⇒ Last Lecture

⇒Energy and Momentum of rotation

⇒ Today

⇒More about Momentum of rotation

Important Concepts

Skinetic energy of rotation adds a new term to the same energy equation, it does not add a new equation.

Momentum of rotation gives an additional equation

There is the additional complication that the moment of inertia can change.

⇒ For particles in orbit, angular momentum gives information about the direction as well as the speed

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Angular Momentum for Orbits

Conserved because gravity points radially so it does not exert any torque.

⇒ Point particle: $\vec{L} = \vec{r} \times \vec{p}$ $|L| = |r||p|\sin \phi$

Conservation of angular momentum is a separate equation from conservation of energy.

The resulting equations are:

$$r_1 m v_1 \sin \phi_1 = r_2 m v_2 \sin \phi_2$$

$$\frac{-GMm}{r_1} + \frac{1}{2}mv_1^2 = \frac{-GMm}{r_2} + \frac{1}{2}mv_2^2$$

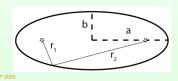
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Connection of L and E to Orbit

⇒ In general, orbits are ellipses: $r_1 + r_2 = 2a$

The semi-major axis (denoted "a" in drawing) is determined by the total mechanical energy.

The semi-minor axis (denoted "b" in drawing) is determined by energy and angular momentum.



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L and E and a and b

⇒ Basic equations: $r_1 m v_1 \sin \phi_1 = L = r_2 m v_2 \sin \phi_2$

$$\frac{-GMm}{r_1} + \frac{1}{2}mv_1^2 = E = \frac{-GMm}{r_2} + \frac{1}{2}mv_2^2$$

Substitute and do algebra to find: $E = \frac{-GMm}{2a}$

⇒ And also: $b = \frac{L}{\sqrt{-2mE}}$ (don't forget that E < 0)

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Torque Checklist

⇒ Make a careful drawing showing where forces act

Clearly indicate what axis you are using

Clearly indicate whether CW or CCW is positive

For each force:

Draw (imaginary) line from axis to point force acts. If distance and angle are clear from the geometry τ=Frsin(θ)

⊃Draw (imaginary) line parallel to the force. If distance from axis measured perpendicular to this line (lever arm) is clear, then the torque is the force times this distance

○ Don't forget CW versus CCW, is the torque + or -

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