# MIT, 2.098J/6.255J/15.093J <br> Optimization Methods, Fall 2009 <br> Problem Set \#8 

Due: Lec \#23 (not to be turned in).

1. BT Exercise 9.5.
2. BT Exercise 9.11.
3. (a) Program in MATLAB three functions that implement (i) the Steepest Descent Algorithm, (ii) the Conjugate Gradient Algorithm, and (iii) Newton's method to solve min $\mathrm{f}(\mathrm{x})$. The functions should be given as parameters.
Hints: You can use a subroutine function for the line search component. Although we recommend MATLAB for this part of the homework, you may also use any programming language you prefer.
(b) For $\mathrm{i}=1,2$ we let,

$$
\begin{gathered}
f_{i}(x)=1 / 2 x^{\prime} Q_{i} x+c_{i}^{\prime} x+10 \\
g_{i}(x, \theta)=1 / 2 x^{\prime} Q_{i} x+c_{i}^{\prime} x+10-\theta\left(e^{\prime} \log (x)+\log \left(1-e^{\prime} x\right)\right),
\end{gathered}
$$

where $e$ is the vector of ones, and $\log (\mathrm{x})$ is a vector with the operator $\log$ applied to each component. Implement and run the three algorithms we learnt in class (steepest descent, Newton's method and conjugate gradient method) in MATLAB to solve the following four problems: $\min f_{1}(x), \min f_{2}(x), \min g_{1}(x, \theta)$ and $\min g_{2}(x, \theta)$ using

$$
Q_{1}=\left[\begin{array}{cc}
1 & -5 \\
-5 & 100
\end{array}\right] ; c_{1}=\left[\begin{array}{c}
-15 \\
150
\end{array}\right]
$$

and starting from $x_{0}=(0.2,0.2)^{\prime}$.

$$
Q_{2}=\left[\begin{array}{ccc}
8.5 & -1.5 & 3 \\
-1.5 & 8.5 & 3 \\
3 & 3 & 4
\end{array}\right] ; c_{2}=\left[\begin{array}{c}
-10 \\
-10 \\
-10
\end{array}\right]
$$

and starting from $x_{0}=(0.3,0.4,0.1)^{\prime}$ and $\theta=1$.
(c) For each of the three algorithms, plot $f\left(x_{k}\right)$ vs. $k$ and $\frac{f\left(x_{k+1}\right)-f\left(x^{*}\right)}{f\left(x_{k}\right)-f\left(x^{*}\right)}$ vs $k$, where $x^{*}$ is the optimal solution.
(d) Using the answer to (c), discuss the rate of convergence for each of the three algorithms and compare it with the one predicted from theory.
(e) Illustrate numerically what happens to the solution of the problem min $g_{2}(x, \theta)$ as $\theta$ varies in the interval $[0.01,10]$.
4. Consider the following problem:

$$
\begin{array}{ll}
\min & f(x)=-x_{1} \\
\mathrm{s.t.} & x_{1}^{2}+x_{2}^{2} \leq 1 \\
& \left(x_{1}-1\right)^{3}-x_{2} \leq 0
\end{array}
$$

- Show that the KKT constraint qualification holds at point $\bar{x}=(1,0)$.
- Show that point $\bar{x}=(1,0)$ is a KKT point and also a global optimal solution.

5. (a) Use the KKT conditions to solve the following problem

$$
\begin{array}{ll}
\min & f(x)=x^{\prime} Q x+c^{\prime} x \\
\mathrm{s.t.} & g(x)=x^{\prime} R x \leq 1 \\
& e^{\prime} x=1
\end{array}
$$

where $Q$ is an invertible matrix, although not necessarily positive definite and $R$ is a positive definite matrix. Note that $e$ is a vector of ones.
(b) Apply your solution to the case where

$$
Q_{2}=\left[\begin{array}{ccc}
1 & 0 & -2 \\
0 & 1 & 0 \\
-2 & 0 & 1
\end{array}\right] ; c_{2}=\left[\begin{array}{c}
-1 \\
-1 \\
-1
\end{array}\right] ; R=\left[\begin{array}{ccc}
1 & -0.5 & -0.4 \\
-0.5 & 1 & 0 \\
-0.4 & 0 & 1
\end{array}\right]
$$

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