

Class 18: Outline

Hour 1:

Levitation

Experiment 8: Magnetic Forces

Hour 2:

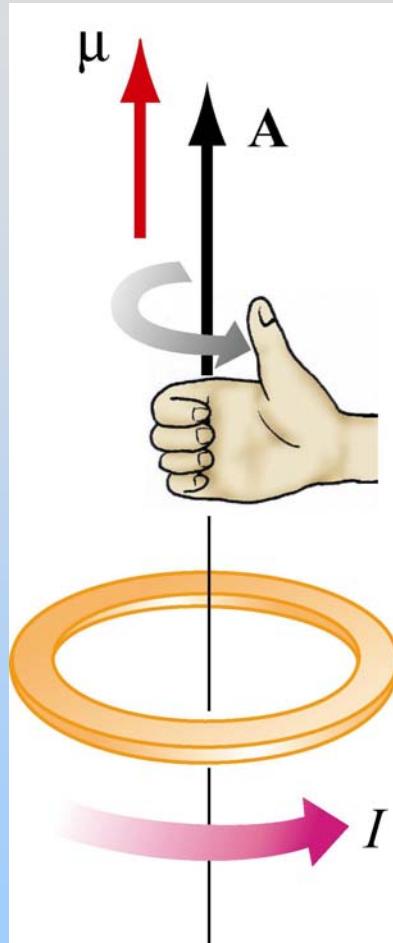
Ampere's Law

Review: Right Hand Rules

1. Torque: Thumb = torque, fingers show rotation
2. Feel: Thumb = I, Fingers = B, Palm = F
3. Create: Thumb = I, Fingers (curl) = B
4. Moment: Fingers (curl) = I, Thumb = Moment

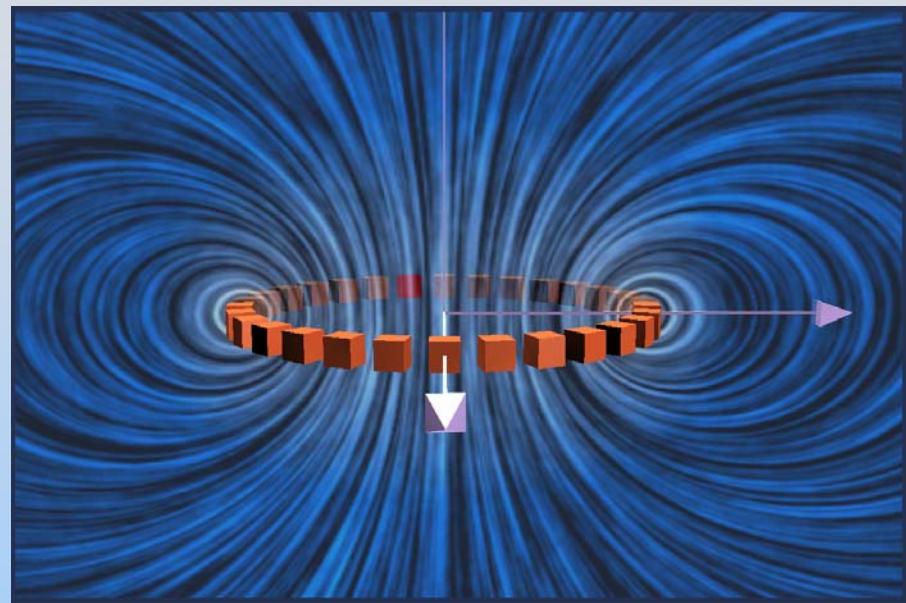
Last Time: Dipoles

Magnetic Dipole Moments



$$\vec{\mu} \equiv IA\hat{n} \equiv I\vec{A}$$

Generate:



Feel: $U_{Dipole} = -\vec{\mu} \cdot \vec{B}$

- 1) Torque to align with external field
- 2) Forces as for bar magnets (seek field)

