

1.053J/2.003J Dynamics and Control I  
Fall 2006

Exam 1  
30<sup>th</sup> October, 2006

**Important Notes:**

1. You are allowed to use one letter-size sheet (two-sides) of notes.
2. There are three problems on the exam. You have 80 minutes to solve them.

1. A space shuttle orbiter and an astronaut

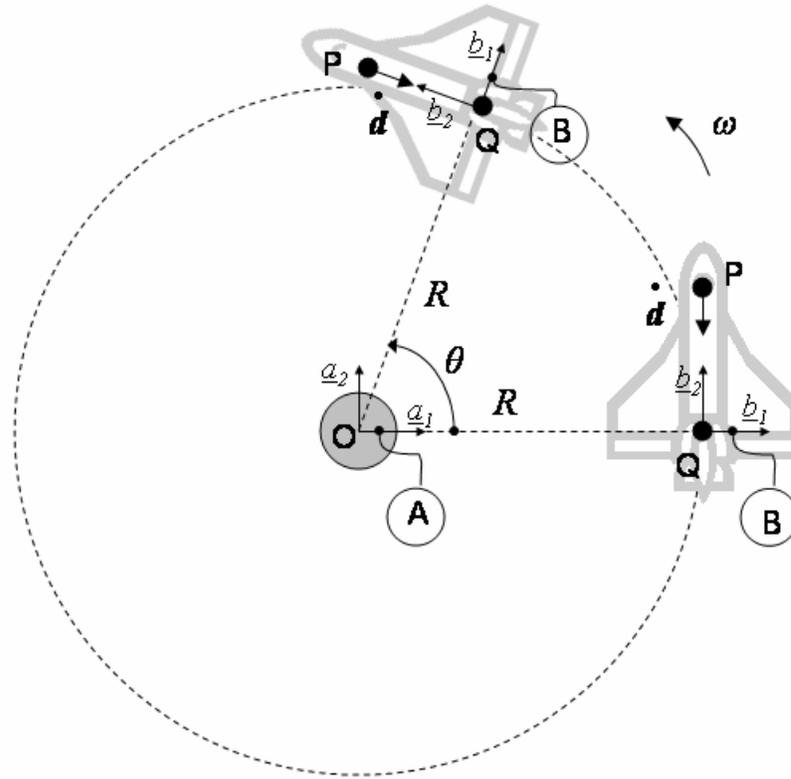


Figure 1

A space shuttle is orbiting the earth in a circular orbit with a *constant* angular speed  $\omega$  as shown in Figure 1. A point Q fixed on the space shuttle is at distance  $R$  from the origin O. Frame A is fixed. Frame B is attached to the space shuttle. The space shuttle orbits such that the basis vector  $\underline{b}_2$  always remains tangential to the orbit as shown in the figure.

Clearly,  $\dot{\theta} = \omega$ .

- Find the acceleration of point Q with respect to frame A as a function of  $\theta$  and  $\dot{\theta}$ .
- An astronaut represented by point P begins to walk with a *constant* speed  $\dot{d}$  with respect to the space shuttle along  $-\underline{b}_2$ , i.e. the negative  $\underline{b}_2$  direction from the cockpit towards point Q as shown in the figure. Find the acceleration of P with respect to frame A if P is at distance  $d$  from point Q.
- Find a relationship between  $\dot{d}$  and  $\omega$  such that at a certain location on her path, her acceleration with respect to frame A is exactly zero. Find that location as well relative to the space shuttle.

