

## Mixed-Integer Programming I

### Mixed-Integer Linear Programming

$$\begin{array}{ll} \max & cx + hy \\ \text{s.t.} & Ax + Gy \leq b \\ & x \text{ integral} \end{array}$$

where  $c$ ,  $h$ ,  $A$ ,  $G$ , and  $b$  are rational vectors and matrices, respectively.

### Projections

- Let  $P \subseteq \mathbb{R}^{n+p}$ , where  $(x, y) \in P$  is interpreted as  $x \in \mathbb{R}^n$  and  $y \in \mathbb{R}^p$ .
- The projection of  $P$  onto the  $x$ -space  $\mathbb{R}^n$  is

$$\text{proj}_x(P) = \{x \in \mathbb{R}^n : \exists y \in \mathbb{R}^p \text{ with } (x, y) \in P\}.$$

**Theorem 1.** Let  $P = \{(x, y) : Ax + Gy \leq b\}$ . Then

$$\text{proj}_x(P) = \{x : v^t(b - Ax) \geq 0 \text{ for all } t \in T\},$$

where  $\{v^t\}_{t \in T}$  is the set of extreme rays of  $\{v : vG = 0, v \geq 0\}$ .

### The Fundamental Theorem of MILP

**Theorem 2** (Meyer 1974). Given rational matrices  $A$  and  $G$  and a rational vector  $b$ , let  $P = \{(x, y) : Ax + Gy \leq b\}$  and  $S = \{(x, y) \in P : x \text{ integral}\}$ . There exist rational matrices  $A'$ ,  $G'$ , and a rational vector  $b'$  such that

$$\text{conv}(S) = \{(x, y) : A'x + G'y \leq b'\}.$$

Proof:

- We may assume that  $S \neq \emptyset$ .
- By the Minkowski-Weyl Theorem,  $P = \text{conv}(V) + \text{cone}(R)$ , where  $V = (v^1, \dots, v^p)$  and  $R = (r^1, \dots, r^q)$ .
- We may assume that  $V$  is a rational matrix and  $R$  is an integral matrix.

- Consider the following truncation of  $P$ :

$$T = \left\{ (x, y) : (x, y) = \sum_{i=1}^p \lambda_i v^i + \sum_{j=1}^q \mu_j r^j, \sum_{i=1}^p \lambda_i = 1, \right. \\ \left. \lambda \geq 0, 0 \leq \mu \leq 1 \right\}.$$

- $T$  is bounded and is the projection of a rational polyhedron. It therefore is a rational polytope.
- Let  $T_I = \{(x, y) \in T : x \text{ integral}\}$ . Claim:  $\text{conv}(T_I)$  is a rational polytope.
- Since  $T$  is a polytope,  $X = \{x : \exists y \text{ s.th. } (x, y) \in T_I\}$  is finite.
- For fixed  $\bar{x} \in X$ ,  $T_{\bar{x}} = \{(\bar{x}, y) : (\bar{x}, y) \in T_I\}$  is a rational polytope. Hence,  $T_{\bar{x}} = \text{conv}(V_{\bar{x}})$  for some rational matrix  $V_{\bar{x}}$ .
- Since  $X$  is finite, there is a rational matrix  $V_{T_I}$  which contains all the columns of all matrices  $V_{\bar{x}}$ , for  $\bar{x} \in X$ .
- Therefore,  $\text{conv}(T_I) = \text{conv}(V_{T_I})$ , which proves the claim.
- $(\bar{x}, \bar{y}) \in S$  iff  $\bar{x}$  is integral and there exist  $\lambda \geq 0$ ,  $\sum_{i=1}^p \lambda_i = 1$ , and  $\mu \geq 0$  such that

$$(\bar{x}, \bar{y}) = \sum_{i=1}^p \lambda_i v^i + \sum_{j=1}^q (\mu_j - \lfloor \mu_j \rfloor) r^j + \sum_{j=1}^q \lfloor \mu_j \rfloor r^j.$$

- The point  $\sum_{i=1}^p \lambda_i v^i + \sum_{j=1}^q (\mu_j - \lfloor \mu_j \rfloor) r^j$  belongs to  $T$ .
- Since  $\bar{x}$  and  $\lfloor \mu_j \rfloor r^j$  are integral it also belongs to  $T_I$ .
- Thus

$$S = T_I + R_I, \tag{1}$$

where  $R_I$  is the set of integral conic combinations of  $r^1, \dots, r^q$ .

