



Space Systems Architecture

Lecture 3

Introduction to

Tradespace Exploration

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Space Systems, Policy, and Architecture Research Consortium
A joint venture of MIT, Stanford, Caltech & the Naval War College
for the NRO

A process for understanding complex solutions to complex problems

- Model-based high-level assessment of system capability
- Ideally, *many* architectures assessed
- Avoids optimized *point solutions* that will not support evolution in environment or user needs
- Provides a basis to explore technical and policy *uncertainties*
- Provides a way to assess the value of *potential* capabilities

Allows informed “upfront” decisions and planning



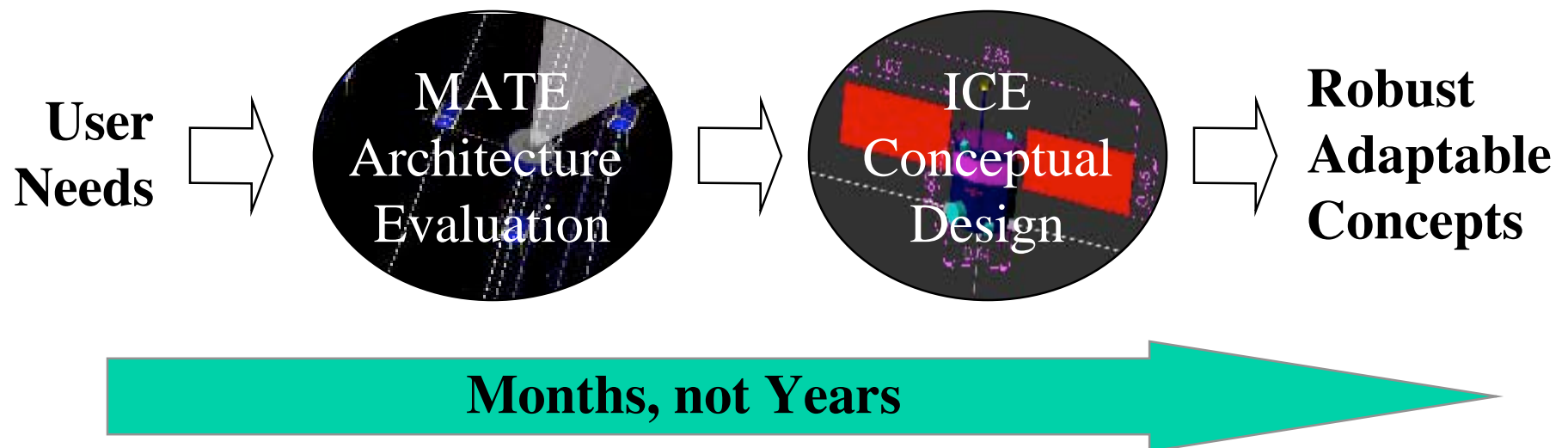
Integrated Concurrent Engineering

A process creating preliminary designs very fast

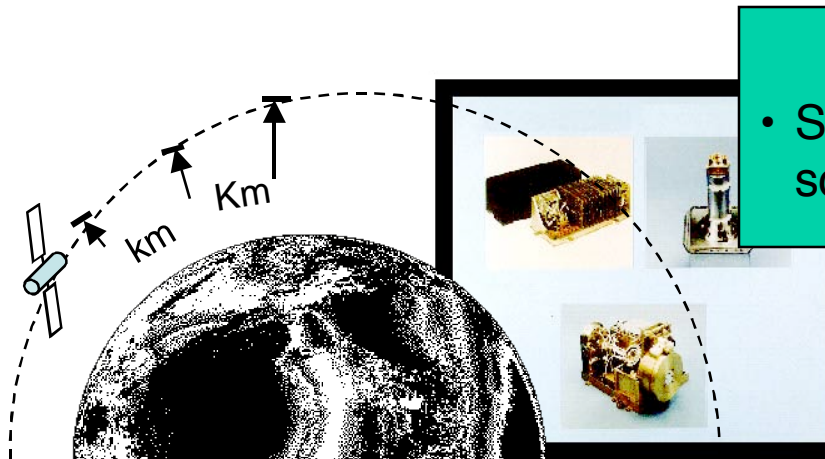
- State-of-the-art rapid preliminary design method
- Design tools linked both electronically and by co-located humans
- Design sessions iterate/converge designs in hours
- Requires ready tools, well poised requirements

Allows rapid reality check on chosen architectures
Aids transition to detailed design

- Linked method for progressing from vague user needs to conceptual/preliminary design very quickly
- MANY architectures, several/many designs considered
- Understanding the trades allows selection of robust and adaptable concepts, consideration of policy, risk.



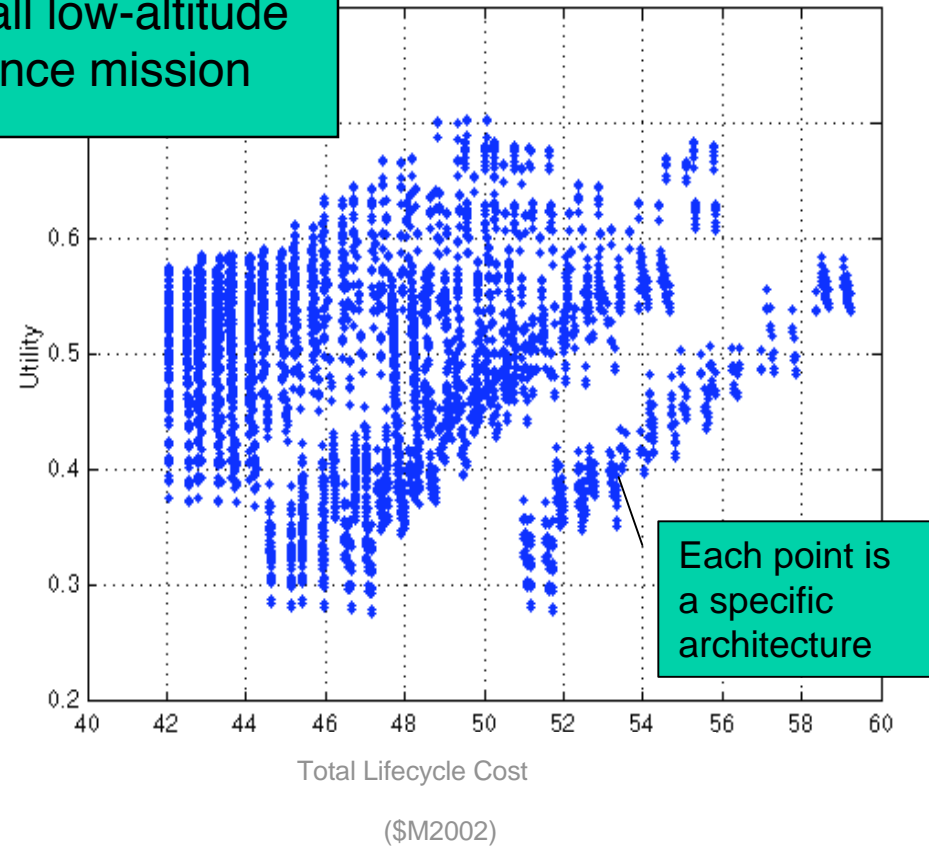
What is an Architecture Trade Space?