## 2. L-shape

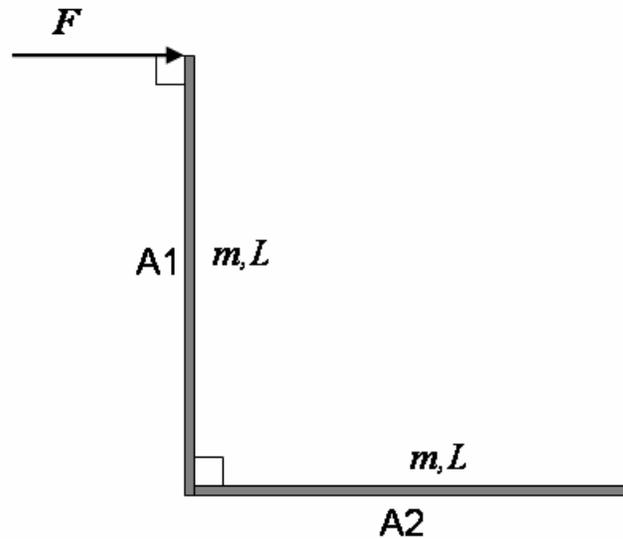


Figure 2

Consider the L-shaped structure, shown in Figure 2, which consists of two slender rods A1 and A2 that are glued together. Each has mass  $m$  and length  $L$ . A massless(!) rocket is attached to one end of rod A1. At  $t = 0$ , the rocket is ignited and it produces a thrust of magnitude  $F$  on the L-shape. Throughout the motion, the direction of force  $F$  remains perpendicular to rod A1 as shown in the figure. Ignore gravity and assume that the motion is planar.

- Find the center of mass of the L-shaped object.
- Assume that the L-shaped object behaves as a rigid body in 2D. Define convenient frames, identify generalized co-ordinates of the L-shaped object and find the equations of motion of the system.

### 3. System of pulleys

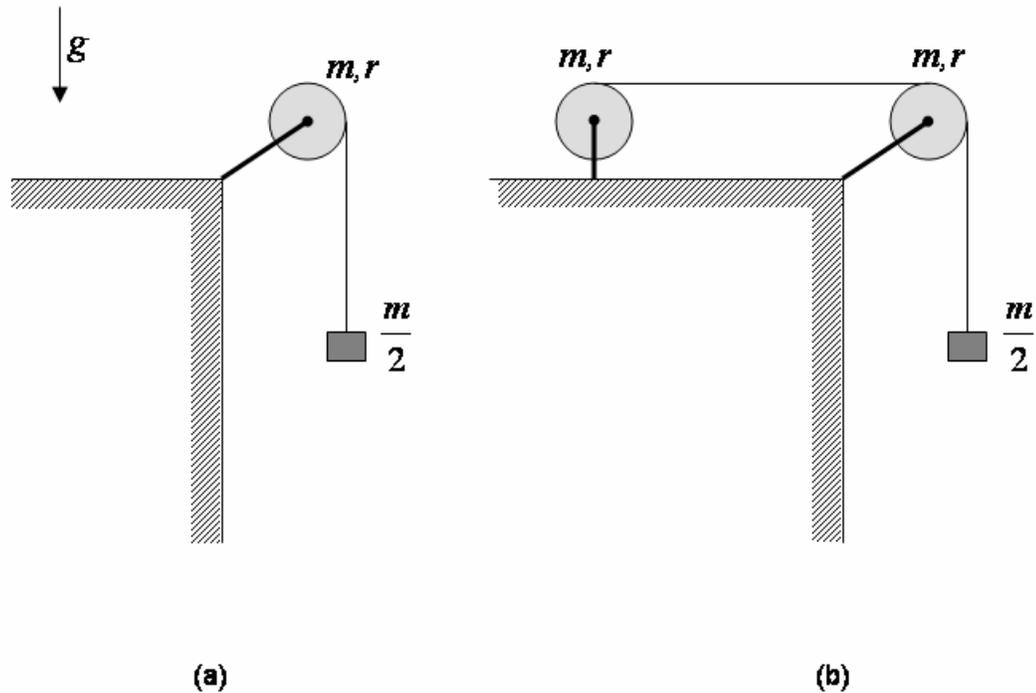


Figure 3

- A point mass of mass  $\frac{m}{2}$  is hanging from a thin, massless and inextensible string that winds several turns around a pulley of mass  $m$  and radius  $r$  as shown in Figure 3(a). The pulley is free to rotate about the pivot supported from the table and accordingly, the string winds/unwinds and the point mass moves up and down. This system can be imagined as a spool. Initially the point mass is supported such that it is hanging vertically and suddenly the support is removed. Using the work-energy principle, find the acceleration of the point mass. Note that gravity acts.
- Instead of one pulley, now suppose that the same point mass is hanging from a string that goes over two identical pulleys, each of mass  $m$  and radius  $r$ , as shown in Figure 3(b). The left-most pulley acts like a spool. Find the acceleration of the point mass in this case.
- Observe the pattern of your answers in part a and part b. Based on this, how many identical pulleys you need to design a system such that the acceleration of the point mass is  $\frac{g}{5}$ , where  $g$  is the acceleration due to gravity.