## Unbiased Estimation and Risk Inequalities

### MIT 18.655

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# Unbiased Estimation and Risk Inequalities Unbiased Estimation

• The Information Inequality

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## Unbiased Estimation

### Comments on Unbiased Estimation

- Estimation decision problem:
  - $X \sim P_{\theta}, \theta \in \Theta$
  - $\theta(P) = E[X \mid P_{\theta}]$
  - Estimation:  $\mathcal{A} = \times$
  - Loss function:  $L: \Theta \times A \to R$ .
  - Decision procedures:  $\mathcal{D} = \{ \delta : \mathcal{X} \to \mathcal{A} \}$
- Restrict estimation procedures to the subclass:

 $\mathcal{D}_0 = \{ \delta \in \mathcal{D} : E[\delta(X) \mid \theta] = \theta, \text{ for all } \theta \in \Theta \}.$ 

 Apply decision-theoretic principles to identify optimal procedures in  $\mathcal{D}_0$ .

Choice of  $\mathcal{D}_0$  equivalent to choice of constraints:

- Unbiasedness
- Linearity (in X)
- Computational algorithms (e.g., orthogonal polynomials in X, Fourier series. generalized-basis series) ★ 문 ▶ 문 MIT 18.655

## Unbiased Estimation

### Comments on Unbiased estimation (continued)

- Significant role of unbiasedness in survey sampling.
- Bayes estimates are necessarily biased (Problem 3.4.20).
- Unbiasedness not preserved under non-linear re-parametrization (not equivariant).
- Asymptotic unbiasedness:

$$rac{Bias^2(\hat{ heta}_n)}{Var[\hat{ heta}_n \mid heta]} o 0.$$

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## Outline

## Unbiased Estimation and Risk Inequalities Unbiased Estimation

• The Information Inequality

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## Information Inequality: Preliminaries

**Definition: Regular Problem** A statistical inference problem with  $X \sim P_{\theta}, \theta \in \Theta$  which satisfies the following regularity conditions:

• 
$$\mathcal{X} = \{x : p(x \mid \theta) > 0\}$$
 does not depend on  $\theta$ .  
•  $\frac{\partial logp(x \mid \theta)}{\partial \theta}$  exists and is finite for all  $x \in \mathcal{X}$  and  $\theta \in \Theta$ .  
• For any statistic  $T$  such that  $E[|T(X)| \mid \theta] < \infty$   
 $\frac{\partial}{\partial \theta} \left[ \int T(x)p(x \mid \theta)dx \right] = \int T(x)\frac{\partial}{\partial \theta}[p(x \mid \theta)]dx$ .

**Definition: Efficient Score Function**. For a fixed  $\theta_0 \in \Theta$ , the *efficient score* for X is  $u(X; \theta_0) = \frac{\partial \log p(x \mid \theta)}{\partial \theta}|_{\theta = \theta_0}$ Note: The second secon

Note: The magnitude of  $u(X; \theta_0)$  scales how far  $\theta_0$  is from  $\hat{\theta}_{MLE}$ .

**Proposition** The Efficient Score Function has the following properties:

$$E[u(X;\theta_0) \mid \theta = \theta_0] = 0.$$
  
Var[u(X;\theta\_0) \mid \theta = \theta\_0] = E([u(X;\theta\_0)]^2 \mid \theta = \theta\_0) = I(\theta\_0).

 $I(\theta)$  is the Fisher information about  $\theta$  contained in X which satisfies the following identity

$$I(\theta_0) = Var[(u(X; \theta_0) \mid \theta_0] = E\left[-\frac{\partial^2 \log p(X \mid \theta_0)}{\partial \theta^2} \mid \theta_0\right]$$