X-TOS

- Small low-altitude science mission

Sat Case; New Utilities; 9930 archs

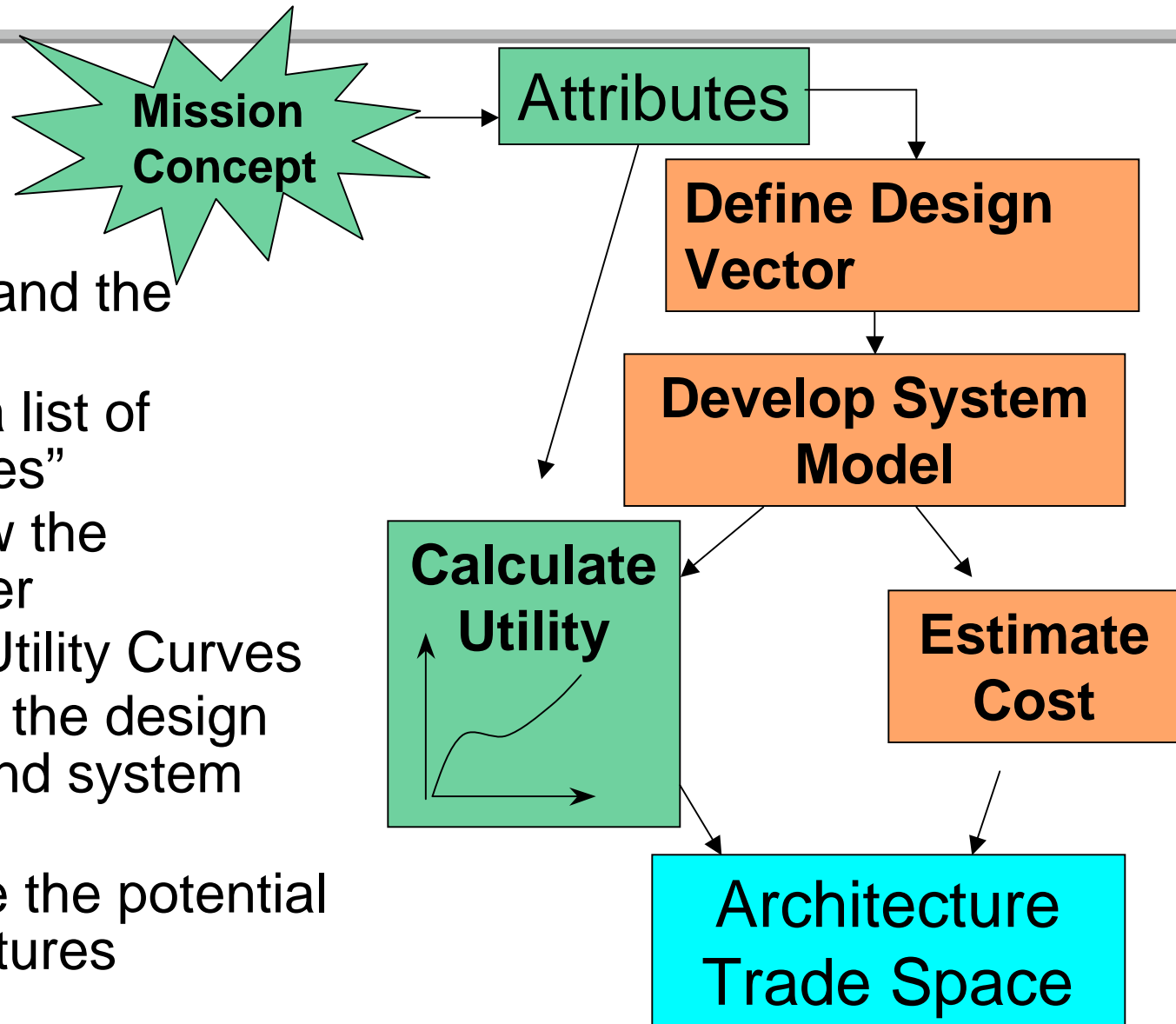


DESIGN VARIABLES: The architectural trade parameters

- **Orbital Parameters**
 - Apogee altitude (km) 150-1100
 - Perigee altitude (km) 150-1100
 - Orbit inclination 0, 30, 60, 90
- **Physical Spacecraft Parameters**
 - Antenna gain
 - communication architecture
 - propulsion type
 - power type
 - delta_v

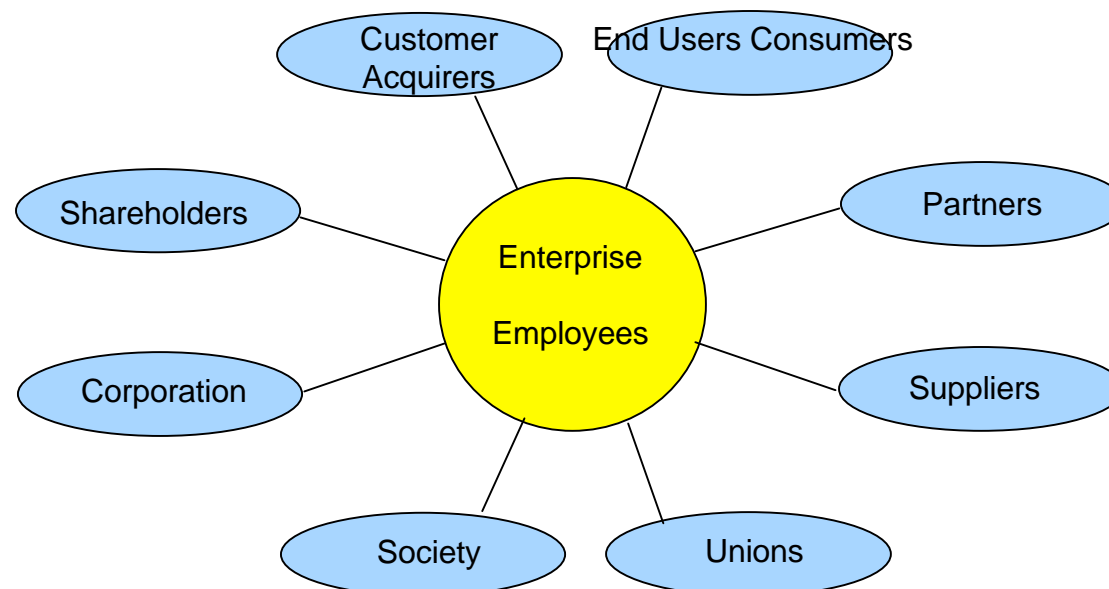
Assessment of the utility and cost of a large space of possible system architectures

Developing A Trade Space

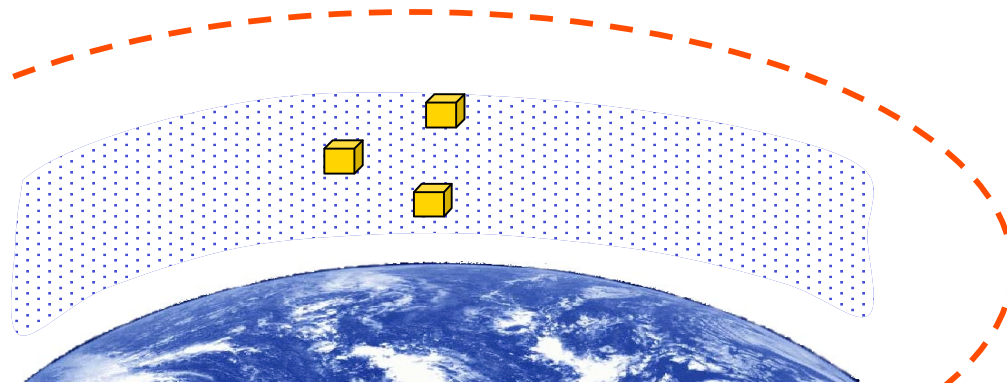


- Understand the Mission
- Create a list of “Attributes”
- Interview the Customer
- Create Utility Curves
- Develop the design vector and system model
- Evaluate the potential Architectures

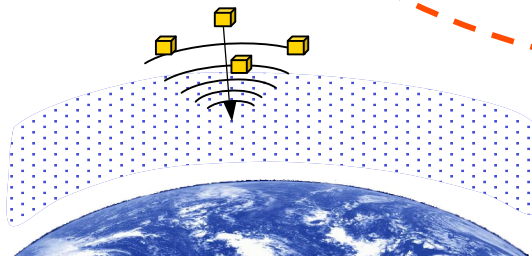
- Many interested parties in a complex system
- Each “customer” has a set of needs
- They are different, and can be contradictory



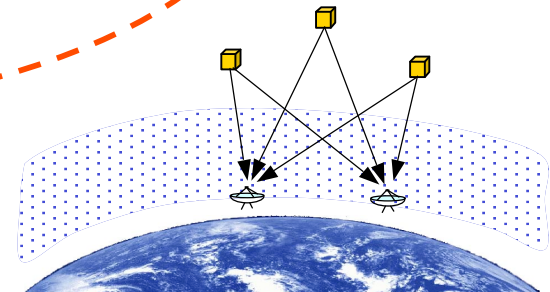
**ATOS:
Multi-vehicle
Ionosphere
Explorer**



