

**MITOPENCOURSEWARE**  
MASSACHUSETTS INSTITUTE OF TECHNOLOGY

**6.776**

***High Speed Communication Circuits***

***Lecture 17***

***Noise in Voltage Controlled Oscillators***

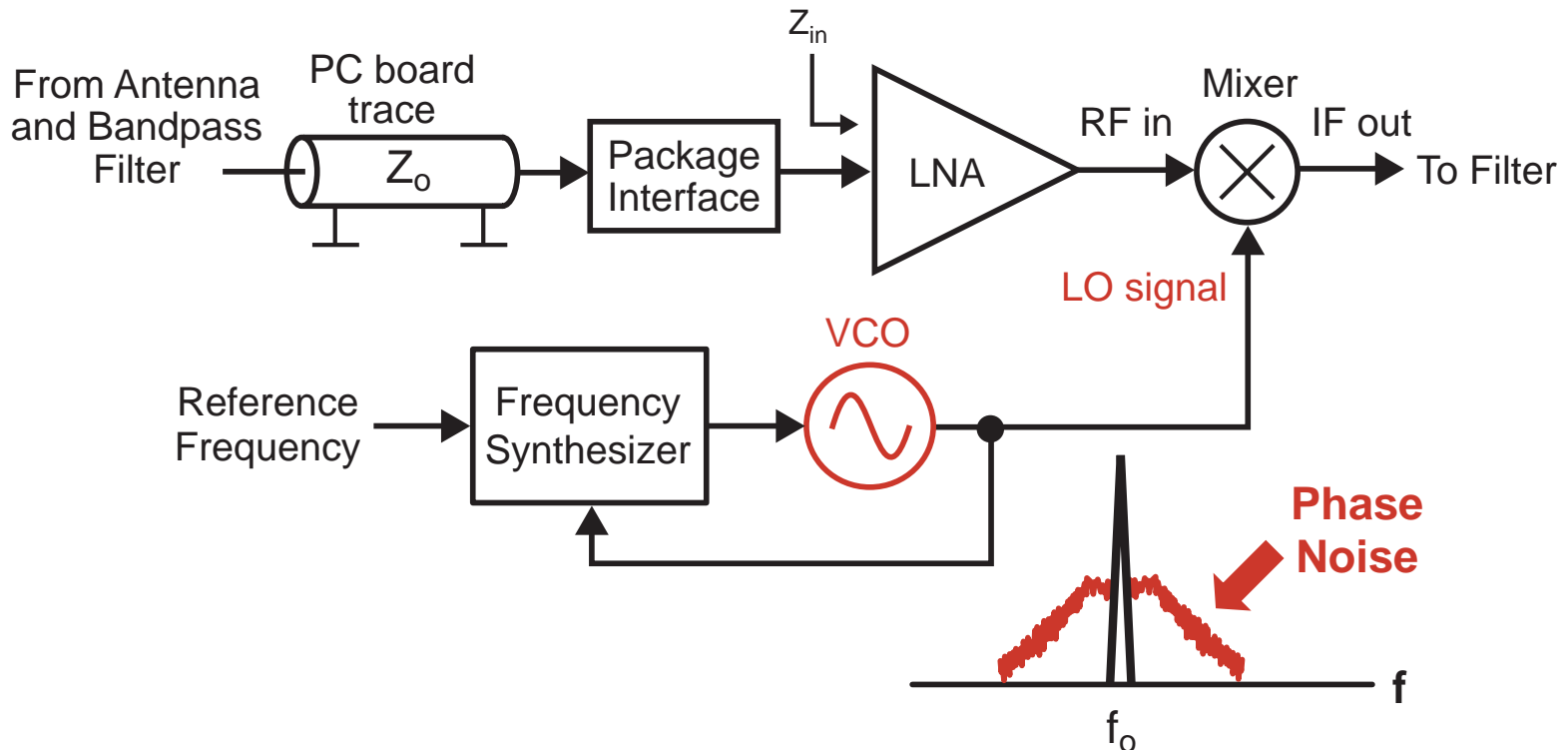
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**April 12, 2005**

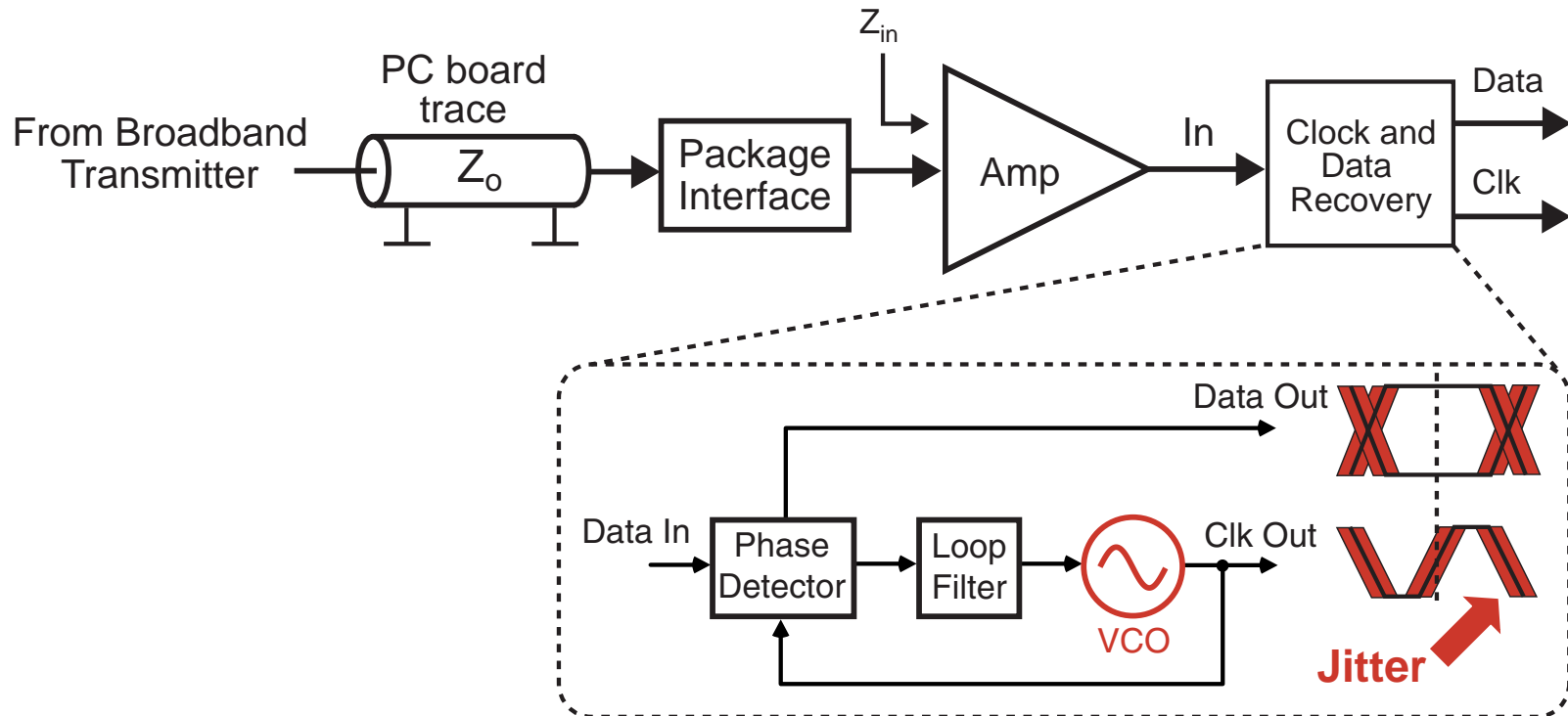
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# VCO Noise in Wireless Systems



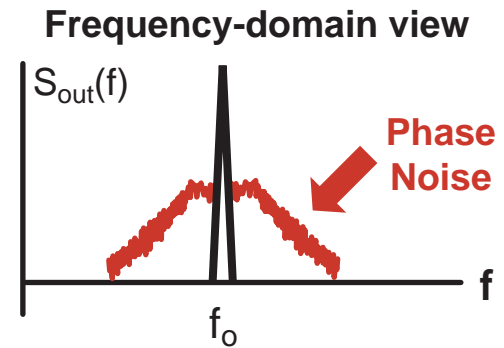
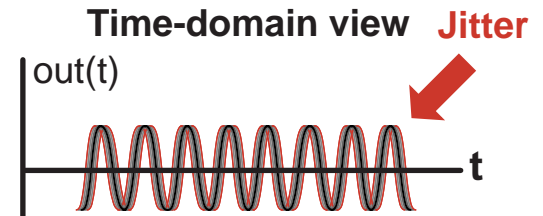
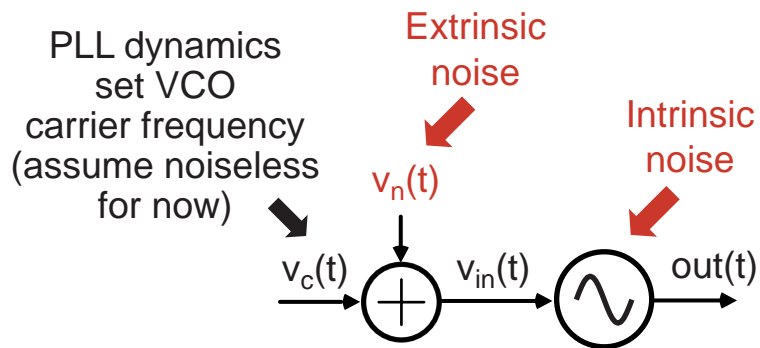
- **VCO noise has a negative impact on system performance**
  - Receiver – lower sensitivity, poorer blocking performance
  - Transmitter – increased spectral emissions (output spectrum must meet a mask requirement)
- **Noise is characterized in frequency domain**

# VCO Noise in High Speed Data Links



- **VCO noise also has a negative impact on data links**
  - Receiver – increases bit error rate (BER)
  - Transmitter – increases jitter on data stream (transmitter must have jitter below a specified level)
- **Noise is characterized in the time domain**

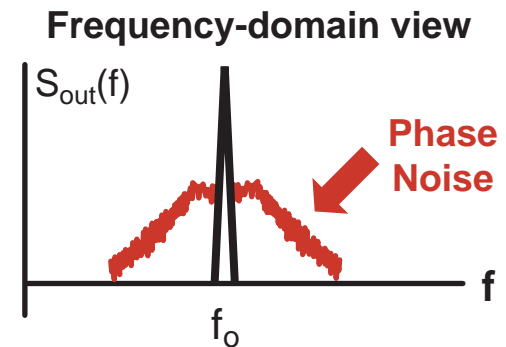
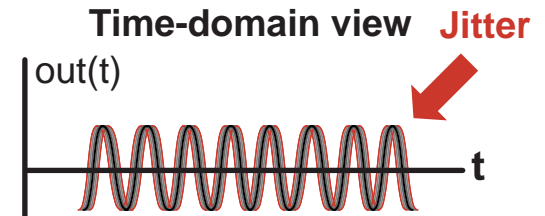
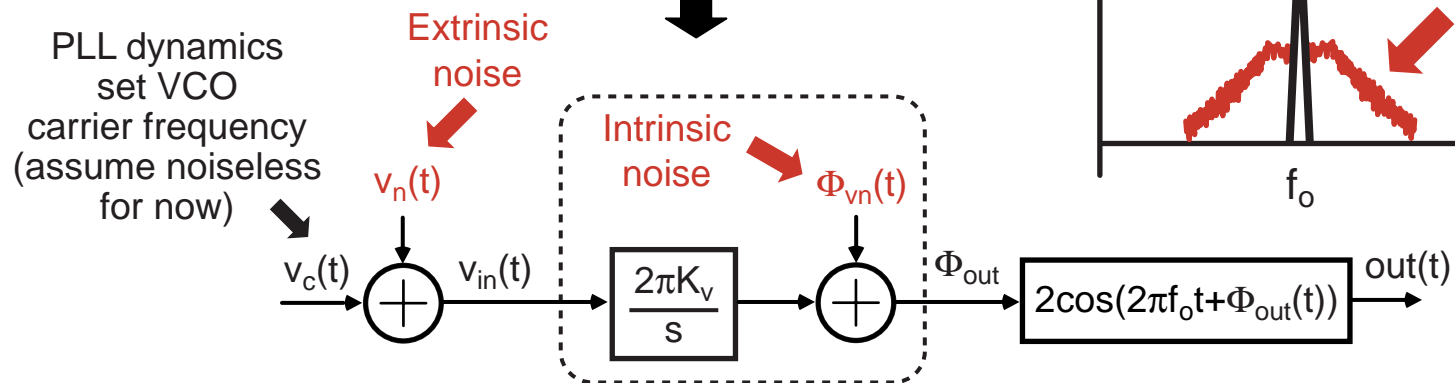
# Noise Sources Impacting VCO



- **Extrinsic noise**
  - Noise from other circuits (including PLL)
- **Intrinsic noise**
  - Noise due to the VCO circuitry

# VCO Model for Noise Analysis

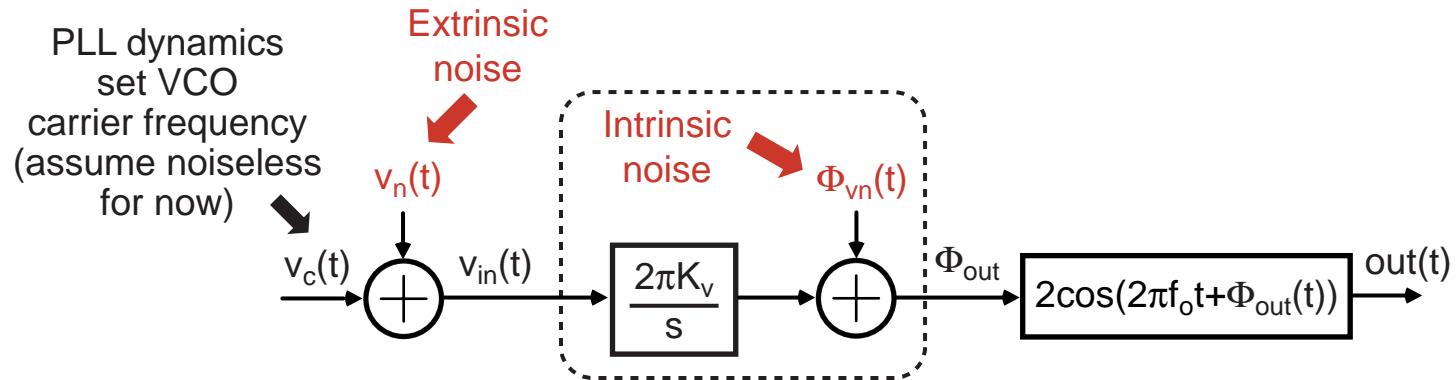
Note:  $K_V$  units are Hz/V



- We will focus on phase noise (and its associated jitter)
  - Model as phase signal in output sine waveform

$$out(t) = 2 \cos(2\pi f_0 t + \underline{\Phi_{out}(t)})$$

# Simplified Relationship Between $\Phi_{out}$ and Output



$$out(t) = 2 \cos(2\pi f_o t + \Phi_{out}(t))$$

- Using a familiar trigonometric identity

$$out(t) = 2 \cos(2\pi f_o t) \cos(\Phi_{out}(t)) - 2 \sin(2\pi f_o t) \sin(\Phi_{out}(t))$$

- Given that the phase noise is small

$$\cos(\Phi_{out}(t)) \approx 1, \quad \sin(\Phi_{out}(t)) \approx \Phi_{out}(t)$$

$$\Rightarrow out(t) = 2 \cos(2\pi f_o t) - 2 \sin(2\pi f_o t) \Phi_{out}(t)$$

## Calculation of Output Spectral Density

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$$\underline{out(t) = 2 \cos(2\pi f_o t) - 2 \sin(2\pi f_o t) \Phi_{out}(t)}$$

- Calculate autocorrelation

$$R\{out(t)\} = R\{2 \cos(2\pi f_o t)\} + R\{2 \sin(2\pi f_o t)\} \cdot R\{\Phi_{out}(t)\}$$

- Take Fourier transform to get spectrum

$$S_{out}(f) = S_{sin}(f) + S_{sin}(f) * S_{\Phi_{out}}$$

- Note that \* symbol corresponds to convolution
- In general, phase spectral density can be placed into one of two categories
  - Phase noise –  $\Phi_{out}(t)$  is non-periodic
  - Spurious noise -  $\Phi_{out}(t)$  is periodic

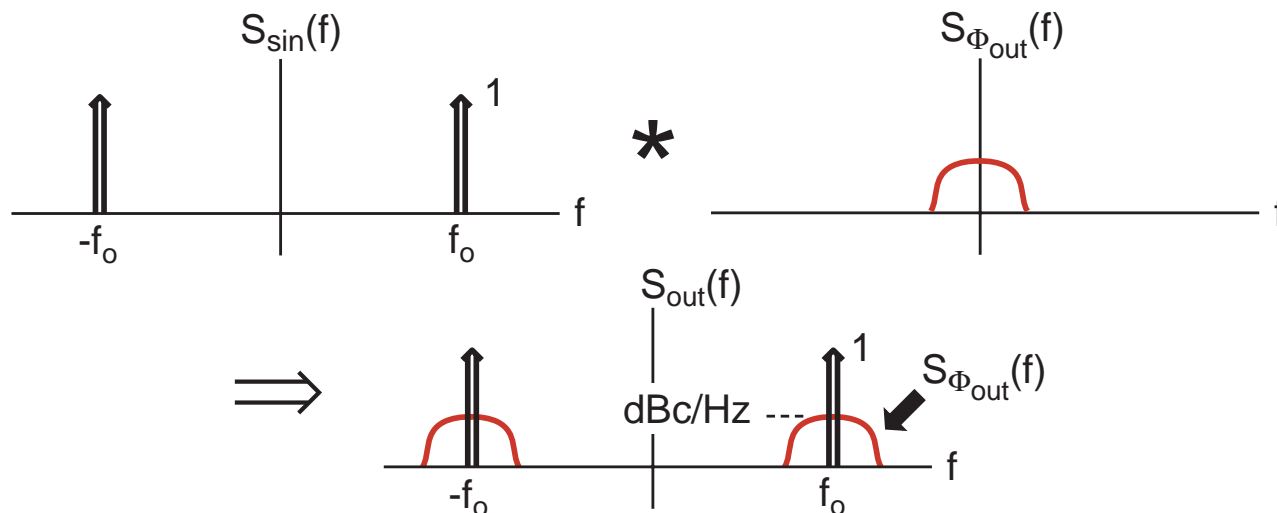
# Output Spectrum with Phase Noise

- Suppose input noise to VCO ( $v_n(t)$ ) is bandlimited, non-periodic noise with spectrum  $S_{v_n}(f)$ 
  - In practice, derive phase spectrum as

$$S_{\Phi_{out}}(f) = \left(\frac{K_v}{f}\right)^2 S_{v_n}(f)$$

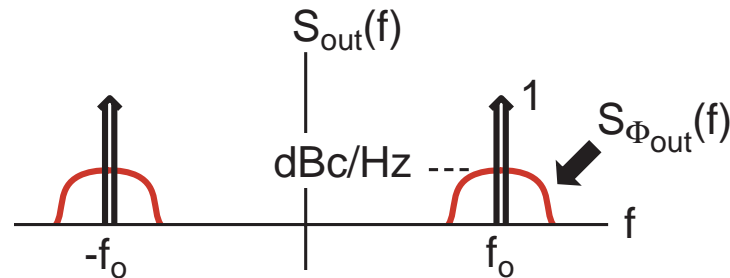
- Resulting output spectrum

$$S_{out}(f) = S_{sin}(f) + S_{sin}(f) * S_{\Phi_{out}}$$





# Measurement of Phase Noise in dBc/Hz



- **Definition of  $L(f)$**

$$L(f) = 10 \log \left( \frac{\text{Spectral density of noise}}{\text{Power of carrier}} \right)$$

