

Solutions

9.1 a) For each surface of the film, $H_{\text{magstat}} = -(1/2)M = -M_s \cos\theta$, so $H_{\text{magstat}} = -M$.

$$f_{\text{magstat}} = -\mu_0 M_s \cdot H_{\text{magstat}}$$

$$f = -\mu_0 M_s H \cos\theta + (\mu_0/2) M_s^2 \cos^2\theta$$

$\partial f/\partial\theta = 0$ gives: $H = M_s \cos\theta = M_{\perp}$ (after division by $\sin\theta$, which is zero only at and above saturation). Thus:

$$H/M_s = M_{\perp}/M_s = m$$

The system saturates when $H = M_s = 1.27$ MA/m or when $B = B_s = 1.6$ T

b) [111] is the easy axis, so the only anisotropy is shape. Answer is same as a)

$$\text{but } H_a = H_{\text{magstat}} = -NM \text{ with } N = 1/3 \text{ instead of } 1. \quad m = 3H/M_s$$

Saturation is achieved at $(1/3) \mu_0 M_s \approx 0.2$ T.

9.2 Putting $m = 1$ in Eq. 9.13 gives $\sin 2\theta_0 = 0$ which can only be satisfied for $\theta_0 = 0$ or $\pi/2$. So the $m(H)$ curves in Fig. 9.3 never reach $m = 1$ except for the two limiting cases, for $\theta_0 = 0$ or $\pi/2$.

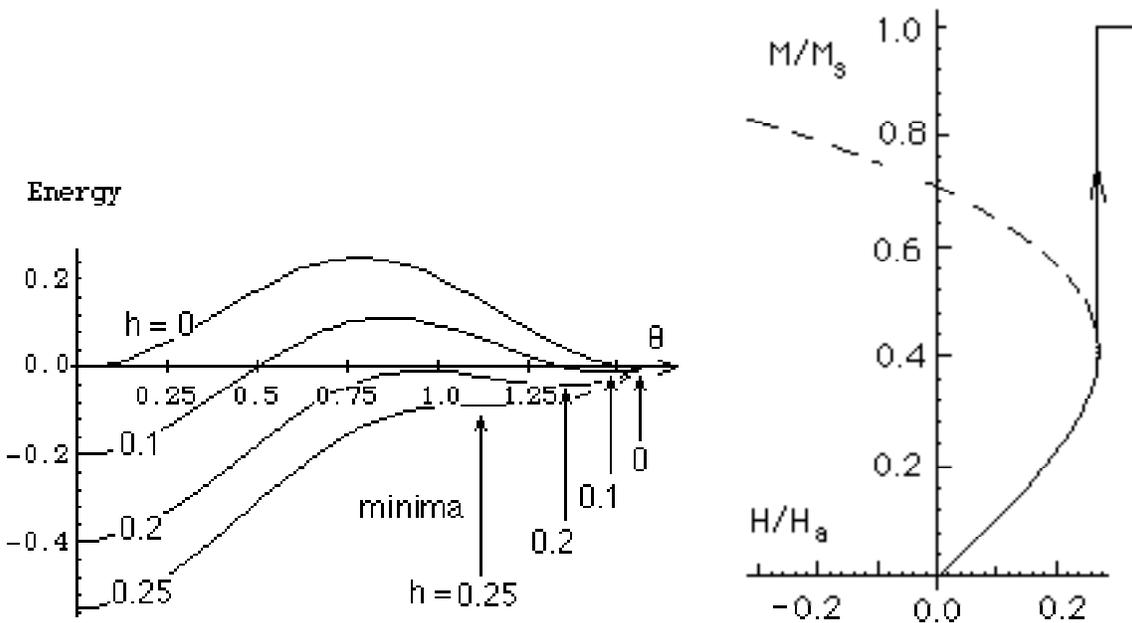
9.3 The energy density, $f = K_1 \sin^2\theta \cos^2\theta - M_s H \cos\theta$, is plotted below. f is minimized for the equation of motion: $(m - 2m^3) - h = 0$, where $h = M_s H/2K_1$. This cubic equation may have up to three different solutions. The physically meaningful one(s) can be discerned by considering the energy as a function of θ .