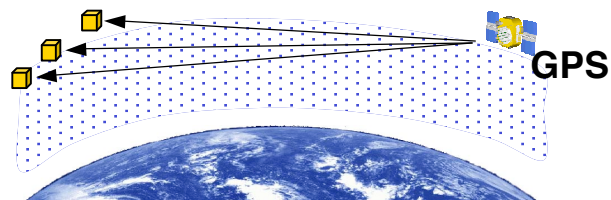
In Situ



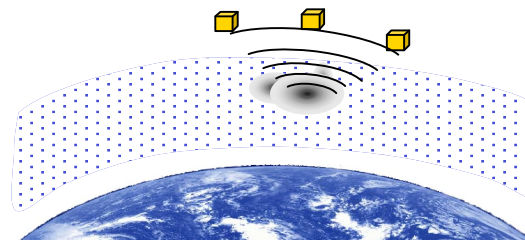
Topside Sounding



Direct Scintillation Sensing

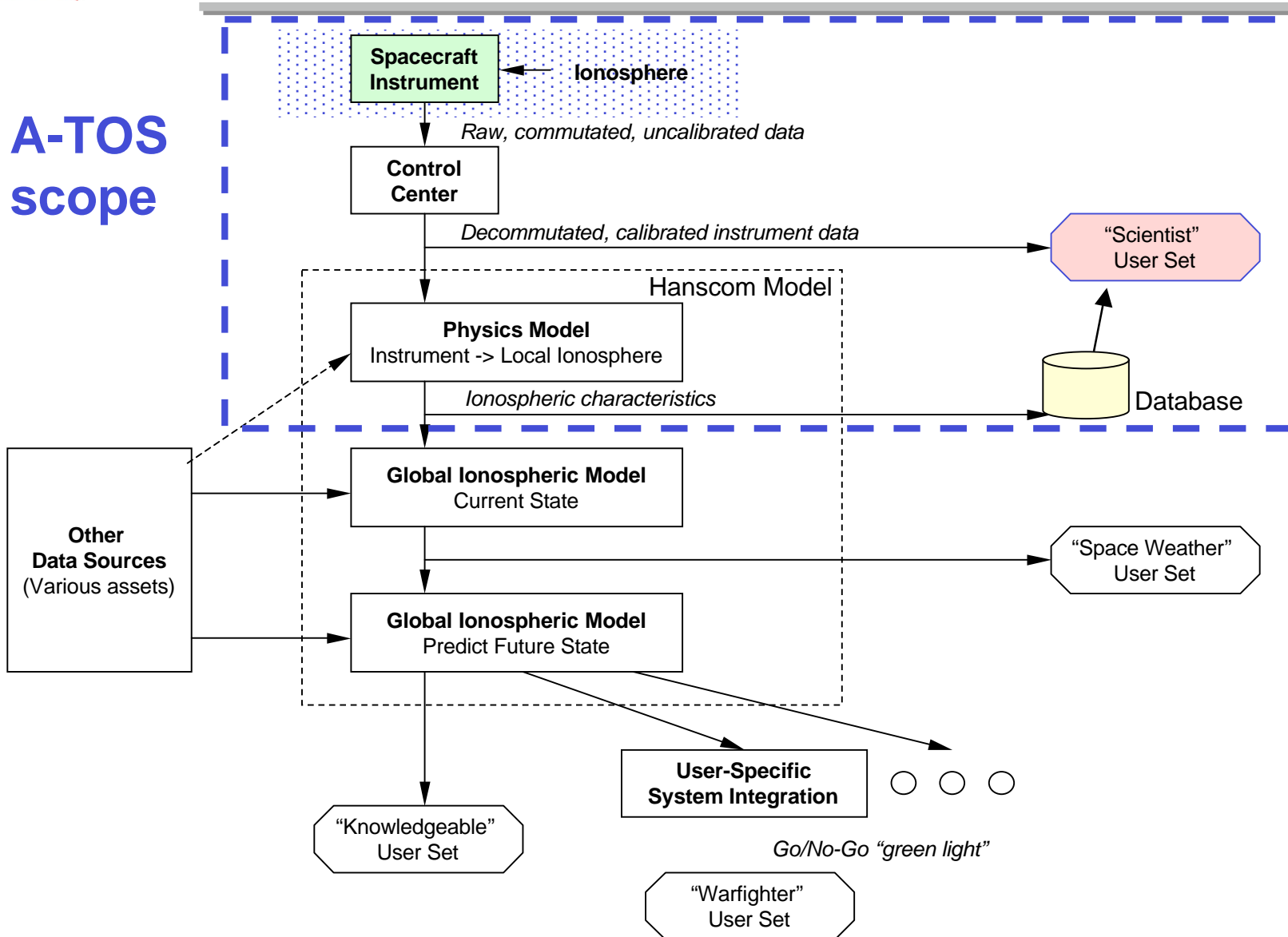


GPS Occultation

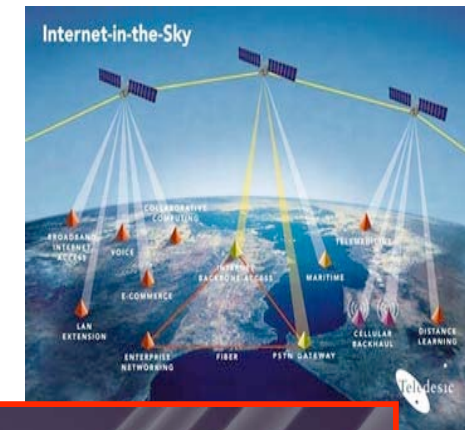


UV Sensing

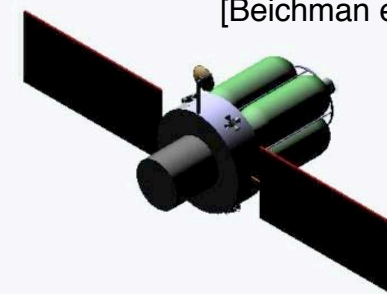
A-TOS scope


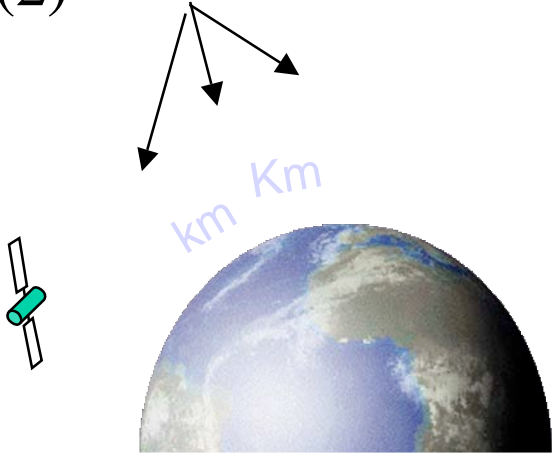
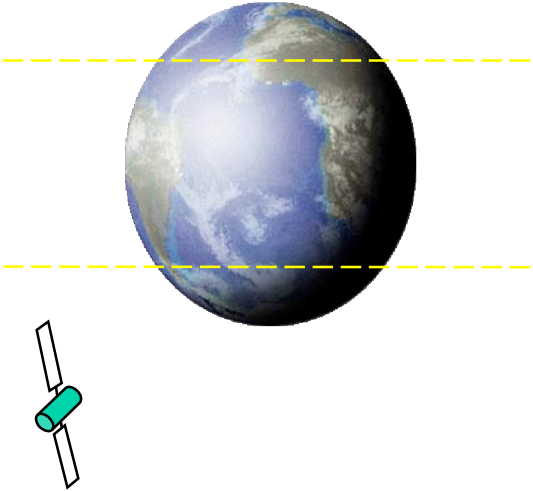
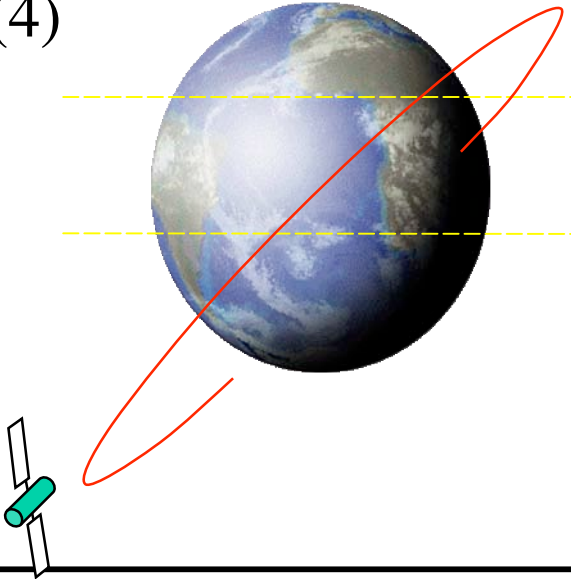
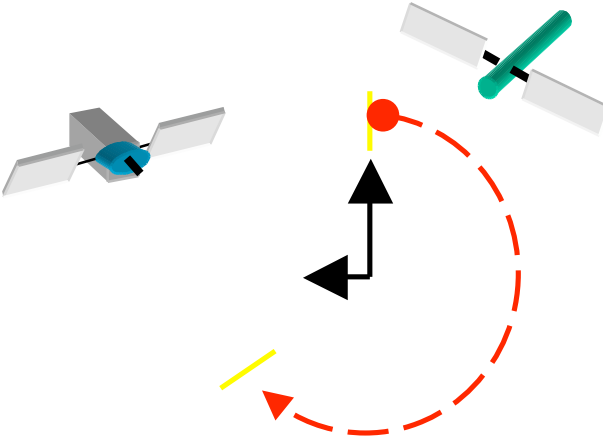


- “what the decision makers need to consider”
- (and/or what the user truly cares about)
- Examples: Billable minutes = GINA metrics
- TPF Pictures = camera performance metrics
- Rescue/move satellites = mass moving, grappling capability, timeliness
 - Could have sub-cartoons for above

