Matrix Mechanics

should have read CDTL pages 94-121 read CTDL pages 121-144 ASAP

Last time: * Numerov-Cooley Integration of 1-D Schr. Eqn. Defined on a Grid. * 2-sided boundary conditions (two different kinds of boundary condition) * nonlinear system - iterate to eigenenergies (Newton-Raphson)

So far focussed on $\psi(x)$ and Schr. Eq. as differential equation. Variety of methods $\{E_i, \psi_i(x)\} \leftrightarrow V(x)$

Often we want to evaluate integrals of the form

overlap of special
 ψ with standard
functions { ϕ } $\int \psi^*(x)\phi_i(x)dx = a_i$ a is "mixing coefficient"
 ϕ_i is a member of a "complete"
set of basis functions, { ϕ }expectation values and
transition moments $\int \phi_i^* \hat{x}^n \phi_j dx = (x^n)_{ij}$ a

There are going to be elegant tricks for evaluating these integrals and relating one integral to others that are already known. Also "selection" rules for knowing automatically which integrals are zero: symmetry, commutation rules

Today: begin matrix mechanics - deal with matrices composed of these integrals focus on manipulating these matrices rather than solving a differential equation - find eigenvalues and eigenvectors of *matrices* instead (COMPUTER "DIAGONALIZATION"). LINEAR ALGEBRA.

Η Ι * Perturbation Theory: tricks to find approximate eigenvalues of infinite matrices G Η * Wigner-Eckart Theorem and 3-j coefficients: use symmetry to identify and inter-L relate values of nonzero integrals Ι G * Density Matrices: information about "state of system" as separate from Η "measurement operators" Т \mathbf{S}

First Goal:Dirac notation as convenient NOTATIONAL simplificationIt is actually a new abstract picture
(vector spaces) — but we will stress the *utility* of $\psi \leftrightarrow |\rangle$ relationships
rather than the *philosophy*!

Find equivalent matrix form of standard $\psi(x)$ concepts and methods.

- 1. <u>Orthonormality</u> $\int \psi_i^* \psi_j dx = \delta_{ij}$
- 2. <u>Completeness</u> $\psi(x)$ is an arbitrary function

(expand ψ) A. Always possible to expand $\psi(x)$ uniquely in a COMPLETE BASIS SET $\begin{cases} \phi \\ * \end{cases} \psi(x) = \sum_{i} a_i \phi_i(x)$ mixing coefficient — how to get it? $* \quad a_i = \int \phi_i^* \psi dx$ left multiply by ϕ^*_i and integrate over x

(expand $\hat{B}\psi$) B. Always possible to expand $\hat{B}\psi$ in { ϕ } since we can write ψ in terms of { ϕ }. So simplify the question we are asking to $\hat{B}\phi_i = \sum_j b_j \phi_j$ What are the $\left\{b_j\right\}$? Multiply by $\int \phi_j^*$ $b_j = \int \phi_j^* \hat{B}\phi_i \, dx \equiv B_{ji}$ $\hat{B}\phi_i = \sum_j \underline{B}_{ji}\phi_j$ note counter-intuitive pattern of indices. We will return to this.

* The effect of any operator on ψ_i is to give a linear combination of ψ_i 's.

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3. Products of Operators

$$\left(\hat{A}\hat{B}\right)\!\varphi_{i}=\hat{A}\!\left(\hat{B}\varphi_{i}\right)=\hat{A}\!\sum_{j}B_{ji}\varphi_{j}$$

can move numbers (but not operators) around freely

$$\begin{split} &= \sum_{j} B_{ji} \hat{A} \phi_{j} = \sum_{j} \sum_{k} B_{ji} A_{kj} \phi_{k} & \text{note repeated j-index} \\ &= \sum_{j,k} (A_{kj} B_{ji}) \phi_{k} = \sum_{k} (\mathbf{A} \mathbf{B})_{ki} \phi_{k} & \text{note repeated k-index} \end{split}$$

* Thus the product of 2 operators follows the rules of matrix multiplication: $\hat{A}\hat{B}$ acts like ${\bf A}\,{\bf B}$

Recall rules for matrix multiplication:

$$\left(\begin{array}{c} \hline \\ \end{array}\right) \left(\begin{array}{c} \\ \end{array}\right) \text{ indices of a matrix are } A_{row, column}$$

must match # of columns on left to # of rows on right



Need a notation that accomplishes all of this *memorably* and compactly.

