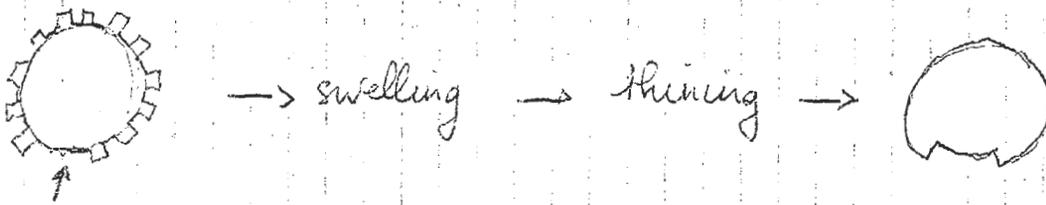


6.866 10/26

D412

### Iterative Modification

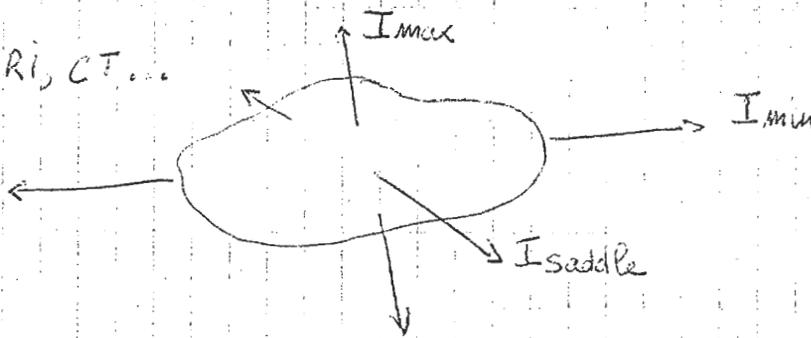
An application of swelling / thinning: detect missing teeth on a part



3 swell, 6 thin, 3 swell...

Another application: detect contours error, etc...

3D: MRI, CT...



3D Connectivity problem

... cubical voxels!



6 face adj.  
 12 edge adj.  
 8 vertex adj.  
 26

} none of them is a good connectivity

### Tessellation of space

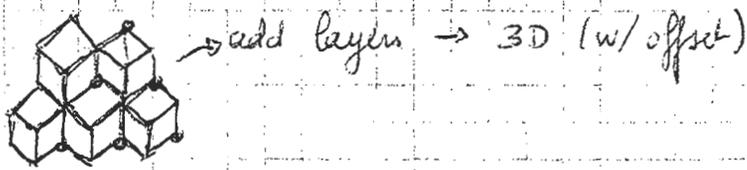
semi-regular → truncated octahedron



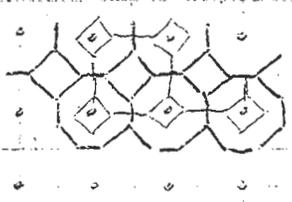
8 hexagons  
 6 squares  
 14 faces

rhombic dodecahedron : all 12 faces have the same area -

How does it tessellate space? Go back to 2D:



you can also keep square tessellation and change def. of connectivity



octahedron seen from the top.

Calculus of Variation (COV) [A6]

finite # parameters -> calculus BUT what if we have an unknown function (i.e. unknown # parameters)



what if  $N \rightarrow \infty$ ?

Example: shape from gradient

$$\min_{z(x,y)} \iint (p(x,y) - z_x(x,y))^2 + (q(x,y) - z_y(x,y))^2 dx dy$$

$p$  and  $q$ : known  $z$ : unknown In practice, there is an error - Finding  $z$  is a COV-problem - Usually, we discretize - messy...

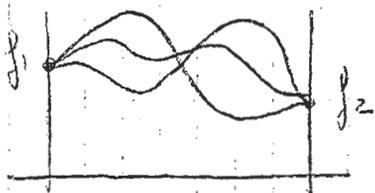
Example II: optical flow

Example: simple

$$I = \int_{x_1}^{x_2} F(x; f, f') dx$$

$$f(x_1) = f_1$$

$$f(x_2) = f_2$$



• Assume  $f(x)$  is a solution

• Make a "small variation"

• Add a test function  $\eta(x)$

Any variation makes things worse...

$f(x) + \epsilon \eta(x)$  - We expect a quadratic dependence on  $\epsilon$ .

$$\left. \frac{dI}{d\epsilon} \right|_{\epsilon=0} = 0 \quad \text{for all } \eta(x) \text{ such as } \eta(x_1) = \eta(x_2) = 0.$$

$$f'(x) \rightarrow f'(x) + \epsilon \eta'(x) \quad \text{thus } I \rightarrow \int_{x_1}^{x_2} F(x; f + \epsilon \eta; f' + \epsilon \eta') dx$$

See appendix A6 for details =

$$\int_{x_1}^{x_2} (\eta(x) F_f + \eta'(x) F_{f'}) dx = 0 \quad \text{for all } \eta(x)$$

$$\text{Suppose we take: } \eta(x) = \delta(x - x_0) \rightarrow \int_{x_1}^{x_2} \eta(x) (F_f - F_{f'}) dx = 0 \quad \text{WRONG!}$$

But integration by parts is RIGHT! ( $\int u dv = uv \Big|_a^b - \int v du$ )

$$\int_{x_1}^{x_2} \eta'(x) F_{f'} dx = \underbrace{\eta(x) F_{f'}}_0 \Big|_{x_1}^{x_2} - \int_{x_1}^{x_2} \eta(x) \frac{d}{dx} F_{f'} dx$$

$$\text{Thus: } \int_{x_1}^{x_2} \eta(x) \left[ F_f - \frac{d}{dx} F_{f'} \right] dx = 0 \quad \text{for all } \eta(x)$$