- **Units are dBc/Hz**

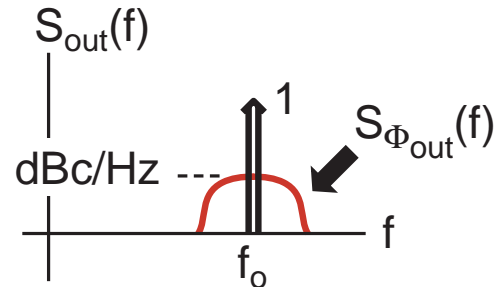
- **For this case**

$$L(f) = 10 \log \left( \frac{2S_{\Phi_{out}}(f)}{2} \right) = 10 \log(S_{\Phi_{out}}(f))$$

- **Valid when  $\Phi_{out}(t)$  is small in deviation (i.e., when carrier is not modulated, as currently assumed)**

## Single-Sided Version

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- **Definition of  $L(f)$  remains the same**

$$L(f) = 10 \log \left( \frac{\text{Spectral density of noise}}{\text{Power of carrier}} \right)$$

- **Units are dBc/Hz**

- **For this case**

$$L(f) = 10 \log \left( \frac{S_{\Phi_{out}}(f)}{1} \right) = 10 \log(S_{\Phi_{out}}(f))$$

- **So, we can work with either one-sided or two-sided spectral densities since  $L(f)$  is set by *ratio* of noise density to carrier power**

# Output Spectrum with Spurious Noise

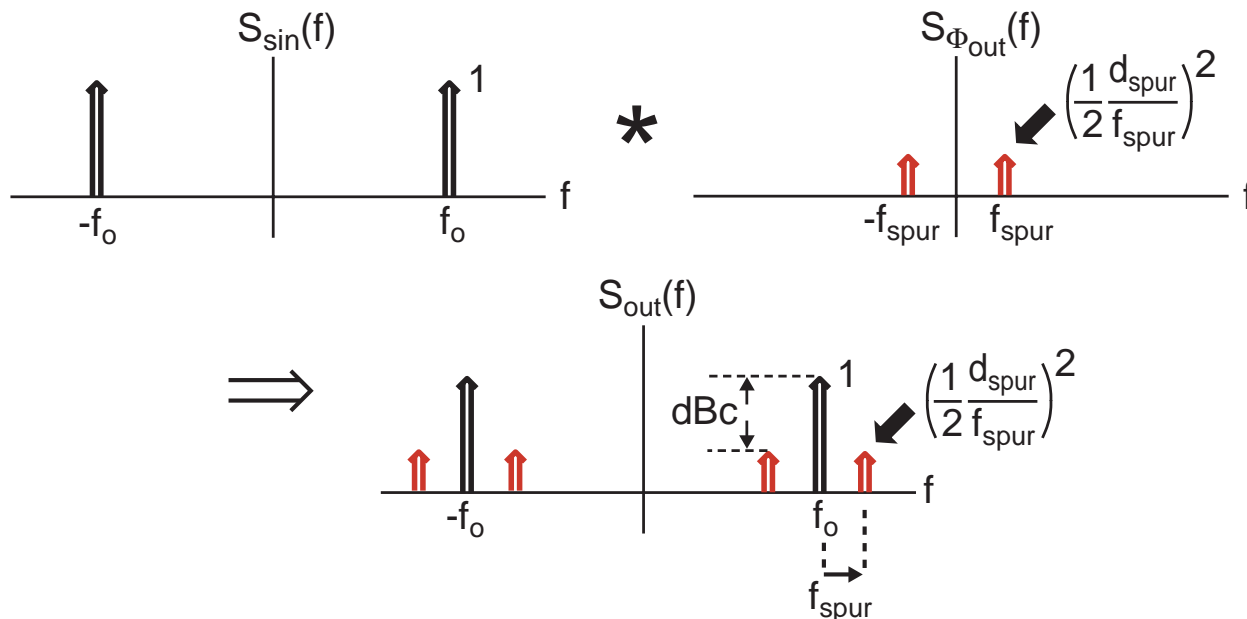
- Suppose input noise to VCO is

$$v_n(t) = \frac{d_{spur}}{K_v} \cos(2\pi f_{spur} t)$$

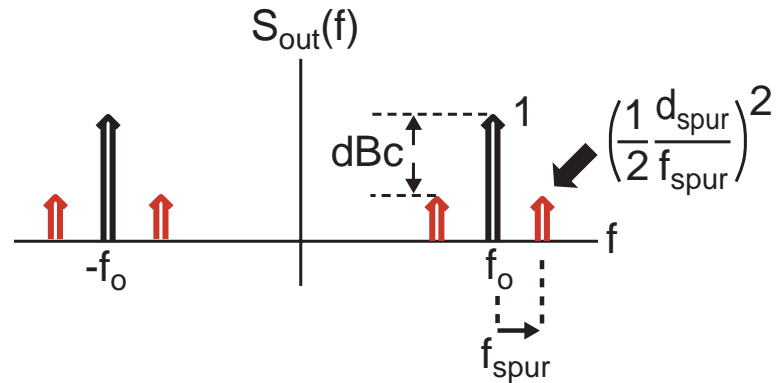
$$\Rightarrow \Phi_{out}(t) = 2\pi K_v \int v_n(t) dt = \frac{d_{spur}}{f_{spur}} \sin(2\pi f_{spur} t)$$

- Resulting output spectrum

$$S_{out}(f) = S_{sin}(f) + S_{sin}(f) * S_{\Phi_{out}}$$



# Measurement of Spurious Noise in dBc



## ■ Definition of dBc

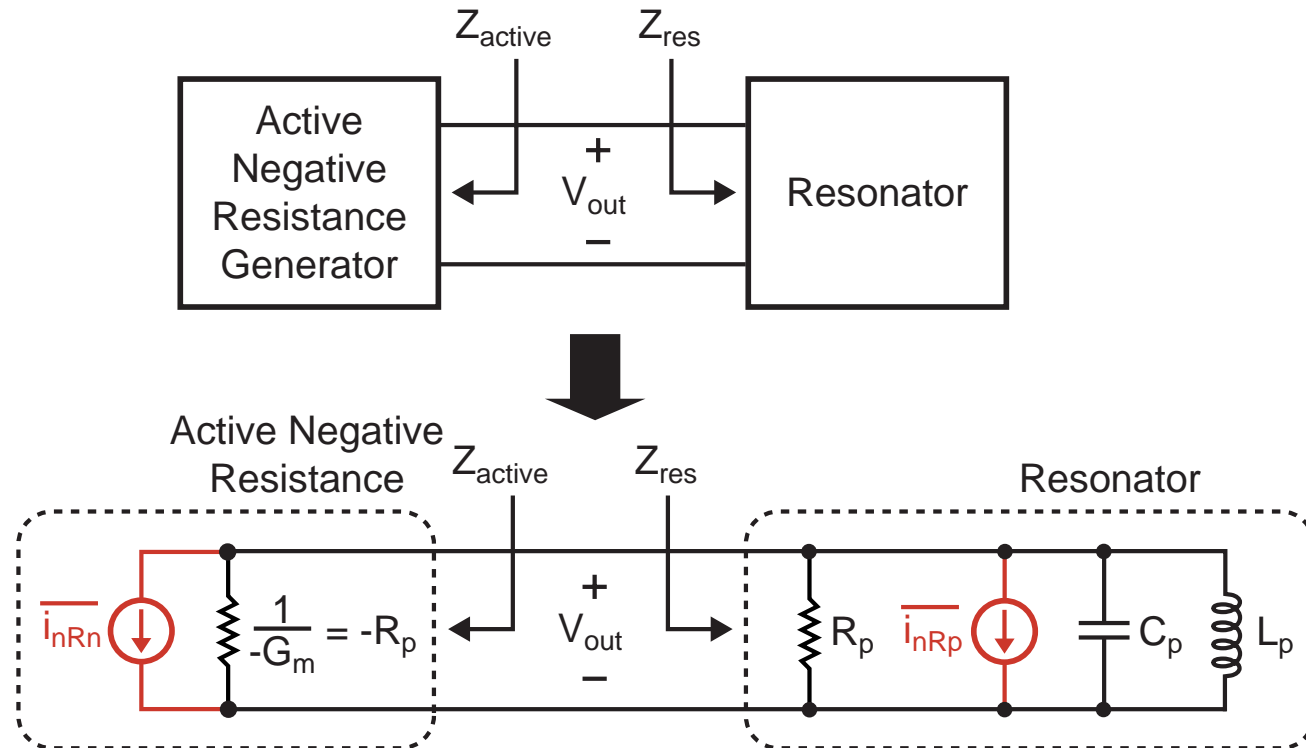
$$10 \log \left( \frac{\text{Power of tone}}{\text{Power of carrier}} \right)$$

- We are assuming double sided spectra, so integrate over positive and negative frequencies to get power
  - Either single or double-sided spectra can be used in practice

## ■ For this case

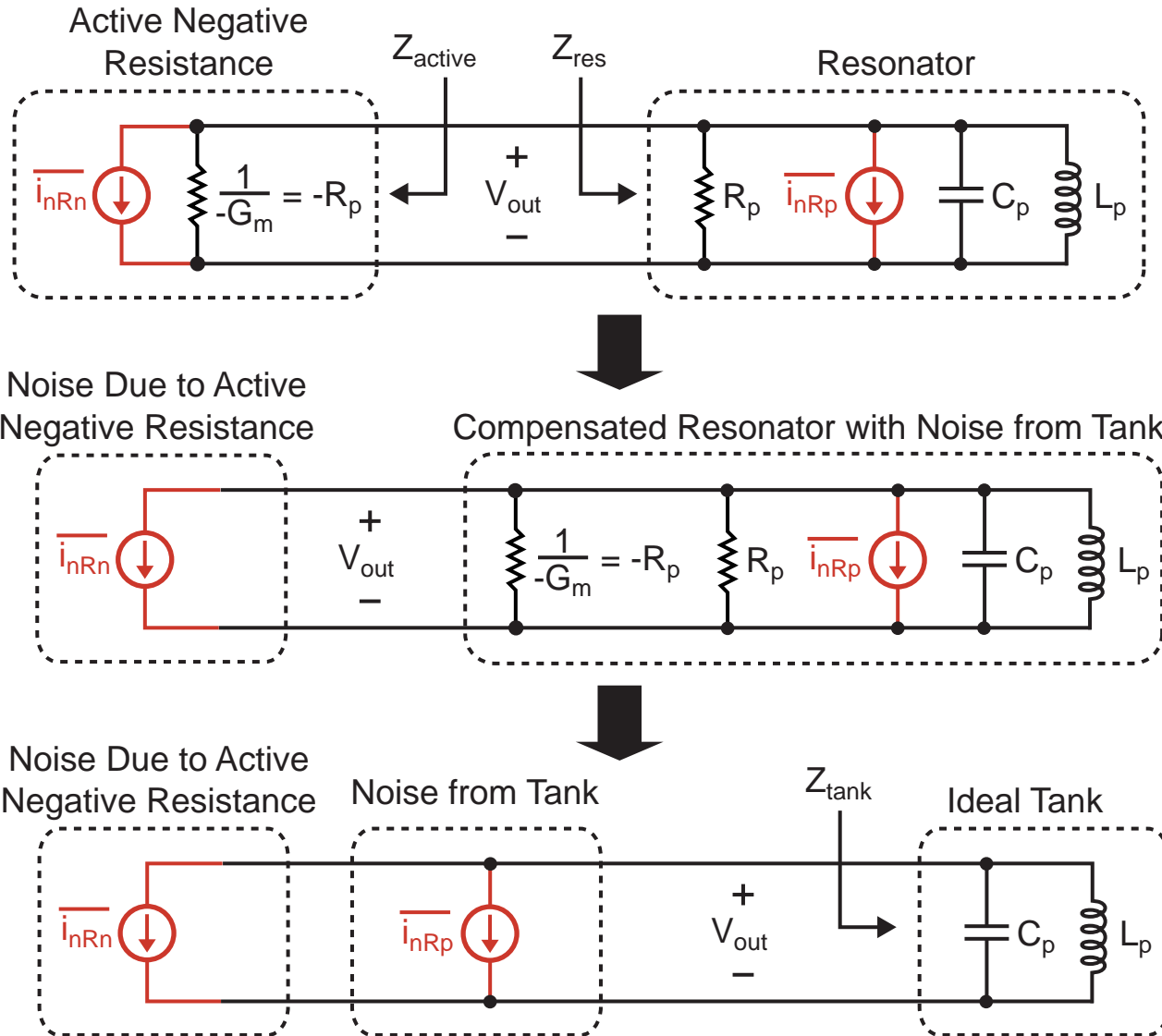
$$10 \log \left( \frac{2 \left( \frac{d_{spur}}{2 f_{spur}} \right)^2}{2} \right) = 20 \log \left( \frac{d_{spur}}{2 f_{spur}} \right) \text{ dBc}$$

# Calculation of Intrinsic Phase Noise in Oscillators

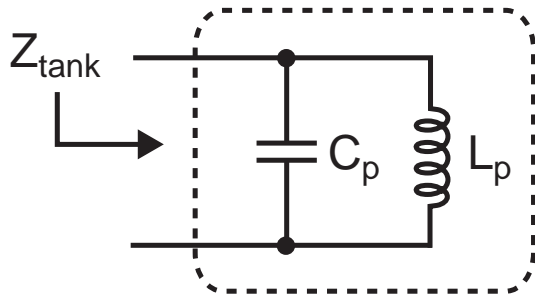


- **Noise sources in oscillators are put in two categories**
  - Noise due to tank loss
  - Noise due to active negative resistance
- **We want to determine how these noise sources influence the phase noise of the oscillator**

# Equivalent Model for Noise Calculations



# Calculate Impedance Across Ideal LC Tank Circuit



$$Z_{tank}(w) = \frac{1}{j\omega C_p} \parallel j\omega L_p = \frac{j\omega L_p}{1 - \omega^2 L_p C_p}$$

- Calculate input impedance about resonance

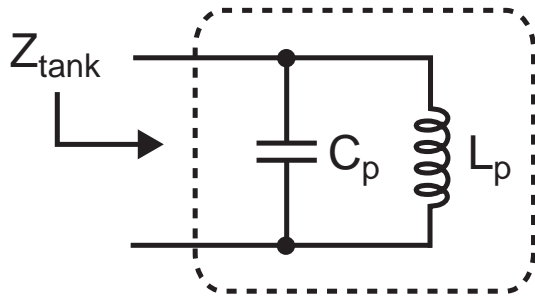
Consider  $\omega = \omega_o + \Delta\omega$ , where  $\omega_o = \frac{1}{\sqrt{L_p C_p}}$

$$Z_{tank}(\Delta\omega) = \frac{j(\omega_o + \Delta\omega)L_p}{1 - (\omega_o + \Delta\omega)^2 L_p C_p}$$

$$= \frac{j(\omega_o + \Delta\omega)L_p}{\underbrace{1 - \omega_o^2 L_p C_p}_{= 0} - 2\Delta\omega(\omega_o L_p C_p) - \underbrace{\Delta\omega^2 L_p C_p}_{\text{negligible}}} \approx \frac{j(\omega_o + \Delta\omega)L_p}{-2\Delta\omega(\omega_o L_p C_p)}$$

$$\Rightarrow Z_{tank}(\Delta\omega) \approx \frac{j\omega_o L_p}{-2\Delta\omega(\omega_o L_p C_p)} = \boxed{\frac{j}{2\omega_o C_p} \left( \frac{\omega_o}{\Delta\omega} \right)}$$

# A Convenient Parameterization of LC Tank Impedance



$$Z_{tank}(\Delta\omega) \approx -\frac{j}{2\omega_o C_p} \left( \frac{\omega_o}{\Delta\omega} \right)$$