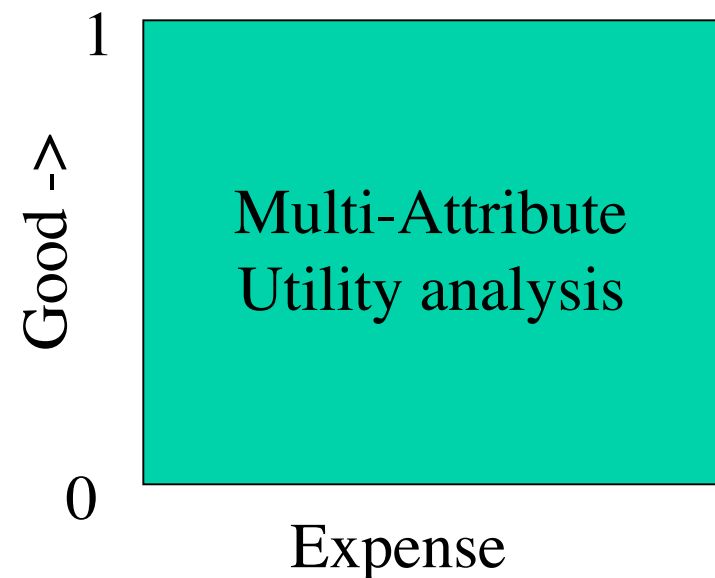
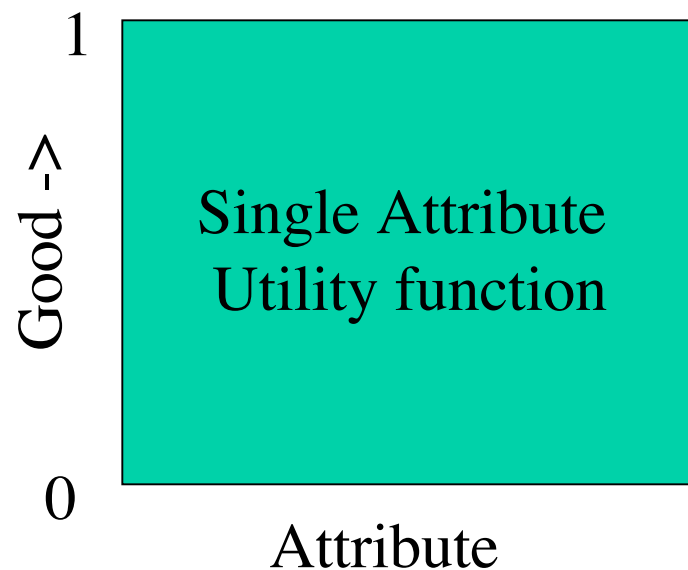


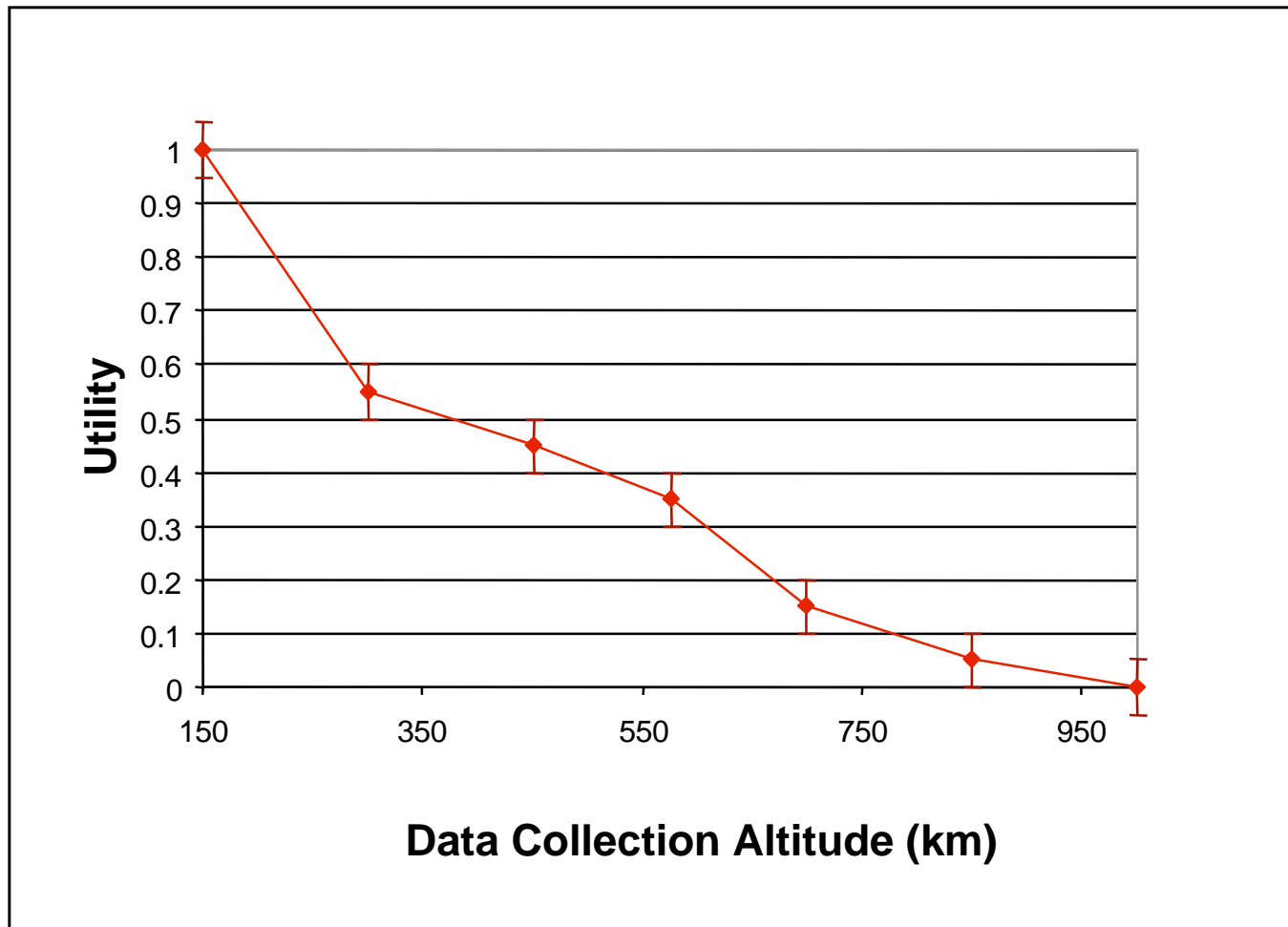
[Beichman et al, 1999]

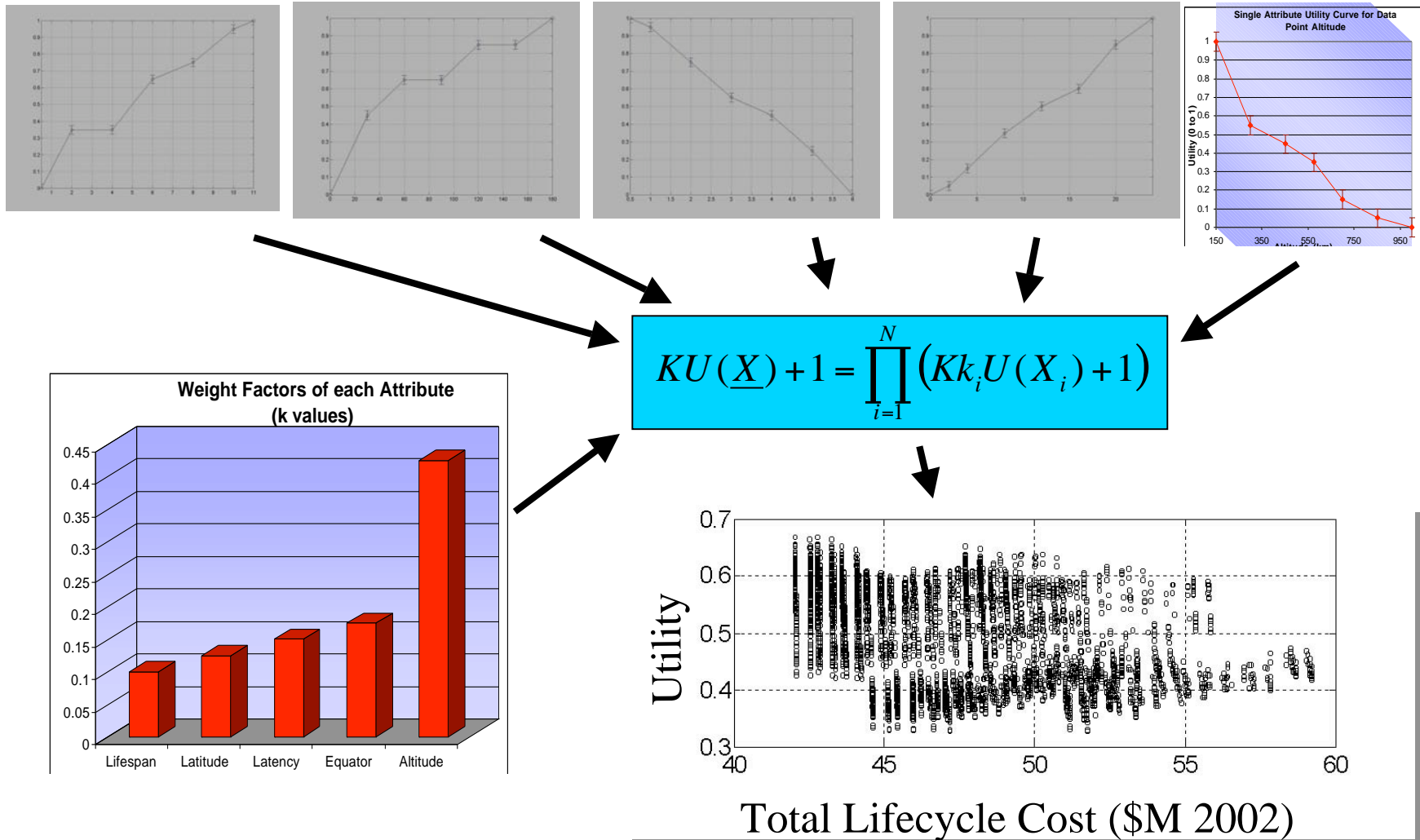


<p>1) Data Life Span 2) Data Altitude 3) Maximum Latitude 4) Time Spent at Equator 5) Data Latency</p>	<p>(1)</p> 	<p>(2)</p> 
<p>(3)</p> 	<p>(4)</p> 	<p>(5)</p> 

