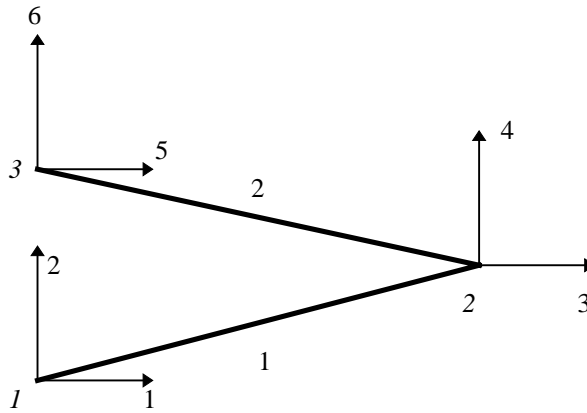


Global numbering of nodes (*italics*), elements, and degrees of freedom (numbers on vectors):



Form element stiffness matrix from column vectors (see text p. 56):

```
with(linalg); a1:=matrix(4,1,[-c,-s,c,s]);a2:=matrix(1,4,[-c,-s,c,s]);
```

$$a1 := \begin{bmatrix} -c \\ -s \\ c \\ s \end{bmatrix}$$

$$a2 := [-c \quad -s \quad c \quad s]$$

Multiply these to get element stiffness matrix of Eq. 2.10:

```
k:=evalm( (A*E/L) * a1 &* a2 );
```

$$k := \begin{bmatrix} \frac{A E c^2}{L} & \frac{A E c s}{L} & -\frac{A E c^2}{L} & -\frac{A E c s}{L} \\ \frac{A E c s}{L} & \frac{A E s^2}{L} & -\frac{A E c s}{L} & -\frac{A E s^2}{L} \\ -\frac{A E c^2}{L} & -\frac{A E c s}{L} & \frac{A E c^2}{L} & \frac{A E c s}{L} \\ -\frac{A E c s}{L} & -\frac{A E s^2}{L} & \frac{A E c s}{L} & \frac{A E s^2}{L} \end{bmatrix}$$

Trigonometric relations

```
c:=cos(theta);s:=sin(theta); theta:=arctan((y[2]-y[1])/(x[2]-x[1]));
```

$$c := \cos(\theta)$$

$$s := \sin(\theta)$$

$$\theta := \arctan\left(\frac{y_2 - y_1}{x_2 - x_1}\right)$$

Nodal coordinates of element 1

```
x[1]:=0;y[1]:=0;x[2]:=1.5;y[2]:=.25;
```

Set precision, get length

```
Digits:=4;L:=sqrt((x[2]-x[1])^2 + (y[2]-y[1])^2 );
```

$$L := 1.521$$

Define area and modulus (unprotecting E this way is dangerous)

$$A := 3.142e-4; \text{unprotect}(E); E := 210e9;$$

$$A := .0003142$$

$$E := .210 \cdot 10^{12}$$

Evaluate stiffness matrix, save as k1

$$k1 := \text{map}(\text{eval}, k);$$

$$k1 := \begin{bmatrix} .4221 \cdot 10^8 & .7035 \cdot 10^7 & -.4221 \cdot 10^8 & -.7035 \cdot 10^7 \\ .7035 \cdot 10^7 & .1173 \cdot 10^7 & -.7035 \cdot 10^7 & -.1173 \cdot 10^7 \\ -.4221 \cdot 10^8 & -.7035 \cdot 10^7 & .4221 \cdot 10^8 & .7035 \cdot 10^7 \\ -.7035 \cdot 10^7 & -.1173 \cdot 10^7 & .7035 \cdot 10^7 & .1173 \cdot 10^7 \end{bmatrix}$$

Redefine nodal coordi , for element 2

$$x[1] := 1.5; y[1] := -.25; x[2] := 0; y[2] := .5;$$

Reevaluate stiffness matrix, save as k2

$$k2 := \text{map}(\text{eval}, k);$$

$$k2 := \begin{bmatrix} .4221 \cdot 10^8 & -.7035 \cdot 10^7 & -.4221 \cdot 10^8 & .7035 \cdot 10^7 \\ -.7035 \cdot 10^7 & .1173 \cdot 10^7 & .7035 \cdot 10^7 & -.1173 \cdot 10^7 \\ -.4221 \cdot 10^8 & .7035 \cdot 10^7 & .4221 \cdot 10^8 & -.7035 \cdot 10^7 \\ .7035 \cdot 10^7 & -.1173 \cdot 10^7 & -.7035 \cdot 10^7 & .1173 \cdot 10^7 \end{bmatrix}$$

Define global stiffness matrix

$$K := \text{matrix}(6, 6, [[k1[1,1], k1[1,2], k1[1,3], k1[1,4], 0, 0], [k1[2,1], k1[2,2], k1[2,3], k1[2,4], 0, 0], [k1[3,1], k1[3,2], k1[3,3]+k2[1,1], k1[3,4]+k2[1,2], k2[1,3], k2[1,4]], [k1[4,1], k1[4,2], k1[4,3]+k2[2,1], k1[4,4]+k2[2,2], k2[2,3], k2[2,4]], [0, 0, k2[3,1], k2[3,2], k2[3,3], k2[3,4]], [0, 0, k2[4,1], k2[4,2], k2[4,3], k2[4,4]]]);$$

$$K := \begin{bmatrix} .4221 \cdot 10^8 & .7035 \cdot 10^7 & -.4221 \cdot 10^8 & -.7035 \cdot 10^7 & 0 & 0 \\ .7035 \cdot 10^7 & .1173 \cdot 10^7 & -.7035 \cdot 10^7 & -.1173 \cdot 10^7 & 0 & 0 \\ -.4221 \cdot 10^8 & -.7035 \cdot 10^7 & .8442 \cdot 10^8 & 0 & -.4221 \cdot 10^8 & .7035 \cdot 10^7 \\ -.7035 \cdot 10^7 & -.1173 \cdot 10^7 & 0 & .2346 \cdot 10^7 & .7035 \cdot 10^7 & -.1173 \cdot 10^7 \\ 0 & 0 & -.4221 \cdot 10^8 & .7035 \cdot 10^7 & .4221 \cdot 10^8 & -.7035 \cdot 10^7 \\ 0 & 0 & .7035 \cdot 10^7 & -.1173 \cdot 10^7 & -.7035 \cdot 10^7 & .1173 \cdot 10^7 \end{bmatrix}$$

Solve for unknown displacements - expand rows 3 and 4 of system (dof 1,2,5,6 known to have zero displacement):

$$\text{row3} := K[3,3]*u[3] + K[3,4]*u[4] = 0; \text{row4} := K[4,3]*u[3] + K[4,4]*u[4] = -2000;$$

$$\text{row3} := .8442 \cdot 10^8 u_3 = 0$$

$$\text{row4} := .2346 \cdot 10^7 u_4 = -2000$$

Solve for unknown displacements:

solve({row3,row4},{u[3],u[4]});

$$\{u_3 = 0, u_4 = -.0008526\}$$

Solve for unknown forces from **f=KU**:

Left-hand side (displacement) vector:

U:=matrix(6,1,[0,0,0,-.0008526,0,0]);

$$U := \begin{bmatrix} 0 \\ 0 \\ 0 \\ -.0008526 \\ 0 \\ 0 \end{bmatrix}$$

Form **KU** product to get right-hand side (force) vector

'f'=evalm(K*U);

$$f = \begin{bmatrix} 5998. \\ 1000. \\ 0 \\ -2000. \\ -5998. \\ 1000. \end{bmatrix}$$

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3.11 Mechanics of Materials

Fall 1999

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