Dirac's bra and ket notation

Heisenberg's matrix mechanics

 $|\rangle$ is a column matrix , i.e. a vector $\begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_N \end{pmatrix}$

The ket contains all of the "mixing coefficients" for ψ expressed in some (implicit) basis set.

[These are projections onto unit vectors in N-dimensional vector space.] Must be clear <u>what state</u> is being expanded in <u>what basis</u>

$$\psi(\mathbf{x}) = \sum_{i} \left[\int \phi_{i}^{*} \psi d\mathbf{x} \right] \phi_{i}(\mathbf{x})$$
$$|\psi\rangle = \begin{pmatrix} \int \phi_{1}^{*} \psi d\mathbf{x} \\ \int \phi_{2}^{*} \psi d\mathbf{x} \\ \vdots \\ \int \phi_{N}^{*} \psi d\mathbf{x} \end{pmatrix}_{\phi} = \begin{pmatrix} a_{1} \\ a_{2} \\ \vdots \\ a_{N} \end{pmatrix}$$

express $\{\psi\}$ basis in $\{\phi_i\}$ basis

* Ψ expressed in φ basis
* a column of complex #s
* nothing here is a function of x

▲ bookkeeping device (RARELY USED) to specify basis set

The * stuff is needed to make sure $\langle \psi | \psi \rangle = 1$ even though $\langle \phi_i | \psi \rangle$ is complex.

The symbol $\langle a | b \rangle$, a bra-ket, is defined in the sense of a product of $(1 \times N) \otimes (N \times 1)$ matrices $\rightarrow a \ 1 \times 1$ matrix: a number!



We have proved that sum of | mixing coefficients $|^2 = 1$. These mixing coefficients "squared" are called "mixing fractions" or "fractional characters".

now in $\langle | \rangle$ picture $\langle \psi | \psi \rangle = \left(\underbrace{\int \phi_1 \psi * dx}_{\text{row vector: "bra"}} \int \phi_2 \psi * dx \cdots \right) \left(\underbrace{\int \phi_1^* \psi dx}_{\underbrace{\int \phi_2^* \psi dx}_{\text{vector "ket"}}} \right) = 1 \times 1 \text{ matrix}$ $= \sum_j \left| \int \phi_j^* \psi dx \right|^2$ same result as in wavefunction representation

[CTDL talks about "dual vector spaces" — best to walk before you run. Always translate $\langle \rangle$ into Ψ picture until you are sure you understand the notation.]

Any symbol $\langle \rangle$ is a complex numAny symbol $ \rangle \langle $ is a square matr	ıber. ix.
again $\langle \psi \psi \rangle = (\langle \psi \phi_1 \rangle \ \langle \psi \phi_2 \rangle$	$) \left(\begin{array}{c} \langle \phi_1 \psi \rangle \\ \langle \phi_2 \psi \rangle \\ \vdots \end{array} \right)$
$= \sum_{i} \langle \Psi \phi_{i} \rangle \langle \phi_{i} \Psi \rangle =$ unit matrix 1	$\langle \psi \psi \rangle = 1$
what is $ \phi_1\rangle\langle\phi_1 = (100) \begin{pmatrix} 1\\0\\\vdots\\0 \end{pmatrix} = \begin{pmatrix} 1\\0\\\vdots\\0 \end{pmatrix}$	0 0 0
what is $\sum_{i} \phi_{i}\rangle \langle \phi_{i} = \begin{pmatrix} 1 & 0 \\ & 1 & 0 \\ & 0 & 1 \\ 0 & & \ddots \end{pmatrix}$	unit or identity matrix = 1 Large zero (0) denotes a lot of

"completeness" or "closure" involves insertion of 1 between any two symbols.

Use 1 to evaluate the matrix elements of the product of 2 operators, AB (we know how to do this in Ψ picture).

In the Heisenberg picture, how do we get an exact equivalent of $\psi(x)$? Use basis set $\delta(x,x_0)$ for all x_0 – this is a "complete" basis (eigenbasis for \hat{x} , eigenvalue x_0) - perfect localization at any x_0

This
$$\langle \mathbf{x} \mid \Psi \rangle$$
 symbol is the same thing as $\Psi(\mathbf{x})$
 $\uparrow \qquad \qquad \left(\text{i.e., } \int \delta(x, x')^* \psi(x') dx' = \psi(x) \right)$
 \mathbf{x} is continuously variable $\leftrightarrow \delta(\mathbf{x})$