- “What the attributes are WORTH to the decision makers”
- Single Attribute utility maps attribute to utility
- Multi-attribute utility maps an architecture (as expressed by its attributes) to utility







- “Parameters of the Trade Space”

Variable:	First Order Effect:
Orbital Parameters:	
•Apogee altitude (200 to 2000 km)	Lifetime, Altitude
•Perigee altitude (150 to 350 km)	Lifetime, Altitude
•Orbit inclination (0 to 90 degrees)	Lifetime, Altitude
	Latitude Range
	Time at Equator
Physical Spacecraft Parameters:	
•Antenna gain (low/high)	Latency
•Comm Architecture (TDRSS/AFSCN)	Latency
•Propulsion type (Hall / Chemical)	Lifetime
•Power type (fuel / solar)	Lifetime
•Total ΔV capability (200 to 1000 m/s)	Lifetime

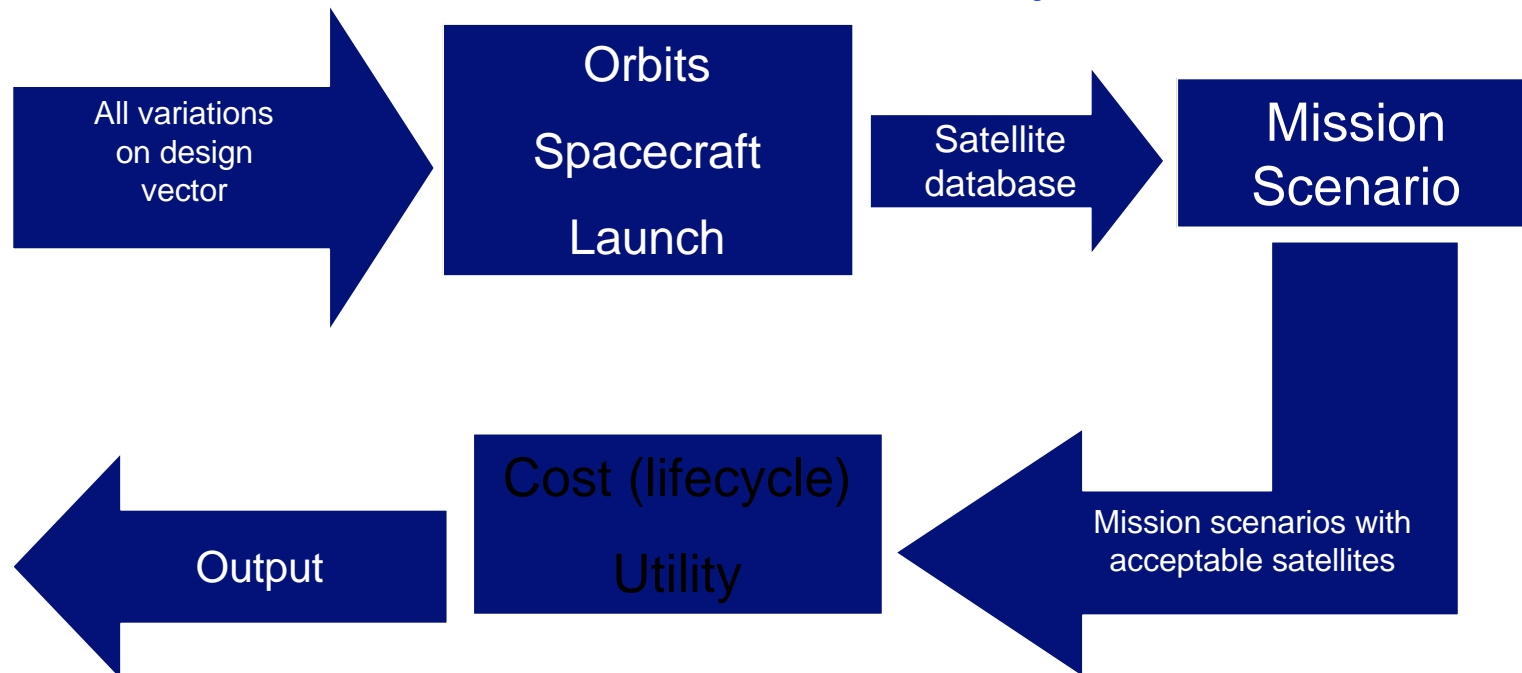
	Design Vars	Perigee	Apogee	Delta-V	Propulsion	Inclination	Comm System	Ant. Gain	Power system	Mission Scenario	Total Impact
Attributes											
Data Lifespan		9	9	9	6	0	0	0	6	9	48
Sample Altitude		9	9	0	0	0	0	0	0	9	27
Diversity of Latitudes		0	0	0	0	9	0	0	0	9	18
Time at Equator		0	6	0	0	9	0	0	0	9	24
Latency		3	3	0	0	3	9	9	6	3	36
Total		21	27	9	6	21	9	9	12	39	
Cost		9	9	3	6	6	3	6	6	9	
Total w/Cost		30	36	12	12	27	12	15	18	48	

Identify key interactions for modeling

Sums identify attributes and Design Variables that are likely to be (or not be) distinguishers

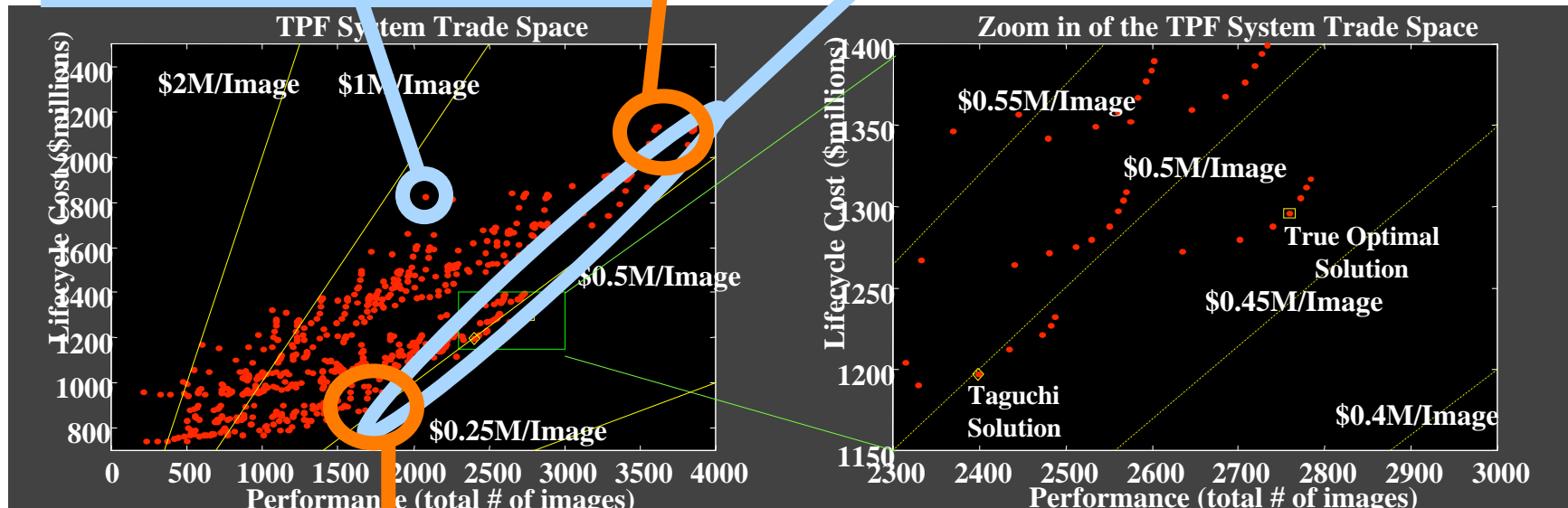
Mapping Design Vector to Attributes and Utilities - Simulation Models

