PS7 BI

$$\begin{aligned} \mathcal{V}_{a} &= \int_{\tau=\pi_{2}}^{\tau=\pi_{2}} \pi^{2} d\tau \left\{ \int_{\theta=0}^{\theta=\pi} \sin\theta d\theta \left(\int_{0}^{\theta\pi} d\theta \right) \right\} \\ &= \pi \\ \int_{\tau=\pi_{1}}^{\pi} d\theta &= \left[\phi \right]_{0}^{2\pi} = 2\pi \\ \int_{\tau=\pi_{2}}^{\pi} \sin\theta d\theta &= \left[\cos \theta \right]_{0}^{\pi} = 2 \\ &= 0 \\ \int_{\tau=\pi_{2}}^{\pi=\pi_{2}} \pi^{2} d\pi &= \left[\frac{\pi^{3}}{3} \right]_{\pi_{1}}^{\pi_{2}} &= \frac{1}{3} \left(\pi_{2}^{3} - \pi_{1}^{3} \right) \\ &= \frac{1}{3} \left(\pi_{2}^{3} - \pi_{1}^{3} \right) \left\{ 2 \left(2\pi \right) \right\} \\ &= \frac{\mathcal{V}_{a}}{2} = \frac{4\pi}{3} \left(\pi_{2}^{3} - \pi_{1}^{3} \right) \left\{ 2 \left(2\pi \right) \right\} \\ &= \frac{\mathcal{V}_{a}}{2} = \frac{4\pi}{3} \left(6,410^{3} - 6,400^{3} \right) km^{3} \\ &= 5.155 \times 10^{-9} km^{3} \end{aligned}$$

PS7 B2

2. a)
$$\frac{1}{x}$$
 (real) $(\longrightarrow x)$
 $\int_{\alpha_{1}, \alpha_{2}}^{\infty} complex numbers$
 $\int_{\alpha_{1}, \alpha_{2}}^{\alpha_{1}, \alpha_{2}} complex numbers$
 $x (\alpha_{1}\phi_{1}(x) + \alpha_{2}\phi_{2}(x)) = \alpha_{1}(x\phi_{1}(x)) + \alpha_{2}(x\phi_{2}(x))$
thus, $\times \mu$ linear
 $(\phi_{1}|x\phi_{2}) = \int_{\alpha_{1}}^{\alpha_{1}} (\phi_{1}(x))^{*}(x\phi_{2}(x)) dx$
 $= \int_{\alpha_{2}}^{\infty} (\phi_{1}(x))^{*}\phi_{2}(x) dx$ ($x = x^{*}$ because
 $x \mu \alpha neal$
 $= \int_{\alpha_{2}}^{\infty} (x\phi_{1}(x))^{*}\phi_{2}(x) dx$ number)
 $\langle \phi_{1}|x\phi_{2} \rangle = \langle x\phi_{1} | \phi_{2} \rangle$
 $\frac{x \mu hermitian}{1}$
b) [optional] $[x, p_{x}](\longrightarrow [x, -ih\frac{\partial}{\partial x}])$
 $\cdot [x, p_{x}]\phi(x) = [x, -ih\frac{\partial}{\partial x}]\phi(x) - [-ih\frac{\partial}{\partial x}(x\phi(x))]$
 $= -ihx\frac{d}{dx}\phi(x) + ih[\frac{d}{dx}x)\phi(x) + ihx\frac{d}{dx}\phi(x)$
 $\Rightarrow [x, p_{x}]\phi(x) = ih\phi(x)$

