Algorithms red in tooth and claw

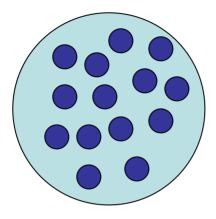
Evolutionary computation for design

Simon Greenwold MIT 10.27.04 A family of optimization techniques that share

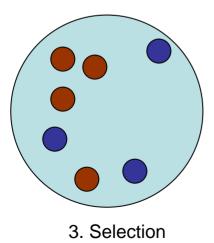
- 1) Genetic inheritance
- 2) A fitness metric (objective function)
- 3) Struggle for survival and reproduction

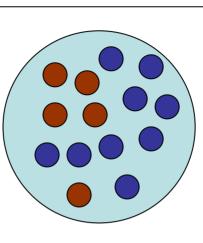
Nothing here indicates that it has any value for designers

The fundamentals

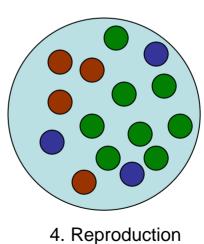


1. Population of individuals (solutions)





2. Evaluation of fitness



Repeat...

Evolutionary computation for design

History

A branch of A-Life Arises from Artificial Intelligence

Strong AI: we can model intelligence

Weak AI: we can produce the effect of intelligence

A-Life: perhaps we can't even engineer intelligence

		PROJECT MAC			
		PRODUCT PAR	1		
Artificial Int	telligence Group			July 7, 19	66
Vision Memo. 1	No. 100.				
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effectively 1	n the constructio	n of a sign	ificant	part of a t	visual system
	r task was chosen	partly bea	ause it	can be segn	mented into
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	which will allow	individuals	to work	independen	ntly and yet
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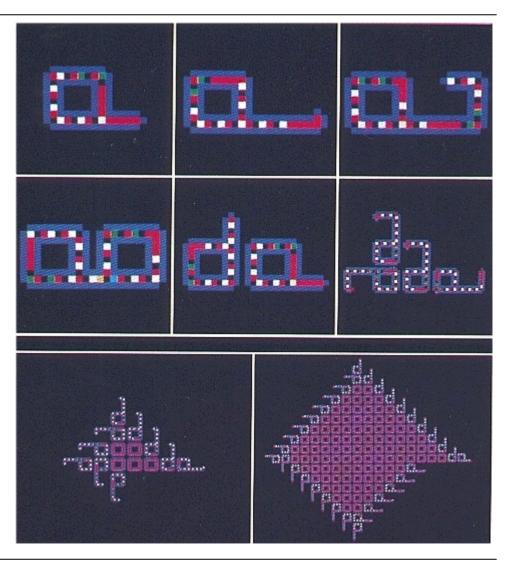
Project MAC

Early experiments

Following von Neumann...

Chris Langton's self-replicating cellular automata (CA) loops

Fundamentally, not evolutionary computation



Simon Greenwold, MIT 10.27.04

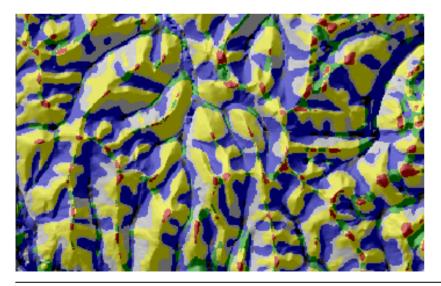
Stochastic optimization

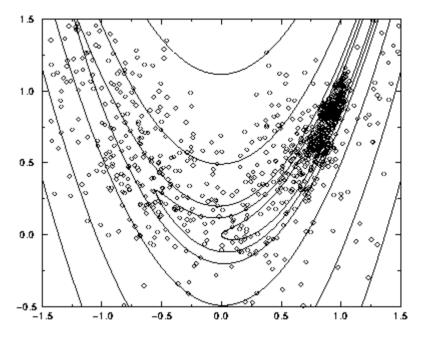
John Holland (develops GA 1962-75) hybrid of A-life and classical optimization

Simulated annealing

a gradual reduction in random energy samples a large space attempts to find global maxima/minima

GA is a very similar technique (search strategy)





Solution-space sampling of a simulated-annealing run

The inadequacy of hill-climbing for global maxima

GA Specifics

Population

randomly initialized genome often a bit-string, anything that can be combined

Decoding

genotype to phenotype

Evaluation

fitness (objective) function single-valued! goodness as a number?