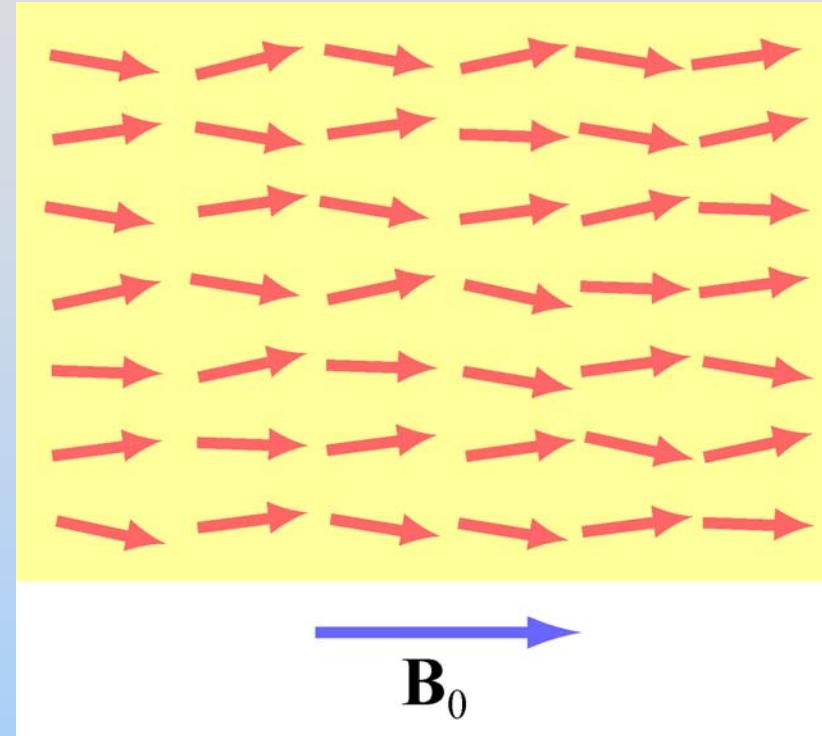
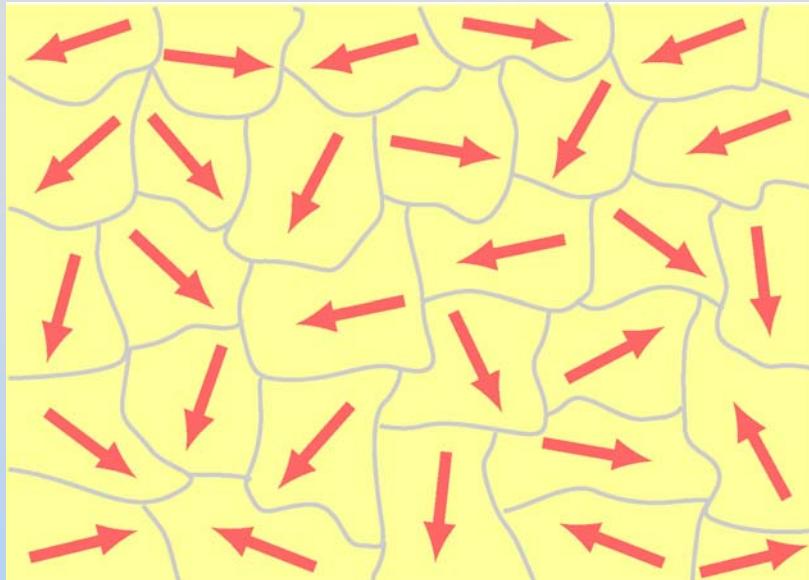
Some Fun: Magnetic Levitation

Put a Frog in a 16 T Magnet...

For details: <http://www.hfml.sci.kun.nl/levitate.html>

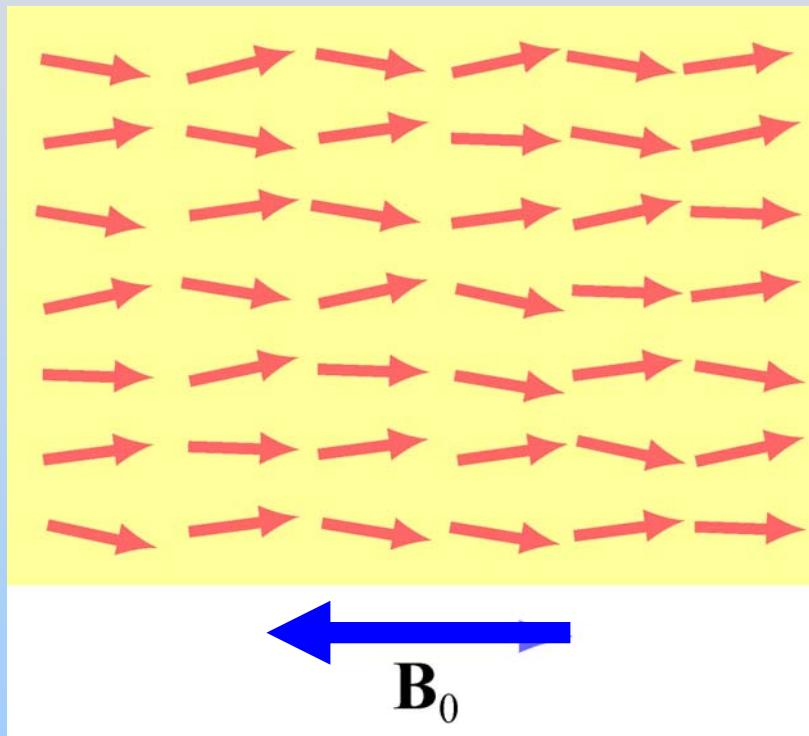
How does that work?
First a BRIEF intro to
magnetic materials

Para/Ferromagnetism



Applied external field B_0 tends to align the atomic magnetic moments (unpaired electrons)

