

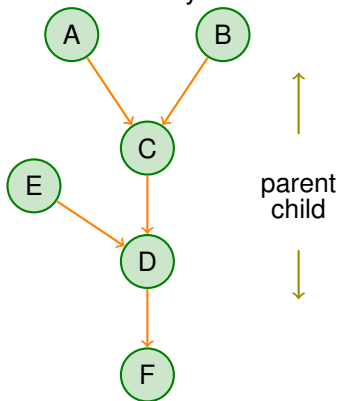
# Quantifying Uncertainty

Sai Ravela

M. I. T

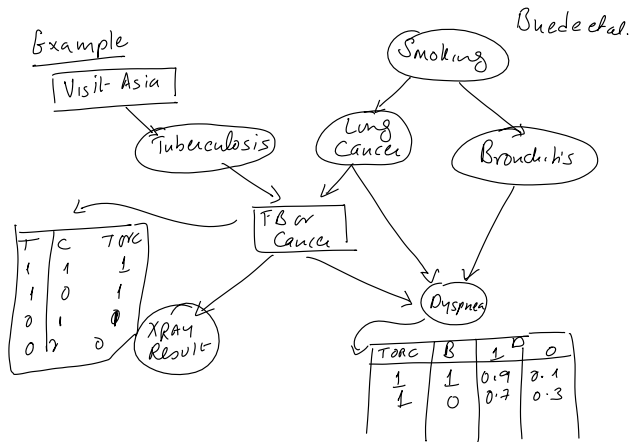
2012

## Revisiting Graphs and Hierarchical Bayes:



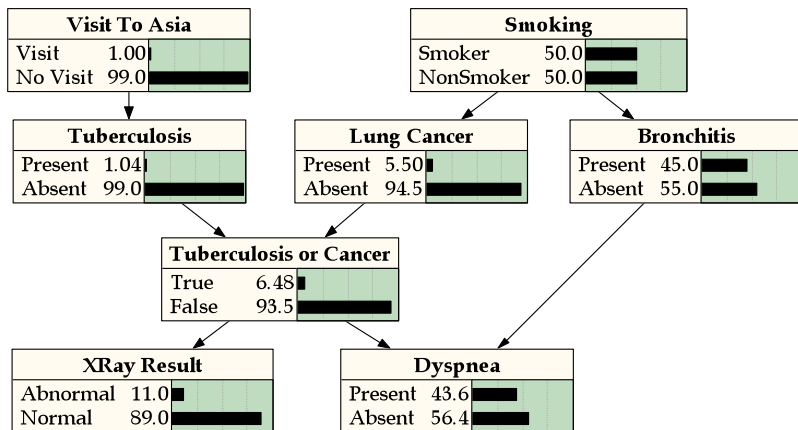
- a Hierarchical relationship between variables
  - b All are random
  - c Represented by directed acyclic graphs
- ⇒ Bayesian Networks

## example



Buede et al.

## example



Bayesian Networks can be used to model a large “interdisciplinary” dependences and assess

- a Evidence

- b Uncertainty

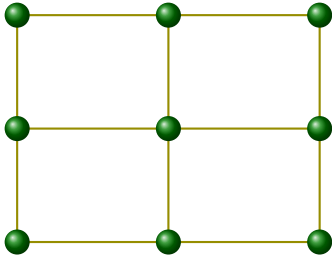
You will find tons of material and papers using Bayesian Networks. Especially in Ecological and Environmental application. and climate

# Markov Networks

A markov chain is a Bayesian Network



We may model “lattices” through Markov Networks



Markov random field example “two-way interactions”

Recall again

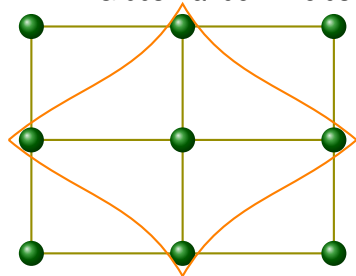


$$\begin{aligned} P(x_1, x_2, x_3) &= p(x_1 | x_2, x_3) p(x_2 | x_3) p(x_3) \\ &= p(x_1 | x_2) p(x_2 | x_3) p(x_3) \\ &= p(x_3 | x_2) p(x_2 | x_1) p(x_1) \\ &= p(x_1 | x_2) p(x_3 | x_2) p(x_2) \end{aligned}$$



# General Formulation

MRF == Gibbs Random Fields



Clique  $\equiv N_c(X_{ij})$

$$P(X_{ij} | \underline{X}) = P(X_{ij} | N_c(X_{ij}))$$

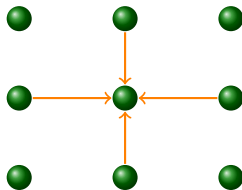
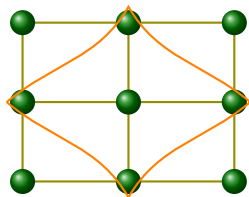
E.g Ising model for ferromagnetism