Selection

proportional tournament elitism

Breeding

multiple genomes combined (can be more than two) mutation and crossover

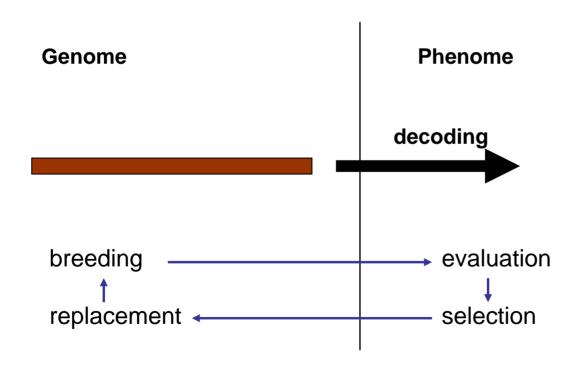
Replacement

replace entire population or just the worst must retain diversity

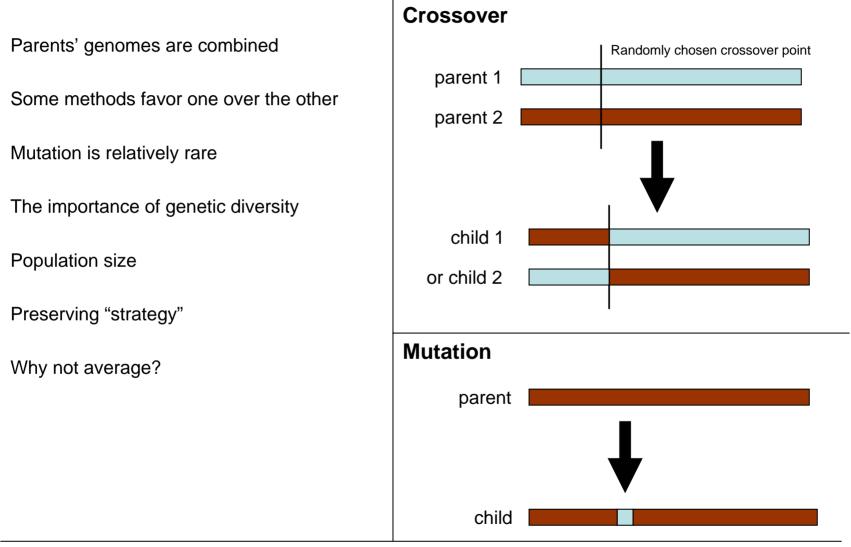
Genotype vs. Phenotype

Problem specified phenotype

Encoding into genome is up to you Must be extremely clever (most are bad)



Crossover and Mutation



Why operate on genomes?

Why not do combinatorial population work directly on phenotypes?

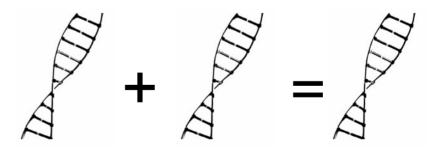
conduciveness to operations

generality of operations

nonlinearity of decoding

power of decoding

correlation of genes vs. traits



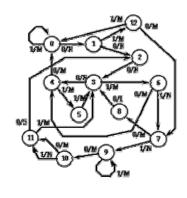
Genesys: The John Muir Trail

David Jefferson, 1992

evolving ant brains to follow a trail of food fitness is amount eaten in a certain time

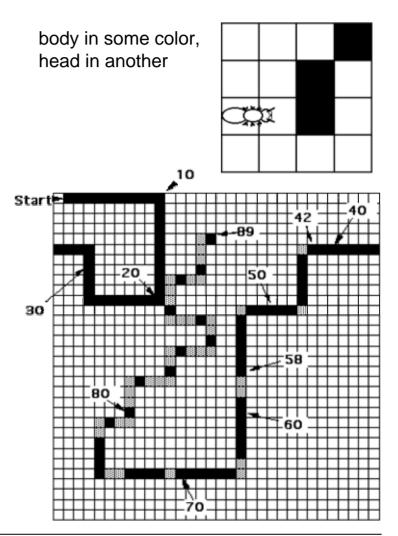
in any state left, right, forward, no movement and exit to another state number of states is crucial

Old New State Input State Action **Ø1**



behavior expressed as Finite State Machine (FSA)

00 0001 0111 0101 1111 1010 1111 1010 1011



Evolutionary computation for design

Genome

Simon Greenwold, MIT 10.27.04

John Koza c. 1992

Represents genomes as "programs" (trees of operations and values)