Diamagnetism

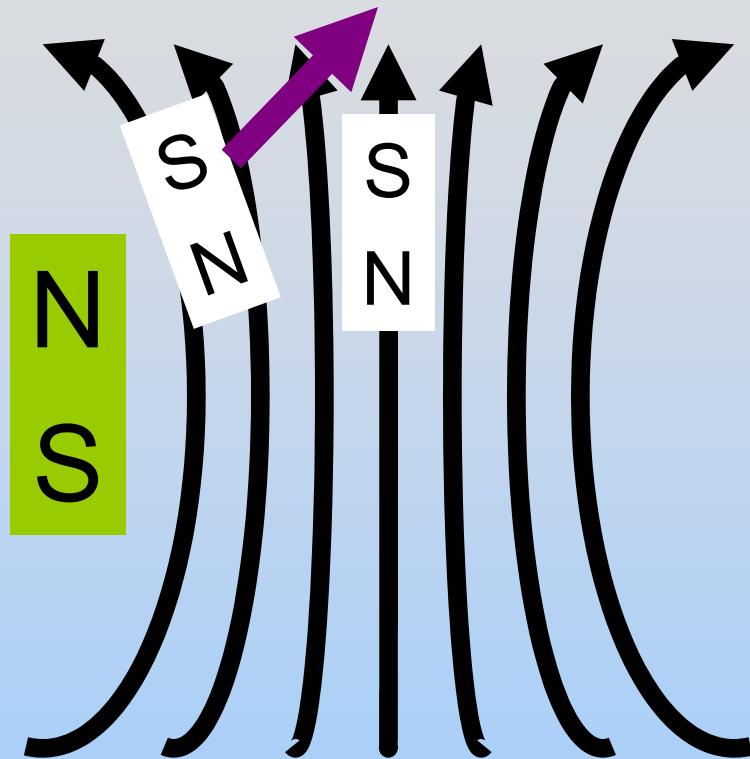


Everything is slightly diamagnetic. Why?
More later.

If no magnetic moments (unpaired electrons) then this effect dominates.

Back to Levitation

Levitating a Diamagnet



- 1) Create a strong field
(with a field gradient!)
- 2) Looks like a dipole field
- 3) Toss in a frog (diamagnet)
- 4) Looks like a bar magnet
pointing *opposite* the field
- 5) Seeks *lower* field (force *up*)
which balances gravity

Most importantly, it's stable:

Restoring force always towards the center

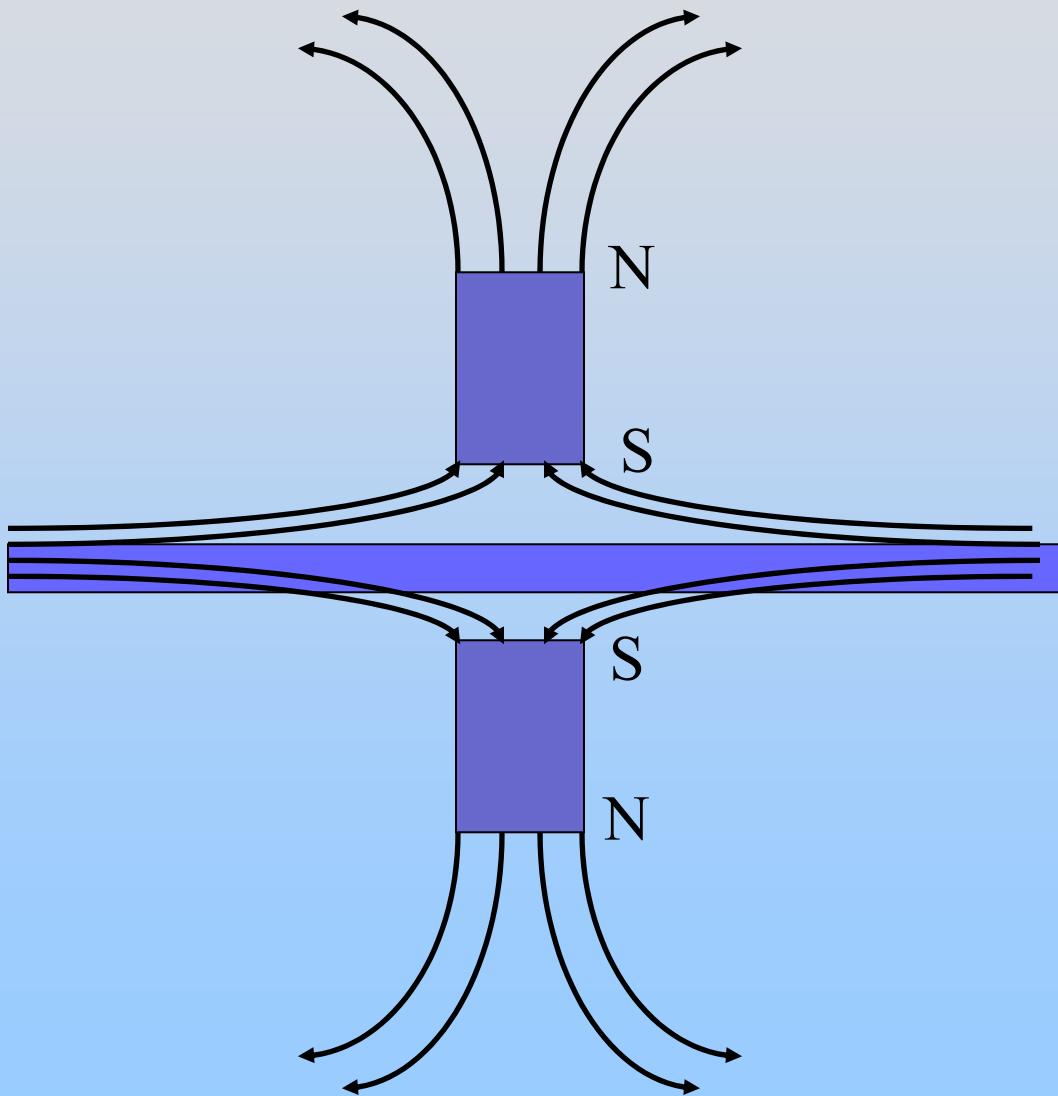
Using ∇B to Levitate

- Frog
- Strawberry
- Water Droplets
- Tomatoes
- Crickets

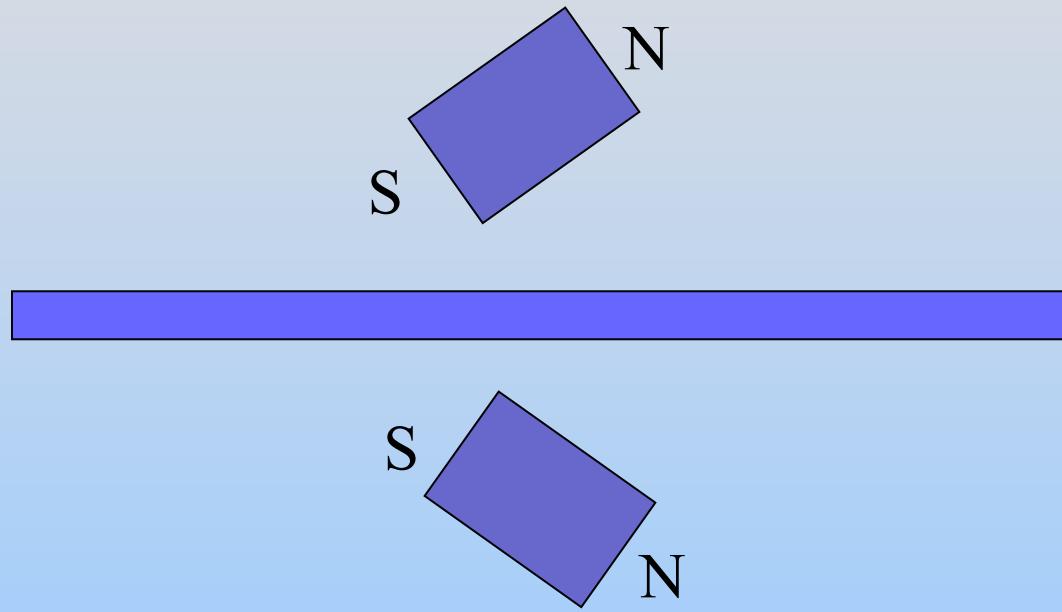
For details: <http://www.hfml.ru.nl/levitation-movies.html>

Demonstrating: Levitating Magnet over Superconductor

Perfect Diamagnetism: “Magnetic Mirrors”



Perfect Diamagnetism: “Magnetic Mirrors”