Proof:

$$\int p(x \mid \theta) dx = 1$$

$$\implies \int \frac{\partial p(x \mid \theta)}{\partial \theta} dx = \frac{\partial}{\partial \theta} (1) = 0$$

$$\implies \int [\frac{\partial p(x \mid \theta)}{\partial \theta} / p(x \mid \theta)] p(x \mid \theta) dx = 0$$

$$\implies \int [\frac{\partial \log[p(x \mid \theta)]}{\partial \theta} p(x \mid \theta) dx = 0$$

$$\implies E[u(X; \theta) \mid \theta] = 0$$

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$$E[u(X;\theta) \mid \theta] = 0$$

$$\iff \int \left[\frac{\partial \log[p(x\mid\theta)]}{\partial \theta}p(x\mid\theta)dx = 0$$

$$\frac{\partial}{\partial \theta}\left(\int \left[\frac{\partial \log[p(x\mid\theta)]}{\partial \theta}p(x\mid\theta)dx\right] = \frac{\partial}{\partial \theta}(0)\right]$$

$$\int \left(\frac{\partial^2 \log[p(x\mid\theta)]}{\partial \theta^2}p(x\mid\theta) + \frac{\partial \log[p(x\mid\theta)]}{\partial \theta}(\frac{\partial p(x\mid\theta)}{\partial \theta})\right)dx = 0$$
The last line can be written as:
$$\int \left[\frac{\partial^2 \log[p(x\mid\theta)]}{\partial \theta^2}p(x\mid\theta)dx\right] + \int \left[\frac{\partial \log[p(x\mid\theta)]}{\partial \theta}\right]^2p(x\mid\theta)dx = 0$$
I.e.,
$$E\left[\frac{\partial^2 \log[p(x\mid\theta)]}{\partial \theta^2}\mid\theta\right] + E\left[\left(\frac{\partial \log[p(x\mid\theta)]}{\partial \theta}\right)^2\mid\theta\right] = 0$$
So we have
$$I(\theta) = E[(u(X;\theta))^2\mid\theta] = -E\left[\frac{\partial^2 \log[p(x\mid\theta)]}{\partial \theta^2}\mid\theta\right].$$

$$= Var[u(X;\theta)\mid\theta]$$

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**Proposition 3.4.1** Suppose  $P_{\theta}$  is a one-parameter exponential family with density/pmf function:

 $p(x \mid \theta) = h(x) \exp\{\eta(\theta) T(x) - B(\theta)\}$ 

which has non-vanishing continuous derivative on  $\Theta$ . Then the statistical inference problem for  $\theta$  given X is a regular problem.

### Theorem 3.4.1. Information Inequality

For a regular problem, let T(X) be any statistic such that  $E[T(X) \mid \theta] = \psi(\theta).$  $Var[T(X) \mid \theta] < \infty$ , for all  $\theta$ .

Then for all  $\theta$ :

• 
$$Var[T(X) | \theta] \ge \frac{[\psi'(\theta)]^2}{I(\theta)}$$
,  
 $(\psi(\theta) \text{ is differentiable and } I(\theta) = \text{Fisher Information of } P_{\theta}$ .

**Proof:** By the conditions of a regular problem:

$$\psi'(\theta) = \frac{\partial}{\partial \theta} \left( \int T(x)p(x \mid \theta)dx \right)$$
  
=  $\int \left( T(x)\frac{\partial}{\partial \theta}[p(x \mid \theta)] \right) dx$   
=  $\int \left( T(x)\frac{\partial}{\partial \theta}[\log p(x \mid \theta)]p(x \mid \theta) \right) dx$   
=  $E[T(X)U(X;\theta) \mid \theta] = Cov[T(X), U(X;\theta) \mid \theta]$   
(the last equation follows since  $E[U(X;\theta) \mid \theta] = 0.$ )

The theorem follows from the Cauchy-Schwarz Inequality for two random variables:

 $(Cov[T(X), U(X; \theta) | \theta])^2 \leq Var[T(X) | \theta] \times Var[U(X; \theta) | \theta]$ i.e.,

 $[\psi'(\theta)]^2 \leq Var[T(X) \mid \theta] \times I(\theta)$ 

**Corollary** 3.4.1 Suppose T(X) is unbiased estimate of  $\theta$  in a regular problem, then

$${\mathscr A}{ar}({\mathcal T}(X) \mid heta) \geq rac{1}{I( heta)} \hspace{0.5cm} ({ extsf{Cramer-Rao}} \hspace{0.5cm} extsf{Lower Bound})$$