- **Actual tank has loss that is modeled with  $R_p$** 
  - Define  $Q$  according to actual tank

$$Q = R_p \omega_o C_p \Rightarrow \frac{1}{\omega_o C_p} = \frac{R_p}{Q}$$

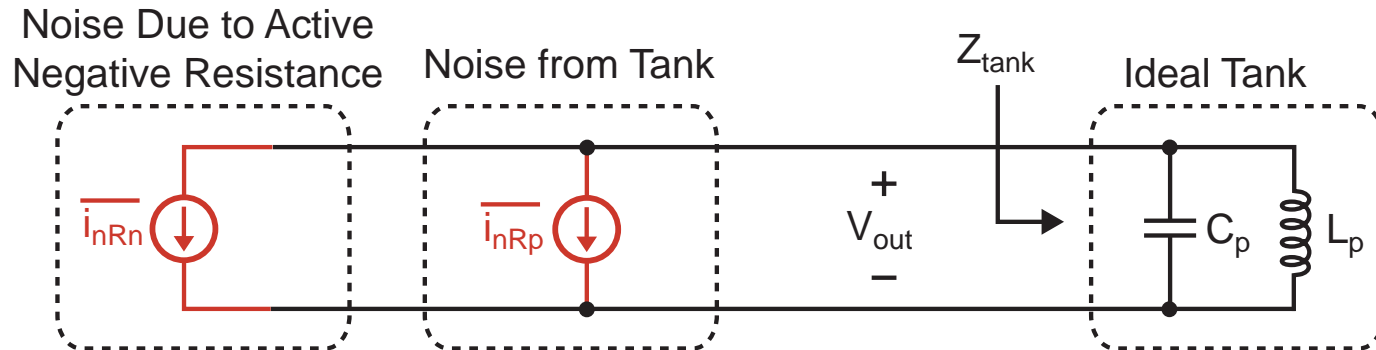
- **Parameterize ideal tank impedance in terms of  $Q$  of actual tank**

$$Z_{tank}(\Delta\omega) \approx -\frac{j R_p}{2 Q} \left( \frac{\omega_o}{\Delta\omega} \right)$$

$$\Rightarrow |Z_{tank}(\Delta f)|^2 \approx \left( \frac{R_p f_o}{2Q \Delta f} \right)^2$$



# Overall Noise Output Spectral Density

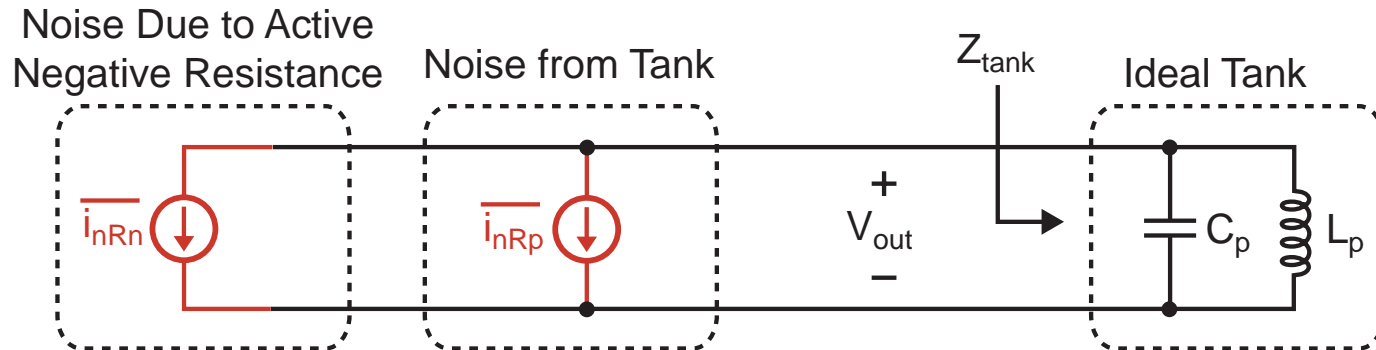


- Assume noise from active negative resistance element and tank are uncorrelated

$$\begin{aligned} \frac{\overline{v_{out}^2}}{\Delta f} &= \left( \frac{\overline{i_{nRp}^2}}{\Delta f} + \frac{\overline{i_{nRn}^2}}{\Delta f} \right) |Z_{tank}(\Delta f)|^2 \\ &= \frac{\overline{i_{nRp}^2}}{\Delta f} \left( 1 + \frac{\overline{i_{nRn}^2}}{\Delta f} / \frac{\overline{i_{nRp}^2}}{\Delta f} \right) |Z_{tank}(\Delta f)|^2 \end{aligned}$$

- Note that the above expression represents total noise that impacts both amplitude and phase of oscillator output

# Parameterize Noise Output Spectral Density



- From previous slide

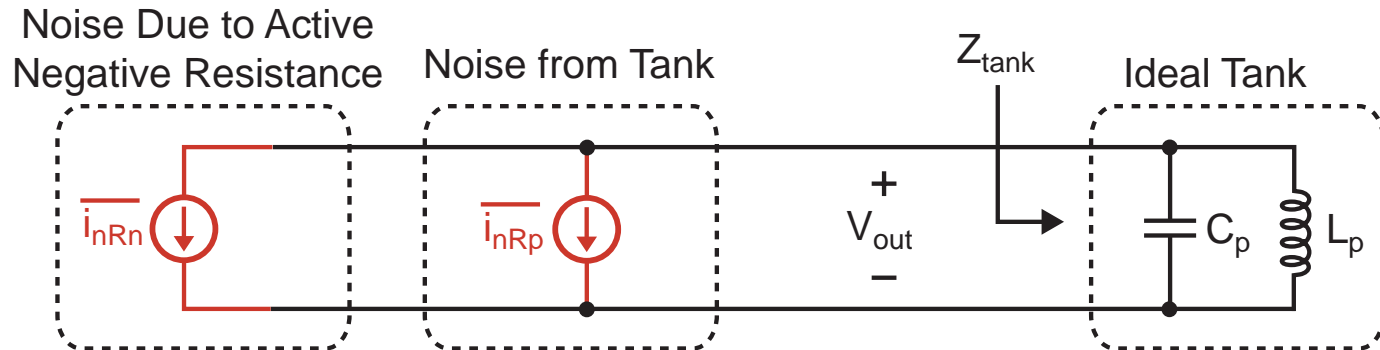
$$\frac{\overline{v_{out}^2}}{\Delta f} = \frac{\overline{i_{nRp}^2}}{\Delta f} \left( 1 + \frac{\overline{i_{nRn}^2}}{\Delta f} / \frac{\overline{i_{nRp}^2}}{\Delta f} \right) |Z_{tank}(\Delta f)|^2$$

**F( $\Delta f$ )**

- F( $\Delta f$ ) is defined as**

$$F(\Delta f) = \frac{\text{total noise in tank at frequency } \Delta f}{\text{noise in tank due to tank loss at frequency } \Delta f}$$

## Fill in Expressions



- **Noise from tank is due to resistor  $R_p$**

$$\frac{\overline{i_{nRp}^2}}{\Delta f} = 4kT \frac{1}{R_p} \quad (\text{single-sided spectrum})$$

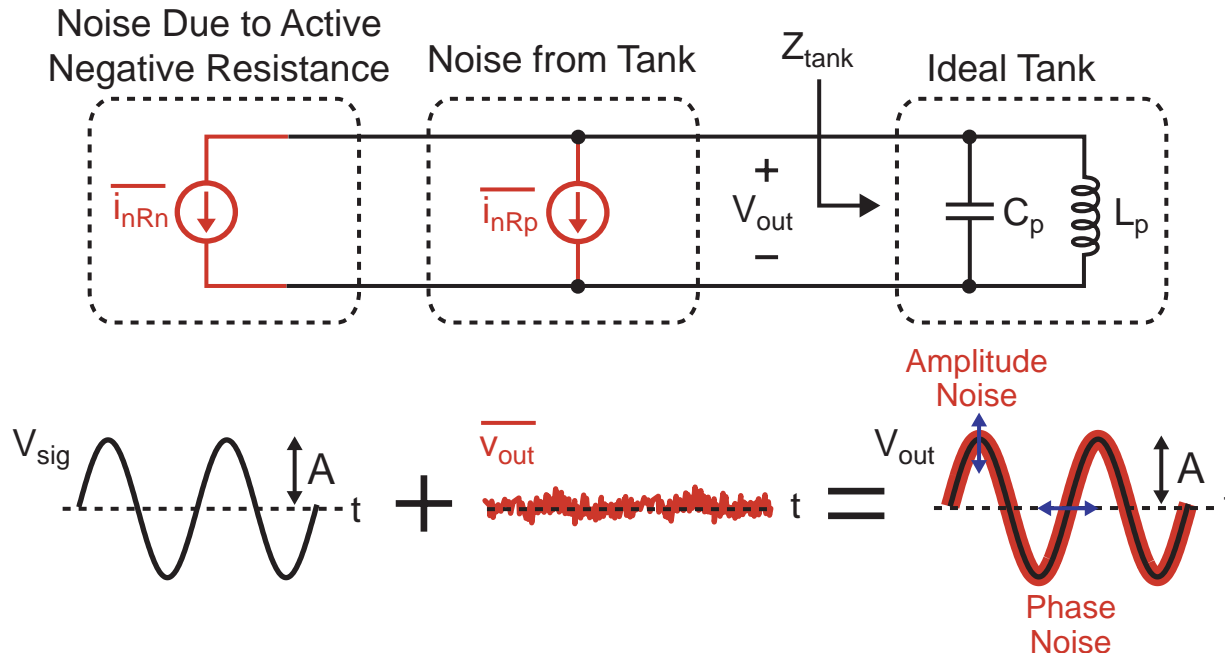
- **$Z_{\text{tank}}(\Delta f)$  found previously**

$$|Z_{\text{tank}}(\Delta f)|^2 \approx \left( \frac{R_p f_o}{2Q \Delta f} \right)^2$$

- **Output noise spectral density expression (single-sided)**

$$\frac{\overline{v_{out}^2}}{\Delta f} = 4kT \frac{1}{R_p} F(\Delta f) \left( \frac{R_p f_o}{2Q \Delta f} \right)^2 = \boxed{4kT F(\Delta f) R_p \left( \frac{1}{2Q \Delta f} \right)^2}$$

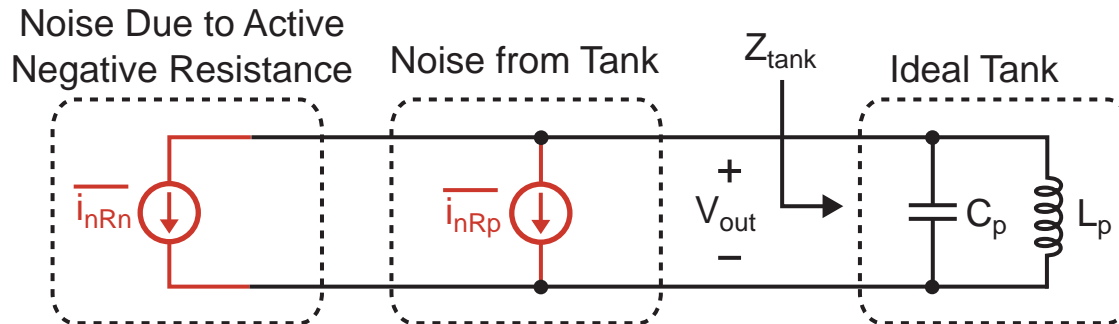
# Separation into Amplitude and Phase Noise



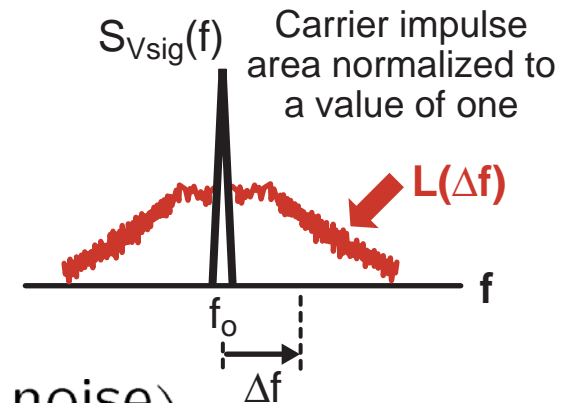
- Equipartition theorem (see Tom Lee, p 534 (1<sup>st</sup> ed.)) states that noise impact splits evenly between amplitude and phase for  $V_{sig}$  being a sine wave
  - Amplitude variations suppressed by feedback in oscillator

$$\Rightarrow \frac{\overline{v_{out}^2}}{\Delta f} \Big|_{\text{phase}} = 2kTF(\Delta f)R_p \left( \frac{1}{2Q} \frac{f_o}{\Delta f} \right)^2 \quad (\text{single-sided})$$

# Output Phase Noise Spectrum (Leeson's Formula)



## Output Spectrum



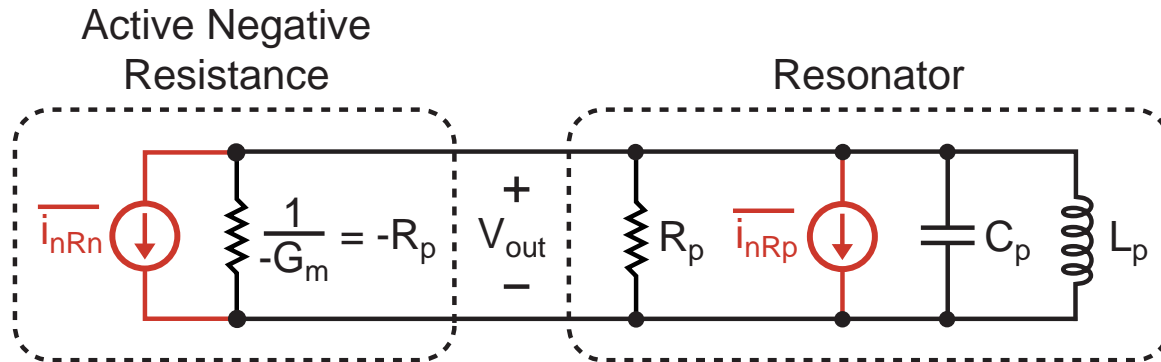
$$L(\Delta f) = 10 \log \left( \frac{\text{Spectral density of noise}}{\text{Power of carrier}} \right)$$

- All power calculations are referenced to the tank loss resistance,  $R_p$

$$P_{sig} = \frac{V_{sig,rms}^2}{R_p} = \frac{(A/\sqrt{2})^2}{R_p}, \quad S_{noise}(\Delta f) = \frac{1}{R_p} \overline{v_{out}^2} \Delta f$$

$$L(\Delta f) = 10 \log \left( \frac{S_{noise}(\Delta f)}{P_{sig}} \right) = 10 \log \left( \frac{2kTF(\Delta f)}{P_{sig}} \left( \frac{1}{2Q} \frac{f_o}{\Delta f} \right)^2 \right)$$

## Example: Active Noise Same as Tank Noise

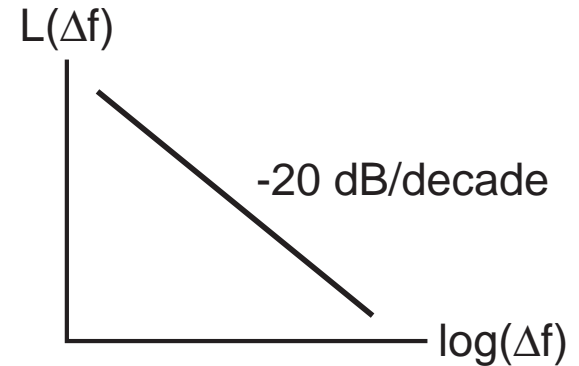


- Noise factor for oscillator in this case is

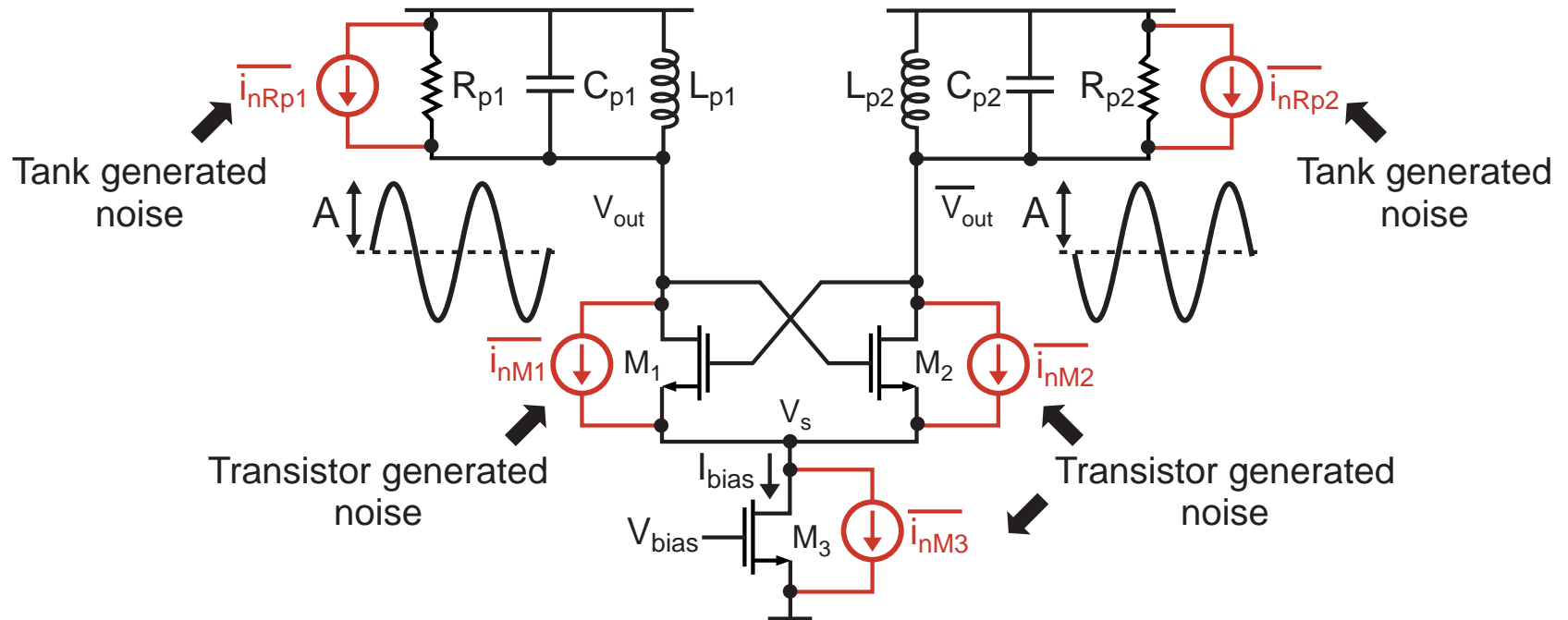
$$F(\Delta f) = 1 + \frac{\overline{i_{nRn}^2}}{\Delta f} / \frac{\overline{i_{nRp}^2}}{\Delta f} = 2$$