No matter what the angle, it floats -- STABILITY

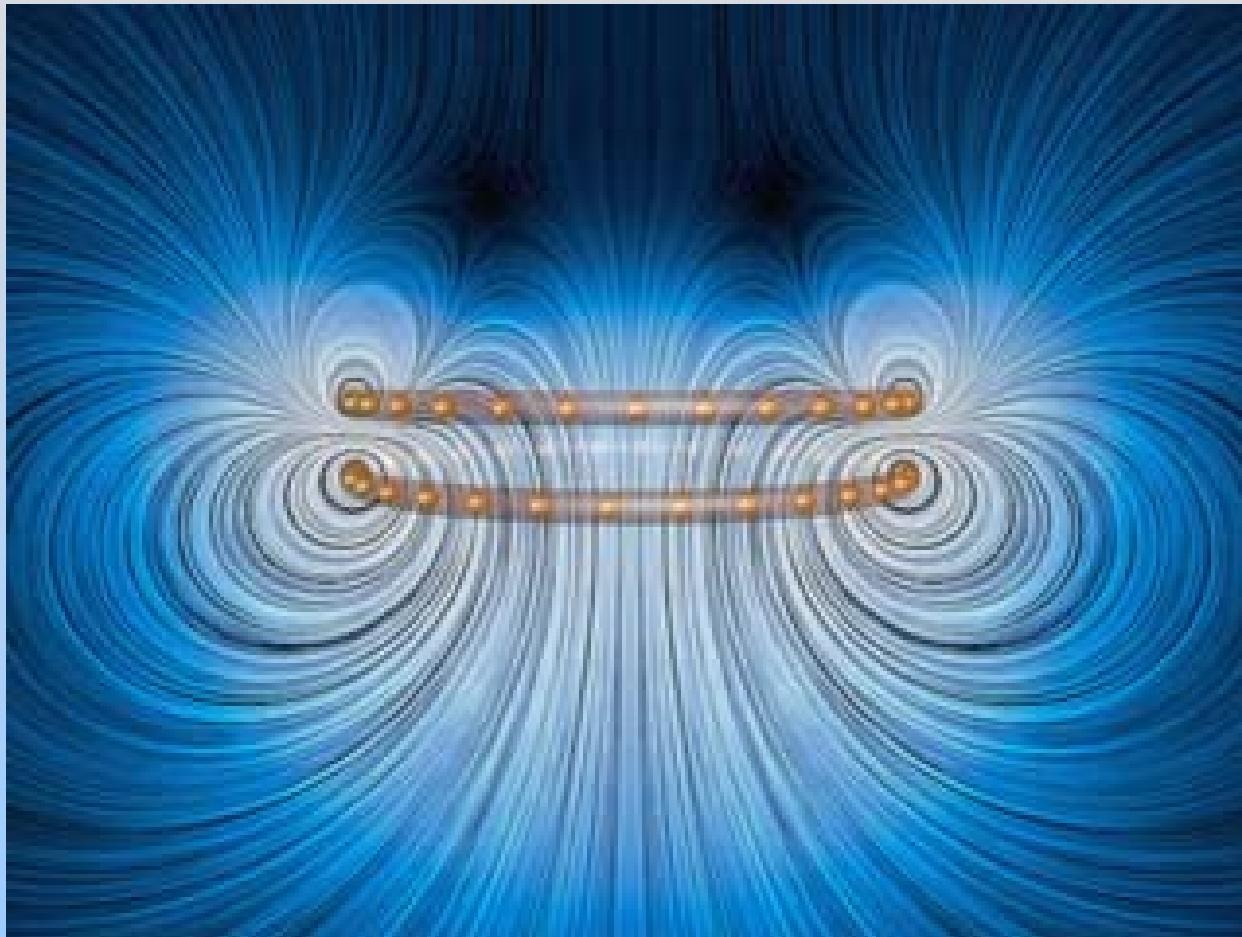
Using ∇B to Levitate

A Sumo Wrestler

For details: <http://www.hfml.sci.kun.nl/levitate.html>

Two PRS Questions Related to Experiment 8: Magnetic Forces

Experiment 8: Magnetic Forces (Calculating μ_0)



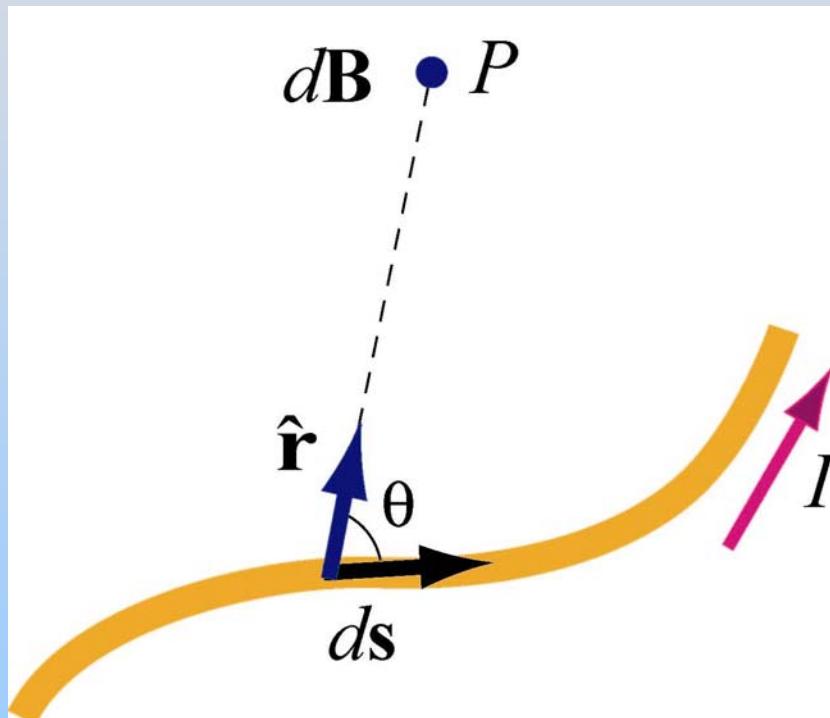
http://ocw.mit.edu/ans7870/8/8.02T/f04/visualizations/magnetostatics/16-MagneticForceRepel/16-MagForceRepel_f65_320.html

Experiment Summary:
Currents *feel* fields
Currents also *create* fields

Recall... Biot-Savart

The Biot-Savart Law

Current element of length $d\mathbf{s}$ carrying current I produces a magnetic field:

