

# Lab 9: SLAM

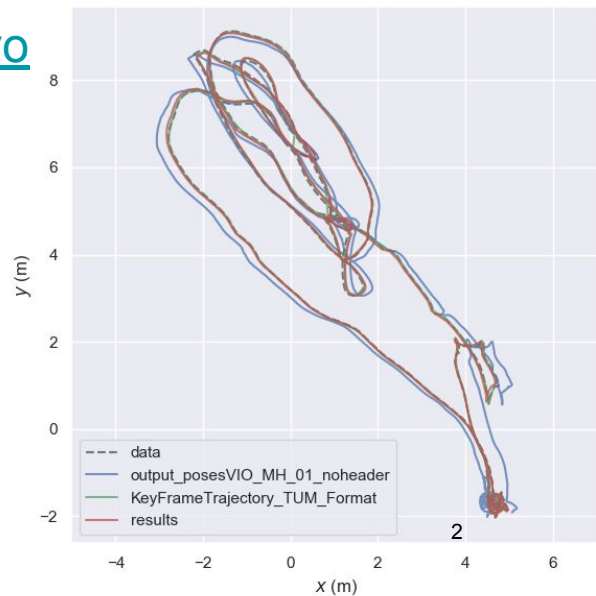
VNAV 2020

ORB-SLAM: [https://github.com/raulmur/ORB\\_SLAM2](https://github.com/raulmur/ORB_SLAM2)

Kimera: <https://github.com/MIT-SPARK/Kimera-VIO>

(optionally) LDSO: <https://github.com/tum-vision/LDSO>

EVO for evaluation: <https://github.com/MichaelGrupp/evo>



## Exercises

<https://mit-spark.github.io/VNAV2020-handouts/lab9/exercises>

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16.485 Visual Navigation for Autonomous Vehicles (VNAV)  
Fall 2020

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