

SPRING 2025 - 18.100B/18.1002

TOBIAS HOLCK COLDING

Lecture 22

Suppose that a_n is a sequence and

$$\sum_{n=0}^{\infty} a_n x^n ,$$

is a power series, the radius of convergence R is

$$R = \frac{1}{M} \text{ where } M = \limsup |a_n|^{\frac{1}{n}} .$$

Lemma: The radius of convergence is the same for the power series

$$\sum_{n=0}^{\infty} a_n x^n$$

as the power series

$$\sum_{n=1}^{\infty} n a_n x^{n-1} .$$

.

Proof. Since

$$n^{\frac{1}{n-1}} = e^{\frac{\log n}{n-1}} \rightarrow 1 ,$$

and

$$\limsup_{n \rightarrow \infty} |a_n|^{\frac{1}{n}} = \limsup_{n \rightarrow \infty} |a_n|^{\frac{1}{n-1}}$$

we have that

$$\limsup_{n \rightarrow \infty} |n a_n|^{\frac{1}{n-1}} = \limsup_{n \rightarrow \infty} |a_n|^{\frac{1}{n}} .$$

From this the claim follows. □

Iterating this gives:

Corollary: The power series

$$\sum_{n=0}^{\infty} a_n x^n$$

has the same radius of convergence as the power series

$$\sum_{n=k}^{\infty} \frac{n!}{(n-k)!} a_n x^{n-k}.$$

We now get the following:

Theorem: Suppose that

$$f(x) = \sum_{n=0}^{\infty} a_n x^n,$$

is a power series with radius of convergence R , then

$$f^{(k)}(x) = \sum_{n=k}^{\infty} \frac{n!}{(n-k)!} a_n x^{n-k}$$

and

$$\int f(x) dx = \sum_{n=1}^{\infty} \frac{a_{n-1}}{n} x^n.$$

Proof. Let us first argue for $k = 1$. We will see that this is a consequence of Theorem 3 from Lecture 21. Set

$$f_n(x) = \sum_{k=0}^n a_k x^k$$

and

$$f(x) = \sum_{k=0}^{\infty} a_k x^k.$$

Moreover, let R be the radius of convergence for the power series f . We have the following three properties

(1)

$$f_n(0) = a_0 = f(0).$$

(2) On each interval $[-L, L]$, where $L < R$, we have uniform convergence

$$f'_n \rightarrow \sum_{k=1}^{\infty} k a_k x^{k-1}.$$

(3) Each f'_n is continuous.

We see that Theorem 3 applies and show that

$$f' = \sum_{k=1}^{\infty} k a_k x^{k-1}.$$

Iterating this gives the claim for all k . Finally, the claim about the integral

$$\int f(x) dx$$

follows easily from Theorem 2 from Lecture 21. □

Ordinary differential equations: A differential equation is an equation that involves an unknown function and its derivative.

Example: Here are some examples of differential equations

$$\begin{aligned} f'(x) &= x. \\ f'(x) - f^2(x) &= 0. \\ f(x) f'(x) f''(x) &= 1. \end{aligned}$$

For the first of these and each constant c , the function

$$f_c(x) = \frac{1}{2} x^2 + c$$

is a solution. For the second

$$f(x) = \frac{1}{1-x}$$

is a solution. For the third $y = 0$ is a solution and so is $y = x$.

We will be interested in an ordinary differential equation (ODE) of the form

$$y' = f(y) + g(x).$$

Here $y = y(x)$ is the unknown function and f, g are given functions. Note that while g only depend on x the function f also depend on the unknown function y .

We are interested in whether there exist solutions and when they exist if they are unique.

More precisely, suppose that we have the following:

- f be a continuously differentiable function on \mathbf{R} .
- g be a continuous function on \mathbf{R} .
- a is a real number.

We are interested in existence and uniqueness of the ODE:

$$\begin{cases} y'(x) &= f(y(x)) + g(x) \\ y(0) &= a . \end{cases}$$

We will show next time the following:

Picard-Lindelöf theorem: There exists $\delta > 0$ such that there is a unique solution to this ODE on $(-\delta, \delta)$.

REFERENCES

- [TBB] B.S. Thomson, J.B. Bruckner, and A.M. Bruckner, *Elementary Real Analysis, 2nd edition*
TBB can be downloaded at:
<https://classicalrealanalysis.info/com/documents/TBB-AllChapters-Landscape.pdf>
(screen-optimized)
<https://classicalrealanalysis.info/com/documents/TBB-AllChapters-Portrait.pdf>
(print-optimized)

MIT, DEPT. OF MATH., 77 MASSACHUSETTS AVENUE, CAMBRIDGE, MA 02139-4307.

MIT OpenCourseWare
<https://ocw.mit.edu>

18.100B Real Analysis
Spring 2025

For information about citing these materials or our Terms of Use, visit: <https://ocw.mit.edu/terms>.