Overlap of state vector Ψ with $\delta(x) - a$ complex number. $\Psi(x)$ is a complex function of a real variable.

other $\Psi \leftrightarrow \langle | \rangle$ relationships

1. All observable quantities are represented by a Hemitian operator (Why – because the expectation values of a Hermitian operator are always real). Definition of Hermitian operator:

2. Change of basis set

A

$$^{\phi} \leftrightarrow \mathbf{A}^{u} \qquad \{\phi\} \text{ to } \{u\}$$

For a matrix: $A_{ij} = A_{ji}^*$ or $A = A^{\dagger}$ Easy to prove that if all expectation values of A are real, then $A = A^{\dagger}$ and vice-versa



$$A^{\phi} = S^{\dagger} A^{u} S$$

 $\mathbf{S}^{\dagger}\cdots\mathbf{S}$ is a special kind of transformation (unitary)

(different from more-familiar **T**⁻¹**AT** "similarity" transformation)

For a state vector (ket):

ate vector (ket):

$$\begin{vmatrix} \phi_{j} \rangle = \sum_{\ell} |u_{\ell}\rangle \langle u_{\ell} | \phi_{j} \rangle = \sum_{\ell=1}^{N} |u_{\ell}\rangle S_{\ell j} = \begin{pmatrix} S_{1j} \\ \vdots \\ S_{Nj} \end{pmatrix}$$

$$\begin{vmatrix} \phi_{j} \rangle = \begin{pmatrix} S_{\ell j} \\ \vdots \\ S_{Nj} \end{pmatrix}$$
This is the j-th column of **S**.

The linear combination of $|u_i\rangle$ for each $|\phi_j\rangle$ is the j-th column of S. Also, the linear combination of $\left|\phi_{j}\right\rangle$ for each $|u_i\rangle$ is the i-th column of S[†]. [This is a very useful thing to remember.]

$$|u_{i}\rangle = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix}_{u} = \begin{pmatrix} S_{1i}^{\dagger} \\ \vdots \\ S_{Ni}^{\dagger} \\ 0 \end{pmatrix}_{\phi} = S_{1i}^{\dagger} \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}_{i} + S_{2i}^{\dagger} \begin{pmatrix} 0 \\ 1 \\ \vdots \\ \vdots \end{pmatrix} + \dots S_{Ni}^{\dagger} \begin{pmatrix} 0 \\ \vdots \\ \vdots \\ 1 \end{pmatrix}$$

$$pure state in sta$$

What kind of matrix is S?

$$S_{\ell j} = \left\langle u_{\ell} | \phi_{j} \right\rangle$$
$$S_{\ell j}^{*} = \left[\left\langle u_{\ell} | \phi_{j} \right\rangle \right]^{*} = \left\langle \phi_{j} | u_{\ell} \right\rangle \equiv S_{j\ell}^{\dagger}$$

 \dagger means take complex conjugate and interchange indices. Using the definitions of S and S^{\dagger} :

$$S_{\ell j}S_{jk}^{\dagger} = \left\langle u_{\ell} \middle| \phi_{j} \right\rangle \left\langle \phi_{j} \middle| u_{k} \right\rangle$$
$$\sum_{j} S_{\ell j}S_{jk}^{\dagger} = \sum_{j} \left\langle u_{\ell} \middle| \phi_{j} \right\rangle \left\langle \phi_{j} \middle| u_{k} \right\rangle = \left\langle u_{\ell} \middle| 1 \middle| u_{k} \right\rangle = \delta_{\ell k}$$
$$= \left\langle u_{\ell} \middle| u_{k} \right\rangle = \delta_{\ell k} = 1_{\ell k}$$

 $\mathbf{SS}^{\dagger} = \mathbb{I} \quad \text{OR} \qquad \mathbf{S}^{\dagger} = \mathbf{S}^{-1} \quad \text{``Unitary''}$ $\mathbf{S}^{\dagger} \text{ is inverse of } \mathbf{S}!$

a very special and convenient property.