PS7 B3

$$\begin{aligned} \alpha_{1}, \alpha_{2} : \operatorname{complex numbers} \quad ; \quad \phi_{1}, \phi_{2} : \operatorname{wavefunchons} \\ E_{3}, p_{2}^{2}] \left[\alpha_{1} \phi_{1}(x) + \alpha_{2} \phi_{2}(x) \right] &= i\hbar \left[\alpha_{1} \phi_{1}(x) + \alpha_{2} \phi_{2}(x) \right] \\ &= \alpha_{1} \left(i\hbar \phi_{1}(x) \right) + \alpha_{2} \left(i\hbar \phi_{2}(x) \right) \\ E_{3}^{2}, p_{2}^{2}] \left[\alpha_{1} \phi_{1}(x) + \alpha_{2} \phi_{2}(x) \right] &= \alpha_{1} \left([x, p_{2}^{2}] \phi_{1}(x) \right) \\ &+ \alpha_{2} \left([x, p_{2}^{2}] \phi_{1}(x) \right) \\ &+ \alpha_{2} \left([x, p_{1}^{2}] \phi_{2}(x) \right) \end{aligned}$$

$$\left\langle \phi_{1} \right| \left[x_{3}^{2}, p_{1}^{2} \right] \phi_{2}^{2} \right\rangle &= \langle \phi_{1} \mid i\hbar \phi_{2} \rangle \\ &= \int (\phi_{1}(x))^{*} i\hbar \phi_{1}(x) dx \\ &= \int (\phi_{1}(x))^{*} i\hbar \phi_{1}(x) dx \\ &= \int (\phi_{1}(x))^{*} i\hbar \phi_{1}(x) dx \\ &= \int (i\hbar \phi_{1}(x))^{*} \phi_{1}(x) dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{2}^{2}] \phi_{2} \rangle &= - \langle [x_{3}^{2}, p_{1}^{2}] \phi_{1} \mid \phi_{2} \rangle \neq \langle E_{3}^{2}, p_{1}^{2}] \phi_{1} \mid \phi_{2} \rangle \\ &= \int (i\hbar \phi_{1}(x))^{*} \phi_{1}(y) dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{1}^{2}] dy dx \\ &= - \int (i\hbar \phi_{1}(x))^{*} \phi_{1}(y) dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{1}^{2}] dy dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{1}^{2}] dy dx \\ &= - \langle [x_{3}^{2}, p_{1}^{2}] \phi_{1} \mid \phi_{2} \rangle \neq \langle E_{3}^{2}, p_{1}^{2}] \phi_{1} \mid \phi_{2} \rangle \\ &= \int (i\hbar \phi_{1}(x))^{*} \phi_{2}(y) dx \\ &= \int (i\hbar \phi_{1}(x))^{*} \phi_{2}(y) dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{1}^{2}] dy dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{2}^{2}] dy dy dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{2}^{2}] dy dy dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{2}^{2}] dy dy dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{2}^{2}] dy dy dx \\ \langle \phi_{1} \mid [x_{3}^{2}, p_{2}^{2}] dy dy dy dy \\ \langle \phi_{1} \mid [x_{3}^{2}, \phi_{2}^{2}] dy dy dy \\ \langle \phi_{1} \mid [x_{3}^{2}, \phi_{2}^{2}] dy dy dy \\ \langle \phi_{1} \mid [x_{3}^{2}, \phi_{2}^{2}] dy dy dy \\ \langle \phi_{1} \mid [x_{3}^{2}, \phi_{2}^{2}] dy dy dy \\ \langle \phi_{1} \mid [x_{3}^{2}, \phi_{2}^{2}] dy dy dy \\ \langle \phi_{1} \mid [x_{3}^{2}, \phi_{2}^{2}] dy dy \\ \langle \phi_{1} \mid$$

$$\langle \phi_{1} | i \frac{d^{2}}{dx^{2}} \phi_{2} \rangle = \int (\phi_{1}(x))^{*} (i \frac{d^{2}}{dx^{2}} \phi_{2}(x))$$

$$= i \int_{-\infty}^{-\omega_{1}+\omega_{2}} (\phi_{1}(x))^{*} \frac{d^{2}}{dx^{2}} \phi_{2}(x)$$