Can even define and call subroutines

Phenome is the production of running the program

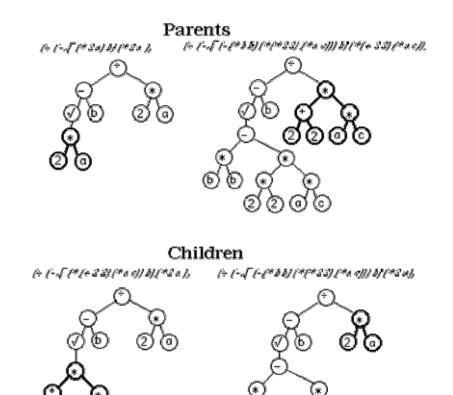
Crossover is grafting of branches from one genome to another

Not usually any mutation

Steady-state population (no specific generations)

Space of exploration very broad

Evolutionary computation for design



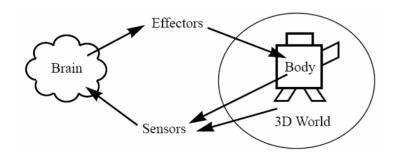
Compelling work: Karl Sims

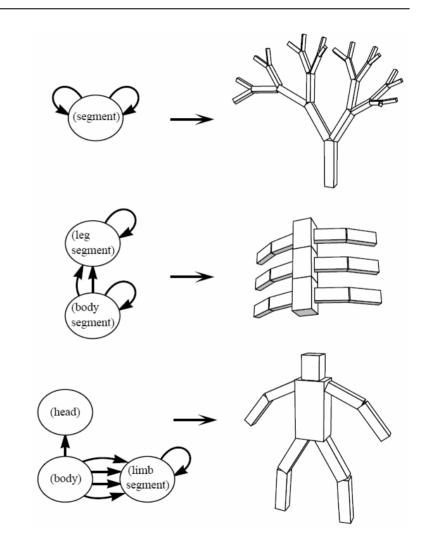
Evolved virtual creatures, 1994 (like all great work, looks easy)

genome coded for both form and behavior sensors and effectors (muscles) and a neural "brain"

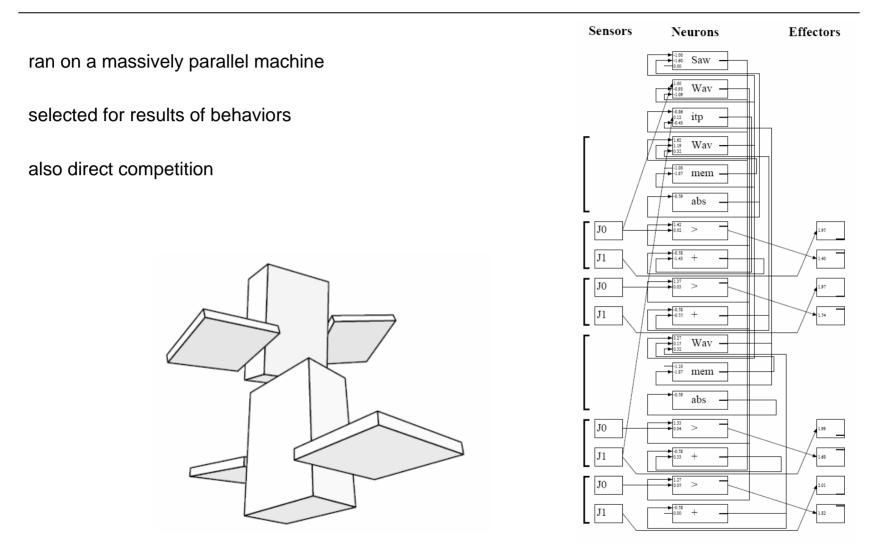
incredibly complicated genome multiple nested directed graphs

careful physics simulation as environment





Compelling work: Karl Sims

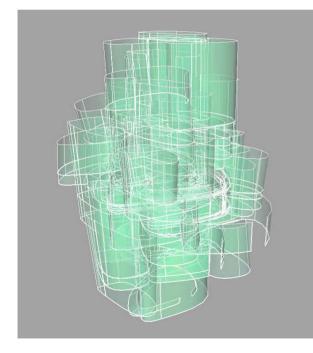


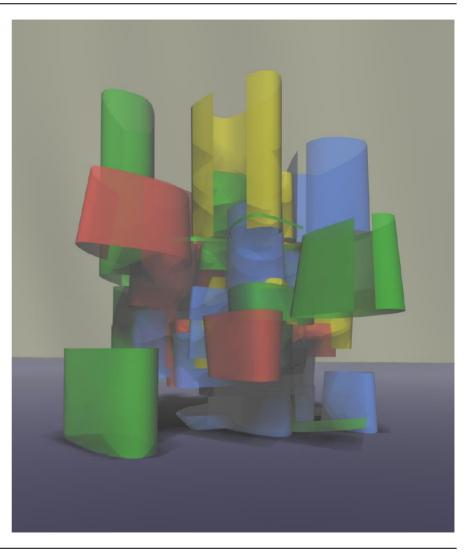


Genetic programming for growing extruded NURBS clusters

Testa, O'Reilly, and me

Plugin to Maya (3.x at the time)