- (1) implies that

$$\text{conv}(S) = \text{conv}(T_I) + \text{cone}(R).$$

- By the above claim  $\text{conv}(T_I)$  is a rational polytope.
- Thus  $\text{conv}(S)$  is a rational polyhedron (having the same recession cone as  $P$ ). □

### Union of Polyhedra

- Consider  $k$  polyhedra  $P_i = \{x \in \mathbb{R}^n : A_i x \leq b^i\}$ ,  $i = 1, \dots, k$ .
- One can show that  $\overline{\text{conv}}(\cup_{i=1}^k P_i)$  is a polyhedron.

- Furthermore, we will show that this polyhedron can be obtained as the projection onto  $\mathbb{R}^n$  of a polyhedron with polynomially many variables and constraints in a higher-dimensional space.

- (The closure is needed: let  $P_1$  be a single point and let  $P_2$  be a line that does not contain  $P_2$ .)

**Theorem 3.** For  $i = 1, \dots, k$ , let  $P_i = Q_i + C_i$  be nonempty polyhedra. Then  $Q = \text{conv}(\cup_{i=1}^k Q_i)$  is a polytope,  $C = \text{conv}(\cup_{i=1}^k C_i)$  is a finitely generated cone, and  $\overline{\text{conv}}(\cup_{i=1}^k P_i) = Q + C$ .

- No proof here, but note that the claims on  $Q$  and  $C$  are straightforward to check.
- One consequence of the proof is that if  $P_1, \dots, P_k$  have identical recession cones, then  $\text{conv}(\cup_{i=1}^k P_i)$  is a polyhedron.

**Theorem 4** (Balas 1974). Consider  $k$  polyhedra  $P_i = Q_i + C_i = \{x \in \mathbb{R}^n : A_i x \leq b^i\}$  and let  $Y \subseteq \mathbb{R}^{n+kn+k}$  be the polyhedron defined by

$$A_i x^i \leq b^i y_i, \sum_{i=1}^k x^i = x, \sum_{i=1}^k y_i = 1, y_i \geq 0 \text{ for } i = 1, \dots, k.$$

Then

$$\text{proj}_x(Y) = Q + C,$$

where  $Q = \text{conv}(\cup_{i=1}^k Q_i)$  and  $C = \text{conv}(\cup_{i=1}^k C_i)$ .

Proof:

- First, let  $x \in Q + C$ .
- There exist  $w^i \in Q_i$  and  $z^i \in C_i$  such that  $x = \sum_i y_i w^i + \sum_i z^i$ , where  $y_i \geq 0$  and  $\sum_i y_i = 1$ .
- Let  $x^i = y_i w^i + z^i$ . Then  $A_i x^i \leq b^i y_i$  and  $x = \sum_i x^i$ .
- This shows  $x \in \text{proj}_x(Y)$ .
- Now, let  $x \in \text{proj}_x(Y)$ .
- There exist  $x^1, \dots, x^k, y$  such that  $x = \sum_i x^i$  where  $A_i x^i \leq b^i y_i$ ,  $\sum_i y_i = 1$ ,  $y \geq 0$ .
- Let  $I = \{i : y_i > 0\}$ .
- For  $i \in I$ , let  $z^i = \frac{x^i}{y_i}$ . Then  $z^i \in P_i$ .
- Since  $P_i = Q_i + C_i$ , we can write  $z^i = w^i + \frac{r^i}{y_i}$  where  $w^i \in Q_i$  and  $r^i \in C_i$ .
- For  $i \notin I$ , we have  $A_i x^i \leq 0$ , that is  $x^i \in C_i$ . Let  $r^i = x^i$  for  $i \notin I$ .
- Then,

$$x = \sum_{i \in I} y_i z^i + \sum_{i \notin I} x^i = \sum_{i \in I} y_i w^i + \sum_i r^i \in Q + C.$$