$$= i \int_{-\infty}^{-\omega_{1}+\omega_{2}} (\phi_{1}(x))^{*} \frac{d^{2}}{dx^{2}} \phi_{2}(x)$$

$$= i \int_{-\infty}^{-\omega_{1}+\omega_{2}} (\phi_{1}(x))^{*} \frac{d^{2}}{dx} \phi_{2}(x)$$

$$= i \int_{-\infty}^{-\omega_{1}+\omega_{2}} (\phi_{1}(x))^{*} \frac{d^{2}}{dx} \phi_{2}(x)$$

$$= \int_{-\infty}^{-\omega_{1}+\omega_{2}} (\phi_{1}(x))^{*} \frac{d}{dx} \phi_{2}(x)$$

$$= \int_{-\infty}^{-\omega_{1}+\omega_{2}} (\phi_{1}(x))^{*} \frac{d}{dx} \phi_{2}(x)$$

$$= -i \left(0 - - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left(0 - - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left(0 - - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left(0 - - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left(0 - - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left(0 - - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left(0 - - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left(0 - - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left(0 - \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx} \right)$$

$$= -i \left\langle \frac{d}{dx} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle \frac{dx}{dx}$$

$$= -i \left\langle \frac{d^{2}}{dx^{2}} \phi_{1} \right| \frac{d}{dx} \phi_{2} \right\rangle$$

$$= -i \left\langle \frac{d^{2}}{dx^{2}} \phi_{1} \right| \frac{dy}{dx} \right\rangle$$

$$= -i \left\langle \frac{d^{2}}{dx^{2}} \phi_{1} \right| \frac{dy}{dx} \right\rangle$$

$$= -i \left\langle \frac{d^{2}}{dx^{2}} \phi_{1} \right| \frac{dy}{dx} \right\rangle$$

 $\Rightarrow \langle i \frac{d^2}{dx^2} \phi_1 | \phi_2 \rangle = +i \langle \frac{d}{Jx} \phi_1 | \phi_2 \rangle (I) (integration by$ from (I) & (II) we conclude $\left(\langle \phi_1 | i \frac{d^2}{dx^2} \phi_2 \rangle \neq \langle i \frac{d^2}{dx^2} \phi_1 | \phi_2 \rangle$ $\frac{1}{dx^2}$ et not hermitian. 3. [optional] Since $\int L_{x} = \hat{y} \hat{p}_{3} - \hat{3} \hat{p}_{y}$ [Py $\left| \left[L_{2}, \hat{p_{y}} \right] \right| = \left[\hat{y} \hat{p_{3}} - \hat{3} \hat{p_{y}}, \hat{p_{y}} \right]$ $=(\hat{y}\hat{\beta}\hat{\beta}\hat{-3}\hat{p}\hat{y})\hat{p}\hat{y}\hat{-}\hat{p}\hat{y}(\hat{y}\hat{\beta}\hat{\beta}\hat{-3}\hat{p}\hat{y})$ $\begin{bmatrix} \hat{L}_{x}, \hat{p}_{y} \end{bmatrix} = \hat{g}\hat{p}\hat{g}\hat{p}_{y} - \hat{g}\hat{p}\hat{g}^{2} - \hat{p}\hat{g}\hat{g}\hat{p}\hat{g} + \hat{p}\hat{g}\hat{g}\hat{p}\hat{g} \quad (\Pi)$ · To calculate [Lx, py] it is convenient to introduce \$(x, y, 3) $[L_{x}, \hat{p}_{y}]\phi(x, y_{3}) = \begin{cases} y \frac{\hbar}{i} \frac{\partial}{\partial z_{1}} \frac{\hbar}{i} \frac{\partial}{\partial y_{1}} - 3 \frac{\hbar}{i} \frac{\partial}{\partial y_{1}} \frac{\hbar}{i} \frac{\partial}{\partial y_{1}} \end{cases}$ $-\frac{\hbar^2}{i \partial y} y \frac{\hbar^2}{i \partial z} + \frac{\hbar^2}{i \partial y} \partial \frac{\hbar^2}{i \partial y} \Big] \phi(x, y, z)$ (cours pondence pounciple) PS7 B6