**Proposition** 3.4.2 For a random sample  $\mathbf{X} = (X_1, \dots, X_n)$  from a distribution  $P_{\theta}$  with density  $p(x \mid \theta)$  satisfying the conditions of a regular problem. If  $I_1(\theta) = E\left[\left(\left(\frac{\partial}{\partial \theta}[\log p(x_1 \mid \theta)]\right)^2 \mid \theta\right]$  then  $I(\theta) = nI_1(\theta)$  and  $Var[T(\mathbf{X}) \mid \theta] \ge \frac{[\psi'(\theta)]^2}{nI_1(\theta)}$ 

**Proof:** This follows directly from the results above upon noting that

$$U(\mathbf{X}; \theta) = \frac{\partial}{\partial \theta} [\log p(\mathbf{x} \mid \theta)]$$
  
=  $\frac{\partial}{\partial \theta} [\sum_{i=1}^{n} \log p(x_i \mid \theta)]$   
=  $\sum_{i=1}^{n} \frac{\partial}{\partial \theta} [\log p(x_i \mid \theta)]$   
=  $\sum_{i=1}^{n} U(X_i; \theta)$   
By the independence of the terms,  
 $Var[U(\mathbf{X}; \theta) \mid \theta] = \sum_{i=1}^{n} Var[U(X_i; \theta)] = nl_1(\theta) = l(\theta).$ 

**Theorem 3.4.2** Consider a *regular problem* with  $X \sim P_{\theta}, \theta \in \Theta$ , and  $T^*(X)$  is an estimator of  $\psi(\theta)$  which is

- Unbiased:  $E[T^*(X) | \theta] = \psi(\theta)$ , for all  $\theta \in \Theta$ .
- Achieves the Cramer-Rao Lower Bound:

$$Var(T^*(X) \mid \theta) = rac{|\psi'(\theta)|^2}{I(\theta)}$$
, for all  $\theta \in \Theta$ .

Then  $\{P_{\theta}\}$  is a one-parameter exponential family with density/pmf:  $p(x \mid \theta) = h(x) \exp\{\eta(\theta) T^*(x) - B(\theta)\}$ 

**Proof:** From the proof of Theorem 3.4.1 for any unbiased estimator of  $\psi(\theta)$ ,

$$\psi(\theta) = E[T(x) | \theta] = \int T(x)p(x | \theta)dx$$
  

$$\Rightarrow \psi'(\theta) = \int T(x)U(x;\theta)p(x | \theta)dx$$
  
where  $U(x;\theta) = \partial \log p(x | \theta)/\partial \theta$   

$$= Cov(T(X), U(X;\theta) | \theta)$$
  

$$\Rightarrow |\psi'(\theta)| \leq \sqrt{Var(T(X) | \theta) \times Var(U(X;\theta) | \theta)}$$
  
with equality if and only if  $U(X;\theta) = a_1(\theta) + a_2(\theta)T(X)$  for some  
functions  $a_1(\theta)$  and  $a_2(\theta)$ .

### Technical Details of Proof:

- For each  $\theta_0 \in \Theta$ , define  $A_{\theta_0} = \{x : U(x; \theta_0) = a_1(\theta_0)T^*(x) + a_2(\theta_0)\}$ Note:  $P_{\theta_0}(A_{\theta_0}) = 1$ (otherwise the absolute correlation would be less than 1)
- Define  $\{\theta_i, i = 1, 2, ...\}$  to be a denumerable dense subset of  $\Theta$ .

• Define 
$$A^{**} = \cap_i A_{\theta_i}$$
. Then  
 $P_{\theta_i}(A^{**}) = 1$ , for all  $\theta_i$ .

• Fix any two values  $x_1, x_2 \in A^{**}$ , for which  $T^*(x_1) \neq T^*(x_2)$ . Solve the equations:

$$U(x_{1}; \theta) = a_{1}(\theta) T^{*}(x_{1}) + a_{2}(\theta) U(x_{2}; \theta) = a_{1}(\theta) T^{*}(x_{2}) + a_{2}(\theta)$$

to obtain equations for  $a_1(\theta), a_2(\theta)$  as linear combinations of  $U(x_1; \theta)$  and  $U(x_2; \theta)$ .

