## Gradient Index (GRIN) optics: radial quadratic



• Focal length  $f = \frac{1}{n_{\max} \alpha d}$ 



# Paraxial focusing by a thin quadratic GRIN lens

Consider a ray from infinity entering the GRIN at elevation r. If focusing is to be achieved, this ray must meet the on-axis ray at a distance f from the exit face; therefore, their optical paths must be equal according to Fermat's principle.

For the on-axis ray,

$$OPL(r=0) = n_{\max}d + f.$$

For the ray at elevation r,

OPL 
$$(r) \approx n_{\max}\left(1 - \frac{\alpha r^2}{2}\right)d + \sqrt{r^2 + f^2},$$

where we have neglected the small elevation decline due to the bending of the ray inside the GRIN.

Applying Fermat's principle in the paraxial approximation,

$$n_{\max}d + f \approx n_{\max}\left(1 - \frac{\alpha r^2}{2}\right)d + \sqrt{r^2 + f^2} \Rightarrow$$

$$f + \frac{n_{\max}\alpha d}{2}r^2 \approx \sqrt{r^2 + f^2} \approx f\left(1 + \frac{r^2}{2f^2}\right) \Rightarrow$$

$$\frac{n_{\max}\alpha d}{2}r^2 \approx \frac{r^2}{2f} \Rightarrow$$

$$f \approx \frac{1}{n_{\max}\alpha d}.$$

$$0$$

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MIT 2.71/2.71

## Gradient Index (GRIN) optics: axial

Axial index profile: fabrication by melding & grinding



- Stack
- Meld
- Grind & polish to a sphere
- <u>Result:</u> Spherical refractive surface with axial index profile n(z)



# Correction of spherical aberration by axial GRIN lenses





# Generalized GRIN: what is the ray path through arbitrary *n*(*r*)?



#### Fermat's principle:

The path  $\Gamma$  that the ray follows is such that the value of the path integral of refractive index  $n(\mathbf{r})$ along  $\Gamma$  is smaller than all other possible paths  $\Gamma'$ .

### Let's take a break from optics ...



# **Mechanical oscillator**



Potential energy: 
$$V = \frac{1}{2}kq^2$$
.  
Kinetic energy:  $T = \frac{1}{2}m\dot{q}^2 = \frac{1}{2}\frac{p^2}{m}$ ,

where  $p \equiv m\dot{q}$  is the momentum.

Since there is no dissipation, the total energy

$$H = T + V$$

must be conserved.



#### Introduction to the Hamiltonian formulation of dynamics

The Hamiltonian formulation is a set of differential equations describing the trajectories of particles that are subject to a potential (force.) The trajectory is described in terms of the particle position  $\mathbf{q}(t)$  and momentum  $\mathbf{p}(t)$ . The <u>Hamiltonian</u> is the total energy, *i.e.* the sum of kinetic and potential energies, and it is conserved if there is no dissipation in the system. For example, for a harmonic oscillator the Hamiltonian is expressed as

$$H(\mathbf{q}, \mathbf{p}) = \frac{\mathbf{p}^2}{2m} + \frac{k\mathbf{q}^2}{2}.$$
 (1)

The first term is the kinetic energy for a particle of mass m, and the second term is the potential energy for linear spring constant k.

The Hamiltonian equations in general are

$$\frac{\mathrm{d}\mathbf{q}}{\mathrm{d}t} = \frac{\partial H}{\partial \mathbf{p}},\tag{2}$$

$$\frac{\mathrm{d}\mathbf{p}}{\mathrm{d}t} = -\frac{\partial H}{\partial \mathbf{q}}.$$
(3)

The expressions on the right-hand side are the gradients of the Hamiltonian with respect to the vectors  $\mathbf{p}$  and  $\mathbf{q}$ , respectively.

Let us consider the simplest case of a one–dimensional harmonic oscillator. In this case the position and momentum are scalars q, p. The Hamiltonian equations become

$$\left. \frac{\mathrm{d}q}{\mathrm{d}t} = \frac{p}{m} \\
\frac{\mathrm{d}p}{\mathrm{d}t} = -kq. \right\} \Rightarrow \frac{\mathrm{d}^2q}{\mathrm{d}t^2} = \frac{1}{m}\frac{\mathrm{d}p}{\mathrm{d}t} = -\frac{k}{m}q \Rightarrow \frac{\mathrm{d}^2q}{\mathrm{d}t^2} + \frac{k}{m}q = 0.$$
(4)

We have arrived at the familiar 2<sup>nd</sup>-order harmonic differential equation. For example, assuming a particle that is initially at position  $q(t = 0) = q_0$  and at rest, p(t = 0) = 0, the solution to the Hamiltonian equations is

$$q(t) = q_0 \cos\left(\sqrt{\frac{k}{m}}t\right), \tag{5}$$

$$p(t) = -q_0 \sqrt{km} \sin\left(\sqrt{\frac{k}{m}}t\right).$$
(6)

The solution set  $\{q(t), p(t)\}$  is the <u>trajectory</u> of the particle. The motion represented by the trajectory that we found is clearly a harmonic oscillation.