Unitary transformations preserve both normalization and orthogonality.

$$\mathbf{A}^{\phi} = \mathbf{S}^{\dagger} \mathbf{A}^{u} \mathbf{S}$$
$$\mathbf{S} \mathbf{A}^{\phi} \mathbf{S}^{\dagger} = \mathbf{S} \mathbf{S}^{\dagger} \mathbf{A}^{u} \mathbf{S} \mathbf{S}^{\dagger} = \mathbf{A}^{u}$$
$$\mathbf{A}^{u} = \mathbf{S} \mathbf{A}^{\phi} \mathbf{S}^{\dagger}$$

Take matrix element of both sides of equation:

$$A_{ij}^{u} = \left\langle u_{i} \mid \mathbf{A} \mid u_{j} \right\rangle = \left(\mathbf{S} \mathbf{A}^{\phi} \mathbf{S}^{\dagger} \right)_{ij}$$
$$= \sum_{k,\ell} \mathbf{S}_{ik} \left\langle \phi_{k} \mid \mathbf{A} \mid \phi_{\ell} \right\rangle \mathbf{S}_{\ell j}^{\dagger}$$

$$\therefore |u_{j}\rangle = \sum_{\ell} |\phi_{\ell}\rangle \mathbf{S}_{\ell j}^{\dagger} |u_{j}\rangle \text{ is j-th column of } \mathbf{S}^{\dagger}$$
$$\phi \rightarrow u \text{ via } \mathbf{S}^{\dagger}, \mathbf{S} : |u_{j}\rangle \text{ is j-th column of } \mathbf{S}^{\dagger}$$

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Thus,

$$\begin{vmatrix} \mathbf{j} \cdot \mathbf{th} \\ |u_j \rangle = \begin{pmatrix} \mathbf{0} \\ \vdots \\ \mathbf{1} \\ \vdots \\ \mathbf{0} \end{pmatrix}_u = \begin{pmatrix} S_{1j}^{\dagger} \\ S_{2j}^{\dagger} \\ \vdots \\ \vdots \\ S_{nj}^{\dagger} \\ \end{pmatrix}_{\phi}$$

Similarly,

$$\mathbf{A}_{pq}^{\phi} = \left\langle \phi_{p} | \mathbf{A} | \phi_{q} \right\rangle = \left(\mathbf{S}^{\dagger} \mathbf{A}^{u} \mathbf{S} \right)_{pq}$$
$$= \sum_{mn} S_{pm}^{\dagger} \left\langle u_{m} | \mathbf{A} | u_{n} \right\rangle S_{nq}$$
$$|\phi_{q}\rangle$$

 $\therefore \left| \phi_{q} \right\rangle = \sum_{n} \left| u_{n} \right\rangle S_{nq} \quad q\text{-th column of S}$ $\left| \phi_{q} \right\rangle = \left(\begin{array}{c} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{array} \right)_{\phi} = \left(\begin{array}{c} S_{1q} \\ S_{2q} \\ \vdots \\ S_{nq} \end{array} \right)_{u}$

Commutation Rules

*
$$\left[\hat{A}, \hat{B}\right] = \hat{A}\hat{B} - \hat{B}\hat{A}$$

e.g. $\left[\hat{x}, \hat{p}\right] = i\hbar$ means $\left(\hat{x}\hat{p}-\hat{p}\hat{x}\right)\phi = x\frac{\hbar}{i}\frac{d\phi}{dx} - \frac{\hbar}{i}\left(\phi + x\frac{d\phi}{dx}\right) = -\frac{\hbar}{i}\phi = \hbar i\phi$
 $= i\hbar\phi$

* If \hat{A} and \hat{B} are Hermitian, is $\hat{A}\hat{B}$ Hermitian?

$$(AB)_{ij} = \sum_{k} A_{ik} B_{kj} = \sum_{k} A^{*}_{ki} B^{*}_{jk} = \sum_{k} B^{*}_{jk} A^{*}_{ki} = (BA)^{*}_{ji}$$

but this is **not** what we need to be able to show that **AB** is Hermitian: That would be: $(\mathbf{AB})_{ii} = (\mathbf{AB})^*_{ii}$ or $\mathbf{AB} = (\mathbf{AB})^{\dagger} \neq (\mathbf{BA})^{\dagger}$

> **AB** is Hermitian only if $[\mathbf{A}, \mathbf{B}] = 0$ However, $\frac{1}{2}[\mathbf{AB} + \mathbf{BA}]$ is Hermitian if both **A** and **B** are Hermitian.

This is a foolproof way to construct a new Hermitian operator out of simpler Hermitian operators.

This is the standard prescription for implementing the Correspondence Principle for constructing a quantum mechanical equivalent of a classical mechanical quantity. Quantities that commute in classical mechanics do not always commute in quantum mechanics. Almost everything that is not classical mechanical in quantum mechanics is derivable from $[\hat{x}, \hat{p}_x] \neq 0!$ MIT OpenCourseWare <u>https://ocw.mit.edu/</u>

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