The equilibrium orientation θ_0 decreases toward zero, i.e. $m = \cos\theta$ increases as H increases. At a field $h \approx 0.25$, the energy minimum near $\theta = 1.2$ vanishes and the magnetization may jump abruptly to $\theta = 0$, $m = 1$.

The calculated form of m versus h is shown. The discontinuous change in m is a first order transition; it corresponds to what is called a *switching field*. It can be

determined from the derivatives of the equation of motion, either $\partial h/\partial m = 0$ or $\partial m/\partial h = \infty$. Thus, the critical magnetization at switching is given by: $1 - 6m_c^2 = 0$. Thus $m_c = 0.408\dots$ (or $\theta_c = 66^\circ$) which occurs for $h_c = 2/(3\sqrt{6}) = 0.272\dots$

Fig. for Sol. 9.3. Left, normalized energy density as a function of θ (radians) for different values of reduced field, $h = H/H_a$. Shift in equilibrium orientation with h is indicated. Right, calculated $m-h$ behavior: m increases with increasing h then at $m_c = 0.408$, jumps to $m = 1.0$. The dashed line in the $m-h$ curve shows the continuation of the mathematical solution. Note that the initial slope $\partial m/\partial h)_0 = 1$ or $\partial M/\partial H = M_s/H_a$ gives the value for the anisotropy field H_a . Thus, the value of K_1 can be determined by measuring $m(h)$ and using either the initial slope or the critical field h_c .



Prob. 9.3. Left, normalized energy density as a function of θ (radians) for different values of reduced field, $h = H/H_1$. Shift in equilibrium orientation with h is indicated. Right, calculated $m-h$ behavior: m increases with increasing h then jumps to $m = 1.0$ at $m_c = 0.408$.

9.4 The energy density is $f = -M_s B_o \cos\theta + K_1 \cos^2 2\theta + B_1 e_{xx} (\cos^2\theta - \nu \sin^2\theta)$

$\partial f / \partial \theta = 0$ gives $m[8K_1(2m^2 - 1) + 2B_1 e_{xx}(1 + \nu)] = M_s B_o$ where $m = \cos\theta$ and $1 - m^2 = \sin^2\theta$. For $e_{xx} = 0$ this gives the result sketched as the solid line: $m_r = 1/\sqrt{2}$, saturation ($m = 1$) occurs at $H = (8K_1/\mu_o M_s) = H_a$.

For $B_1 e_{xx} > 0$, $m_r < 1/\sqrt{2}$

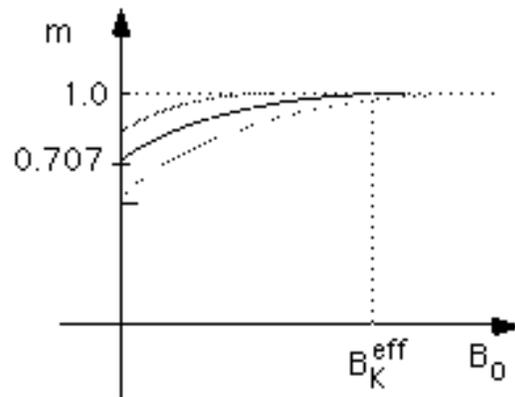
$$B_1 e_{xx} < 0, m_r > 1/\sqrt{2},$$

and $H_a = [8K_1 + 2B_1 e_{xx}(1 + \nu)]/(\mu_o M_s)$.

