

PRA Methodology Overview

22.39 Elements of Reactor Design, Operations, and Safety

Lecture 9

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PRA Synopsis

Figure removed due to copyright restrictions. Futron Corp., International Space Station PRA, Dec. 2000

NPP End States

- Various states of degradation of the reactor core.
- Release of radioactivity from the containment.
- Individual risk.
- Numbers of early and latent deaths.
- Number of injuries.
- Land contamination.

The Master Logic Diagram (MLD)

- Developed to identify Initiating Events in a PRA.
- Hierarchical depiction of ways in which system perturbations can occur.
- Good check for completeness.

MLD Development

- Begin with a top event that is an end state.
- The top levels are typically functional.
- Develop into lower levels of subsystem and component failures.
- Stop when every level below the stopping level has the same consequence as the level above it.



NPP: Initiating Events

- Transients
 - Loss of offsite power
 - Turbine trip
 - Others
- Loss-of-coolant accidents (LOCAs)
 - Small LOCA
 - Medium LOCA
 - Large LOCA

ILLUSTRATION EVENT TREE: Station Blackout Sequences



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Offsite Power Recovery Curves



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STATION BLACKOUT EVENT TREE



Courtesy of U.S. NRC.



Human Performance

- The operators must decide to perform feed & bleed.
- Water is "fed" into the reactor vessel by the highpressure system and is "bled" out through relief valves into the containment. Very costly to clean up.
- Must be initiated within about 30 minutes of losing secondary cooling (a thermal-hydraulic calculation).

J. Rasmussen's Categories of Behavior

- *Skill-based behavior:* Performance during acts that, after a statement of intention, take place without conscious control as smooth, automated, and highly integrated patterns of behavior.
- *Rule-based behavior:* Performance is consciously controlled by a stored rule or procedure.
- *Knowledge-based behavior:* Performance during unfamiliar situations for which no rules for control are available.

Reason's Categories

Unsafe acts

- Unintended action
 - Slip
 - Lapse
 - Mistake
- Intended violation

Latent conditions

- Weaknesses that exist within a system that create *contexts* for human error beyond the scope of individual psychology.
- They have been found to be significant contributors to incidents.
- Incidents are usually a combination of hardware failures and human errors (latent and active).



J. Reason, Human Error, Cambridge University Press, 1990

Pre-IE ("routine") actions



A.D. Swain and H.E. Guttmann, Handbook of Human Reliability Analysis with Emphasis on Nuclear Power Plant Applications, Report NUREG/CR-1278, US Nuclear Regulatory Commission, 1983.

Post-IE errors

- Models still being developed.
- Typically, they include detailed task analyses, identification of performance shaping factors (PSFs), and the subjective assessment of probabilities.
- PSFs: System design, facility culture, organizational factors, stress level, others.



NUREG/CR-6350, May 1996.





FEED & BLEED COOLING DURING LOOP 1-OF-3 SI TRAINS AND 2-OF-2 PORVS FOR SUCCESS



HIGH PRESSURE INJECTION DURING LOOP 1-0F-3 TRAINS FOR SUCCESS



Cut sets and minimal cut sets

• *CUT SET*: Any set of events (failures of components and human actions) that cause system failure.

• *MINIMAL CUT SET*: A cut set that does not contain another cut set as a subset.



$$X_T = \phi(X_1, X_2, \dots, X_n) \equiv \phi(\underline{X})$$

$\phi(\underline{X})$ is the <u>structure or switching function</u>.

It maps an n-dimensional vector of 0s and 1s onto 0 or 1.

Disjunctive Normal Form:

$$\mathbf{X}_{\mathbf{T}} = 1 - \prod_{1}^{\mathbf{N}} (1 - \mathbf{M}_{\mathbf{i}}) \equiv \prod_{1}^{\mathbf{N}} \mathbf{M}_{\mathbf{i}}$$

Sum-of-Products Form:

$$X_T = \sum_{i=1}^N M_i - \sum_{i=1}^{N-1} \sum_{j=i+1}^N M_j M_j + \dots + (-1)^{N+1} \prod_{i=1}^N M_i$$



MCS:
$$M_1 = \{X_A\}$$
 M2 = $\{X_{B1}, X_{B2}\}$

System Logic	$X_{S} = 1 - (1 - X_{A})(1 - X_{B1}X_{B2}) =$ = X _A + X _{B1} X _{B2} - X _A X _{B1} X _{B2}
Failure Probability	$P(fail) = P(X_A) + P(X_{B1} X_{B2}) - P(X_A X_{B1} X_{B2})$

Example (cont'd)

• In general, we cannot assume independent failures of B₁ and B₂. This means that

 $P(X_{B1} X_{B2}) \ge P(X_{B1}) P(X_{B2})$

• How do we evaluate these dependencies?

