Part 1: Stable?

We say that a system is **stable** if, for a bounded, transient input, its output converges to zero as n goes to infinity.

The systems below are specified either as a difference equation or as a system function.

Enter the **magnitude** of the dominant pole for each system and then enter whether the system is stable (type **yes** or **no**) and whether its response is oscillatory (type **yes** or **no**).

Note that strictly alternating signal corresponds to an oscillation of period 2.

Hint: use the SystemFunction class from lab. But, be careful about integer division when defining the coefficients, use 5.0/6, not 5/6.

1.	$y[n] = \frac{5}{6}y[n-1] + y[n-2] + x[n]$			
	dominant pole magnitude:			
	stable?:			
	oscillatory?:			
2.	$\frac{1}{1 + \frac{5}{4}R + \frac{3}{8}R^2}$			
	dominant pole magnitude:			
	stable?			
	oscillatory?			
3.	$y[n] = -\frac{3}{2}y[n-1] - \frac{9}{8}y[n-2] + x[n]$			
	dominant pole magnitude:			
	stable?			
	oscillatory?			
4.	$\frac{1}{1+R+\frac{1}{2}R^2}$			
	dominant pole magnitude:			
	stable?			

Part 2: DiffEq Behavior

For the four sequences given in the following four plots, which difference equation (A,B, C, or D) could have generated the sequence (given a unit sample input). Hint: Think about the poles of the corresponding systems.

Assume the input x[n] = 0 for n > 1. $\mathsf{A}_{\cdot} \ y[n] = \frac{13}{8} y[n-1] - \frac{42}{64} y[n-2] + x[n]$ ${}_{\mathsf{B}.} \ y[n] = -\frac{13}{8} y[n-1] - \frac{42}{64} y[n-2] + x[n]$ $_{\rm C.} y[n] = -\frac{16}{8} y[n-1] - \frac{63}{64} y[n-2] + x[n]$ ${}_{\mathsf{D}.} \ y[n] = \frac{2}{8} y[n-1] + \frac{63}{64} y[n-2] + x[n]$ 1. 5128e] 0 -570e 100 2.



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