Thus, saturation occurs at higher fields

for $B_1 e_{xx} > 0$ and lower fields for

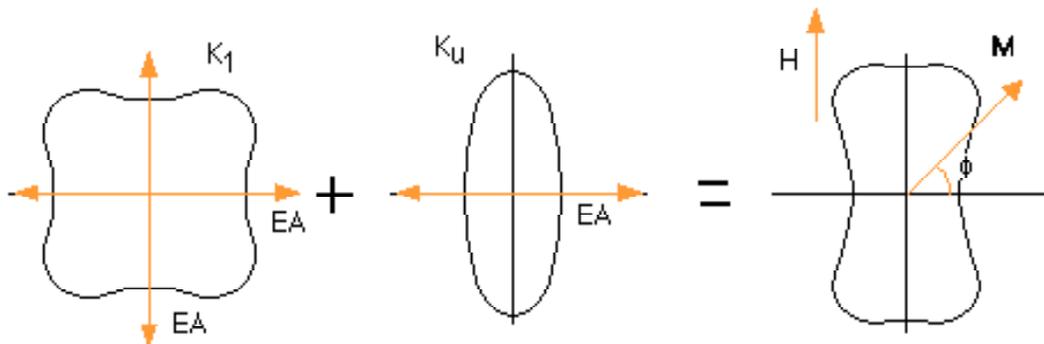
$B_1 e_{xx} < 0$.



9.5. a) From Eq. 6.6, setting $\theta = 90^\circ$, we have

$$f = K_u \sin^2 \phi + (K_1/4) \sin^2 2\phi. \quad -\mu_o M_s H \sin \phi.$$

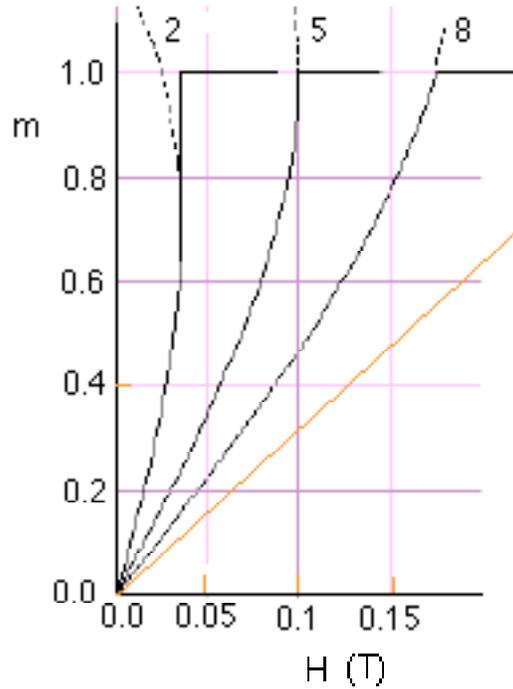
b) Energy surfaces:



c) Zero torque gives $2K_u \sin\phi \cos\phi + K_1 \sin 2\phi \cos 2\phi = \mu_0 M_s H \cos\phi$. Divide by $\cos\phi$ which is zero only at and above saturation. The parameter of interest is the component of magnetization along the field direction, $\sin\phi$, which we define as m . The equation of motion is then expressed:

$$2K_u m + 2K_1 m(1 - 2m^2) = \mu_0 M_s H$$

d) Numerical solutions are shown at the right for three values of the ratio of uniaxial to cubic anisotropy constants, $K_u/K_1 = 2, 5$ and 8 . $K_1 = 10^4 \text{ J/m}^3$ and the field scale is $\mu_0 H$ (T). Note that for $K_u/K_1 = 5$, the infinite slope point occurs at $m = 1$. For smaller K_u , the magnetization shows a discontinuity as was found in Prob. 9.3. For larger K_u , the m - h curve approaches a linear form typical of pure uniaxial, hard-axis magnetization.



9.7 Coercivity goes inversely as permeability. More exactly H_c is proportional to $(K_u + (3/2)\lambda_s \sigma)/\mu_0 M_s$. In amorphous materials there is no magnetocrystalline anisotropy so K is very small. The coercivity then vanishes or goes through a minimum when magnetostriction vanishes.

9.9. $g = 2.11$.