□

## Lift-and-Project Revisited

We consider mixed-0/1 linear programs:

$$\begin{array}{ll}
 \min & cx \\
 \text{s.t.} & Ax \geq b \\
 & x_j \in \{0, 1\} \quad \text{for } j = 1, \dots, n \\
 & x_j \geq 0 \quad \text{for } j = n + 1, \dots, n + p
 \end{array}$$

We let  $P = \{x \in \mathbb{R}_+^{n+p} : Ax \geq b\}$  and  $S = \{x \in \{0, 1\}^n \times \mathbb{R}_+^p : Ax \geq b\}$ .

We assume that  $Ax \geq b$  includes  $-x_j \geq -1$  for  $j = 1, \dots, n$ , but not  $x \geq 0$ .

- Given an index  $j \in \{1, \dots, n\}$ , let

$$P_j = \text{conv}\{(Ax \geq b, x \geq 0, x_j = 0) \cup (Ax \geq b, x \geq 0, x_j = 1)\}.$$

- By definition, this is the tightest possible relaxation among all relaxations that ignore the integrality of all variables  $x_i, i \neq j$ .
- $\bigcap_{j=1}^n P_j$  is called the *lift-and-project closure*:

$$\text{conv}(S) \subseteq \bigcap_{j=1}^n P_j \subseteq P.$$

- On 35 mixed-0/1 linear programs from MIPLIB, the lift-and-project closure reduces the integrality gap by 37% on average [Bonami & Minoux 2005].

## Lift-and-Project Cuts

$P_j$  is the convex hull of the union of two polyhedra:

$$\begin{array}{lll}
 Ax \geq b & & Ax \geq b \\
 x \geq 0 & \text{and} & x \geq 0 \\
 -x_j \geq 0 & & x_j \geq 1
 \end{array}$$

By the above theorem:

$$P_j = \text{proj}_x \left( \begin{array}{l} Ax^0 \geq by_0 \\ -x_j^0 \geq 0 \\ Ax^1 \geq by_1 \\ x_j^1 \geq y_1 \\ x^0 + x^1 = x \\ y_0 + y_1 = 1 \\ x^0, x^1, y_0, y_1 \geq 0 \end{array} \right)$$

- Using the projection theorem, we get that  $P_j$  is defined by the inequalities  $\alpha x \geq \beta$  such that

$$\begin{array}{rccccccc}
\alpha & & -uA & +u_0e_j & & & \geq & 0 \\
\alpha & & & & -vA & -v_0e_j & \geq & 0 \\
\beta & & -ub & & & & \leq & 0 \\
\beta & & & & -vb & -v_0 & \leq & 0 \\
& & u, & u_0, & v, & v_0 & \geq & 0
\end{array} \tag{2}$$

- Such an inequality  $\alpha x \geq \beta$  is called a lift-and-project inequality.
- Given a fractional point  $\bar{x}$ , we can determine if there exists a lift-and-project inequality  $\alpha x \geq \beta$  valid for  $P_j$  that cuts off  $\bar{x}$ .
- This problem amounts to finding  $(\alpha, \beta, u, u_0, v, v_0)$  satisfying (2) such that  $\alpha \bar{x} - \beta < 0$ .
- In order to find a “best” cut in cone (2), we solve the *cut-generating LP*:

$$\begin{array}{rccccccc}
\min & \alpha \bar{x} & -\beta & & & & & \\
\alpha & & -uA & +u_0e_j & & & \geq & 0 \\
\alpha & & & & -vA & -v_0e_j & \geq & 0 \\
& & \beta & -ub & & & \leq & 0 \\
& & \beta & & & & -vb & -v_0 \leq & 0 \\
& & & \sum_i u_i & +u_0 & + \sum_i v_i & +v_0 & = & 1 \\
& & & u, & u_0, & v, & v_0 & \geq & 0
\end{array}$$

