

# Notation

All vectors will be expressed as column vectors. The typographic convention used for a column vector  $\mathbf{x}$  is  $\bar{x}$ . Row vectors will be represented by the transpose of a column vector. For example, if we wish to represent the row vector:

$$(1 \quad 2 \quad 3)$$

we would first define a column vector:

$$\bar{x} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

Then, the row vector would be expressed as:

$$\bar{x}^T = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}^T = (1 \quad 2 \quad 3)$$

The **MATLAB**® command “`x = [1 2 3]`” generates a row vector. To generate a column vector in **MATLAB**®, we use the transpose command “`.’`”. So,  $\bar{x}$  of the previous example would be declared in **MATLAB**® by “`x = [1 2 3].’`”. Note, that the **MATLAB**® command “`.’`” is really the *adjoint* (denoted as  $\dagger$ ). The adjoint of a  $\bar{x}$  is defined as the complex conjugate of the transpose of  $\bar{x}$ , i.e.  $\bar{x}^\dagger = \bar{x}^{*T}$ . Of course for real vectors, the adjoint and the transpose are the same. Just beware when dealing with complex vectors!