

# Notation

All vectors will be expressed as column vectors. The typographic convention used for a column vector  $\mathbf{x}$  is  $\vec{\mathbf{x}}$ . Row vectors will be represented by the transpose of a column vector. For example, if we wish to represent the row vector:

$$\begin{pmatrix} 1 & 2 & 3 \end{pmatrix}$$

we would first define a column vector:

$$\vec{\mathbf{x}} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

Then, the row vector would be expressed as:

$$\vec{\mathbf{x}}^T = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}^T = \begin{pmatrix} 1 & 2 & 3 \end{pmatrix}$$

The **MATLAB**® command “`x = [1 2 3]`” generates a row vector. To generate a column vector in **MATLAB**®, we use the transpose command “`.’`”. So,  $\vec{\mathbf{x}}$  of the previous example would be declared in **MATLAB**® by “`x = [1 2 3].’`”. Note, that the **MATLAB**® command “`.’`” is really the *adjoint* (denoted as  $\dagger$ ). The adjoint of a  $\vec{\mathbf{x}}$  is defined as the complex conjugate of the transpose of  $\vec{\mathbf{x}}$ , i.e.  $\vec{\mathbf{x}}^\dagger = \vec{\mathbf{x}}^*{}^T$ . Of course for real vectors, the adjoint and the transpose are the same. Just beware when dealing with complex vectors!