- Resulting phase noise

$$L(\Delta f) = 10 \log \left( \frac{4kT}{P_{sig}} \left( \frac{1}{2Q} \frac{f_o}{\Delta f} \right)^2 \right)$$

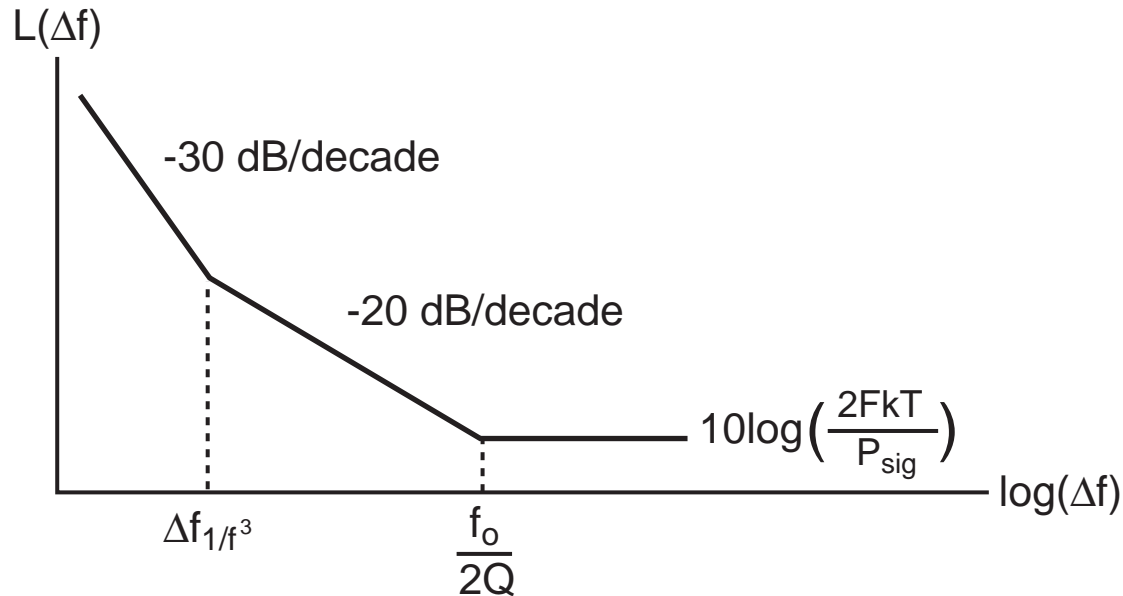


# The Actual Situation is Much More Complicated



- Impact of tank generated noise easy to assess
- Impact of transistor generated noise is complicated
  - Noise from  $M_1$  and  $M_2$  is modulated on and off
  - Noise from  $M_3$  is modulated before influencing  $V_{out}$
  - Transistors have  $1/f$  noise
- Also, transistors can degrade Q of tank

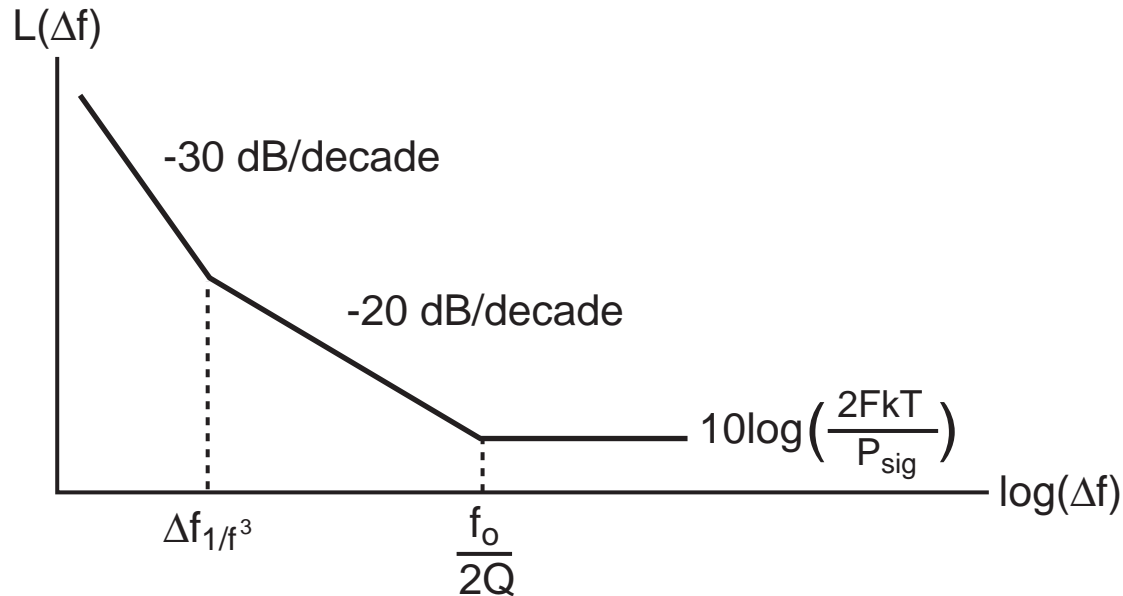
# Phase Noise of A Practical Oscillator



- Phase noise drops at  $-20$  dB/decade over a wide frequency range, but deviates from this at:
  - Low frequencies – slope increases (often  $-30$  dB/decade)
  - High frequencies – slope flattens out (oscillator tank does not filter all noise sources)
- Frequency breakpoints and magnitude scaling are not readily predicted by the analysis approach taken so far



# Phase Noise of A Practical Oscillator

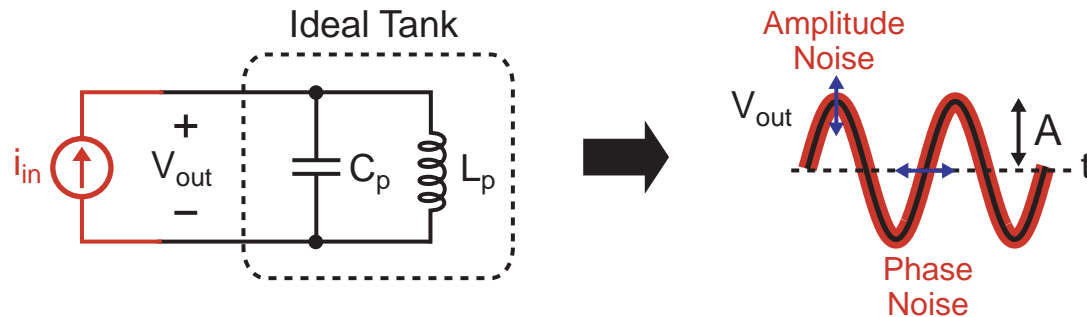


- Leeson proposed an ad hoc modification of the phase noise expression to capture the above noise profile

$$L(\Delta f) = 10 \log \left( \frac{2FkT}{P_{sig}} \left( 1 + \left( \frac{1}{2Q} \frac{f_o}{\Delta f} \right)^2 \right) \left( 1 + \frac{\Delta f_{1/f^3}}{|\Delta f|} \right) \right)$$

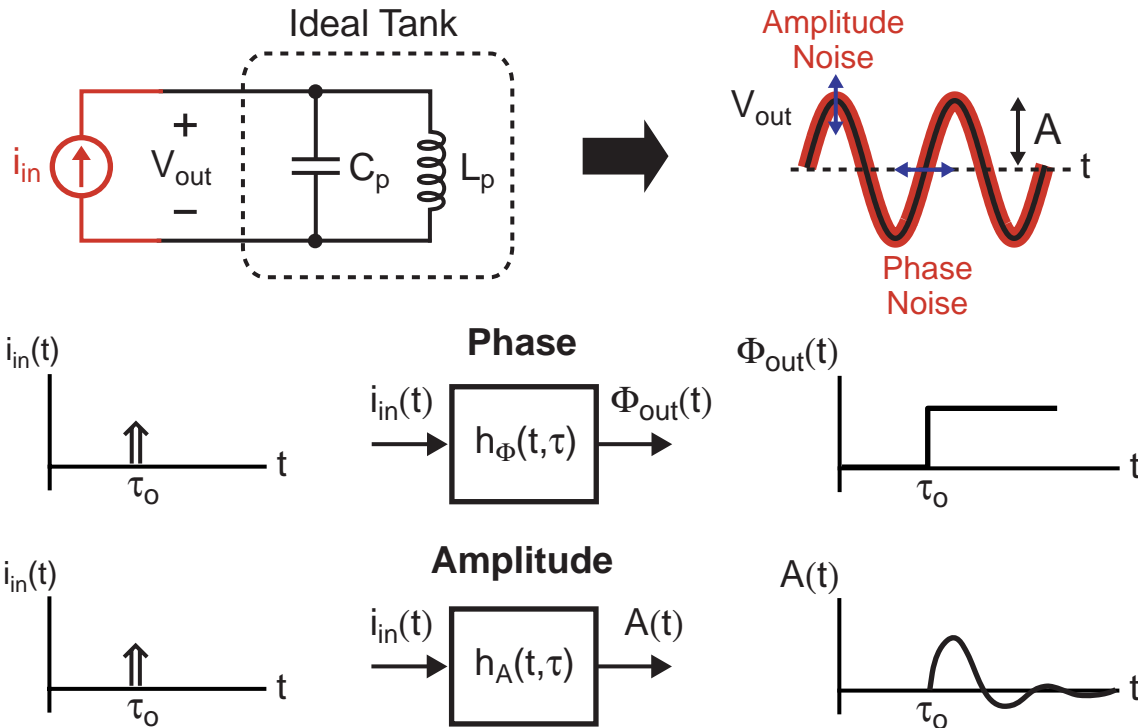
- Note: he assumed that  $F(\Delta f)$  was constant over frequency

# A More Sophisticated Analysis Method



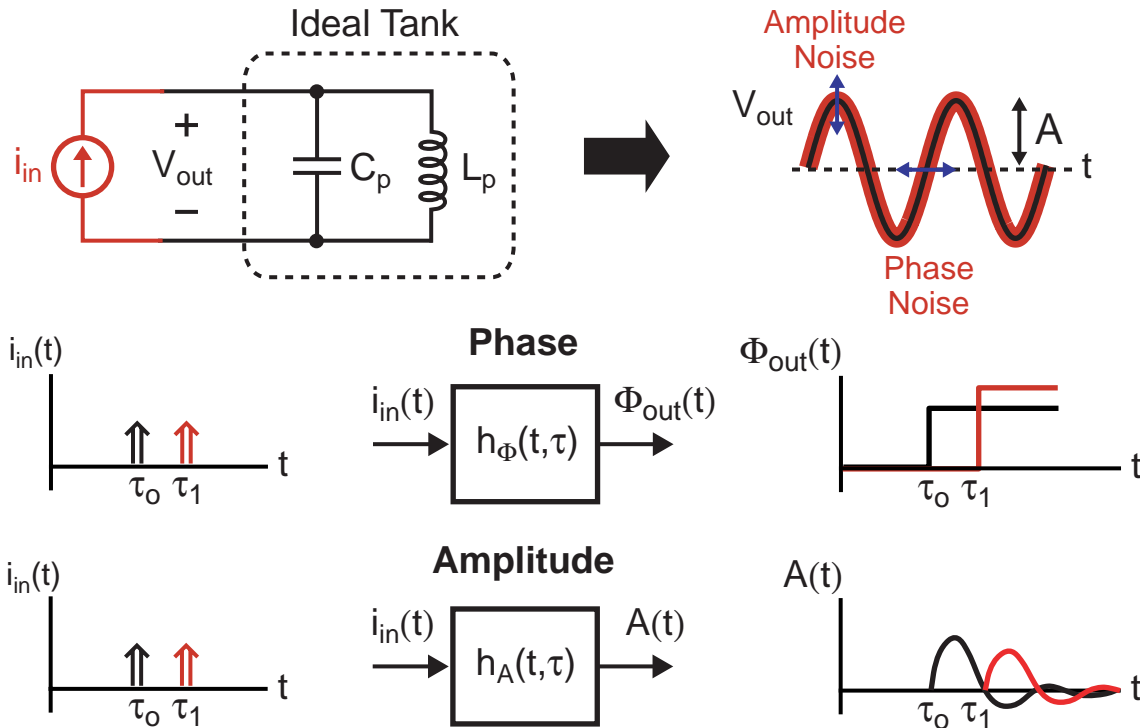
- Our concern is what happens when noise current produces a voltage across the tank
  - Such voltage deviations give rise to both amplitude and phase noise
  - Amplitude noise is suppressed through feedback (or by amplitude limiting in following buffer stages)
    - Our main concern is phase noise
- We argued that impact of noise divides equally between amplitude and phase for sine wave outputs
  - What happens when we have a non-sine wave output?

# Modeling of Phase and Amplitude Perturbations



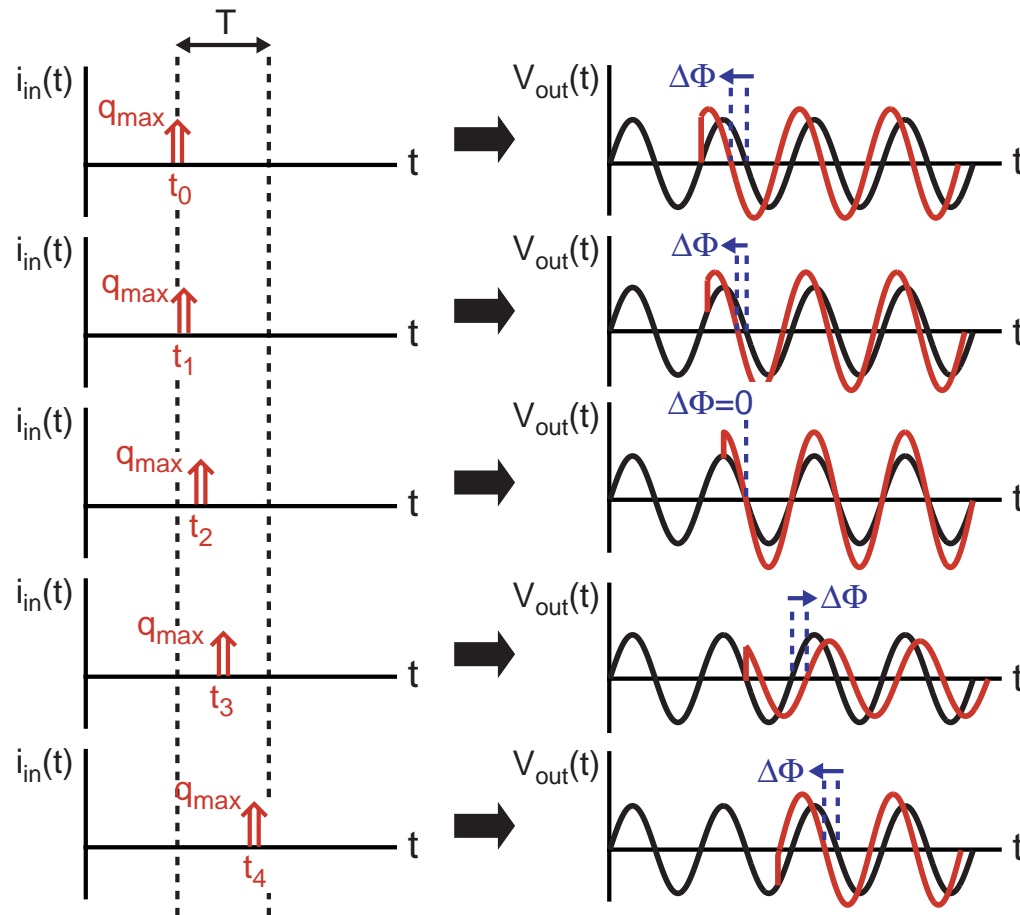
- Characterize impact of current noise on amplitude and phase through their associated impulse responses
  - Phase deviations are accumulated
  - Amplitude deviations are suppressed

# Impact of Noise Current is Time-Varying



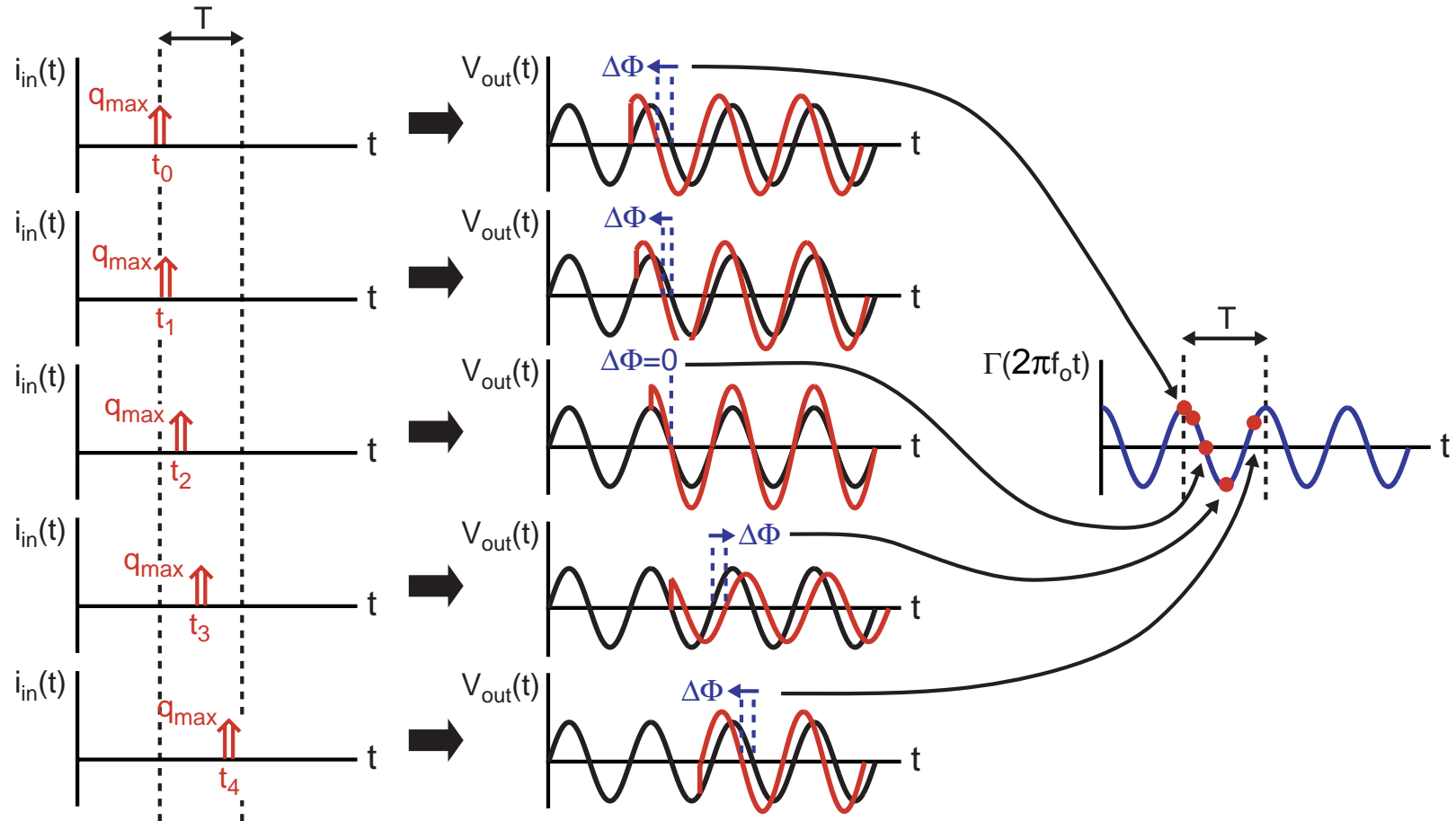
- If we vary the time at which the current impulse is injected, its impact on phase and amplitude changes
  - Need a time-varying model

