## 6.087 Lecture 9 – January 22, 2010

#### Review

- Using External Libraries
  - Symbols and Linkage
  - Static vs. Dynamic Linkage
  - Linking External Libraries
  - Symbol Resolution Issues
- Creating Libraries
- Data Structures
  - B-trees
  - Priority Queues



- Void pointer points to any data type: int x; void \* px = &x; /\* implicit cast to (void \*) \*/ float f; void \* pf = &f;
- Cannot be dereferenced directly; void pointers must be cast prior to dereferencing:

```
printf("%d %f\n", *(int *)px, *(float *)pf);
```

- Functions not variables, but also reside in memory (i.e. have an address) – we can take a pointer to a function
- Function pointer declaration: int (\*cmp)(void \*, void \*);
- · Can be treated like any other pointer
- No need to use & operator (but you can)
- Similarly, no need to use \* operator (but you can)

```
int strcmp_wrapper(void * pa, void * pb) {
  return strcmp((const char *)pa, (const char *)pb);
}
```

- Can assign to a function pointer: int (\*fp)(void \*, void \*) = strcmp\_wrapper; Or int (\*fp)(void \*, void \*) = &strcmp\_wrapper;
- Can call from function pointer: (str1 and str2 are strings)
   int ret = fp(str1, str2); Or

```
int ret = (*fp)(str1, str2);
```

- Hash table (or hash map): array of linked lists for storing and accessing data efficiently
- Each element associated with a key (can be an integer, string, or other type)
- Hash function computes hash value from key (and table size); hash value represents index into array
- Multiple elements can have same hash value results in collision; elements are chained in linked list

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- External libraries provide a wealth of functionality example: C standard library
- Programs access libraries' functions and variables via identifiers known as *symbols*
- Header file declarations/prototypes mapped to symbols at compile time
- Symbols linked to definitions in external libraries during *linking*
- Our own program produces symbols, too

Consider the simple hello world program written below:
 #include <stdio.h>

```
const char msg[] = "Hello, world.";
int main(void) {
   puts(msg);
   return 0;
}
```

· What variables and functions are declared globally?

Consider the simple hello world program written below:
 #include <stdio.h>

```
const char msg[] = "Hello, world.";
int main(void) {
   puts(msg);
   return 0;
}
```

• What variables and functions are declared globally? msg, main(), puts(), others in stdio.h



- Let's compile, but not link, the file hello.c to create hello.o: athena%<sup>1</sup> gcc -Wall -c hello.c -o hello.o
  - -c: compile, but do not link hello.c; result will compile the code into machine instructions but not make the program executable
  - addresses for lines of code and static and global variables not yet assigned
  - need to perform link step on hello.o (using gcc or ld) to assign memory to each symbol
  - linking resolves symbols defined elsewhere (like the C standard library) and makes the code executable

- Let's look at the symbols in the compiled file hello.o: athena%<sup>1</sup> nm hello.o
- Output:

000000000000000 T main 000000000000000 R msg U puts

- 'T' (text) code; 'R' read-only memory; 'U' undefined symbol
- Addresses all zero before linking; symbols not allocated memory yet
- Undefined symbols are defined externally, resolved during linking



- Why aren't symbols listed for other declarations in stdio.h?
- Compiler doesn't bother creating symbols for unused function prototypes (saves space)
- What happens when we link? athena% gcc -Wall hello.o -o hello
  - · Memory allocated for defined symbols
  - Undefined symbols located in external libraries (like libc for C standard library)

- Let's look at the symbols now: athena%' nm hello
- Output: (other default symbols)

```
0000000000400524 T main
000000000040062c R msg
U puts@@GLIBC_2.2.5
```

- Addresses for static (allocated at compile time) symbols
- Symbol puts located in shared library GLIBC\_2.2.5 (GNU C standard library)
- Shared symbol puts not assigned memory until run time



# Static and dynamic linkage

- Functions, global variables must be allocated memory before use
- Can allocate at compile time (static) or at run time (shared)
- Advantages/disadvantages to both
- Symbols in same file, other . o files, or static libraries (archives, . a files) static linkage
- Symbols in shared libraries (.so files) dynamic linkage
- gcc links against shared libraries by default, can force static linkage using -static flag