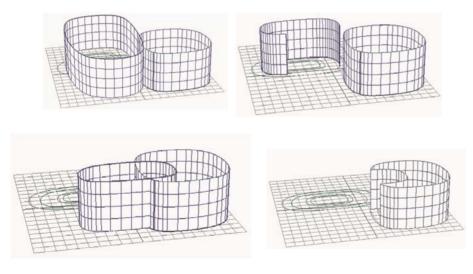




Individuals

A "program" of transformations and boolean operations on NURBS curves

Colors for program or other division of control



Rotate, translate, scale, extrude, union, intersect, difference.

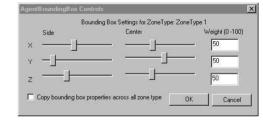
Agents

Bounding box

Size by type

Number of shapes

Fitness a weighted function of the evaluation of arbitrarily many "agents" A framework...



AgentShapeSiz	e Controls		×
Shape size set	ings for ZoneT	ype: Tall	
Min	Мах	Weight (0 -100))
× 1	20	50	
Y 1	20	50	OK
Z 1	20	50	Cancel
Copy shape	e size propertie	s across all zone ty	pes

AgentNumSha	pes Controls		>					
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esired propor)	tion of shapes to be of this	zoneType:						
None	Proportionate	All	OK					
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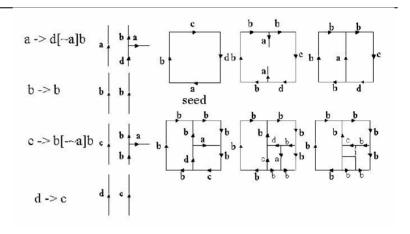
GenR8

O'Reilly & Hemberg

Evolving grammars for surfaces

A well-known decoding: L-Systems

User-defined fitness, attractors, repellers



A shared environment: Tierra

Tom Ray's 1991 TIERRA Synthetic Life program

Organisms as strings of instructions

Executed directly in a virtual machine

To reproduce, had to reproduce themselves in memory

Organisms became the environment

Competition was innate to the system

No external selection mechanism required

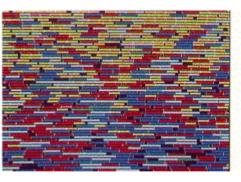
Strategies developed (hosts, parasites - biodiversity)



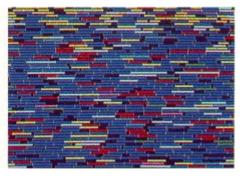
(1) Hosts, red, are very common. Parasites, yellow, have appeared but are still rare.



(2) Parasites have become very common. Hosts immune to parasites, blue, have appeared.



(3) Immune hosts now dominate memory, while parasites and susceptible hosts decline.



(4) The parasites will soon be driven to extinction.

Hard problems

What makes a problem hard?

Magnitude and shape of solution space (discontinuities, any pathology imaginable)

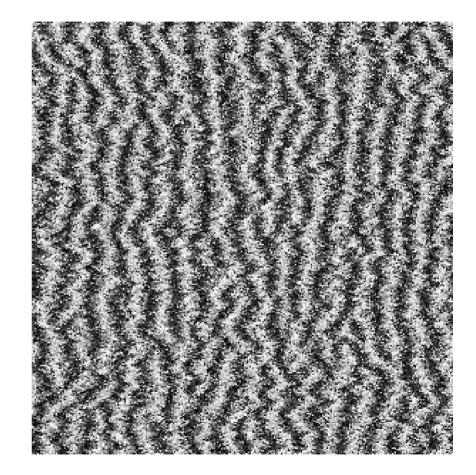
Genomic representation that cover the space exactly

Genomic surface area

The difficulty of fitness functions (weighted concerns, creativity?)

Where are we today?

There is no general solver



GAs vs. interactive-selection systems

Evolutionary computation for design

The limited role of optimization

The fitness problem – what are we selecting for? (and if we know it, why don't we just design it?)

Aesthetic criteria (exploration vs. optimization)

A different relationship to solution space

The parameters frame the solution

Direct optimization is better

Why do these capture the imagination?

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Results from GenR8