Since  $U(x; \theta)$  is continuous in  $\theta$ , so are  $a_1(\theta)$  and  $a_2(\theta)$ .

### Technical Details of Proof (continued):

• Since

 $U(x;\theta) = a_1(\theta)T^*(x) + a_2(\theta)$ , for all  $\theta_i \in \{\theta_i\}$ and both  $U(x;\theta)$  and  $a_1(\theta)$  and  $a_2(\theta)$  are continuous, this equation must hold for all  $\theta$ .

• So 
$$A^{**} = \bigcap_i A_{\theta_i}$$
 must equal  
 $A^* = \{x : U(x; \theta) = a_1(\theta) T^*(x) + a_2(\theta), \text{ for all } \theta \in \Theta\}.$   
and  $P(A^*) = 1.$ 

With

$$U(x;\theta) = \frac{\partial \log p(x|\theta)}{\partial \theta} = a_1(\theta)T^*(x) + a_2(\theta)$$
  
Define:  $\eta(\theta) = \int_{\theta_0}^{\theta} a_1(t)dt$  and  $B(\theta) = -\int_{\theta_0}^{\theta} a_2(t)dt$ ,  
Then

$$\log\left[\frac{p(x|\theta)}{p(x|\theta_0)}\right] = \int_{\theta_0}^{\theta} \left[\frac{\partial \log p(x|\theta)}{\partial \theta}\right] d\theta = T^*(x)\eta(\theta) - B(\theta),$$

and we have:

$$p(x \mid \theta) = h(x)exp\{\eta(\theta)T^*(x) - B(\theta)\}, x \in A^*$$
  
where  $h(x) = p(x \mid \theta_0)$  (for a fixed value  $\theta_0$ ).

## Multiparameter Case

**Definition: Regular Problem** A statistical inference problem with  $X \sim P_{\theta}, \theta \in \Theta$  which satisfies the following regularity conditions:

•  $\mathcal{X} = \{x : p(x \mid \theta) > 0\}$  does not depend on  $\theta$ . •  $\frac{\partial logp(x \mid \theta)}{\partial \theta}$  exists and is finite for all  $x \in \mathcal{X}$  and  $\theta \in \Theta$ . • For any statistic T such that  $E[|T(X)| \mid \theta] < \infty$  $\frac{\partial}{\partial \theta} \left[ \int T(x)p(x \mid \theta)dx \right] = \int T(x)\frac{\partial}{\partial \theta}[p(x \mid \theta)]dx.$ 

**Definition: Efficient Score Function**. For a fixed  $\theta_0 \in \Theta$ , the *efficient score* for X is  $u(X; \theta_0) = \frac{\partial \log p(x \mid \theta)}{\partial \theta}|_{\theta = \theta_0}$ 

Note: The magnitude of  $u(X; \theta_0)$  scales how far  $\theta_0$  is from  $\hat{\theta}_{MLE}$ . The definitions extend to vector-valued  $\theta$  immediately **Proposition** (I). The Efficient Score Function has the following properties:

$$E[u(X;\theta_0) \mid \theta = \theta_0] = 0.$$
  

$$Cov[u(X;\theta_0) \mid \theta = \theta_0] = E([u(X;\theta_0)][u(X;\theta_0)]^T \mid \theta = \theta_0)$$
  

$$= I(\theta_0).$$

(II).  $I(\theta)$  is the  $(d \times d)$  Fisher information matrix whose elements satisfy the following identities

$$[I(\theta_0)]_{i,j} = [Cov[u(X;\theta_0) | \theta_0]]_{i,j}$$
  

$$= E[[u(X;\theta)]_i[u(X;\theta)]_j | \theta = \theta_0]$$
  

$$= E[\frac{\partial \log p(X | \theta)}{\partial \theta_i} \frac{\partial \log p(X | \theta)}{\partial \theta_j} | \theta = \theta_0]$$
  

$$= -E[\frac{\partial^2 \log p(X | \theta)}{\partial \theta_i \partial \theta_j} | \theta = \theta_0]$$
  