 $\begin{bmatrix} L_{x}, p_{y} \end{bmatrix} \phi(x, y, 3) = \left(y \frac{\hbar}{i} \frac{2}{3} \frac{\hbar}{i} \frac{3}{3y} - \frac{\hbar}{i} \frac{2}{3y} \frac{2}{3y} \right) \phi(x, y, 3)$ $+\left(-3\frac{\hbar}{1}\frac{\partial}{\partial y}\frac{\pi}{1}\frac{\partial}{\partial y}+\frac{\hbar}{1}\frac{\partial}{\partial y}(3\frac{\hbar}{1}\frac{\partial}{\partial y})\phi(x,y,3)\right)$ $\begin{bmatrix} \hat{L}_{x}, \hat{p}_{y} \end{bmatrix} \phi(x, y, 3) = \begin{pmatrix} y & \hat{h} & \hat{g} & \hat{h} & \hat{g} \\ y & \hat{i} & \hat{g} & \hat{j} & \hat{g} \\ y & \hat{i} & \hat{g} & \hat{j} & \hat{g} \\ \hat{i} & \hat{g} & \hat{j} \\ \hat{i} & \hat{g} & \hat{i} \\ \hat{i} & \hat{g} & \hat{i} & \hat{g} \\ \hat{i} & \hat{j} \\ \hat{i} & \hat{g} & \hat{i} & \hat{g} \\ \hat{i} & \hat{j} \\ \hat{i} & \hat{i} & \hat{j} \\ \hat{i} & \hat{i} & \hat{j} \\ \hat{i} & \hat{i} & \hat{i} & \hat{i} & \hat{i} \\ \hat{i} & \hat{i} & \hat{i} & \hat{i} & \hat{i} \\ \hat{i} & \hat{i} \\ \hat{i} & \hat{i} &$ $= -\frac{\hbar}{i} \left\{ \frac{\hbar}{i} \frac{\theta}{33} \phi(x,y,3) \right\}$ $= -\frac{\hbar}{i} \left\{ \hat{p}_{3} \phi(x) = i \hbar \hat{p}_{3} \phi(x) \right\}$ Consequently [Las Py] = 2hp3

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4. Summarize the steps that allows us to obtain sphorical harmonics as solutions of the eigenvalue equation for the expectation values of \tilde{T}^2 * Hydrogen atom eigenfunctions (2-body central force system) $(\Psi = \Psi_c(X, Y, Z) \Psi(x, y, 3)$ $\Psi = \Psi_c(X,Y,Z) R_{2\ell}(z) Y_{en}(\theta,\phi)$ $\Psi = \Psi_c(X,Y,Z) R(\eta) \Theta(\theta) \Phi(\phi)$ where $\int X = \frac{m_e x_e + m_n x_n}{M} \approx x_n$ $(m_n \gg m_e)$ $Y = \frac{m_e y_e + m_n y_n}{M} \approx y_n$ $Z = \frac{m_e z_e + m_n z_n}{M} \approx z_n$ (centur - of - mass coordinates) $M = m_e + m_n$ (total mass) $\chi = \chi_e - \chi_n$ $y = y_e - y_n$ y = 3e - 3n(fictions particle coordinates /relative coordinates) 3 = 3e In $\mu = \frac{m_e m_n}{m_e + m_n}$ - ~ me (reducedmass) Vc : center-of-mass wavefunction & wavefunction of the D. D. to lies nuclus which satisfies $\hat{\mathcal{H}}_{c} \Psi_{c} = -\frac{\hbar^{2}}{2M} \left(\frac{\partial^{2}}{\partial X^{2}} + \frac{\partial^{2}}{\partial Y^{2}} + \frac{\partial^{2}}{\partial Z^{2}} \right) \Psi_{c} = E_{c} \Psi_{c}$ PS7B8

· Vinelative wavefunction ~ wavefunction of the electron $\hat{H_2} = -\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \psi + \mathcal{O}(\sqrt{x^2 + y^2 + z^2}) \psi = E_{\pi} \psi$ $\hat{H}_{2}\Psi = -\frac{\hbar^{2}}{2\mu}\left(\frac{1}{\pi^{2}}\frac{\partial}{\partial \tau}\left(\pi^{2}\frac{\partial\Psi}{\partial \tau}\right)\right) + \frac{1}{\pi^{2}}\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial\Psi}{\partial\theta}\right)$ $+\frac{1}{\pi^2}\frac{1}{\sin^2\theta}\frac{g^2\psi}{\partial\phi^2}+\mathcal{O}(\pi)\psi=E_{\pi}\psi$ $\begin{pmatrix} \left(\begin{array}{c} \Psi = \Psi_{c} \Psi = \cdot total \ wavefunction \ of the system \ \left(\begin{array}{c} E = E_{c} + E_{n} = total \ energy \ of the system \ R : naolial part of \ \Psi \end{pmatrix}$ $-\frac{\hbar}{2\mu}\left(\frac{1}{n^2}\frac{d}{dr}\left(\frac{n^2}{dr}\frac{d}{dr}R\right)\right) + \frac{\hbar^2 K}{2\mu n^2}R + \mathcal{O}(r)R = E_{R}R$ Y: angular part of 4 $-\frac{\hbar^2}{sin\partial\theta}\left(\frac{1}{\theta}\left(\frac{\partial}{\partial\theta}\left(\frac{\partial in\theta}{\partial\theta}\right) + \frac{1}{\partial\theta}\left(\frac{\partial^2 Y}{\partial\theta^2}\right) + \frac{1}{\partial\theta^2}\right) + \frac{1}{\partial\theta}\left(\frac{\partial^2 Y}{\partial\theta^2}\right) = \frac{\hbar^2 K Y}{sin^2\theta}$ $\frac{\Lambda^2}{L}Y = \frac{\hbar^2 K Y}{K}$ (I) K constant (eigenvalue of the square of the angular momentum operator)

PS7 B9

* To solve the expensative equation (I), we porform a separation of variables: $Y = \Theta(\Theta) \overline{\Phi}(\phi)$ We obtain : $\frac{1}{\Theta} \frac{1}{\sin \Theta} \frac{1}{2\Theta} \left(\sin \Theta \frac{1}{2\Theta} \right) + \frac{1}{\sin^2 \Theta} \frac{1}{\Phi} \frac{1}{2\phi^2} \Phi = -K$ $\frac{1}{\Theta} \sin \Theta \frac{d}{d\Theta} \left(\sin \Theta \frac{d\Theta}{d\Theta} \right) + K \sin^2 \Theta + \frac{1}{\Phi} \frac{d^2}{d\phi^2} \Phi = 0$ \$ - dependent 0 - dependent Consequently : $\int \frac{d^2 \Phi}{d\phi^2} = -C \Phi$ C constant $\sin \Theta \frac{d}{\partial \Theta} \sin \Theta \frac{d(H)}{d \Theta} + K \sin^2 \Theta (H) = + C(H)$ $\implies \left(\overline{\Phi}(\phi) \right) = A e^{iC'^{2}\phi} + B e^{-iC'^{2}\phi}$ (A, B constant) (\$ is 2TT - poriodic) $\Phi(2\pi) = \Phi(0)$ Thus C^{1/2} is an interest C^{1/2} = m (m=0,1,2,...) $\Phi = Ae^{im\phi} + Be^{-im\phi}$ $\begin{cases} \sin \theta \stackrel{d}{=} \sin \theta \stackrel{d}{=} \frac{d (H)}{d \theta} + K \sin^2 \theta (H) = m^2 (H) \\ (I) \end{cases} \begin{cases} m = 0, 1, 2 \dots \\ K \text{ constant} \end{cases}$ $Y = (H)(\Theta) \overline{\Phi}(\phi)$