# Illustration of Time-Varying Impact of Noise on Phase



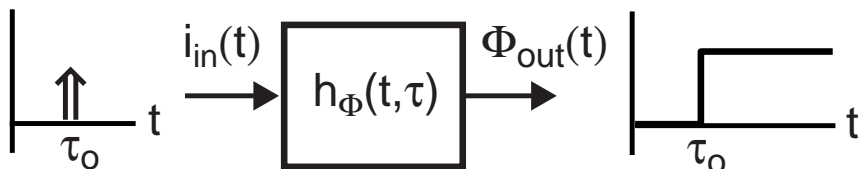
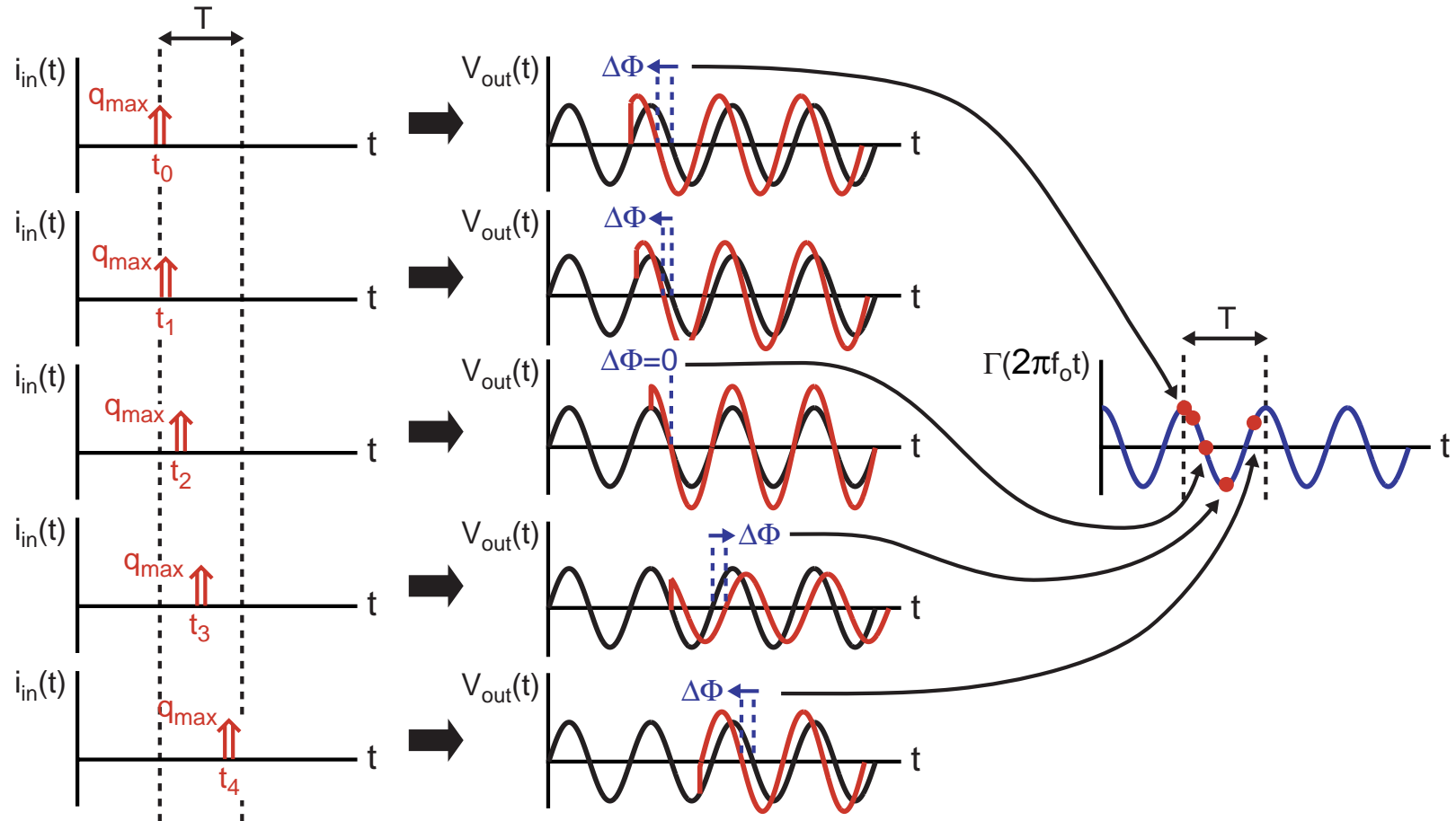
- High impact on phase when impulse occurs close to the zero crossing of the VCO output
- Low impact on phase when impulse occurs at peak of output

# Define Impulse Sensitivity Function (ISF) – $\Gamma(2\pi f_o t)$



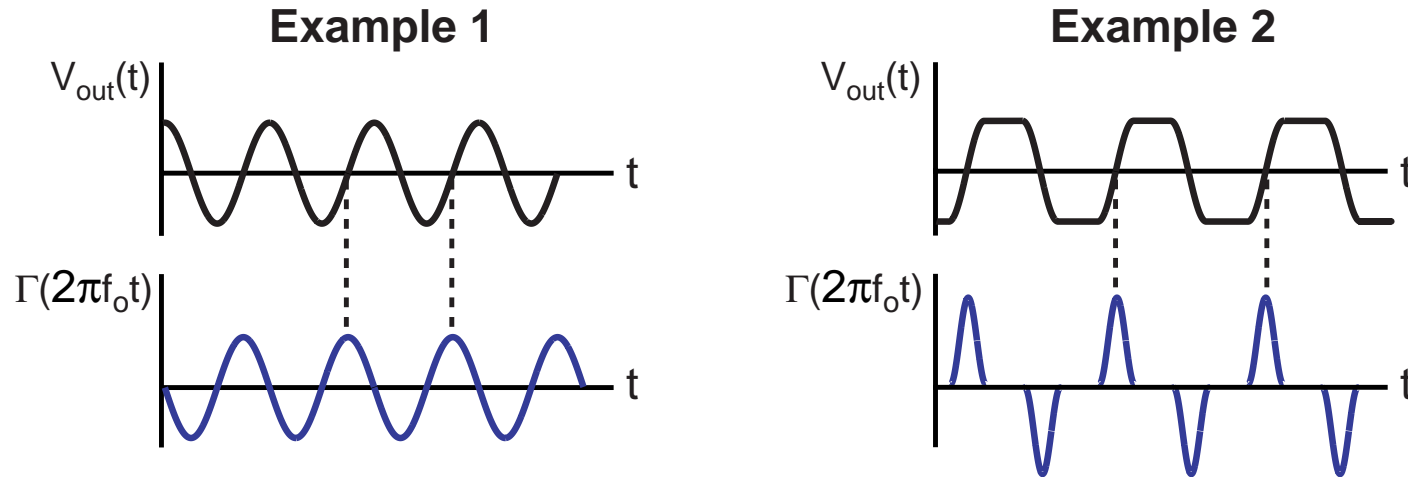
- ISF constructed by calculating phase deviations as impulse position is varied
  - Observe that it is periodic with same period as VCO output

# Parameterize Phase Impulse Response in Terms of ISF



$$h_{\Phi}(t, \tau) = \frac{\Gamma(2\pi f_0 \tau)}{q_{max}} u(t - \tau)$$

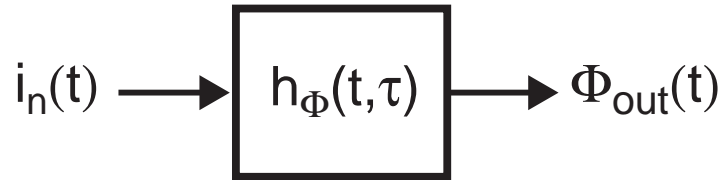
# Examples of ISF for Different VCO Output Waveforms



- **ISF (i.e.,  $\Gamma$ ) is approximately proportional to derivative of VCO output waveform**
  - Its magnitude indicates where VCO waveform is most sensitive to noise current into tank with respect to creating phase noise
- **ISF is periodic**
- **In practice, derive it from simulation of the VCO**



# Phase Noise Analysis Using LTV Framework



- **Computation of phase deviation for an arbitrary noise current input**

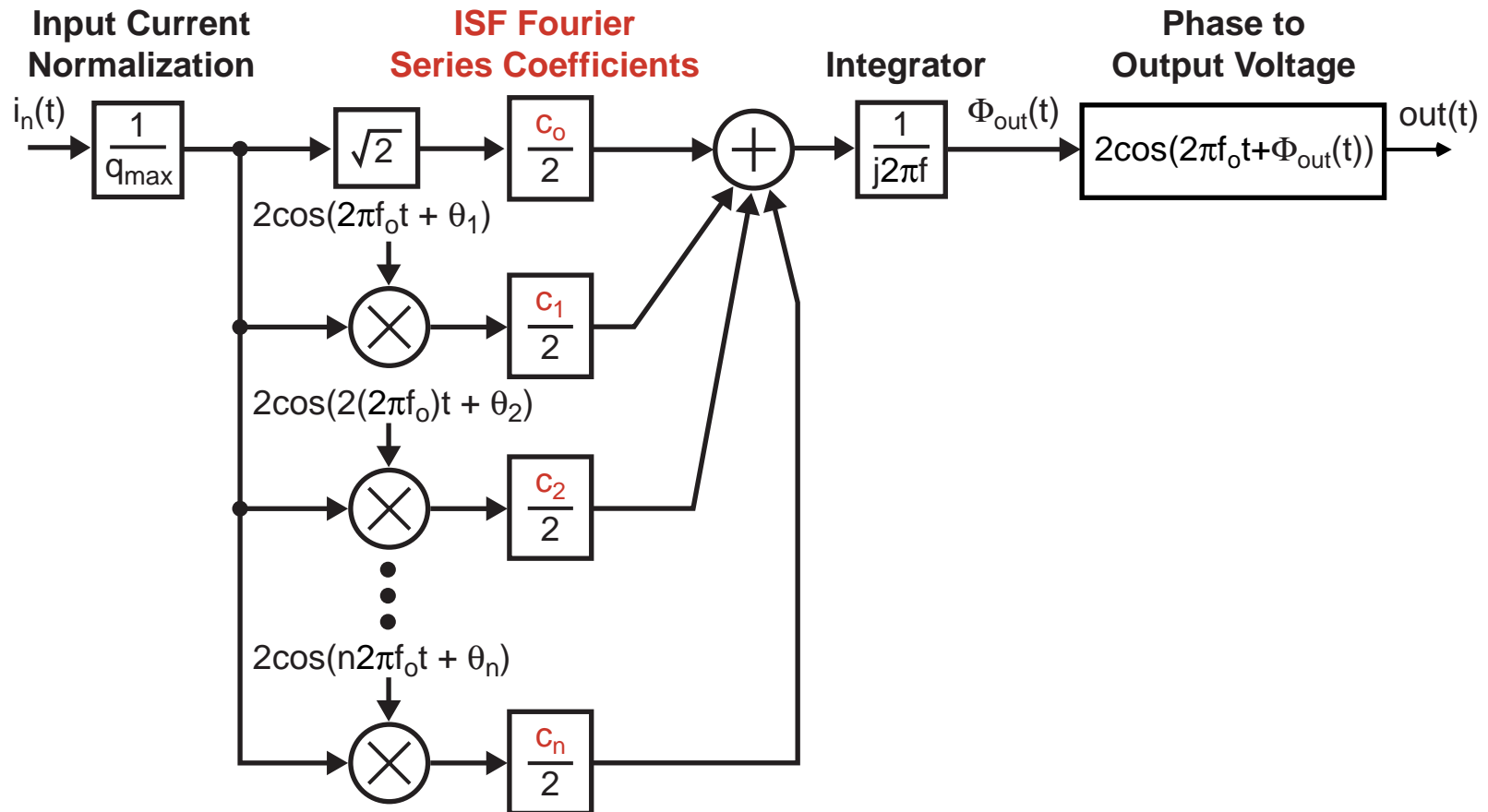
$$\Phi_{out}(t) = \int_{-\infty}^{\infty} h_\Phi(t, \tau) i_n(\tau) d\tau = \frac{1}{q_{max}} \int_{-\infty}^t \Gamma(2\pi f_o \tau) i_n(\tau) d\tau$$

- **Analysis simplified if we describe ISF in terms of its Fourier series (note:  $c_o$  here is different than book)**

$$\Gamma(2\pi f_o \tau) = \frac{c_o}{\sqrt{2}} + \sum_{n=1}^{\infty} c_n \cos(n2\pi f_o \tau + \theta_n)$$

$$\Rightarrow \Phi_{out}(t) = \int_{-\infty}^t \left( \frac{c_o}{\sqrt{2}} + \sum_{n=1}^{\infty} c_n \cos(n2\pi f_o \tau + \theta_n) \right) \frac{i_n(\tau)}{q_{max}} d\tau$$

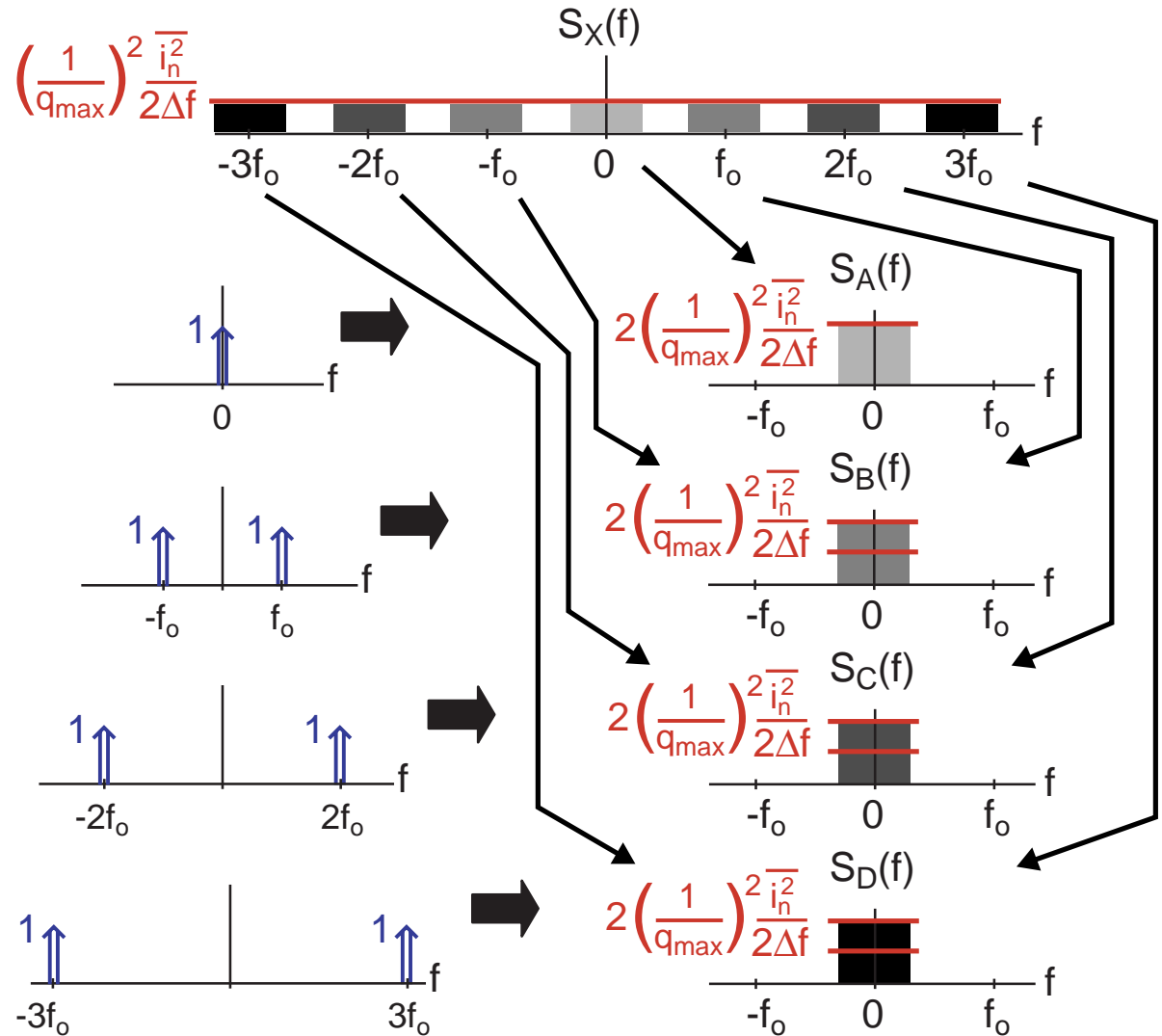
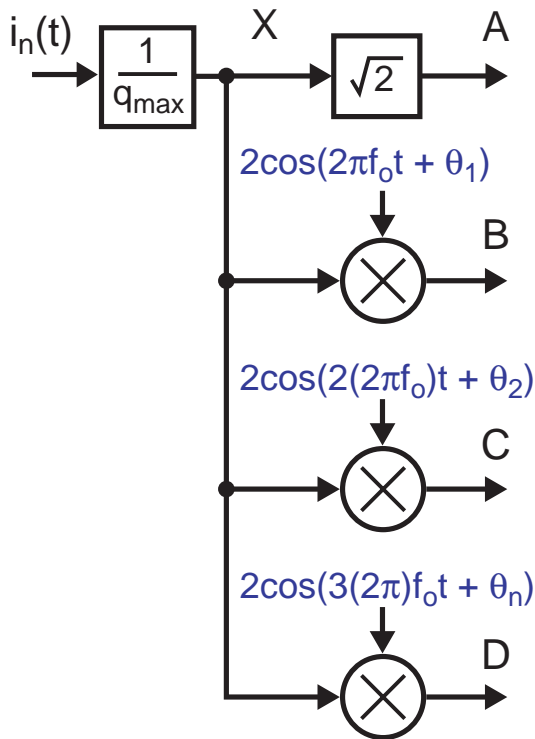
# Block Diagram of LTV Phase Noise Expression