Dependencies

- Some dependencies are modeled explicitly, e.g., fires, missiles, earthquakes.
- After the explicit modeling, there is a class of causes of failure that are treated as a group. They are called *common-cause failures*.

Special Issue on Dependent Failure Analysis, *Reliability Engineering and System Safety*, vol. 34, no. 3, 1991.

The Beta-Factor Model

- The β-factor model assumes that commoncause events always involve failure of all components of a common cause component group
- It further assumes that

$$\beta = \frac{\lambda_{\rm CCF}}{\lambda_{\rm total}}$$

Generic Beta Factors



Data Analysis

- The process of collecting and analyzing information in order to estimate the parameters of the epistemic PRA models.
- Typical quantities of interest are:
 - Initiating Event Frequencies
 - Component Failure Frequencies
 - Component Test and Maintenance Unavailability
 - Common-Cause Failure Probabilities
 - Human Error Rates

General Formulation

 $X_T = \varphi(X_1, \dots, X_n) \equiv \varphi(\underline{X})$

$$X_{T} = 1 - \prod_{i=1}^{N} (1 - M_{i}) \equiv \prod_{i=1}^{N} M_{i}$$
$$X_{T} = \sum_{i=1}^{N} M_{i} - \sum_{i=1}^{N-1} \sum_{j=i+1}^{N} M_{i} M_{j} + \dots + (-1)^{N+1} \prod_{i=1}^{N} M_{i}$$

X_T : the TOP event indicator variable (e.g., core melt, system failure)
 M_i : the ith minimal cut set (for systems) or accident sequence (for core melt, containment failure, et al)

TOP-event Probability

$$\begin{split} P(X_T) &= \sum_{1}^{N} P(M_i) + \ldots + (-1)^{N+1} P\left(\prod_{1}^{N} M_i\right) \\ P(X_T) &\cong \sum_{1}^{N} P(M_i) \end{split} \quad \text{Rare-event approximation} \end{split}$$

The question is how to calculate the probability of \boldsymbol{M}_{i}

 $P(M_i) = P(X_k^i \dots X_m^i)$

RISK-SIGNIFICANT INITIATING EVENTS

Risk-Significant Initiating Event	Period	Number of Events	Mean Frequency	Trend	
General Transients	1998 – 2004	2120	7.57E-1		
BWR General Transients	1997 – 2004	699	8.56E-1	ļ	
PWR General Transients	1998 – 2004	1421	7.10E-1	l	
Loss of Feedwater	1993 – 2004	188	9.32E-2		
Loss of Heat Sink	1995 – 2004	259	1.24E-1	ļ	
BWR Loss of Heat Sink	1996 – 2004	154	1.88E-1	ļ	
PWR Loss of Heat Sink	1991 – 2004	105	9.23E-2	ļ	
Loss of Instrument Air (BWR)	1994 – 2004	19	7.60E-3	l	
Loss of Instrument Air (PWR)	1990 - 2004	17	1.19E-2	l	
Loss of Vital AC Bus	1988 – 2004	43	2.98E-2		
Loss of Vital DC Bus	1988 - 2004	3	2.35E-3		
Stuck Open SRV (BWR)	1993 – 2004	14	2.07E-2		
Stuck Open SRV (PWR)	1988 – 2004	2	2.30E-3		
Steam Generator Tube Rupture	1988 – 2004	3	3.48E-3		
Very Small LOCA	1988 – 2004	5	3.92E-3	\leftrightarrow	
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INITIATING EVENT TRENDS PWR General Transients BWR General Transients



PWR Loss of Heat Sink



BWR Loss of Heat Sink

1992

1994

1996

Year



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1998

2000

2002

2004

BLPL Nov. 1, 2005

BWR loss of heat sink, and 90% interval

90% interval (prediction limits)

Fitted line

Maximum likelihood estimate (n/T) (baseline p

INITIATING EVENTS INSIGHTS

- Most initiating events have decreased in frequency over past 10 years.
- Combined initiating event frequencies are 4 to 5 times lower than values used in NUREG-1150 and IPEs.
- General transients constitute majority of initiating events; more severe challenges to plant safety systems are about one-quarter of events.