* To solve (I), we introduce the following change of variables

$$g = \cos \theta \qquad P(g) = (P(\Phi)) = P(\cos \theta)$$

$$\begin{cases} \sin \theta = \sqrt{1-y^2} \qquad (0 \leqslant \theta \leqslant \pi) \\ \frac{d}{d\theta} = -\sin \theta \frac{d}{d(\cos \theta)} = -\sqrt{1-y^2} \frac{d}{dy} \end{cases}$$
(I) is thus rewritten as
$$\begin{bmatrix} (1-y^2) \frac{d^2 P}{dy^2} - \frac{2y}{dy} \frac{dP}{dy} - \frac{m^2}{1-y^2} P + KP = 0 \quad (II) \\ \frac{d}{d\theta} = -\sin \theta \frac{d}{d\theta} = -\sin^2 \theta \frac{d}{d(\cos \theta)} \quad (-\sin^2 \theta) \frac{dP}{d\phi} \end{bmatrix}$$

$$= + (1+y^2) \frac{d}{dy} (1-y^2) \frac{dP}{dy} = \frac{1}{d\theta} \qquad (-\sin^2 \theta) \frac{dP}{d\phi} = -\sin^2 \theta \frac{d}{d(1-y^2)} \frac{dP}{dy} = \frac{1}{d\phi} \qquad (1-y^2) \frac{dP}{dy} = \frac{1}{d\phi} \qquad (1-y^2) \frac{dP}{d\phi} = -\sin^2 \theta \frac{d}{d\phi} \qquad (1-y^2) \frac{dP}{d\phi} = \frac{1}{d\phi} \qquad (1-y^2) \frac{dP}{d\phi} + K P - m^2 P \end{bmatrix}$$
(#)
$$F_{0} = -m^2 P$$
(#)
$$F_{0} = \cos \theta = \frac{1}{d\theta} = \frac{1}{d\theta} \qquad (1-y^2) \frac{dP}{d\phi} + K P - m^2 P \end{bmatrix}$$

$$The solutions of (II) ore known as the associated Legendre function of the theorem constant for the theorem to theorem to the theorem to the theorem to the theorem to theo$$

The corresponding expensature K equals l(l+1) (l'enteger) Moreover we' admit that (II) can be solved only if m < l $\overline{\Phi} = Ae^{im\phi} + Be^{-im\phi}; \quad (m = 0, 1, 2..., (l-1), l)$ * То лит ир $\mathcal{P}_{em} = \mathcal{D} P_e^{m}(y) \quad ; \quad (\ell = 0, 1, 2, \dots)$ $Y = \bigoplus(\Phi) \oint(\phi) ; \quad \vec{L}^{2} Y = \hbar^{2} l(l+1) Y$

THERMODYNAMICS

- 1. **single-component phase diagrams**. Shown below is a hypothetical phase diagram for a single-component closed system. Answer the following questions about this diagram:
 - a. Apply the phase rule to each of the marked locations 1, 2, and 3, and determine whether those points on the diagram correctly mark stable equilibria.
 - b. Is the molar volume change of transformation $\Delta \overline{V}_{\alpha \rightarrow gas}$ for the transformation of solid α to the gas phase positive or negative?
 - c. For the fixed pressure P', draw a qualitative plot of the Gibbs free energy of this material for each phase as a function of temperature over the range shown.



(a) The Gibbs phase rule for single-component phase diagrams is: D + P = C + 2

Since the number of components C = 1, we have: D + P = 3

The number of degrees of freedom (D) added to the number of phases present (P) must be = 3 for a stable equilibrium.