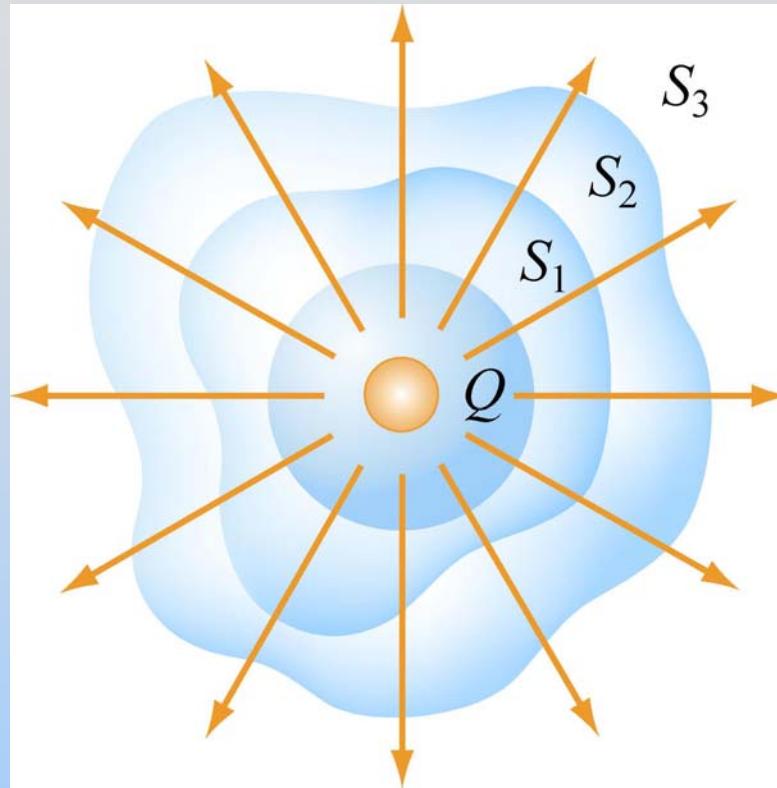


$$d\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \frac{I d\vec{\mathbf{s}} \times \hat{\mathbf{r}}}{r^2}$$

Today: 3rd Maxwell Equation: Ampere's Law

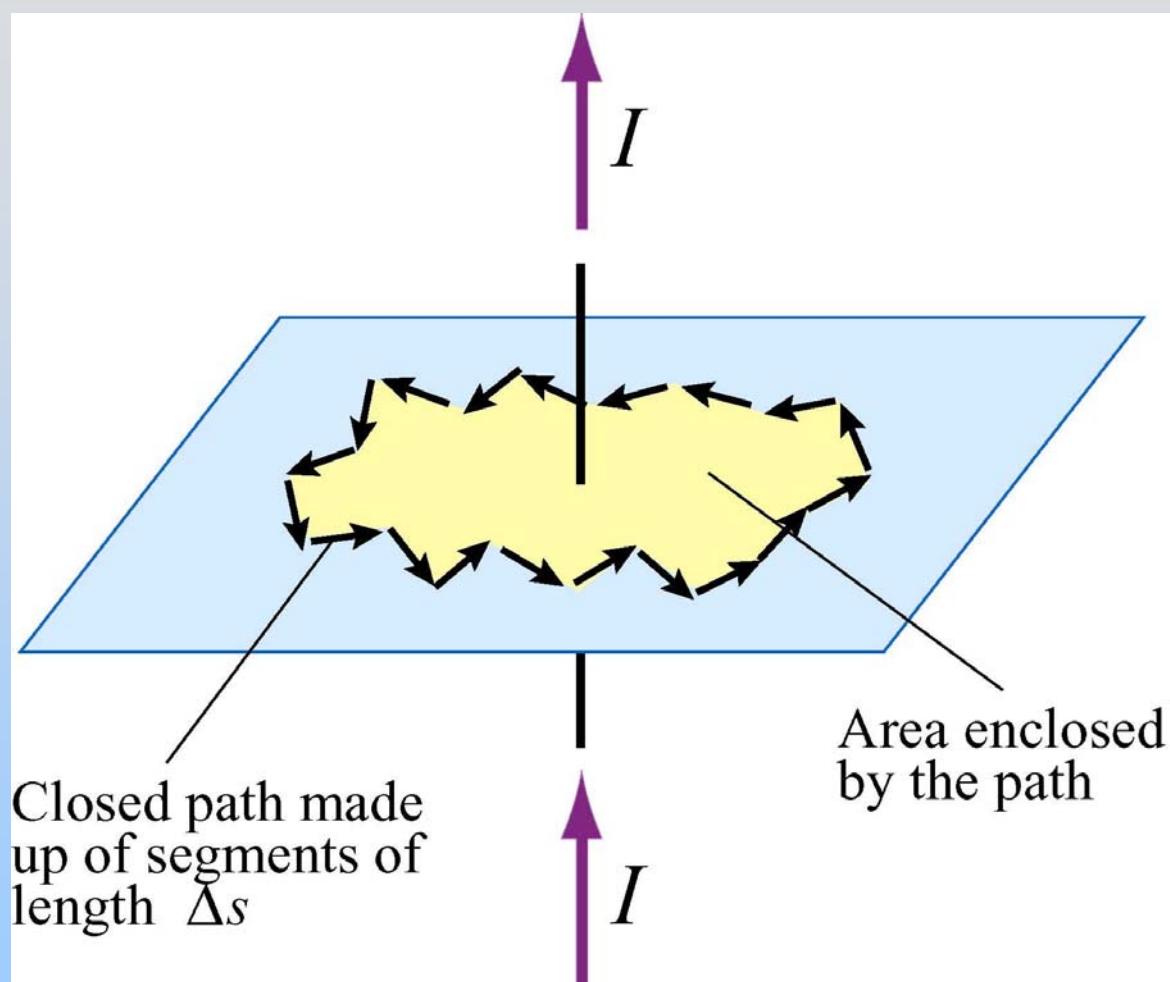
Analogous (in use) to Gauss's
Law

Gauss's Law – The Idea



The total “flux” of field lines penetrating any of these surfaces is the same and depends only on the amount of charge inside