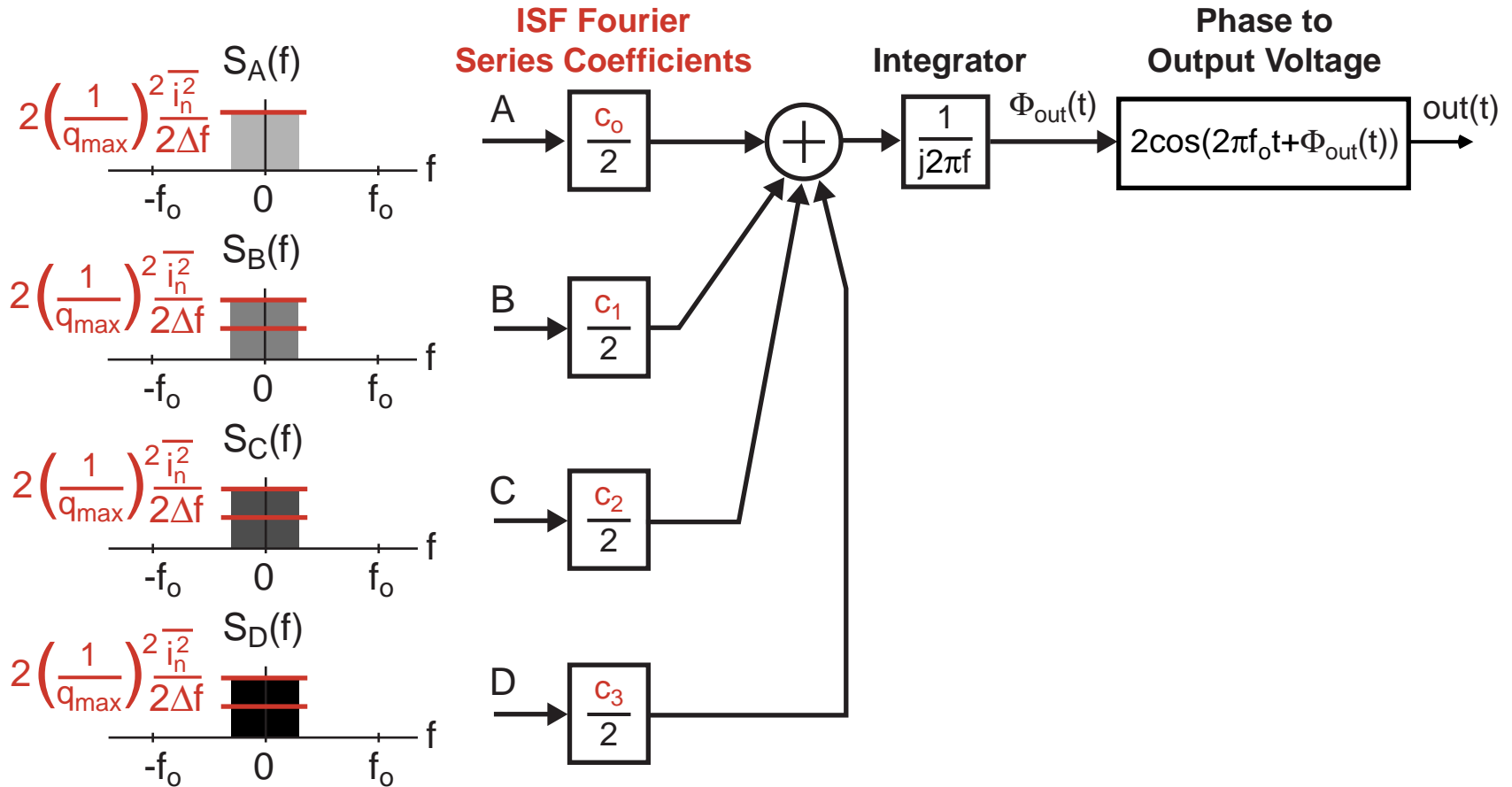
- **Noise from current source is mixed down from different frequency bands and scaled according to ISF coefficients**

# Phase Noise Calculation for White Noise Input (Part 1)

Note that  $\frac{\overline{i_n^2}}{\Delta f}$  is the single-sided noise spectral density of  $i_n(t)$



# Phase Noise Calculation for White Noise Input (Part 2)



$$S_{\Phi_{out}}(f) = \left| \frac{1}{j2\pi f} \right|^2 \left( \left( \frac{c_0}{2} \right)^2 S_A(f) + \left( \frac{c_1}{2} \right)^2 S_B(f) + \dots \right)$$

# Spectral Density of Phase Signal

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- From the previous slide

$$S_{\Phi_{out}}(f) = \left(\frac{1}{2\pi f}\right)^2 \left( \left(\frac{c_0}{2}\right)^2 S_A(f) + \left(\frac{c_1}{2}\right)^2 S_B(f) + \dots \right)$$

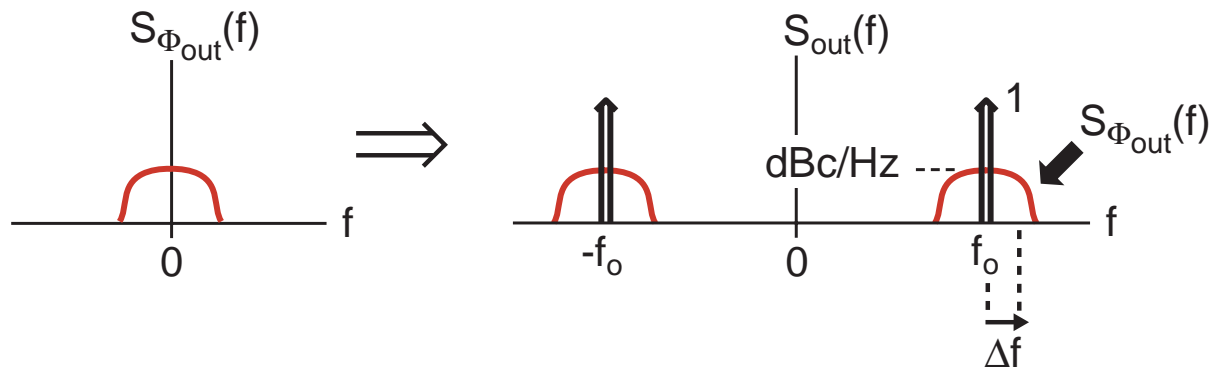
- Substitute in for  $S_A(f)$ ,  $S_B(f)$ , etc.

$$S_{\Phi_{out}}(f) = \left(\frac{1}{2\pi f}\right)^2 \left( \left(\frac{c_0}{2}\right)^2 + \left(\frac{c_1}{2}\right)^2 + \dots \right) 2 \left(\frac{1}{q_{max}}\right)^2 \frac{\overline{i_n^2}}{2\Delta f}$$

- Resulting expression

$$S_{\Phi_{out}}(f) = \left(\frac{1}{2\pi f}\right)^2 \left( \sum_{n=0}^{\infty} c_n^2 \right) \frac{1}{4} \left(\frac{1}{q_{max}}\right)^2 \frac{\overline{i_n^2}}{\Delta f}$$

# Output Phase Noise



- We now know

$$S_{\Phi_{out}}(f) = \left| \frac{1}{2\pi f} \right|^2 \left( \sum_{n=0}^{\infty} c_n^2 \right) \frac{1}{4} \left( \frac{1}{q_{max}} \right)^2 \frac{\overline{i_n^2}}{\Delta f}$$

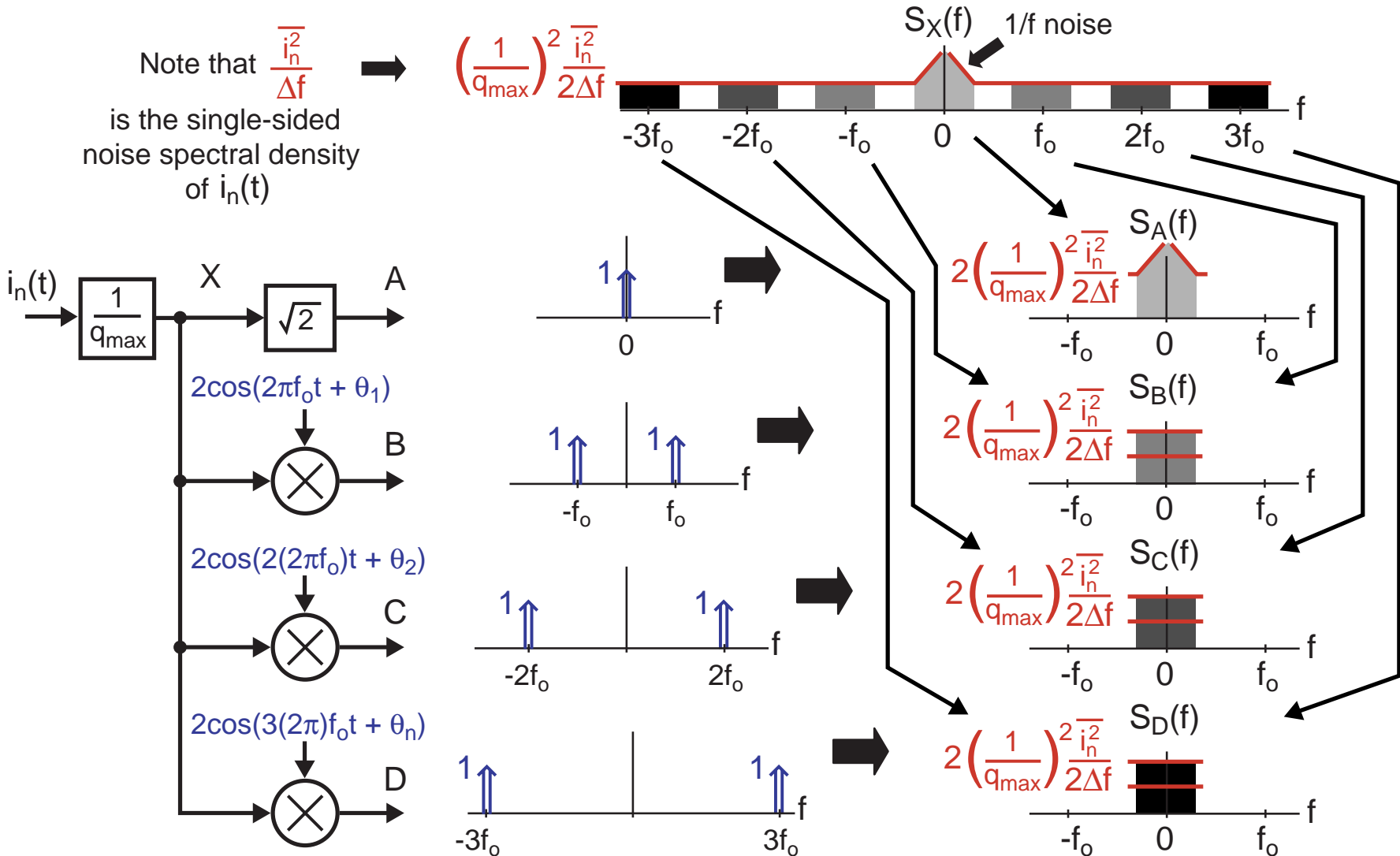
$$L(\Delta f) = 10 \log(S_{\Phi_{out}}(\Delta f))$$

- Resulting phase noise

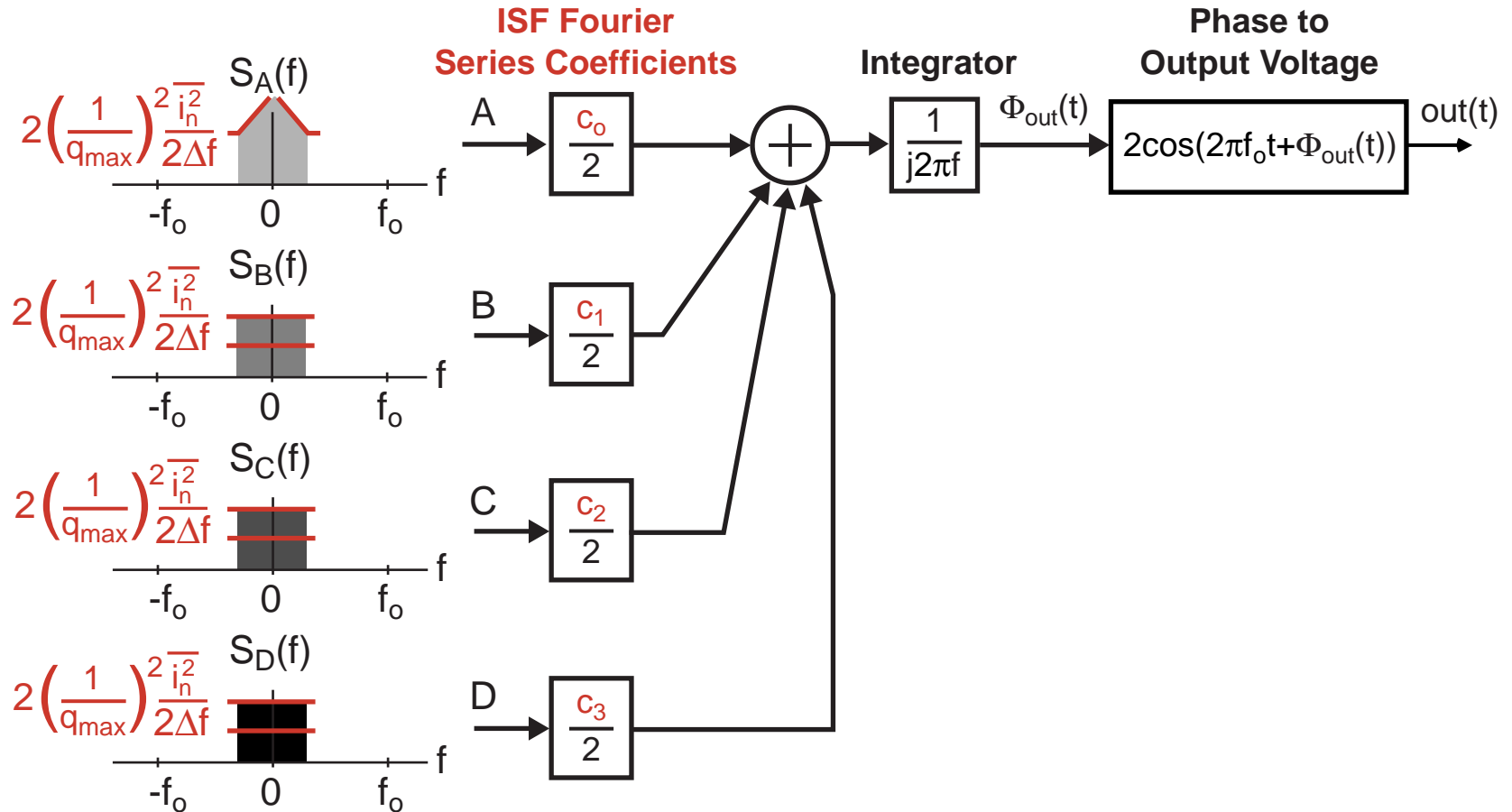
$$L(\Delta f) = 10 \log \left( \left( \frac{1}{2\pi \Delta f} \right)^2 \left( \sum_{n=0}^{\infty} c_n^2 \right) \frac{1}{4} \left( \frac{1}{q_{max}} \right)^2 \frac{\overline{i_n^2}}{\Delta f} \right)$$

# The Impact of $1/f$ Noise in Input Current (Part 1)

Note that  $\frac{\overline{i_n^2}}{\Delta f}$  is the single-sided noise spectral density of  $i_n(t)$



# The Impact of 1/f Noise in Input Current (Part 2)



$$S_{\Phi_{out}}(f) \Big|_{1/f^3} = \left| \frac{1}{j2\pi f} \right|^2 \left( \frac{C_0}{2} \right)^2 S_A(f)$$



## Calculation of Output Phase Noise in $1/f^3$ region

- From the previous slide

$$S_{\Phi_{out}}(f) \Big|_{1/f^3} = \left( \frac{1}{2\pi f} \right)^2 \left( \frac{c_o}{2} \right)^2 S_A(f)$$