$X_{i,j} \in \{-1, 1\}$

$$E_{ij}(x) = \frac{-1}{kT} \sum_{X_{l,m} \in N_c(X_{ij})} X_{ij} \cdot X_{lm}$$

$$P(x) = \frac{1}{Z} e^{-\sum_{ij} E_{ij}(x)}$$

# The joint and conditional views



$$P(\mathbf{x}) = \prod_{ij} \psi_{ij}(x_{ij}, N_c(x_{ij}))$$

$$P(x_i | \underline{x} \setminus x(i, j)) = p(x_{ij} | N(x_{ij}))$$

# Hammersley-Clifford

$$P(\underline{x}) = \frac{1}{Z} \prod_{c \in CL(g)} \phi_c(x_c)$$

$c$ -clique,  $\forall x \in c, C \subseteq \{x, N(x)\}$

## For Bayesian Networks

$$p(x) = \prod_i p(x_i | pa(x_i))$$

*pa* -parent

## For Markov Networks

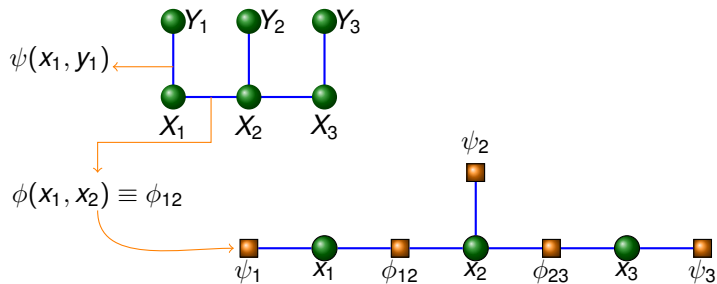
$$p(x) = \prod_i p(x_i) \prod_{ij} p(x_i, x_j)$$

# Probabilities and Potentials

$$P(\mathbf{x}) \propto \prod_i \psi(x_i) \prod_{ij} \phi(x_i, x_j)$$

So “renormalization” doesn’t become an issue

# Factor graph



# Inference and Belief Propagation

What is  $p(\underline{x}) \equiv p(x_1, x_2, \dots, x_n)$ ?

what is  $p(x_1)$ ?

$$\begin{aligned}
 p(x_1) &= \int_{x_3} \int_{x_2} p(x_1, x_2, x_3) \\
 &= \int_{x_3} \int_{x_2} \phi(x_1) \psi(x_1, x_2) \phi(x_2) \psi(x_2, x_3) \phi(x_3) \\
 &= \phi(x_1) \int_{x_2} \psi(x_1, x_2) \phi(x_2) \int_{x_3} \phi(x_3) \psi(x_2, x_3)
 \end{aligned}$$



# Message Passing

$$\phi(x_1) \quad \underbrace{\psi(x_1, x_2)\phi(x_2) \quad \psi(x_2, x_3)\phi(x_3)}_{\mu_{3 \rightarrow 2}(x_2)}$$

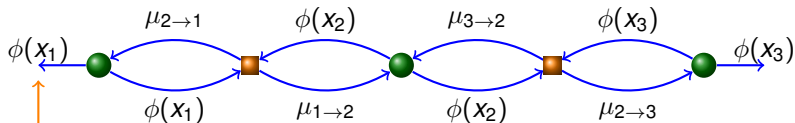
$$\mu_{2 \rightarrow 1}(x_1) = \int_{x_2} \psi(x_1, x_2)\phi(x_2)\psi_{3 \rightarrow 2}(x_2)$$

# Generalizing

$$b_j(x_j) = \sum_{k \in N_c(j)} \mu_{k \rightarrow j}(x_j)$$

$$\mu_{j \rightarrow i} \mu_i^j(x_i) = \sum_j \psi(x_i, x_j) \sum_{k \in N_c(j)} \mu_{k \rightarrow j}(x_j)$$

# Example



Constant  
at either end

"Forward-Backward", "Frontier Propagation": variety of schemes

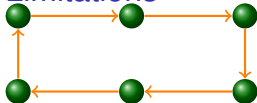
## Inference on

- ▶ Markov Networks
- ▶ Bayesian(Belief) Networks

## Via

- ▶ Belief Propagation
- ▶ As an example, let's look at EnKF/S from previous lecture as message passing.

## Limitations



- ▶ Graphs with loops: BP does not converge globally.

Why?

$$\phi(x_1) \quad \underbrace{\psi(x_1, x_2)}_{x_2} \phi(x_2) \quad \underbrace{\psi(x_2, x_3)}_{x_3} \phi(x_3) \psi(x_1, x_3)$$

Have to carry  $x_1$  around

But-local convergence is often “good enough”

MIT OpenCourseWare  
<http://ocw.mit.edu>

## 12.S990 Quantifying Uncertainty

Fall 2012

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.