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ANNUAL LOOP FREQUENCY TREND





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LOOP FREQUENCY INSIGHTS

- Overall LOOP frequency during critical operation has decreased over the years (from 0.12/ry to 0.036/ry)
- Average LOOP duration has increased over the years:
 - Statistically significant increasing trend for 1986–1996
 - Essentially constant over 1997-2004
- 24 LOOP events between 1997 and 2004; 19 during the "summer" period
- No grid-related LOOP events between 1997 and 2002; 13 in 2003 and 2004
- Decrease in plant-centered and switchyard-centered LOOP events; grid events are starting to dominate Department of Nuclear Science and Engineering 40

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SYSTEM RELIABILITY STUDY RESULTS

STUDY	MEAN UNRELIABILITY	UNPLANNED DEMAND TREND	FAILURE RATE TREND	UNRELIABILITY TREND
AFW (1987–2004)	5.19E-4			¢
EDG (1997–2004)	2.18E-2	N/A	N/A	•
HPCI (1987–2004)	6.25E-2			
HPCS (1987–2004)	9.48E-2			$ \qquad \qquad$
HPI (1987–2004)	1.09E-3			$ \Longleftrightarrow $
IC (1987–2004)	2.77E-2			
RCIC (1987–2004)	5.18E-2		Ļ	

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PWR SYSTEM RELIABILITY STUDIES EDG Unavailability (FTS) AFW Unavailability (FTS)



HPI Unreliability (8 hr mission)



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AFW Unreliability (8 hr mission)



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PWR SYSTEM INSIGHTS

- EDG
 - EDG start reliability much improved over past 10 years.
 - Failure-to-run rates lower than in most PRAs.
- AFW
 - Industry average reliability consistent with or better than Station Blackout and ATWS rulemaking.
 - Wide variation in plant specific AFW reliability primarily due to configuration.
 - Failure of suction source identified as a contributor (not directly modeled in some PRAs).
- HPI
 - Wide variation in plant specific HPI reliability due to configuration.
 - Various pump failures are the dominant failure contributor.

BWR SYSTEM RELIABILITY STUDIES

HPCI Unreliability (8 hr mission)



HPCS Unreliability (8 hr mission)



0.08 RCIC unavailability (FTS model) and 90% intervals Fitted model 90% confidence band 0.06 0.04 0.04 0.04 0.04 0.02

RCIC Unavailability (FTS)

RCIC Unreliability (8 hr mission)

1994

1996

Fiscal Year

1998

2000

2002

2004

U01 Sept. 1, 2005



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0.00

1988

I og model p-value = 0.1

1990

1992

BWR SYSTEM INSIGHTS

- HPCI
 - Industry-wide unreliability shows a statistically significant decreasing trend.
 - Dominant Failure: failure of the injection valve to reopen during level cycling.
- HPCS
 - Industry average unreliability indicates a constant trend.
 - Dominant Failure: failure of the injection valve to open during initial injection.
- RCIC
 - Industry average unreliability indicates a constant trend.
 - Dominant Failure: failure of the injection valve to reopen during level cycling.

45

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COMMON-CAUSE FAILURE (CCF) EVENTS

• Criteria for a CCF Event:

- Two or more components fail or are degraded at the same plant and in the same system.
- Component failures occur within a selected period of time such that success of the PRA mission would be uncertain.
- Component failures result from a single shared cause and are linked by a coupling mechanism such that other components in the group are susceptible to the same cause and failure mode.
- Equipment failures are not caused by the failure of equipment outside the established component boundary.

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CCF OCCURRENCE RATE



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Coupling Factors - Complete CCF Events