- Assume that input current has  $1/f$  noise with corner frequency  $f_{1/f}$

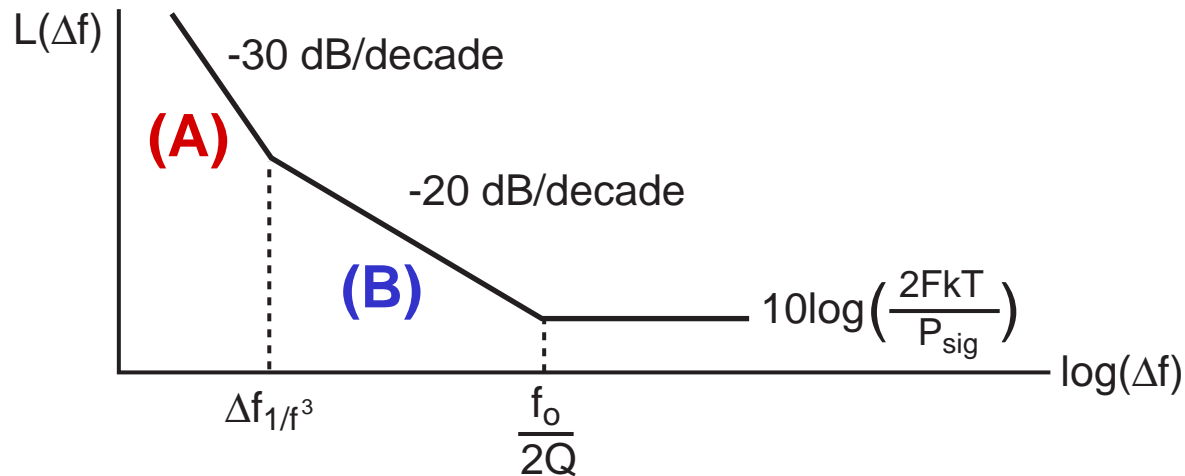
$$S_A(f) = \left( \frac{1}{q_{max}} \right)^2 \frac{\overline{i_n^2}}{\Delta f} \left( \frac{f_{1/f}}{\Delta f} \right)$$

- Corresponding output phase noise

$$L(\Delta f) \Big|_{1/f^3} = 10 \log \left( \left( \frac{1}{2\pi \Delta f} \right)^2 \left( \frac{c_o}{2} \right)^2 S_A(f) \right)$$

$$= 10 \log \left( \left( \frac{1}{2\pi \Delta f} \right)^2 (c_o^2) \frac{1}{4} \left( \frac{1}{q_{max}} \right)^2 \frac{\overline{i_n^2}}{\Delta f} \left( \frac{f_{1/f}}{\Delta f} \right) \right)$$

# Calculation of $1/f^3$ Corner Frequency



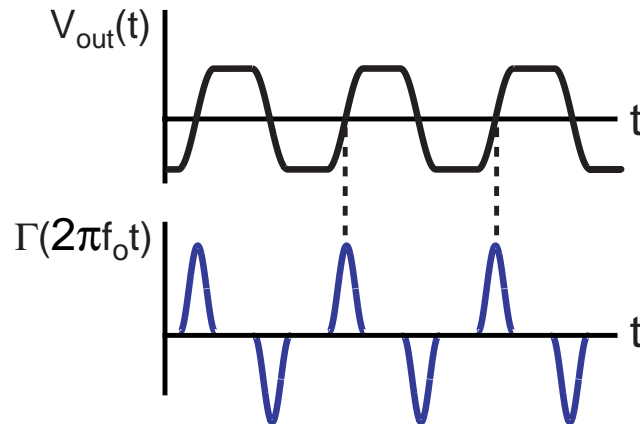
$$(A) \quad L(\Delta f) \Big|_{1/f^3} = 10 \log \left( \left( \frac{1}{2\pi \Delta f} \right)^2 (c_o^2) \frac{1}{4} \left( \frac{1}{q_{max}} \right)^2 \frac{\overline{i_n^2}}{\Delta f} \left( \frac{f_{1/f}}{\Delta f} \right) \right)$$

$$(B) \quad L(\Delta f) = 10 \log \left( \left( \frac{1}{2\pi \Delta f} \right)^2 \left( \sum_{n=0}^{\infty} c_n^2 \right) \frac{1}{4} \left( \frac{1}{q_{max}} \right)^2 \frac{\overline{i_n^2}}{\Delta f} \right)$$

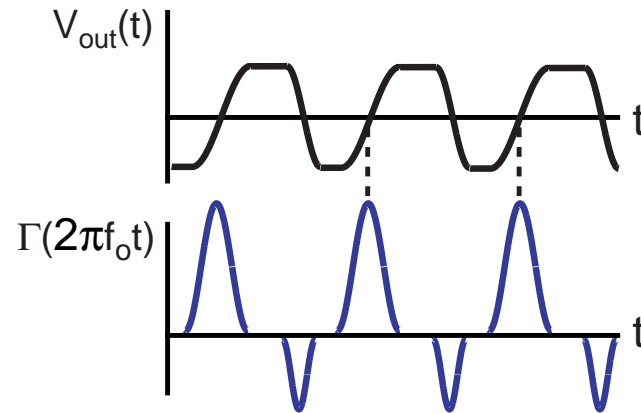
$$(A) = (B) \text{ at: } \Rightarrow \Delta f_{1/f^3} = \left( c_o^2 / \sum_{n=0}^{\infty} c_n^2 \right) f_{1/f}$$

# Impact of Oscillator Waveform on $1/f^3$ Phase Noise

ISF for Symmetric Waveform

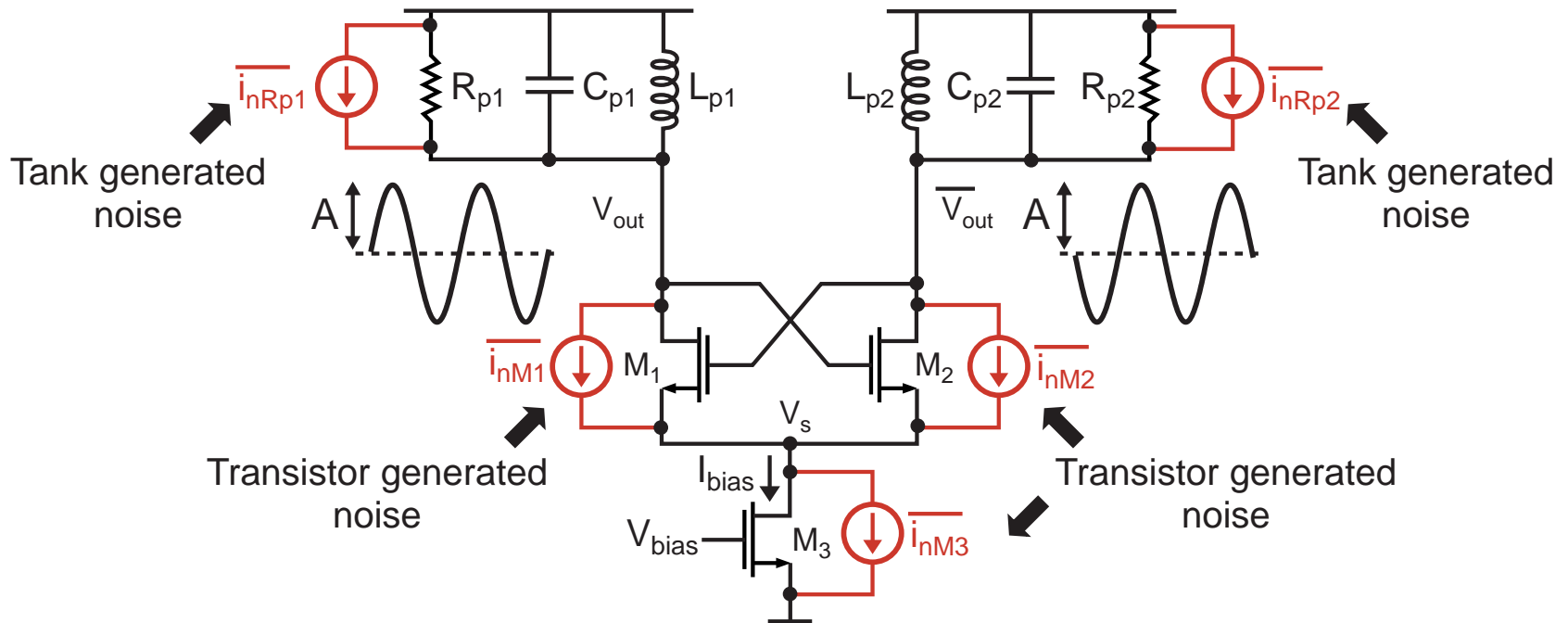


ISF for Asymmetric Waveform



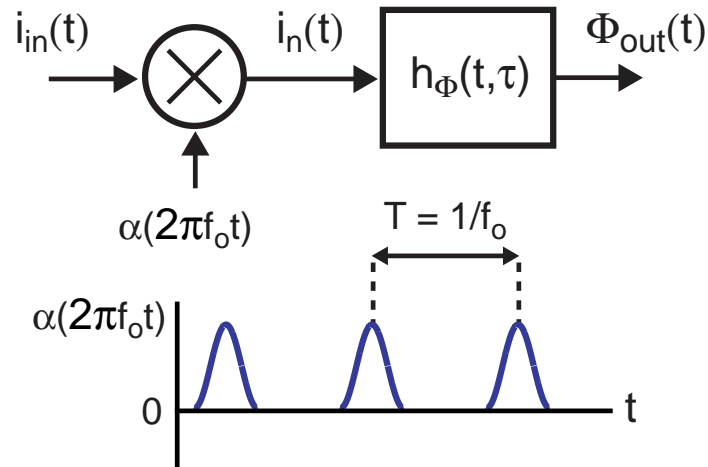
- Key Fourier series coefficient of ISF for  $1/f^3$  noise is  $c_0$ 
  - If DC value of ISF is zero,  $c_0$  is also zero
- For symmetric oscillator output waveform
  - DC value of ISF is zero – no upconversion of flicker noise! (i.e. output phase noise does not have  $1/f^3$  region)
- For asymmetric oscillator output waveform
  - DC value of ISF is nonzero – flicker noise has impact

# Issue – We Have Ignored Modulation of Current Noise



- In practice, transistor generated noise is modulated by the varying bias conditions of its associated transistor
  - As transistor goes from saturation to triode to cutoff, its associated noise changes dramatically
- Can we include this issue in the LTV framework?

# Inclusion of Current Noise Modulation



- Recall

$$\Phi_{out}(t) = \int_{-\infty}^{\infty} h_{\Phi}(t, \tau) i_n(\tau) d\tau = \frac{1}{q_{max}} \int_{-\infty}^t \Gamma(2\pi f_o \tau) i_n(\tau) d\tau$$

- By inspection of figure

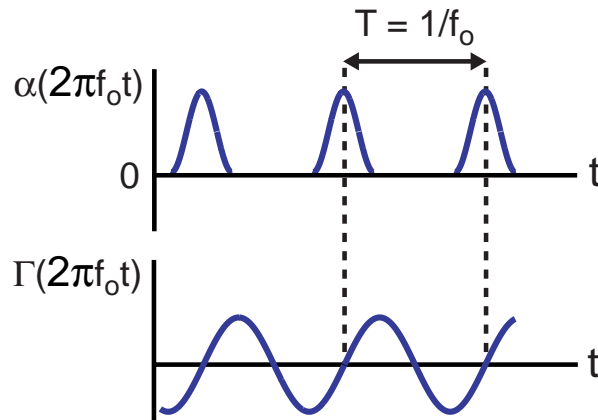
$$\Rightarrow \Phi_{out}(t) = \frac{1}{q_{max}} \int_{-\infty}^t \Gamma(2\pi f_o \tau) \alpha(2\pi f_o \tau) i_{in}(\tau) d\tau$$

- We therefore apply previous framework with ISF as

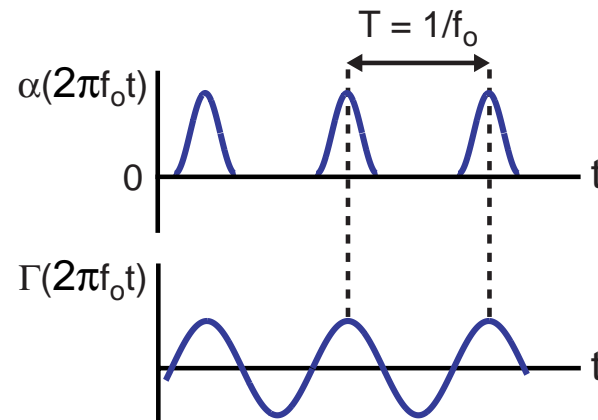
$$\Gamma_{eff}(2\pi f_o \tau) = \Gamma(2\pi f_o \tau) \alpha(2\pi f_o \tau)$$

# Placement of Current Modulation for Best Phase Noise

Best Placement of Current Modulation for Phase Noise



Worst Placement of Current Modulation for Phase Noise

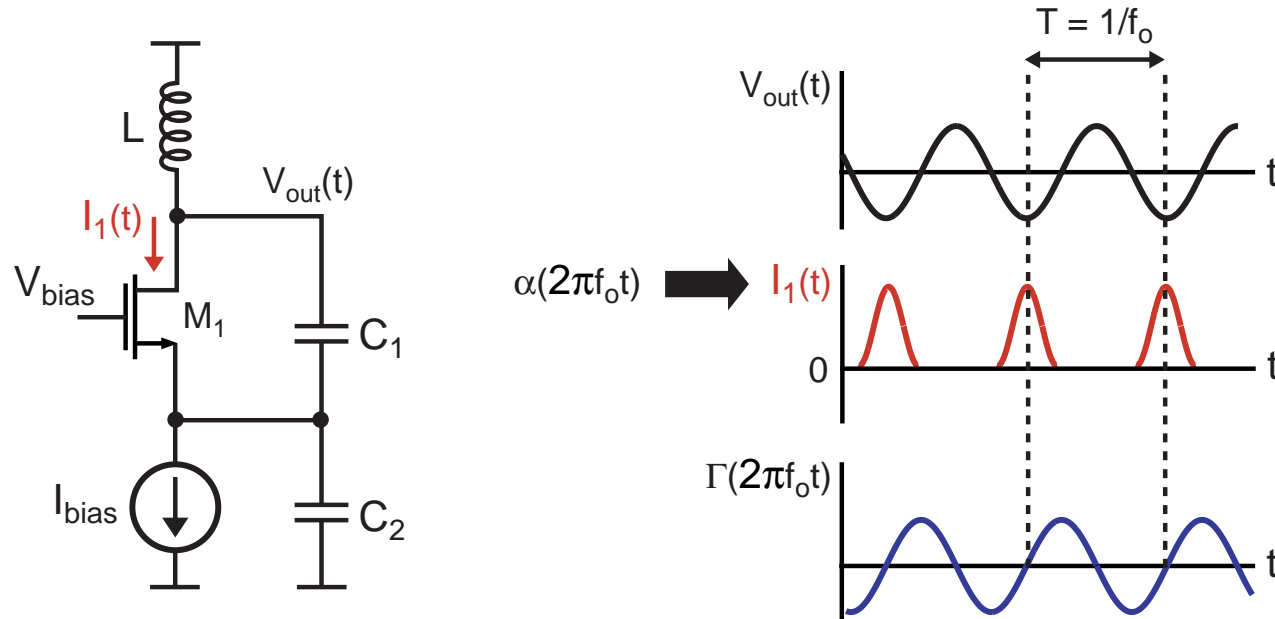


- Phase noise expression (ignoring 1/f noise)

$$L(\Delta f) = 10 \log \left( \left( \frac{1}{2\pi \Delta f} \right)^2 \left( \sum_{n=0}^{\infty} c_n^2 \right) \frac{1}{4} \left( \frac{1}{q_{max}} \right)^2 \frac{\overline{i_n^2}}{\Delta f} \right)$$

- Minimum phase noise achieved by minimizing sum of square of Fourier series coefficients (i.e. rms value of  $\Gamma_{eff}$ )

# Colpitts Oscillator Provides Optimal Placement of $\alpha$



- **Current is injected into tank at bottom portion of VCO swing**
  - Current noise accompanying current has minimal impact on VCO output phase

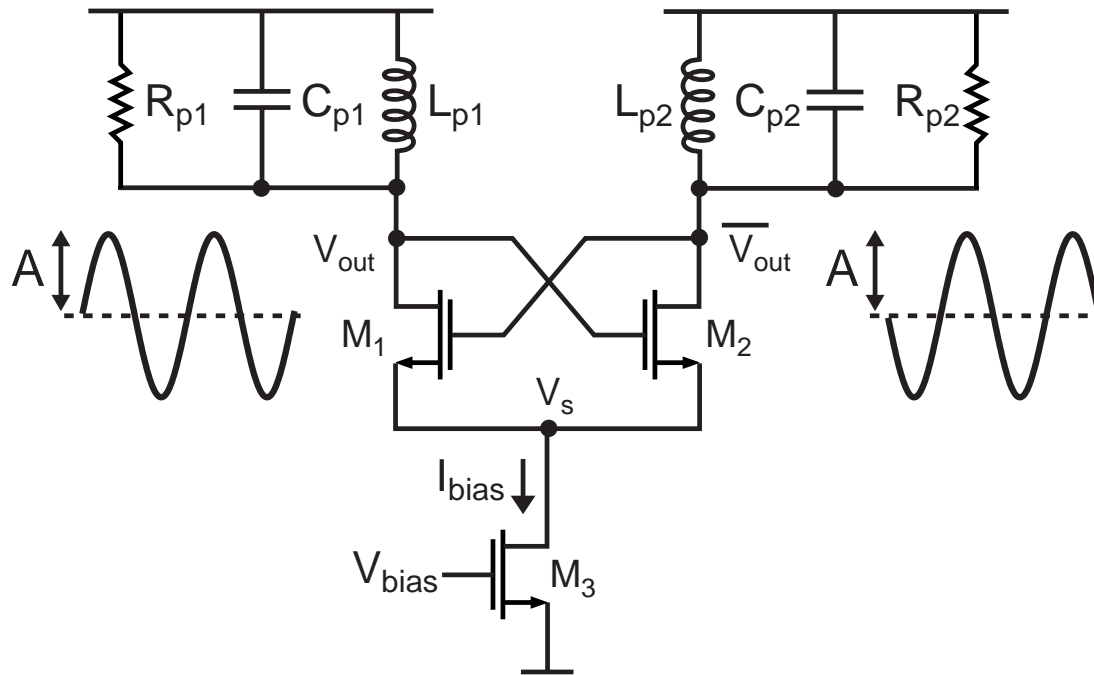
## ***Summary of LTV Phase Noise Analysis Method***

