf{W}\mathbf{\Lambda}^{-1}\mathbf{W}^{-1}\mathbf{b}$

- But how is \mathbf{W}^{-1} computed?

- $(\mathbf{W}^{-1})^T$ are the eigenvectors of \mathbf{A}^T

- If $\mathbf{A} = \mathbf{A}^T$ and $\|\mathbf{w}_i\|_2 = 1$, then $\mathbf{W}^{-1} = \mathbf{W}^T$

- Eigenvalue matrix is unitary: $\mathbf{W}\mathbf{W}^T = \mathbf{I}$

- Eigenvectors are orthogonal: $\mathbf{w}_i \cdot \mathbf{w}_j = \delta_{ij}$

Eigendecomposition

- Useful when analyzing linear systems of ordinary differential equations:

$$\dot{\mathbf{x}}(t) = \mathbf{A}\mathbf{x}$$

- substitute: $\mathbf{A} = \mathbf{W}\mathbf{\Lambda}\mathbf{W}^{-1}$
- let: $\mathbf{y}(t) = \mathbf{W}^{-1}\mathbf{x}(t)$
- then: $\dot{\mathbf{y}}(t) = \mathbf{\Lambda}\mathbf{y}(t)$ or $\dot{y}_i(t) = \lambda_i y_i(t)$
 - The system of ODEs is decoupled and easy to solve!
- What if there is not a complete set of eigenvectors?
 - Matrix cannot be diagonalized.
 - Components cannot be decoupled.
 - Jordan Normal Form: $\mathbf{A} = \mathbf{M}\mathbf{J}\mathbf{M}^{-1}$
 - \mathbf{J} is almost diagonal

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