XTOS Simulation Software Flow Chart



Each point is an evaluated architecture

Many good architectures at c. \$0.5M/Image

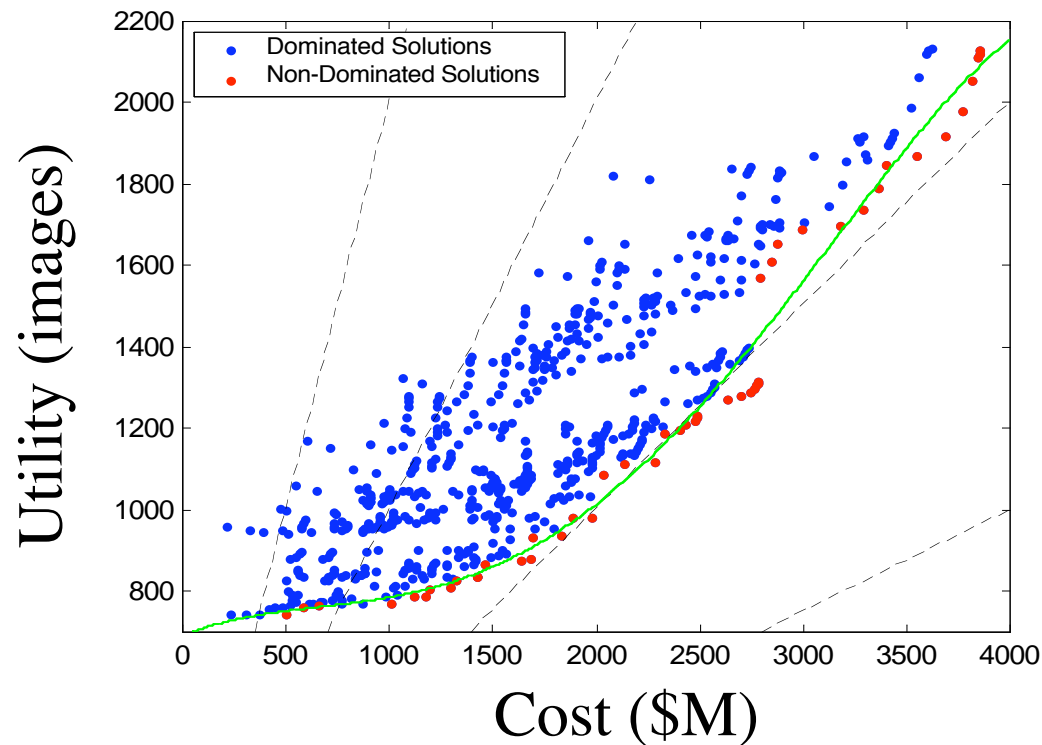


Cadillac

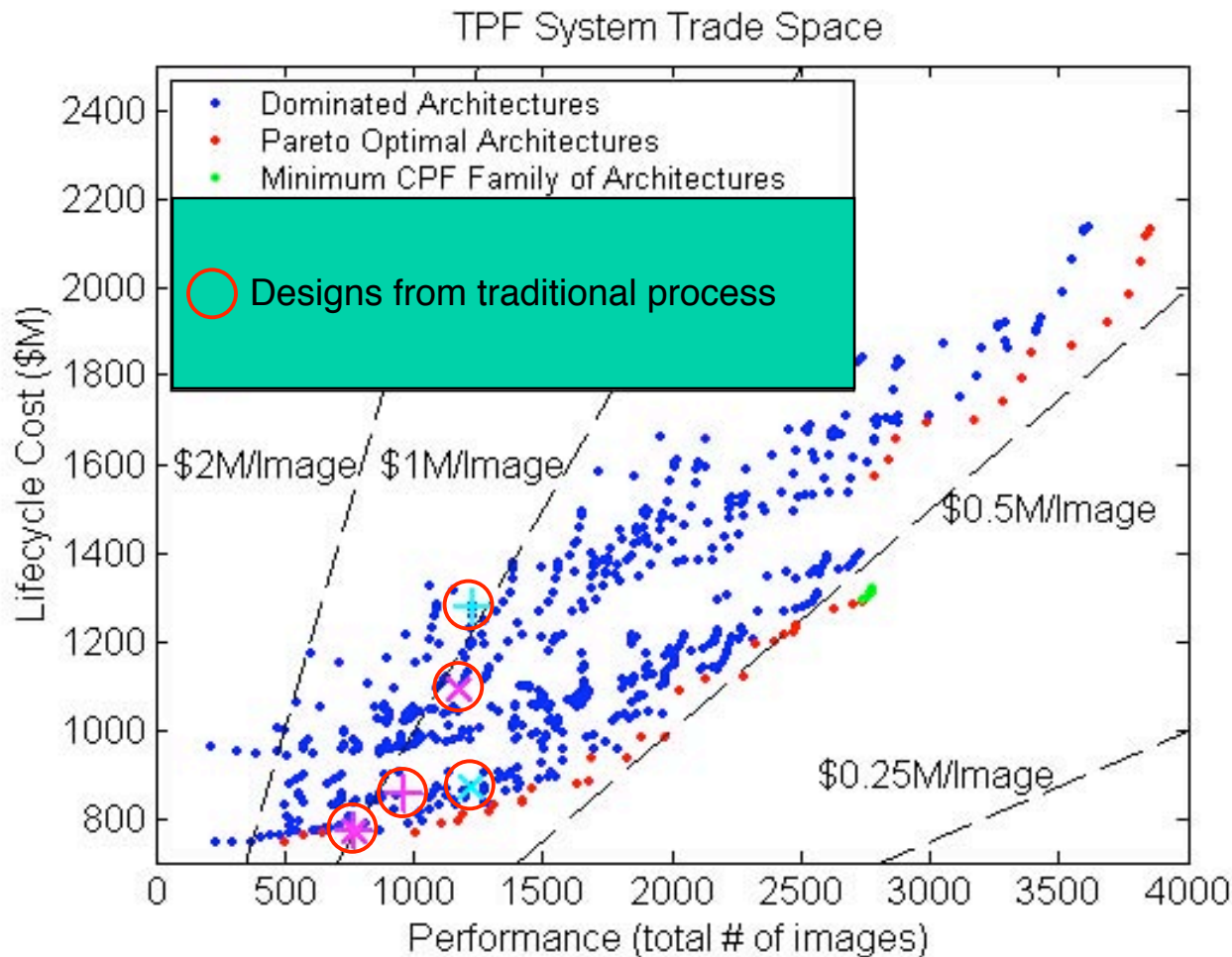
Chevy

TPF: a science imaging system

- Set of “best” solutions
- “Dominated” solutions are more expensive or less capable



Using the Trade Space to Evaluate Point Designs



From Jilla, 2002

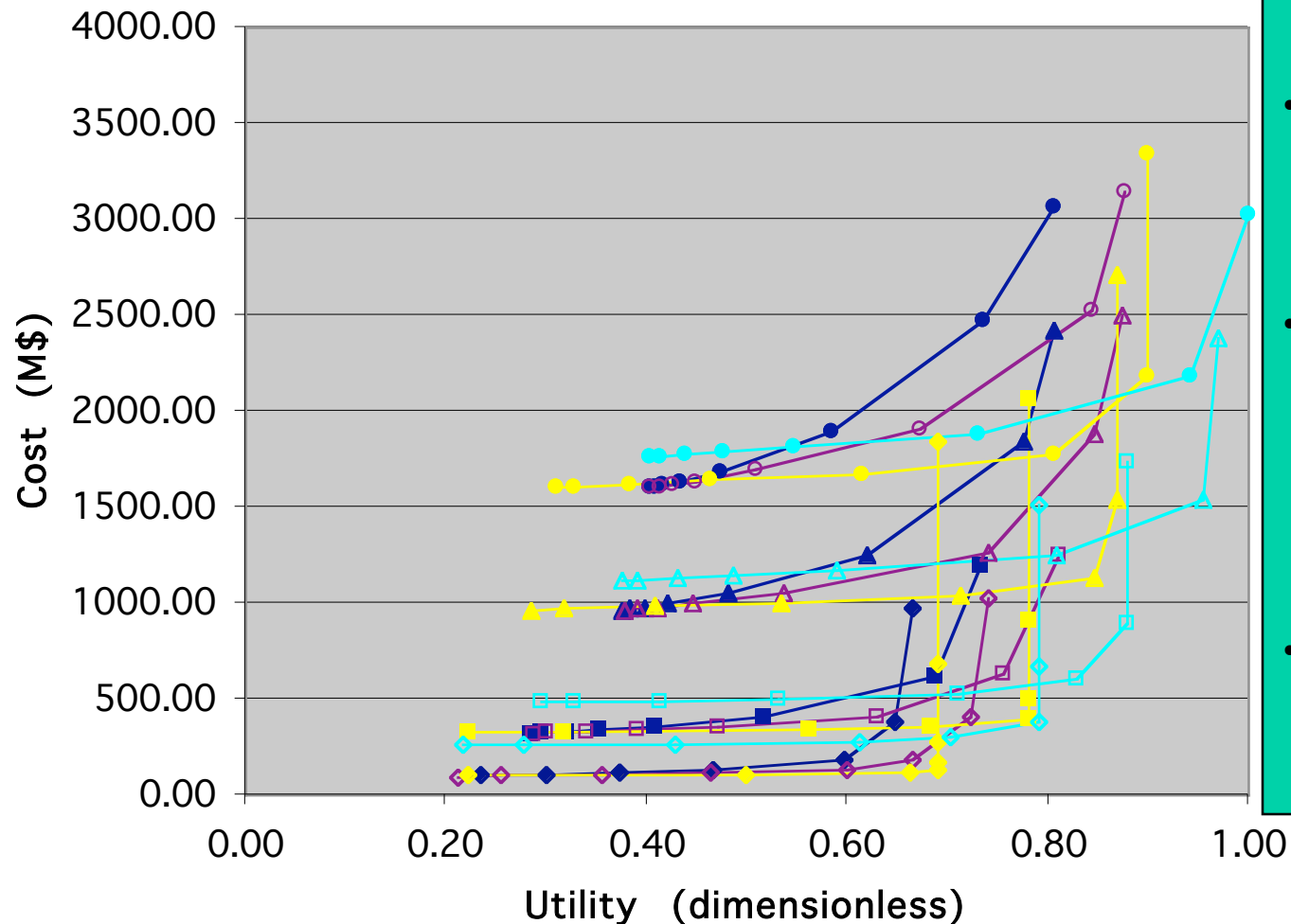
TPF

- Terrestrial Planet Finder - a large astronomy system
- Design space: Apertures separated or connected, 2-D/3-D, sizes, orbits
- Images vs. cost