# Static linkage

- What happens if we statically link against the library? athena%<sup>1</sup> gcc -Wall -static hello.o -o hello
- Our executable now contains the symbol puts:

```
:
00000000004014c0 W puts
:
0000000000400304 T main
:
000000000046cd04 R msg
```

• 'W': linked to another defined symbol



- · At link time, statically linked symbols added to executable
- Results in much larger executable file (static 688K, dynamic – 10K)
- Resulting executable does not depend on locating external library files at run time
- To use newer version of library, have to recompile

- Dynamic linkage occurs at run-time
- During compile, linker just looks for symbol in external shared libraries
- Shared library symbols loaded as part of program startup (before main())
- Requires external library to define symbol exactly as expected from header file declaration
  - changing function in shared library can break your program
  - · version information used to minimize this problem
  - reason why common libraries like <code>libc</code> rarely modify or remove functions, even broken ones like <code>gets()</code>



- Programs linked against C standard library by default
- To link against library libnamespec.so or libnamespec.a, use compiler flag -lnamespec to link against library
- Library must be in library path (standard library directories + directories specified using -L directory compiler flag
- Use -static for force static linkage
- This is enough for static linkage; library code will be added to resulting executable

- Shared library located during compile-time linkage, but needs to be located again during run-time loading
- Shared libraries located at run-time using linker library ld.so
- Whenever shared libraries on system change, need to run ldconfig to update links seen by ld.so
- During loading, symbols in dynamic library are allocated memory and loaded from shared library file

# Loading shared libraries on demand

- In Linux, can load symbols from shared libraries on demand using functions in dlfcn.h
- Open a shared library for loading: void \* dlopen(const char \*file, int mode); values for mode: combination of RTLD\_LAZY (lazy loading of library), RTLD\_NOW (load now), RTLD\_GLOBAL (make symbols in library available to other libraries yet to be loaded), RTLD\_LOCAL (symbols loaded are accessible only to your code)

# Loading shared libraries on demand

- Get the address of a symbol loaded from the library:
   void \* dlsym(void \* handle, const char \* symbol\_name);
   handle from call to dlopen; returned address is pointer to
   variable or function identified by symbol\_name
- Need to close shared library file handle after done with symbols in library:

int dlclose(void \* handle);

• These functions are not part of C standard library; need to link against library libdl: -ldl compiler flag

- Symbols can be defined in multiple places
- Suppose we define our own  ${\tt puts}\left( \right)$  function
- But, puts () defined in C standard library
- When we call  ${\tt puts}$  () , which one gets used?

- Symbols can be defined in multiple places
- Suppose we define our own  ${\tt puts}\left( \right)$  function
- But, puts () defined in C standard library
- When we call puts (), which one gets used?
- Our puts() gets used since ours is static, and puts() in
  C standard library not resolved until run-time
- If statically linked against C standard library, linker finds two puts() definitions and aborts (multiple definitions not allowed)

# Symbol resolution issues

- How about if we define puts () in a shared library and attempt to use it within our programs?
- Symbols resolved in order they are loaded
- Suppose our library containing puts() is libhello.so, located in a standard library directory (like /usr/lib), and we compile our hello.c code against this library: athena%1 gcc -g -Wall hello.c -lhello -o hello.o
- Libraries specified using -1 flag are loaded in order specified, and before C standard library
- Which puts() gets used here? athena% gcc -g -Wall hello.c -lc -lhello -o hello.o



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#### Creating Libraries

- Data Structures
  - B-trees
  - Priority Queues



# **Creating libraries**

- Libraries contain C code like any other program
- Static or shared libraries compiled from (un-linked) object files created using gcc
- Compiling a static library:
  - compile, but do not link source files: athena%<sup>1</sup> gcc -g -Wall -c infile.c -o outfile.o
  - collect compiled (unlinked) files into an archive: athena% ar -rcs libname.a outfile1.o outfile2.o ...

