Recitation 18: "Pythagorators," and other circuits Prof. Joel L. Dawson

Way back at the beginning of the term, in Recitation 2, we talked about what it means to do engineering design. Quoting from those notes:

"In engineering design, we make use of nature's laws to build useful machines."

The Gilbert Principle is a classic example of how we use the exponential I_C vs. V_{BE} relationship to build analog computation elements. Before examining this in more detail, let's use the class exercise to look at another intriguing case.

<u>CLASS EXERCISE</u>: Consider the following



Using KVL, write V_0 as a function of I, I_{SI} , and I_{S2} . Can you think of any useful function served by V_0 ?

(Workspace)

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How about <u>that</u>?! Note that while the temperature dependence of V_{BE} is complicated, the temperature dependence of a ΔV_{BE} is simple:

$$\Delta V_{BE} = \frac{kT}{q} \ln\left(\frac{I_{C1}}{I_s}\right) - \frac{kT}{q} \ln\left(\frac{I_{C2}}{I_s}\right) = \frac{kT}{q} \ln\left(\frac{I_{C1}}{I_{C2}}\right)$$

If $\frac{I_{C1}}{I_{C2}}$ is independent of temperature, we say that ΔV_{BE} is "PTAT," or

<u>Proportional to Absolute Temperature.</u>

So...we took advantage of our detailed knowledge of bipolar transistors to build a thermometer. The Gilbert Principle takes advantage of our knowledge in a different way, and for a different end.

Final Note: Do not use circuits like the class exercise without some sort of start-up circuitry. Note that I=0 is a valid state.

As we saw in lecture yesterday, the Gilbert Principle is a kind of mathematical shorthand for KVL. Let's review.

Current square-root circuit:



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Write out KVL:

$$V_{BE1} + V_{BE2} - V_{BE3} - V_{BE4} = 0$$

$$V_T \ln\left(\frac{I_1}{I_s}\right) + V_T \ln\left(\frac{I_B}{I_s}\right) - V_T \ln\left(\frac{I_0}{I_s}\right) - V_T \ln\left(\frac{I_0}{I_s}\right) = 0$$

$$\mathcal{V}_T \ln\left(\frac{I_1 I_B}{I_s^2}\right) = \mathcal{V}_T \ln\left(\frac{I_0^2}{I_s^2}\right)$$

$$I_0 = \sqrt{I_B I_1} = k\sqrt{I_1}$$

Pretty neat. From this example, simple though it is, we can draw a couple of very general conclusions.

- (1) Translinear circuits are \underline{fast} .
- (2) Translinear circuits always involve an even number of $V_{BE}s$.

To understand (1), look at all of the C_{μ} s. None of them get Miller multiplied. $C_{\mu 1}$ Even gets bootstrapped, while $C_{\mu 4}$ gets shorted out altogether.

To understand (2), consider a tempting but <u>extremely wrong</u> way to implement the square root function.



Translinear principle:

(The units don't even work.)

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KVL:

$$\mathcal{V}_{T} \ln\left(\frac{I_{1}}{I_{s}}\right) = 2\mathcal{V}_{T} \ln\left(\frac{I_{0}}{I_{s}}\right)$$
$$\ln\left(\frac{I_{1}}{I_{s}}\right) = \ln\left(\frac{I_{0}^{2}}{I_{s}^{2}}\right)$$
$$I_{0} = \sqrt{I_{s}} \sqrt{I_{1}}$$
$$Vitally important for the second secon$$

Vitally important that all of the I_S s cancel out. This is only possible if the number of CW V_{BE} s equals the number of CCW V_{BE} s.

To finish off the basics, we recall that we sometimes have the freedom to change emitter areas. If we write

 $I_s = A_E J_s$

We have

$$\sum_{CW} V_{BEm} = \sum_{CCW} V_{BEn}$$
$$\prod_{CW} \frac{I_{Cm}}{I_{Sm}} = \prod_{CCW} \frac{I_{Cn}}{I_{Sn}}$$
$$\prod_{CW} \frac{I_{Cm}}{A_{En}J_S} = \prod_{CCW} \frac{I_{Cn}}{A_{En}J_S}$$
$$\overline{\prod_{CW} \frac{I_{Cm}}{A_{Em}}} = \prod_{CCW} \frac{I_{Cn}}{A_{En}}$$

This is the most general translinear principle.

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Now, at last, a Pythagorator. One such cell was shown to you in lecture yesterday. Here is a seven-transitor version.



How to analyze? Start with

And

 $I_0 = I_5 + I_6$

 $I_{7} = I_{0}$

The left Gilbert loop gives:

$$I_1 I_2 = I_5 I_7 = I_5 I_0$$
$$I_x^2 = I_5 I_0 \Longrightarrow I_5 = \frac{I_x^2}{I_0}$$

Right Gilbert loop gives:

$$I_6 = \frac{I_y^2}{I_0}$$

So for the output:

$$I_{0} = I_{5} + I_{6} = \frac{I_{x}^{2}}{I_{0}} + \frac{I_{y}^{2}}{I_{0}}$$
$$I_{0}^{2} = I_{x}^{2} + I_{y}^{2}$$
$$I_{0} = \sqrt{I_{x}^{2} + I_{y}^{2}}$$



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