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- **Step 1: calculate the impulse sensitivity function of each oscillator noise source using a simulator**
- **Step 2: calculate the noise current modulation waveform for each oscillator noise source using a simulator**
- **Step 3: combine above results to obtain  $\Gamma_{\text{eff}}(2\pi f_o t)$  for each oscillator noise source**
- **Step 4: calculate Fourier series coefficients for each  $\Gamma_{\text{eff}}(2\pi f_o t)$**
- **Step 5: calculate spectral density of each oscillator noise source (before modulation)**
- **Step 6: calculate overall output phase noise using the results from Step 4 and 5 and the phase noise expressions derived in this lecture (or the book)**



# Alternate Approach for Negative Resistance Oscillator

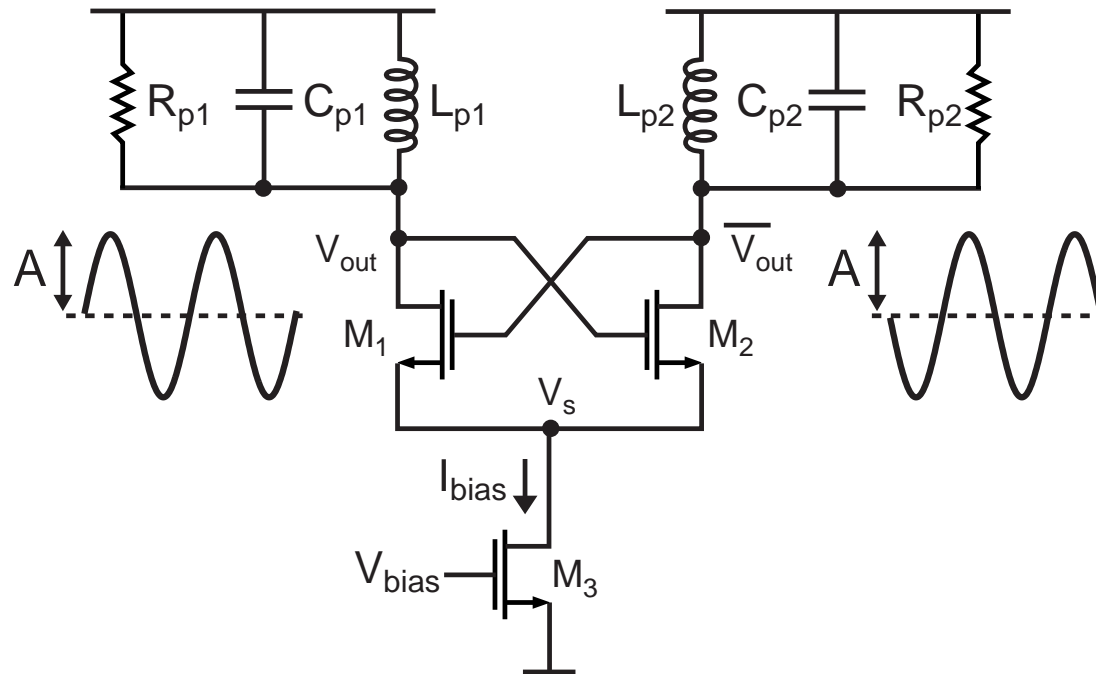


- Recall Leeson's formula

$$L(\Delta f) = 10 \log \left( \frac{2kTF(\Delta f)}{P_{sig}} \left( \frac{1}{2Q} \frac{f_o}{\Delta f} \right)^2 \right)$$

- Key question: how do you determine  $F(\Delta f)$ ?

## *$F(\Delta f)$ Has Been Determined for This Topology*



- Rael et. al. have come up with a closed form expression for  $F(\Delta f)$  for the above topology
- In the region where phase noise falls at -20 dB/dec:

$$F(\Delta f) = 1 + \frac{2\gamma I_{bias} R_p}{\pi A} + \gamma \frac{4}{9} g_{do, M3} R_p$$

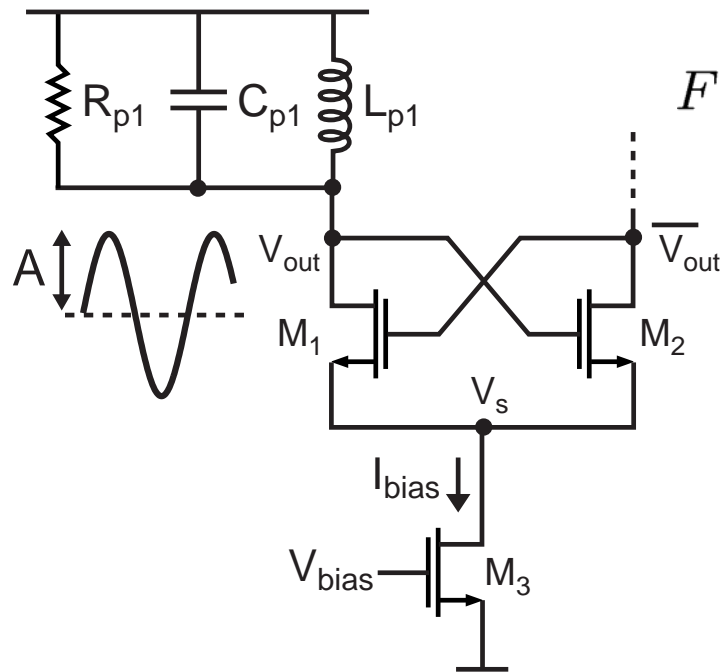
$$(R_p = R_{p1} = R_{p2})$$

## ***References to Rael Work***

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- **Phase noise analysis**
  - J.J. Rael and A.A. Abidi, “Physical Processes of Phase Noise in Differential LC Oscillators”, Custom Integrated Circuits Conference, 2000, pp 569-572
- **Implementation**
  - Emad Hegazi et. al., “A Filtering Technique to Lower LC Oscillator Phase Noise”, JSSC, Dec 2001, pp 1921-1930

# Designing for Minimum Phase Noise



$$F(\Delta f) = 1 + \frac{2\gamma I_{bias} R_p}{\pi A} + \gamma \frac{4}{9} g_{do, M3} R_p$$

(A)
(B)
(C)

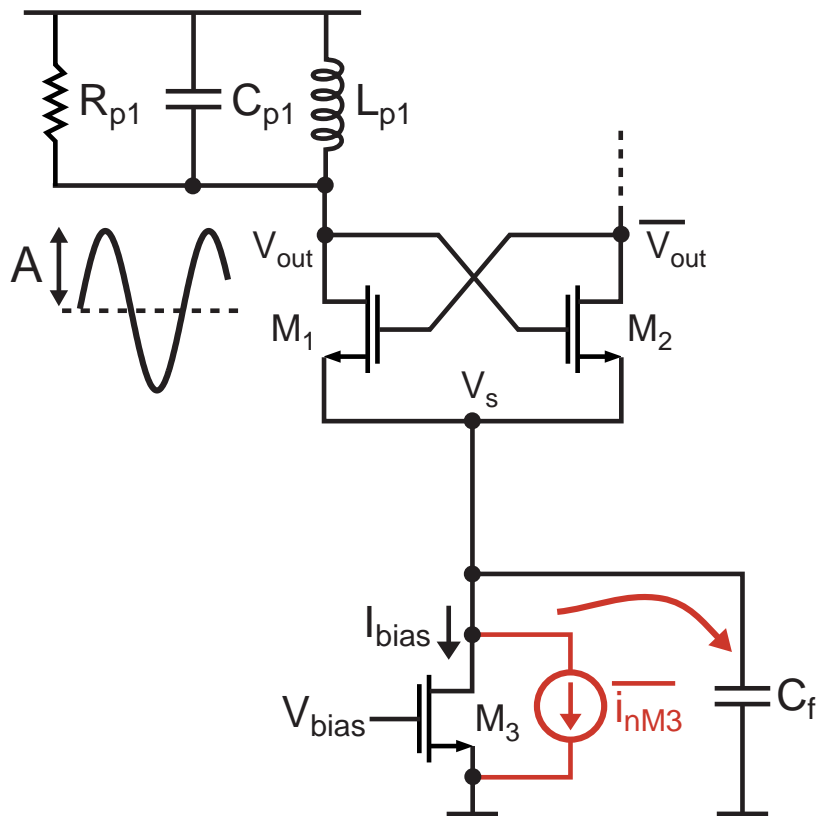
(A) Noise from tank resistance

(B) Noise from  $M_1$  and  $M_2$

(C) Noise from  $M_3$

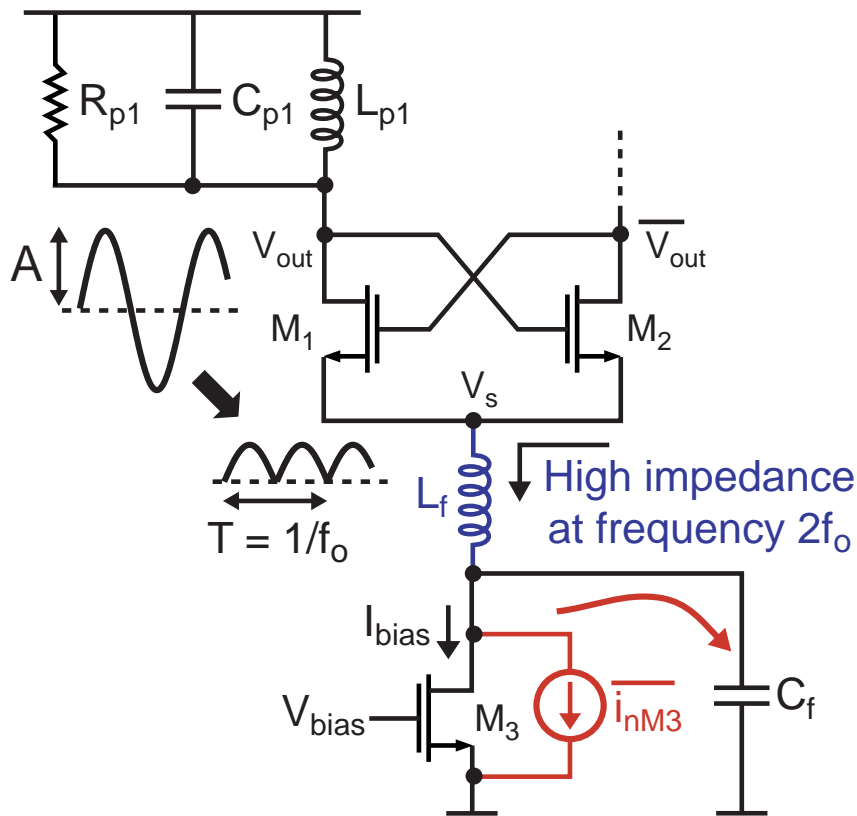
- To achieve minimum phase noise, we'd like to minimize  $F(\Delta f)$
- The above formulation provides insight of how to do this
  - Key observation: (C) is often quite significant

# Elimination of Component (C) in $F(\Delta f)$



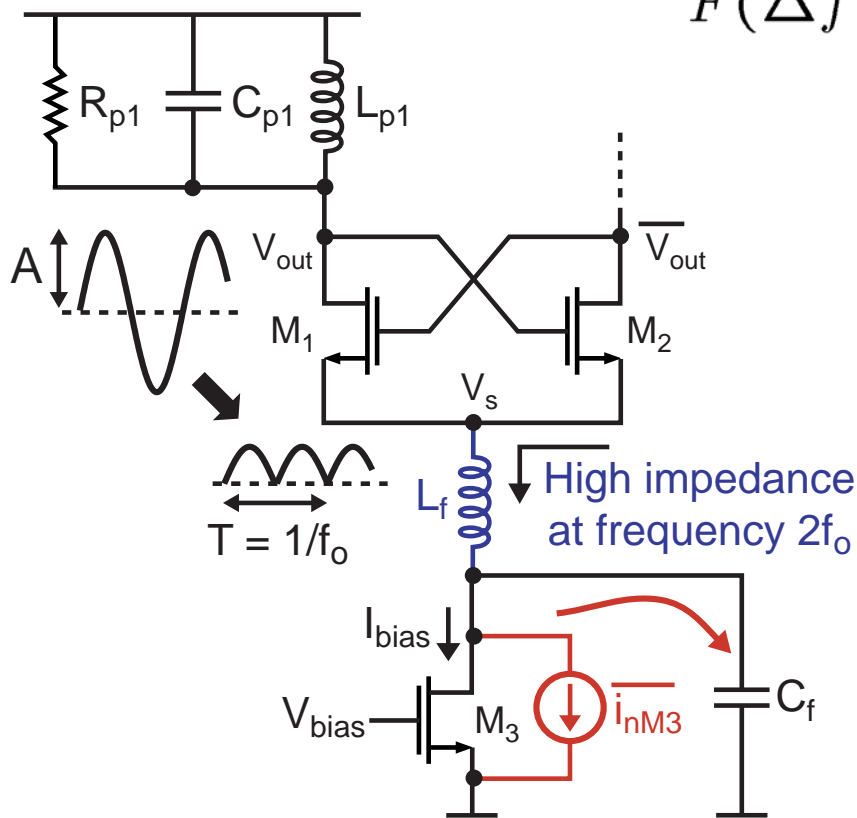
- Capacitor  $C_f$  shunts noise from  $M_3$  away from tank
  - Component (C) is eliminated!
- Issue – impedance at node  $V_s$  is very low
  - Causes  $M_1$  and  $M_2$  to present a low impedance to tank during portions of the VCO cycle
    - Q of tank is degraded

## Use Inductor to Increase Impedance at Node $V_s$



- Voltage at node  $V_s$  is a rectified version of oscillator output
  - Fundamental component is at twice the oscillation frequency
- Place inductor between  $V_s$  and current source
  - Choose value to resonate with  $C_f$  and parasitic source capacitance at frequency  $2f_0$
- Impedance of tank not degraded by  $M_1$  and  $M_2$ 
  - Q preserved!

# Designing for Minimum Phase Noise – Next Part



$$F(\Delta f) = 1 + \frac{2\gamma I_{bias} R_p}{\pi A} + \gamma \frac{4}{9} g_{d,M3} R_p$$

(A)
(B)
(C)

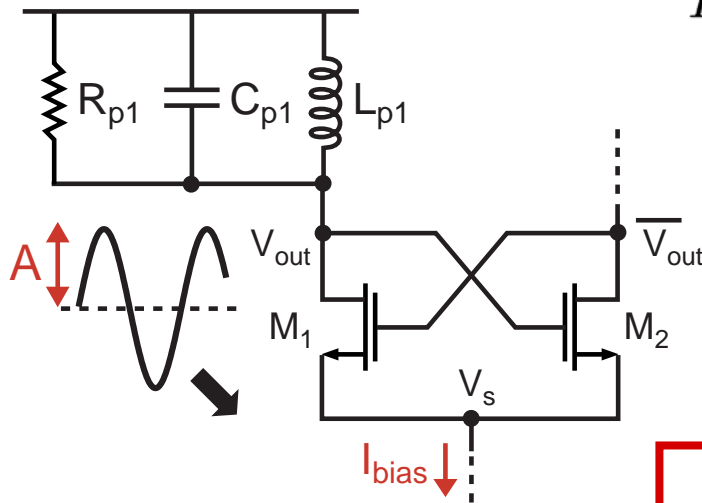
(A) Noise from tank resistance

(B) Noise from  $M_1$  and  $M_2$

~~(C) Noise from  $M_3$~~

- Let's now focus on component (B)
  - Depends on bias current and oscillation amplitude

## Minimization of Component (B) in $F(\Delta f)$



$$F(\Delta f) = 1 + \frac{2\gamma I_{bias} R_p}{\pi A}$$

**(B)**

- Recall from Lecture 11

$$A = \frac{2}{\pi} I_{bias} R_p$$

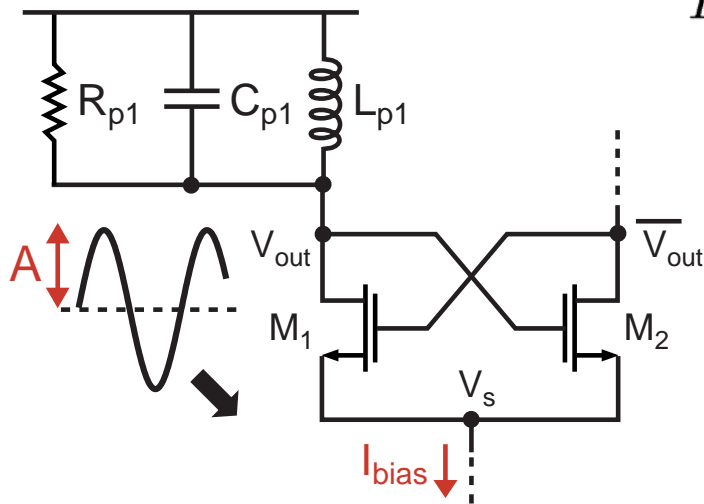
$$\Rightarrow F(\Delta f) = 1 + \frac{2\gamma I_{bias} R_p}{\pi(2/\pi) I_{bias} R_p} = 1 + \gamma$$

- So, it would seem that  $I_{bias}$  has no effect!
  - Not true – want to maximize A (i.e.  $P_{sig}$ ) to get best phase noise, as seen by:

$$L(\Delta f) = 10 \log \left( \frac{2kTF(\Delta f)}{P_{sig}} \left( \frac{1}{2Q} \frac{f_o}{\Delta f} \right)^2 \right)$$



# Current-Limited Versus Voltage-Limited Regimes



$$F(\Delta f) = 1 + \frac{2\gamma I_{bias} R_p}{\pi A} \quad (\text{B})$$

- Oscillation amplitude,  $A$ , cannot be increased above supply imposed limits
- If  $I_{bias}$  is increased above the point that  $A$  saturates, then  $(\text{B})$  increases
- Current-limited regime: amplitude given by  $A = \frac{2}{\pi} I_{bias} R_p$
- Voltage-limited regime: amplitude saturated

**Best phase noise achieved at boundary between these regimes!**

## ***Final Comments***

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- **Hajimiri method useful as a numerical procedure to determine phase noise**
  - Provides insights into  $1/f$  noise upconversion and impact of noise current modulation
- **Rael method useful for CMOS negative-resistance topology**
  - Closed form solution of phase noise!
  - Provides a great deal of design insight
- **Another numerical method**
  - Spectre RF from Cadence now does a reasonable job of estimating phase noise for many oscillators
    - Useful for verifying design ideas and calculations