[Beichman et al, 1999]

Understanding Limiting Physical or Mission constraints



SPACETUG

- General purpose orbit transfer vehicles
- Different propulsion systems and grappling/observation capabilities
- Lines show increasing fuel mass fraction

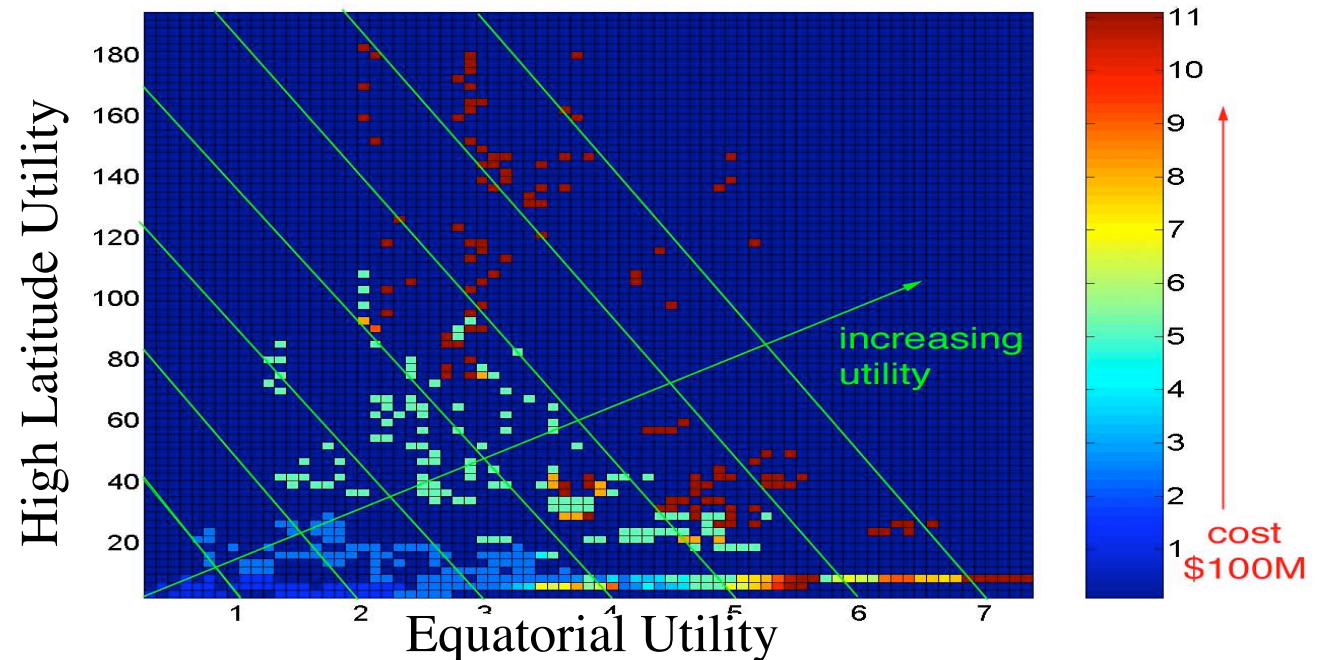
Hits a “wall” of either physics (can’t change!) or utility (can)

- Best low-cost mission do only one job well
- More expensive, higher performance missions require more vehicles
- Higher-cost systems can do multiple missions
- Is the multiple mission idea a good one?

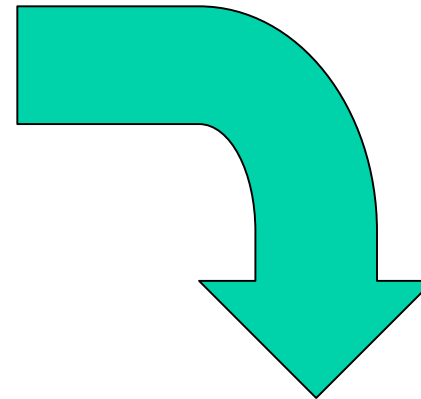
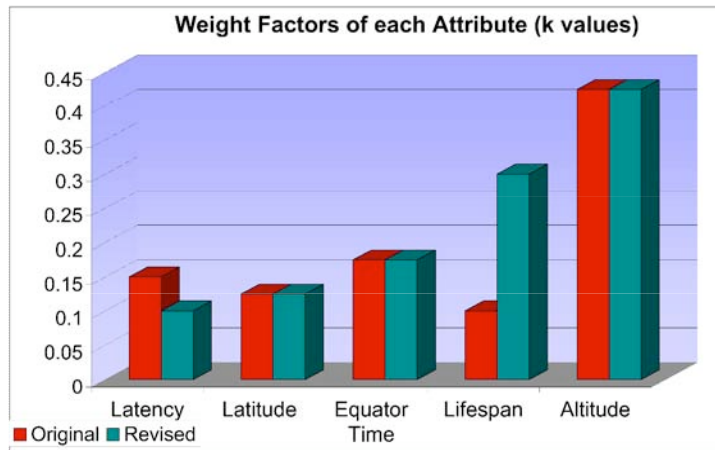
A-TOS

- Swarm of very simple satellites taking ionospheric measurements
- Several different missions

Color scale: Life Cycle Cost, 1380 data points, grid: 75x75, density: 0.08



Changes in User Preferences Can be Quickly Understood

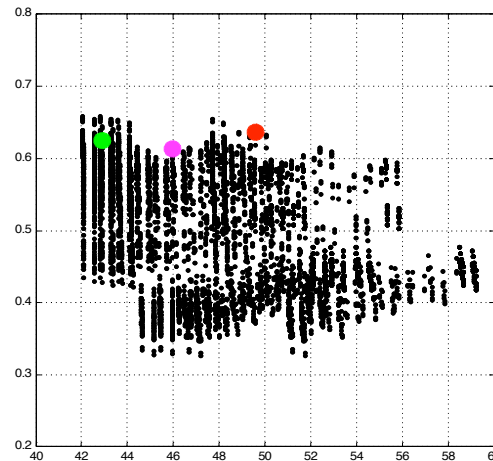


Architecture trade space reevaluated in less than one hour

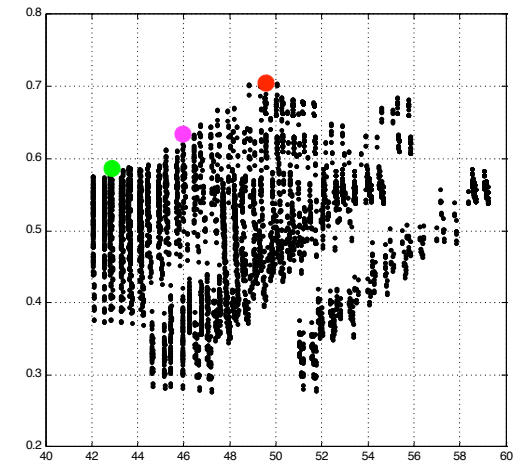
User changed preference weighting for lifespan