Examining the marked points on the diagram:

- (1) a 3-phase field- a region with two degrees of freedom (temperature and pressure can be varied independently within the field and the same equilibrium is maintained). Plugging into the phase rule:
 - D + P = 2 + 3 = 5

...thus this is definitely **not** a stable equilibrium.

(2) Point 2 marks the intersection of three single-phase regions: it is a triple point where liquid, gas, and the solid phase b are in equilibrium at a single temperature and pressure: D

$$+ P = 0 + 3 = 3$$

...this phase equilibrium is stable.

(3) Point 3 marks liquid-solid b equilibrium, with one degree of freedom- if the temperature is changed, the pressure required to maintain the two-phase equilibrium is predetermined. Likewise, if the pressure is changed, the temperature is predetermined:

$$D + P = 1 + 2 = 3$$

...this is a stable phase equilibrium.

(b) The Clausius-Clapevron equation relates the slope of the pressure vs. temperature phase boundary to the enthalpy change, temperature, and volume change at a phase transition:

$$\frac{dP}{dT}\Big|_{equilibrium} = \frac{\Delta \overline{H}_{trans}}{T_{trans}\Delta \overline{V}_{trans}}$$

The enthalpy change of first-order phase transitions must be positive (remember, the entropy is always increasing with temperature for stability, and at a phase transition $\Delta \overline{H}_{trans} = T_{trans} \Delta \overline{S}_{trans}$; absolute temperature must be positive therefore enthalpy changes at the transition must be positive). Since the enthalpy change and Ttrans are positive, the sign on the phase transition volume change is the same as the sign of the slope of the P vs. T phase boundary. Looking at the phase diagram, we see that along the α /gas phase boundary, the pressure increases as temperature increasesdP/dT is positive. Thus, the volume change on transformation of solid α to gas is positive.

(c). Using the information from the phase diagram, we can construct the following gualitative diagram:



...the diagram must exhibit: (1) negative slope and curvature for each free energy curve (requirements for stability), and (2) free energy curves of phases cross at points of two-phase equilibrium; the stable phase at each temperature must exhibit the lowest free energy.

- Free energy behavior of solutions [DJI1][DJI2]. Shown on the following page is a diagram of free energies for a two-component A-B system at a fixed temperature of 500 K and fixed pressure of 1 atm. This system exists in 3 different phases- liquid, and two solid phases α and β. Two copies of the diagram are provided to sketch on. Use this diagram to answer the questions below:
 - a. Using the top copy of the free energy diagram, draw common tangents that identify composition regions of two-phase equilibrium at this temperature and pressure. Draw a 'composition bar' at the bottom of the diagram as in lecture, and denote which phases are present as a function of composition.
 - b. At the composition marked X' on the diagram, the system is in equilibrium with 2 phases in coexistence.
 - i. What two phases are present?
 - ii. What are the phase fractions, in terms of parameters given on the diagram?
 - iii. What is the composition of each phase that is present?
 - c. On the lower copy of the phase diagram, draw constructions or mark points as necessary to identify the following quantities for a system with composition X':
 - i. The chemical potential of A in each phase, and B in each phase present.

- ii. The standard state chemical potential of A and B in each phase present.
- (a) See diagram below.
- (b) (i) Liquid and solid α .
 - (ii) To identify the relevant compositions, points X_B^{α} and X_B^{L} are marked on the top free energy diagram below. Applying the lever rule:

$$f^{\alpha} = \frac{\left(X_{B}^{L} - X'\right)}{\left(X_{B}^{L} - X_{B}^{\alpha}\right)}$$
$$f^{L} = \frac{\left(X' - X_{B}^{\alpha}\right)}{\left(X_{B}^{L} - X_{B}^{\alpha}\right)}$$

(iii) The compositions are given by the points where the common tangent touches each free energy curve:

Liquid has composition X_B^L Solid a has composition X_B^{α}

(c) See the diagram below. We must extrapolate the free energy curves to get the intercepts with the $X_B = 0$ and $X_B = 1$ axes for the standard state chemical potentials.