Thus:

$$\boxed{F_f - \frac{d}{dx} F_{f'} = 0}$$

EULER EQUATION

example:

$$\min_{f(x)} \int_{x_1}^{x_2} \sqrt{1 + f'(x)^2} dx$$

$$F_f = 0 \quad F_{f'} = \frac{f'(x)}{\sqrt{1 + f'(x)^2}} \Rightarrow \frac{d}{dx} \left( \frac{f'(x)}{\sqrt{1 + f'(x)^2}} \right) = 0$$

$$\frac{f'(x)}{\sqrt{1 + f'(x)^2}} = k \Rightarrow f'(x) \text{ is a constant!} \quad \underline{f(x) = mx + c}$$

Simple because:

- ① boundary conditions
- ② first derivative only
- ③ one function
- ④ single independent variable

General:

$$\textcircled{1} \quad [ \eta(x) F_{f'} ]_{x_1}^{x_2} = 0 \text{ for all } \eta(x)$$

$$F_{f'} = 0 \text{ at } x_1 \text{ and } x_2$$

"natural boundary conditions"

- ② higher derivatives

$$I = \int_{x_1}^{x_2} F(x, f, f', f'', \dots) dx \Rightarrow \boxed{F_f - \frac{d}{dx} F_{f'} + \frac{d^2}{dx^2} F_{f''} - \dots = 0}$$

B.C on all but highest derivatives

- ③ More than one function  $u(x, y)$   $v(x, y)$

$$I = \int_{x_1}^{x_2} F(x, f_1, f_2, f_1', f_2', \dots) dx = 0 \quad \boxed{F_{f_i} - \frac{d}{dx} F_{f_i'} = 0}$$

- ④ Two indep. variables  $x, y$

$$I = \int_{x_1}^{x_2} \int_{y_1}^{y_2} F(x, y, f, f_x, f_y) dx dy \quad \text{boundary } \partial D$$

Same plan:  $\eta(x, y) \iint_D (\eta F_y + \eta_x F_x + \eta_y F_y) dx dy = 0$

Note:

Gauss's integral theorem:  $\iint_D \left( \frac{\partial Q}{\partial x} + \frac{\partial P}{\partial y} \right) dx dy = \int_{\partial D} Q dy - P dx$

Thus:  $\iint_D \dots = \int_{\partial D} (\eta F_x dy - \eta F_y dx) = 0 \quad (\eta = 0 \text{ on } \partial D)$

By expanding  $\iint_D \frac{\partial}{\partial x} (\eta F_x) + \frac{\partial}{\partial y} (\eta F_y) dx dy$ , we get:

$\iint_D \eta \left( F_y - \frac{\partial}{\partial x} F_x - \frac{\partial}{\partial y} F_y \right) dx dy = 0$  for all  $\eta$  thus

$F_y - \frac{\partial}{\partial x} F_x - \frac{\partial}{\partial y} F_y = 0$

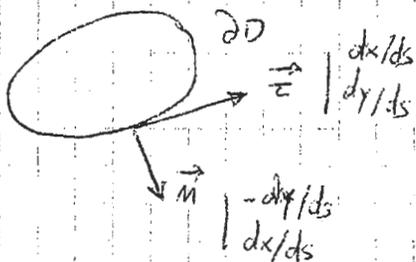
2D EULER EQUATION (PDE)

Note: what if we don't know B.C.?

we need  $\int_{\partial D} \eta (\dots) = 0$

w/o B.C, "natural BC" is:  $F_x \frac{dy}{ds} = F_y \frac{dx}{ds}$  on  $\partial D$

or,  $(F_x, F_y) \cdot \left( \frac{\partial y}{\partial s}, -\frac{\partial x}{\partial s} \right) = 0$



Example: Shape from gradient  $p(x,y)$   $q(x,y)$

$$\min_{z(x,y)} \iint_D \underbrace{(p(x,y) - z_x(x,y))^2 + (q(x,y) - z_y(x,y))^2}_{F} dx dy$$

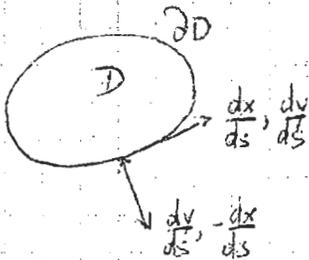
Euler  $\Rightarrow F_z - \frac{\partial}{\partial x} F_{z_x} - \frac{\partial}{\partial y} F_{z_y} = 0$  where  $f$  is  $\equiv$

$$0 - \frac{\partial}{\partial x} (-2(p - z_x)) - \frac{\partial}{\partial y} (-2(q - z_y)) = 0$$

Thus:  $\frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} = z_{xx} + z_{yy} \checkmark \nabla^2 z$  Laplacian

$z_x = p$ ?  $z_y = q$ ? Hard to satisfy because of noise, too many constraints  
This is an over-determined problem -

B.C.? "Natural"  $(F_{z_x}, F_{z_y}) \cdot \left( \frac{dy}{ds}, -\frac{dx}{ds} \right) = 0$



$(p - z_x, q - z_y) \cdot ( , ) = 0$

$(p, q) \cdot \hat{n} = (z_x, z_y) \cdot \hat{n}$  (sanity check)

Other example:

