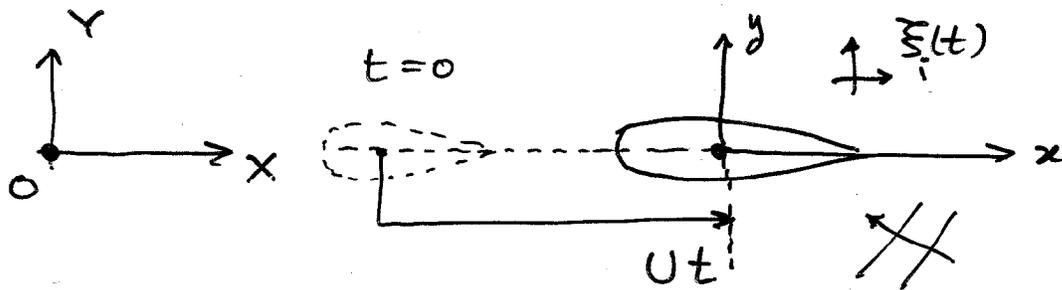


RANKINE INTEGRAL EQUATIONS FOR SHIP FLOW PROBLEMS WITH FORWARD SPEED

- THE GREEN INTEGRAL EQUATION EXTENDS EASILY TO FLOWS PAST SHIPS IN CALM WATER AND IN WAVES WHEN THE FREE SURFACE CONDITION IS MORE COMPLEX THAN THAT OF THE $U=0$ FREQUENCY DOMAIN PROBLEM
- NEUMANN-KELVIN PROBLEM IN TIME DOMAIN



CONSIDER A VESSEL WHICH STARTS FROM REST AT $t=0$ AND TRANSLATES FORWARD WITH CONSTANT VELOCITY U AND ALSO POSSIBLY OSCILLATING WITH AMPLITUDES $\xi_i(t)$ IF AMBIENT WAVES ARE PRESENT.

IT WAS SHOWN EARLIER THAT THE SIMPLEST FORWARD SPEED FREE SURFACE CONDITION FOR THE FORWARD SPEED PROBLEM TAKES THE FORM:

$$\left\{ \begin{array}{l} \left(\frac{\partial}{\partial t} - U \frac{\partial}{\partial x} \right)^2 \varphi + g \frac{\partial \varphi}{\partial z} = 0, \quad z=0 \\ \frac{\partial \varphi}{\partial n} = V, \quad \text{on } \bar{S}_B \end{array} \right.$$

RELATIVE TO THE SHIP FRAME. THE NORMAL VELOCITY V ON \bar{S}_B CAN BE OF THREE FORMS:

$$V(\vec{x}) = \begin{cases} U \eta_1, & t > 0: \text{ FORWARD TRANSLATION} \\ \eta_i \xi_i(t), & t > 0: \text{ RADIATION} \\ -\frac{\partial \varphi_I}{\partial n}, & t > 0: \text{ DIFFRACTION} \end{cases}$$

- MORE GENERAL FREE-SURFACE CONDITIONS WITH SPACE DEPENDENT COEFFICIENTS ARISING FROM GRADIENTS OF THE DOUBLE-BODY FLOW EXIST AND ARE DESCRIBED IN THE LITERATURE THE STEPS IN DERIVING THE RELEVANT INTEGRAL EQUATIONS ARE VERY SIMILAR TO THE ONES THAT FOLLOW:

- WAVE GREEN FUNCTIONS THAT SATISFY ANALYTICALLY THE TIME-DOMAIN FREE SURFACE CONDITION STATED ABOVE EXIST AND ARE DERIVED IN W & L. THEIR EVALUATION IS HOWEVER TIME-CONSUMING AND THEY APPLY ONLY TO THE NEUMANN-KELVIN FORMULATION. —

- PROCEEDING WITH THE DERIVATION OF THE GREEN INTEGRAL EQUATION AS ABOVE AND USING THE RANKINE SOURCE AS THE GREEN FUNCTION :

$$\begin{aligned}\varphi_2(\vec{x}) &= -\frac{1}{4\pi} |\vec{x} - \vec{\xi}|^{-1} \\ &\equiv G(\vec{x}; \vec{\xi})\end{aligned}$$

WE OBTAIN :

$$\begin{aligned}\frac{1}{2} \varphi(\vec{\xi}) + \iint_{S_B} \varphi(\vec{x}) \frac{\partial G(\vec{x}; \vec{\xi})}{\partial n_x} dS_x \\ + \iint_{S_F(z=0)} \left[\varphi(\vec{x}) \frac{\partial G(\vec{x}; \vec{\xi})}{\partial z} - G(\vec{x}; \vec{\xi}) \frac{\partial \varphi}{\partial z} \right] dx dy \\ = \iint_{S_B} G(\vec{x}; \vec{\xi}) \nabla(\vec{x}) dS_x. —\end{aligned}$$

- NOTE THAT THE INTEGRAL OVER THE FREE SURFACE ($z=0$) DOES NOT VANISH SINCE WE HAVE NOT USED THE RELEVANT WAVE GREEN FUNCTION.
- OTHERWISE THE REMAINING INTEGRAL OVER S_B RETAINS ITS FORM. THE INTEGRAL OVER S_{∞} CAN BE SHOWN TO VANISH. THE PROOF IS NON-TRIVIAL AND MAY BE FOUND IN REFERENCES.

OVER $z=0$, IT FOLLOWS FROM THE FREE-SURFACE CONDITION:

$$\frac{\partial \psi}{\partial z} = -\frac{1}{g} \left(\frac{\partial}{\partial t} - u \frac{\partial}{\partial x} \right)^2 \psi, \quad z=0$$

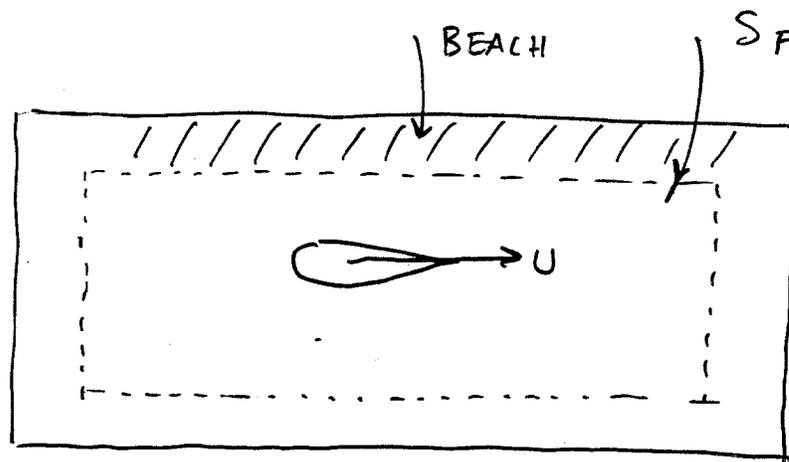
UPON SUBSTITUTION, THE SECOND INTEGRAL OVER S_F BECOMES:

$$I_F = \iint_{z=0} \left[\psi(\vec{x}) \frac{\partial G(\vec{x}; \vec{\xi})}{\partial z} + \frac{1}{g} G(\vec{x}; \vec{\xi}) \left(\frac{\partial}{\partial t} - u \frac{\partial}{\partial x} \right)^2 \psi(\vec{x}) \right] ds$$

IT FOLLOWS THAT OVER $z=0$, ONLY VALUES AND TANGENTIAL GRADIENTS OF $\psi(\vec{x})$ ARE NOW PRESENT LEADING TO AN INTEGRO-DIFFERENTIAL EQUATION:

$$\begin{aligned} & \frac{1}{2} \varphi(\vec{\xi}) + \iint_{S_B} \varphi(\vec{x}) \frac{\partial G(\vec{x}; \vec{\xi})}{\partial n_x} dS_x \\ & + \iint_{S_F(z=0)} \left[\varphi(\vec{x}) \frac{\partial G(\vec{x}; \vec{\xi})}{\partial z} + \frac{1}{g} G(\vec{x}; \vec{\xi}) \left(\frac{\partial}{\partial t} - v \frac{\partial}{\partial x} \right)^2 \varphi(\vec{x}) \right] dx dy \\ & = \iint_{S_B} V(\vec{x}) G(\vec{x}; \vec{\xi}) dS_x \end{aligned}$$

- UNKNOWN IS $\varphi(\vec{x})$ OVER S_B & S_F . ITS X-DERIVATIVES MAY BE APPROXIMATED BY CAREFULLY SELECTED NUMERICAL DIFFERENTIATION SCHEMES FORMING A CORE PART OF RANKINE PANEL METHODS, DISCUSSED BELOW
- THE INTEGRAL OVER THE INFINITE FREE SURFACE $S_F(z=0)$ IS TRUNCATED AT SOME FINITE DISTANCE FROM THE SHIP AS DRAWN BELOW



- A DOMAIN DENOTED BY THE SHADED AREA IS ALSO INTRODUCED DEFINED AS THE "BEACH". THIS IS LOCATED AS THE OUTER BOUNDARY OF S_F AND SELECTED SO THAT OVER ITS SURFACE THE FOLLOWING FREE SURFACE CONDITION IS ENFORCED :

$$\left(\frac{\partial}{\partial t} - v \frac{\partial}{\partial x} \right)^2 \psi + g \frac{\partial \psi}{\partial z} + 2v \left(\frac{\partial}{\partial t} - v \frac{\partial}{\partial x} \right) \psi + v^2 \psi = 0, \\ z = 0$$

- THIS CONDITION DIFFERS FROM THE NEUMANN-KELVIN CONDITION BY THE ADDITION OF THE TERMS THAT ARE MULTIPLIED BY THE DISSIPATIVE PARAMETER $v(\vec{x})$ WHICH VARIES FROM $v = 0$ AT THE INNER BOUNDARY TO A FINITE VALUE AT THE OUTER BOUNDARY OF THE BEACH.
- IT CAN BE SHOWN THAT CONVERTING FROM THE TIME TO THE FREQUENCY DOMAIN VIA $\frac{\partial}{\partial t} \rightarrow i\omega$, v IS THE FAMILIAR RAYLEIGH VISCOSITY THAT PLAYS A KEY ROLE IN THE ENFORCEMENT OF THE RADIATION CONDITIONS.— (SEE W & L)