### Mixed Integer Inequalities

- Consider  $S = \{(x, y) \in \mathbb{Z}_+^n \times \mathbb{R}_+^p : \sum_{j=1}^n a_j x_j + \sum_{j=1}^p g_j y_j = b\}$ .
- Let  $b = \lfloor b \rfloor + f_0$  where  $0 < f_0 < 1$ .
- Let  $a_j = \lfloor a_j \rfloor + f_j$  where  $0 \leq f_j < 1$ .
- Then  $\sum_{f_j \leq f_0} f_j x_j + \sum_{f_j > f_0} (f_j - 1)x_j + \sum_{j=1}^p g_j y_j = k + f_0$ , where  $k$  is some integer.
- Since  $k \leq -1$  or  $k \geq 0$ , any  $x \in S$  satisfies

$$\sum_{f_j \leq f_0} \frac{f_j}{f_0} x_j - \sum_{f_j > f_0} \frac{1-f_j}{f_0} x_j + \sum_{j=1}^p \frac{g_j}{f_0} y_j \geq 1 \tag{3}$$

OR

$$- \sum_{f_j \leq f_0} \frac{f_j}{1-f_0} x_j + \sum_{f_j > f_0} \frac{1-f_j}{1-f_0} x_j - \sum_{j=1}^p \frac{g_j}{1-f_0} y_j \geq 1. \tag{4}$$

- This is of the form  $\sum_j a_j^1 x_j \geq 1$  or  $\sum_j a_j^2 x_j \geq 1$ , which implies  $\sum_j \max\{a_j^1, a_j^2\} x_j \geq 1$  for any  $x \geq 0$ .

- For each variable, what is the max coefficient in (3) and (4)?
- We get

$$\sum_{f_j \leq f_0} \frac{f_j}{f_0} x_j + \sum_{f_j > f_0} \frac{1-f_j}{1-f_0} x_j + \sum_{g_j > 0} \frac{g_j}{f_0} y_j - \sum_{g_j < 0} \frac{g_j}{1-f_0} y_j \geq 1.$$

- This is the *Gomory mixed integer (GMI) inequality*.
- In the pure integer programming case, the GMI inequality reduces to

$$\sum_{f_j \leq f_0} \frac{f_j}{f_0} x_j + \sum_{f_j > f_0} \frac{1-f_j}{1-f_0} x_j \geq 1.$$

- Since  $\frac{1-f_j}{1-f_0} < \frac{f_j}{f_0}$  when  $f_j > f_0$ , the GMI inequality dominates

$$\sum_{j=1}^n f_j x_j \geq f_0,$$

which is known as the *fractional cut*.

- Consider now  $S = \{(x, y) \in \mathbb{Z}_+^n \times \mathbb{R}_+^p : Ax + Gy \leq b\}$ .
- Let  $P = \{(x, y) \in \mathbb{R}_+^n \times \mathbb{R}_+^p : Ax + Gy \leq b\}$  be the underlying polyhedron.
- Let  $\alpha x + \gamma y \leq \beta$  be any valid for  $P$ .
- Add a nonnegative slack variable  $s$ , use  $\alpha x + \gamma y + s = \beta$  to derive a GMI inequality, and eliminate  $s = \beta - \alpha x - \gamma y$  from it.
- The result is a valid inequality for  $S$ .
- These inequalities are called the GMI inequalities for  $S$ .
- In contrast to lift-and-project cuts, it is in general NP-hard to find a GMI inequality that cuts off a point  $(\bar{x}, \bar{y}) \in P \setminus S$ , or show that none exists.
- However, one can easily find a GMI inequality that cuts off a basic feasible solution.
- On 41 MIPLIB instances, adding the GMI cuts generated from the optimal simplex tableaux reduces the integrality gap by 24% on average [Bonami et al. 2008]
- GMI cuts are widely used in commercial codes today.
- Numerical issues need to be addressed, however.

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