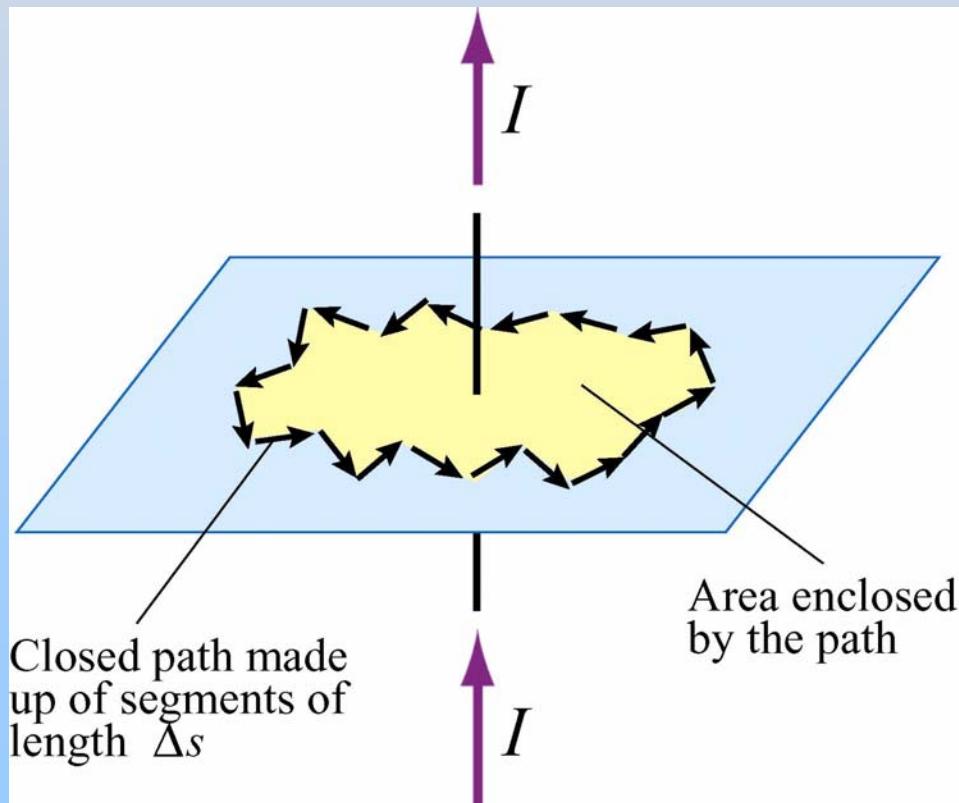
Ampere's Law: The Idea



In order to have a B field around a loop, there must be current punching through the loop

Ampere's Law: The Equation

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$



The line integral is around any closed contour bounding an open surface S .

I_{enc} is current through S :

$$I_{enc} = \int_S \vec{J} \cdot d\vec{A}$$

PRS Question: Ampere's Law

Biot-Savart vs. Ampere

Biot-Savart Law

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s} \times \hat{r}}{r^2}$$

general current source
ex: finite wire
wire loop

Ampere's law

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$

symmetric current source
ex: infinite wire
infinite current sheet

Applying Ampere's Law

1. Identify regions in which to calculate B field
Get B direction by right hand rule
2. Choose Amperian Loops S: Symmetry
B is 0 or constant on the loop!
3. Calculate $\oint \vec{B} \cdot d\vec{s}$
4. Calculate current enclosed by loop S
5. Apply Ampere's Law to solve for B