# Hamiltonian Optics postulates

s: parameterization of the ray trajectory q(s): position vector for the ray trajectory at s; p(s): tangent vector to the ray trajectory at s



Geometrical postulate:

Rays are continuous and piecewise differentiable

Dynamical postulate:

Momentum changes along trajectory arc length in proportion to the local refractive index gradient

$$\Delta \mathbf{p}(s) \approx \nabla n \left( \mathbf{q} \left( s' \right) \right) \Delta s$$

 $\Delta \mathbf{q}(s) \approx \frac{\mathbf{p}(s')}{|\mathbf{p}(s')|} \Delta s$  $\Rightarrow \frac{\mathrm{d}\mathbf{q}}{\mathrm{d}s} = \frac{\mathbf{p}(s)}{|\mathbf{p}(s)|}$ 

 $\Rightarrow \frac{\mathrm{d}\mathbf{p}}{\mathrm{d}s} = \nabla n \Big( \mathbf{q} \left( s \right) \Big)$ 

These are the "equations of motion," i.e. they yield the ray trajectories.



# The ray Hamiltonian

s: parameterization of the ray trajectory q(s): position vector for the ray trajectory at s; p(s): tangent vector to the ray trajectory at s



The choice  $H = |\mathbf{p}| - n(\mathbf{q})$  yields

 $\nabla_{\mathbf{q}} H \equiv \frac{\partial H}{\partial \mathbf{q}} = -\nabla_{\mathbf{q}} n\left(\mathbf{q}\right) \qquad \nabla_{\mathbf{p}} H \equiv \frac{\partial H}{\partial \mathbf{p}} = \frac{\mathbf{p}\left(s\right)}{\left|\mathbf{p}\left(s\right)\right|}$ 

Therefore, the equations of motion become

$$\frac{\mathrm{d}\mathbf{q}}{\mathrm{d}s} = \frac{\partial H}{\partial \mathbf{p}} \qquad \qquad \frac{\mathrm{d}\mathbf{p}}{\mathrm{d}s} = -\frac{\partial H}{\partial \mathbf{q}}$$

Since the ray trajectory satisfies a set of Hamiltonian equations on the quantity *H*, it follows that *H* is conserved.

The actual value of *H*=const. is <u>arbitrary</u>.



## The ray Hamiltonian and the Descartes sphere



## The ray Hamiltonian and the Descartes sphere



Figure by MIT OpenCourseWare. Adapted from Fig. 1.5 in Wolf, Kurt B. Geometric Optics in Phase Space. New York, NY: Springer, 2004.



## Hamiltonian analogies: optics vs mechanics

Hamiltonian of mechanical system  $H_{\rm m} = \frac{|\mathbf{p}|^2}{2m} + V(\mathbf{q})$   $E = H_{\rm m}$  (conserved) Momentum  $\mathbf{p} = m \frac{\mathrm{d}\mathbf{q}}{\mathrm{d}t} \Rightarrow \frac{\mathrm{d}s}{\mathrm{d}t} = \frac{|\mathbf{p}|}{m}$  Velocity Mechanical Hamiltonian equations  $\frac{\mathrm{d}\mathbf{q}}{\mathrm{d}s} = \frac{\mathbf{p}}{|\mathbf{p}|} \qquad \frac{\mathrm{d}\mathbf{p}}{\mathrm{d}s} = -\frac{m}{|\mathbf{p}|}\frac{\partial V(\mathbf{q})}{\partial \mathbf{q}}$ **Optical Hamiltonian equations**  $\frac{\mathrm{d}\mathbf{q}}{\mathrm{d}s} = \frac{\mathbf{p}}{|\mathbf{p}|} \qquad \frac{\mathrm{d}\mathbf{p}}{\mathrm{d}s} = \frac{\partial n(\mathbf{q})}{\partial \mathbf{q}}$ Analogous if:  $\frac{\partial V(\mathbf{q})}{\partial \mathbf{q}} \leftrightarrow -\frac{|\mathbf{p}|}{m} \frac{\partial n(\mathbf{q})}{\partial \mathbf{q}} = -\frac{n(\mathbf{q})}{m} \frac{\partial n(\mathbf{q})}{\partial \mathbf{q}} =$  $=-rac{1}{2m}rac{\partial n^2(\mathbf{q})}{\partial \mathbf{q}}.$  $\Rightarrow V(\mathbf{q}) \leftrightarrow -\frac{n^2(\mathbf{q})}{2m} + \text{const.}$ Choose const. =  $-\frac{E+1}{2m} \Rightarrow 2m \left[ E - V(\mathbf{q}) \right] \quad \leftrightarrow \quad n^2(\mathbf{q}) - 1$ and  $E_{\text{kinetic}} \propto E - V(\mathbf{q}) > 0 \quad \leftrightarrow \quad n(\mathbf{q}) > 1.$ physically allowable physically allowable kinetic energy refractive index





#### Further reading:

• M. Born and E. Wolf, *Principles of Optics*, Cambride University Press, 7<sup>th</sup> edition, sections 4.1-4.2

• K. B. Wolf, Geometrical Optics on Phase Space, Springer, chapters 1, 2

• K. Tian, Three-dimensional (3D) optical information processing, PhD dissertation, MIT 2006.



2.71 / 2.710 Optics Spring 2009

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