2.016 Hydrodynamics

Fall 2005 PS #2



The AUV can carry M and be fully submerged but not sink.

$$r_i = 0.07 \, \text{m}$$

aluminum,
$$5.5 = 2.7 = \frac{\text{lat}}{\text{lho}} = \frac{\text{lat}}{1000} \times \frac{1}{100} \Rightarrow \text{lat} = 2700 \times \frac{1}{100}$$

$$B = \rho \forall g = (1025 \frac{kg}{m})(3.\pi (0.08 n)^2 \cdot 2.0 n)(9.8 \%^2) = 1212 N$$

$$M_{AVV} = f_{A1} \forall_{AL} = f_{A1} \mathbf{3} \pi \left(f_{o}^{2} - f_{c}^{2} \right) l = 2700 f_{o}^{1} f_{m}^{3} - \pi \left(0.08 f_{m}^{2} - 0.07 f_{m}^{2} \right) \cdot 2.0 f_{m}^{2} = 2700 f_{o}^{2} f_{m}^{3} + \pi \left(0.08 f_{m}^{2} - 0.07 f_{m}^{2} \right) \cdot 2.0 f_{m}^{2} = 2700 f_{o}^{2} f_{m}^{2} + 2700 f_{o}^{2} f_{m}$$

$$B = m_0 + M_0$$

$$76.2$$

$$1212 N = 1214 kg - 9.8 \%^2 + M - 9.8 \%^2$$

$$M = 1216 kg$$

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length scale of

2. a) continuum hypothesis = distance between molecular collisions is small compared to our observation.

b) A pathline connects all the points that "Bob the Fluid Blob"
passes through over some period of time.

A streamline is drawn tangent to the flow for
some snapshot in time

\$ 1.11

t=1 t=d t=3

Bob's path over a period of time.

If the flav is steady, then
the streamlines do not
change over time, and
Bob will follow the path of
one of the streamlines.

streamlines of one instant in time

c)
$$(\vec{V} \cdot \vec{\nabla}) \vec{\nabla} = ((u, v, w) \cdot (\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z})) \vec{\nabla}$$

$$= (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) \vec{\nabla}$$

$$= u \frac{\partial \vec{v}}{\partial x} + v \frac{\partial \vec{v}}{\partial y} + w \frac{\partial \vec{v}}{\partial z}$$

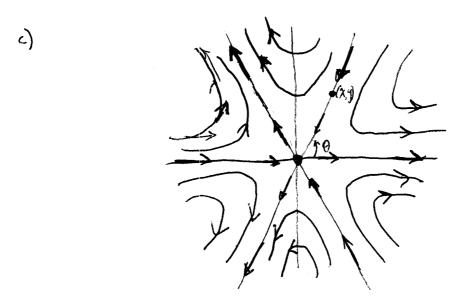
This step is true $= \left(u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} + \omega\frac{\partial u}{\partial z}\right) \hat{c} + \left(u\frac{\partial v}{\partial x} + v\frac{\partial v}{\partial y} + \omega\frac{\partial u}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial y}\right) \hat{f} + \left(u\frac{\partial u}{\partial x} + v\frac{\partial w}{\partial z} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial u}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + \omega\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial z} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial z} + v\frac{\partial w}{\partial z}\right) \hat{f} + \left(u\frac{\partial w}{\partial z$

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3a)
$$\vec{V} = (x^2 - y^2) \hat{i} + (-\lambda x y) \hat{j}$$

$$\vec{\nabla} \cdot \vec{V} = \frac{\partial i x}{\partial x} + \frac{\partial V}{\partial y} = \frac{\partial}{\partial x} (x^2 y^2) + \frac{\partial}{\partial y} (-\lambda x y) = \lambda x - \lambda x = 0$$
Yes.

Yes, the flow is steady (in the Enlering sense) since there is no time dependence.



Slope =
$$\tan \theta = \frac{y-0}{x-0} = \frac{y}{x} = \frac{\sqrt{y-0}}{y}$$

Slope of a streamline is targent to the velocity vector

$$x^2y - y^3 = -2x^2y$$

$$3x^2y-y^3=0$$

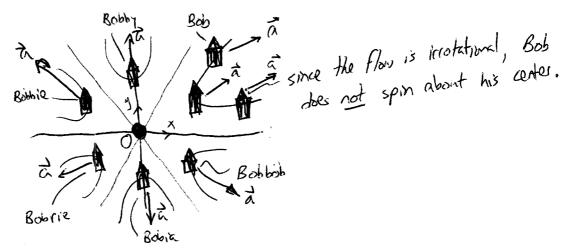
y=squareroot(3)*x is the equation for the line.

$$(\sqrt{3}x-y)(\sqrt{3}x+y)y=0$$

$$\Theta = 60^{\circ}$$

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5)

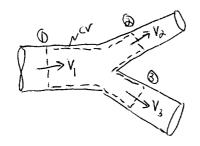


For Bob and all his friends, they are all pushed away from the origin. Therefore, the pressure must be highert at the origin.

The velocity is zero at the origin, and the pressure is highest there. Does this agree with what Bernoulli's equation tells us?

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$$d_1 = 0.00 \text{ m}$$
 $d_2 = 0.015 \text{ m}$
 $d_3 = 0.012 \text{ m}$
 $V_1 = 1.5 \text{ M/s}$
 $M_2 = M_3$

Find Va, V3.

By Conservation of Mass:

$$\frac{d}{dt} \int \rho dV + \int \rho \vec{u} \cdot d\vec{A} = 0$$

$$cate of mass \qquad flux out of$$

$$accumulating = 0 \qquad the control volume ($\vec{n} = \rho VA$)$$

$$0 - (V_1 \pi \frac{d_1^2}{4} + \dot{M}_2 + \frac{\dot{M}_3}{4} = 0)$$

$$\dot{M}_2 = \dot{M}_3 = \frac{1}{2} (V_1 \pi \frac{d_1^2}{4})$$

$$\dot{M}_3 = \dot{M}_3 = \frac{1}{2} (V_1 \pi \frac{d_1^2}{4})$$

$$\dot{M}_4 = (V_2 \pi \frac{d_2^2}{4} = \frac{1}{2} (V_1 \pi \frac{d_1^2}{4}))$$

$$V_3 = \frac{1}{2} (V_1 (\frac{d_1}{d_3}))^2 = \frac{1}{2} (1.5 \%) \cdot (\frac{0.020 \text{ m}}{0.015 \text{ m}})^2 = \sqrt{3.1 \%}$$

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- 5. a) $P_1 + \frac{1}{2} e^{V_1^2} + e^{2} = P_2 + \frac{1}{2} e^{V_2^2} + e^{2}$
 - b) steady, incompressible, invited flow along a streamline, with no work done on the fluid
 - c) Yes. since the fluid is incompressible, the volume flow rate at any sectron must be the same.
 - d) No. Bernoullis's egus time can not be applied across the fan. The propellar does work on the fluid to increase the static pressure, p. Suppose A=A2 & Z=Z2, then V=V2 but P2>P1 due to the fan.