X-TOS

Original



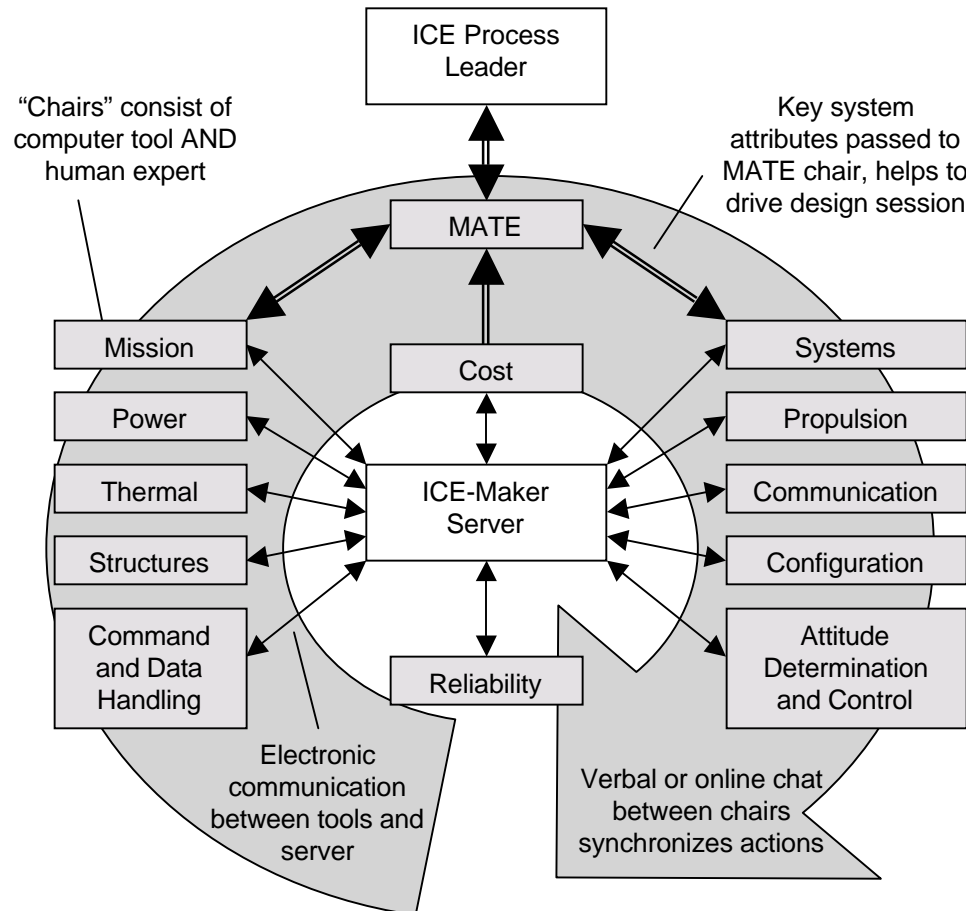
Revised





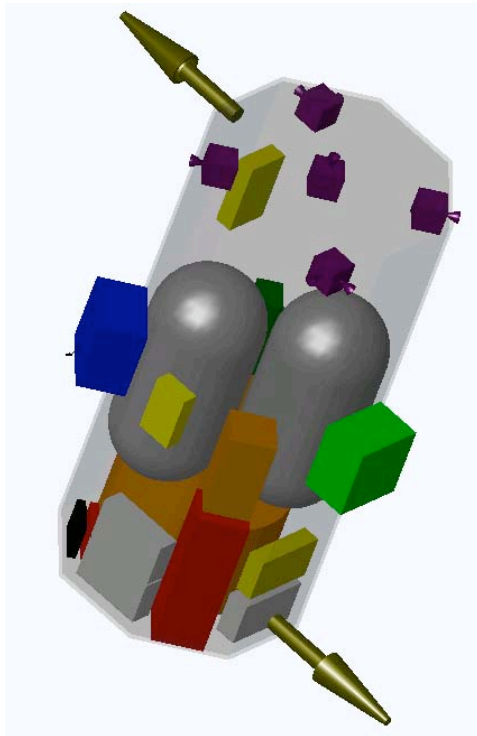
Integrated Concurrent Engineering (ICE)

- ICE techniques from Caltech and JPL
- Linked analytical tools with human experts in the loop
- Very rapid design iterations
- Result is conceptual design at more detailed level than seen in architecture studies
- Allows understanding and exploration of design alternatives
- A reality check on the architecture studies - can the vehicles called for be built, on budget, with available technologies?



- Directed Design Sessions allow very fast production of preliminary designs
- Traditionally, design to requirements
- Integration with MATE allows *utility* of designs to be assessed real time

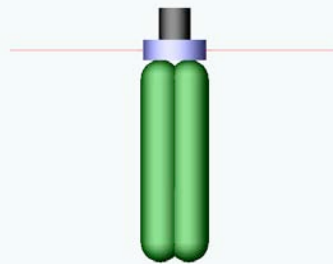
ICE Result - XTOS Vehicle



- Early Designs had excessively large fuel tanks and bizarre shapes
- Showed limits of coarse modeling done in architecture studies
- Vehicle optimized for best utility - maximum life at the lowest practical altitude

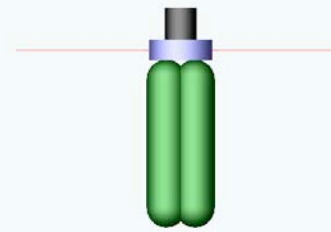
SPACETUG Tug Family *(designed in a day)*

Bipropellant



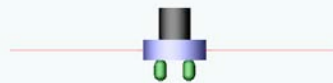
Wet Mass: 11689 kg

Cryogenic



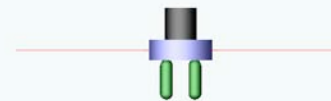
Wet Mass: 6238 kg

Electric – One way

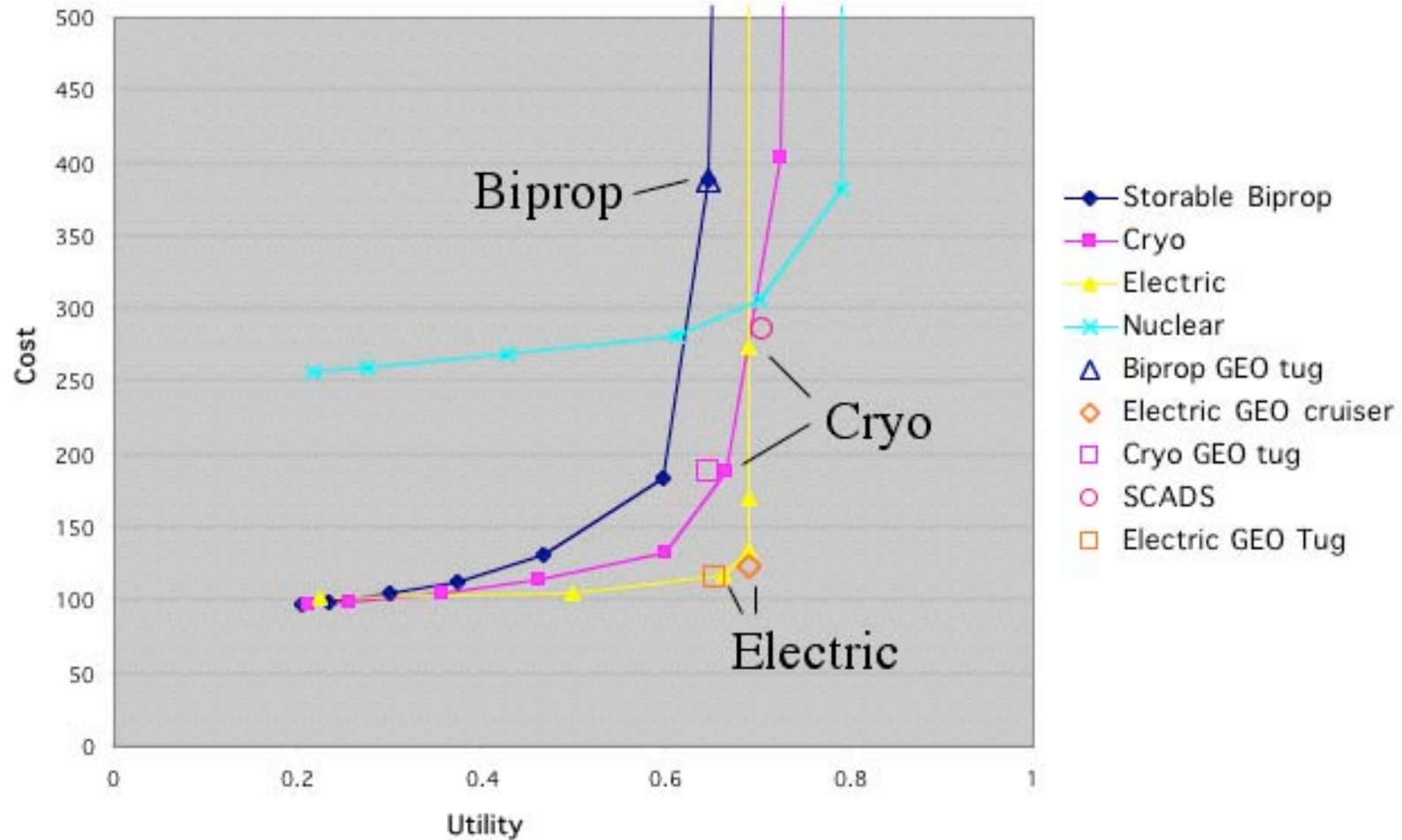


Wet Mass: 997 kg

Electric – Return Trip



Wet Mass: 1112 kg



The GEO mission is near the “wall” for conventional propulsion

- Trade space evaluation allows efficient quantitative assessment of system architectures given user needs
- State-of-the-art conceptual design processes refine selected architectures to vehicle preliminary designs
- Goal is the right system, with major issues understood (and major problems ironed out) entering detailed design

Emerging capability to get from user needs to robust solutions quickly, *while considering full range of options, and maintaining engineering excellence*