# **Creating shared libraries**

- Compile and do not link files using gcc: athena% gcc -g -Wall -fPIC -c infile.c -o outfile.o
- -fpic option: create position-independent code, since code will be repositioned during loading
- Link files using ld to create a shared object (.so) file: athena% ld -shared -soname libname.so -o libname.so.version -lc outfile1.o outfile2.o ...
- If necessary, add directory to LD\_LIBRARY\_PATH environment variable, so ld.so can find file when loading at run-time
- Configure ld.so for new (or changed) library: athena% ldconfig -v



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- Many data structures designed to support certain algorithms
- B-tree generalized binary search tree, used for databases and file systems
- Priority queue ordering data by "priority," used for sorting, event simulation, and many other algorithms

## **B-tree structure**

- Binary search tree with variable number of children (at least t, up to 2t)
- Tree is balanced all leaves at same level
- Node contains list of "keys" divide range of elements in children



[Cormen, Leiserson, Rivest, and Stein. Introduction to Algorithms, 2nd ed. MIT Press, 2001.] Courtesy of MIT Press. Used with permission.



- Initially, B-tree contains root node with no children (leaf node), no keys
- Note: root node exempt from minimum children
   requirement

# **Inserting elements**

- · Insertion complicated due to maximum number of keys
- At high level:
  - 1. traverse tree down to leaf node
  - 2. if leaf already full, split into two leaves:
    - (a) move median key element into parent (splitting parent already full)
    - (b) split remaining keys into two leaves (one with lower, one with higher elements)
  - 3. add element to sorted list of keys
- Can accomplish in one pass, splitting full parent nodes during traversal in step 1



## **Inserting elements**

B-tree with t = 3 (nodes may have 2-5 keys):



[Cormen, Leiserson, Rivest, and Stein. Introduction to Algorithms, 2nd ed. MIT Press, 2001.] Courtesy of MIT Press. Used with permission



# **Inserting elements**

More insertion examples:



[Cormen, Leiserson, Rivest, and Stein. Introduction to Algorithms, 2nd ed. MIT Press, 2001.] Courtesy of MIT Press. Used with permission.



- Search like searching a binary search tree:
  - 1. start at root.
  - 2. if node empty, element not in tree
  - 3. search list of keys for element (using linear or binary search)
  - 4. if element in list, return element
  - 5. otherwise, element between keys, and repeat search on child node for that range
- Tree is balanced search takes  $O(\log n)$  time

# Deletion

- Deletion complicated by minimum children restriction
- When traversing tree to find element, need to ensure child nodes to be traversed have enough keys
  - if adjacent child node has at least *t* keys, move separating key from parent to child and closest key in adjacent child to parent
  - if no adjacent child nodes have extra keys, merge child node with adjacent child
- When removing a key from a node with children, need to rearrange keys again
  - if child before or after removed key has enough keys, move closest key from child to parent
  - if neither child has enough keys, merge both children
  - if child not a leaf, have to repeat this process

## **Deletion examples**



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## **Deletion examples**



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- Abstract data structure ordering elements by priority
- Elements enqueued with priority, dequeued in order of highest priority
- Common implementations: heap or binary search tree
- Operations: insertion, peek/extract max-priority element, increase element priority

- Heap tree with heap-ordering property: priority(child) ≤ priority(parent)
- More sophisticated heaps exist e.g. binomial heap, Fibonacci heap
- We'll focus on simple binary heaps
- Usually implemented as an array with top element at beginning
- Can sort data using a heap O( $n \log n$ ) worst case in-place sort!

# **Extracting data**

- Heap-ordering property  $\Rightarrow$  maximum priority element at top of heap
- Can peek by looking at top element
- Can remove top element, move last element to top, and swap top element down with its children until it satisfies heap-ordering property:
  - 1. start at top
  - 2. find largest of element and left and right child; if element is largest, we are done
  - 3. otherwise, swap element with largest child and repeat with element in new position



# Inserting data/increasing priority

- Insert element at end of heap, set to lowest priority  $-\infty$
- Increase priority of element to real priority:
  - 1. start at element
  - 2. if new priority less than parent's, we are done
  - 3. otherwise, swap element with parent and repeat

## Example of inserting data



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Topics covered:

- Using external libraries
  - symbols and linkage
  - static vs. dynamic linkage
  - linking to your code
  - symbol clashing
- Creating libraries
- Data structures
  - B-tree
  - priority queue

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