(III). If  $\mathbf{X} = (X_1, \dots, X_n)$  is an iid sample from  $X \sim P_{\theta}$  with nformation  $I_1(\theta)$ , then  

$$I(\mathbf{X}) = nI_1(\theta).$$

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**Theorem 3.4.3** For a regular problem with non-singular information matrix  $I(\theta)$ , consider a scalar-valued statistic T(X) estimating the scalar  $\psi(\theta)$ , and suppose

$$E[T(X) \mid \theta] = \psi(\theta)$$
  
$$\dot{\psi}(\theta) = \nabla \psi(\theta) = \frac{\partial \psi(\theta)}{\partial \theta_1}, \dots, \frac{\partial \psi(\theta)}{\partial \theta_1}$$

Then

$$\operatorname{Var}[T(X) \mid \theta] \ge [\dot{\psi}(\theta)]^T [I(\theta)]^{-1} [\dot{\psi}(\theta)]$$

**Proof.** For a random variable Y, and a random d-vector Z, recall the minimum MSPE linear predictor  $\mu_L(Z)$  of Y is given by:

$$\mu_L(Z) = \mu_Y + (Z - \mu_z)^T \Sigma_{Z,Z}^{-1} \Sigma_{Z,Y}$$
  
$$\kappa = F[Y] \quad \mu_Z = F[Z]$$

where  $\mu_Y = E[Y], \ \mu_Z = E[Z],$ 

 $\Sigma_{Z,Z} = Cov(Z) \ (d \times d)$ , and  $\Sigma_{Z,Y} = Cov(Z,Y) \ (d \times 1)$ . The variance of  $\mu_L(Z)$  satisfies

$$Var(\mu_L(Z)) = [\Sigma_{Z,Y}]^T \Sigma_{Z,Z}^{-1} \Sigma_{Z,Y} \leq Var(Y),$$

with equality only if  $Y = \mu_L(Z)$ . The Theorem follows setting Y = T(X) and  $Z = u(X; \theta)$ . **Theorem** 3.4.4 For a regular problem as in Theorem 3.4.3 suppose:

$$T(X) = (T_1(X), \dots, T_d(X))^T \in \mathbb{R}^d$$
  

$$E[T(X) \mid \theta] = \psi(\theta) \quad (d \times 1) \text{ vector}$$
  

$$\overset{\bullet}{\psi}(\theta) = \bigtriangledown \psi(\theta) = \left[\frac{\partial \psi(\theta)}{\partial \theta_1} \mid \dots \mid \frac{\partial \psi(\theta)}{\partial \theta_d}\right] \quad (d \times d) \text{ matrix}$$

Then

$$Var[T(X) \mid heta] \geq [\overset{ullet}{\psi}( heta)][I( heta)]^{-1}[\overset{ullet}{\psi}( heta)]^T$$

where 
$$A \ge B$$
 means  $(A - B)$  is postive semi-definite:  
 $a^{T}(A - B)a \ge 0$ , for all  $a \in \mathbb{R}^{d}$ .  
**Proof.** Problem 3.4.21

Note: For 
$$\hat{\theta}$$
 :  $E[\hat{\theta} \mid \theta] = \theta$ ,  
 $\psi(\theta) = \theta$ , and  $\dot{\psi}(\theta) = I_d$ , the  $(d \times d)$  identity matrix.

and

$$Var(\hat{ heta} \mid heta) \geq [I( heta)]^{-1}$$

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#### Preview:

- When X = (X<sub>1</sub>,...,X<sub>n</sub>) corresponds to a random sample from a population whose distribution has information I<sub>1</sub>(θ) for a single observation, the information in a sample of size n is I(X) = nI<sub>1</sub>(θ)
- As the sample size grows large such samples, optimal estimators of parameters  $q(\theta)$  are sought.
- The Cramer-Rao Lower Bound defines the golden standard of performance for estimators which are unbiased asymptotically.
- Such estimators will be called *asymptotically efficient*.

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