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$

Always True, Occasionally Useful

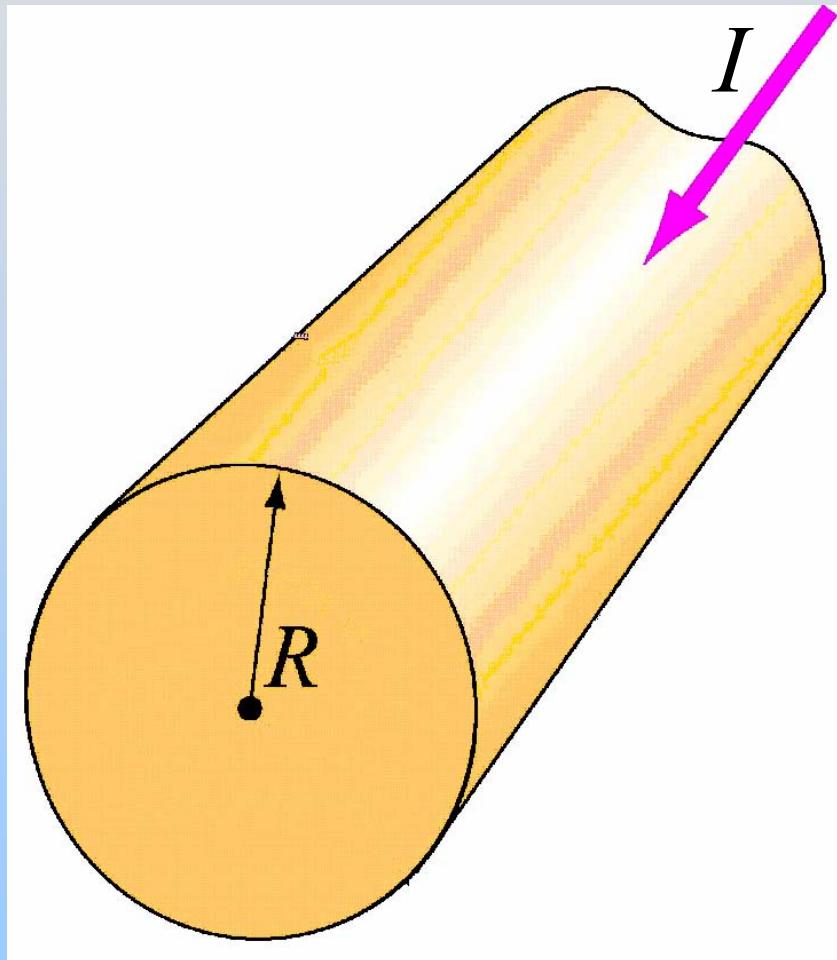
Like Gauss's Law,

Ampere's Law is always true

However, it is only useful for calculation in certain specific situations, involving highly symmetric currents.

Here are examples...

Example: Infinite Wire



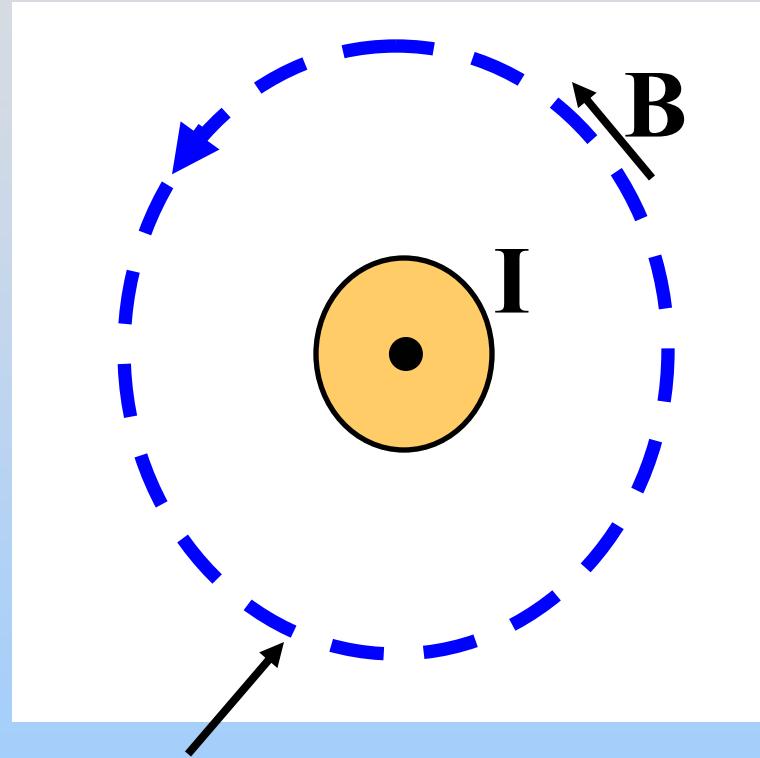
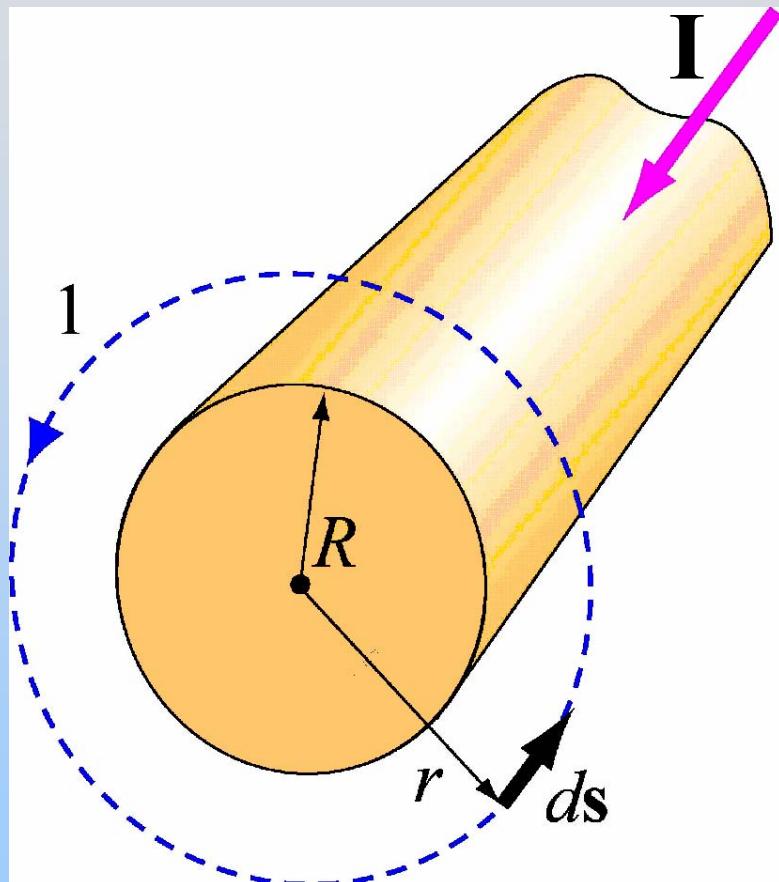
A cylindrical conductor has radius R and a uniform current density with total current I

Find B everywhere

Two regions:

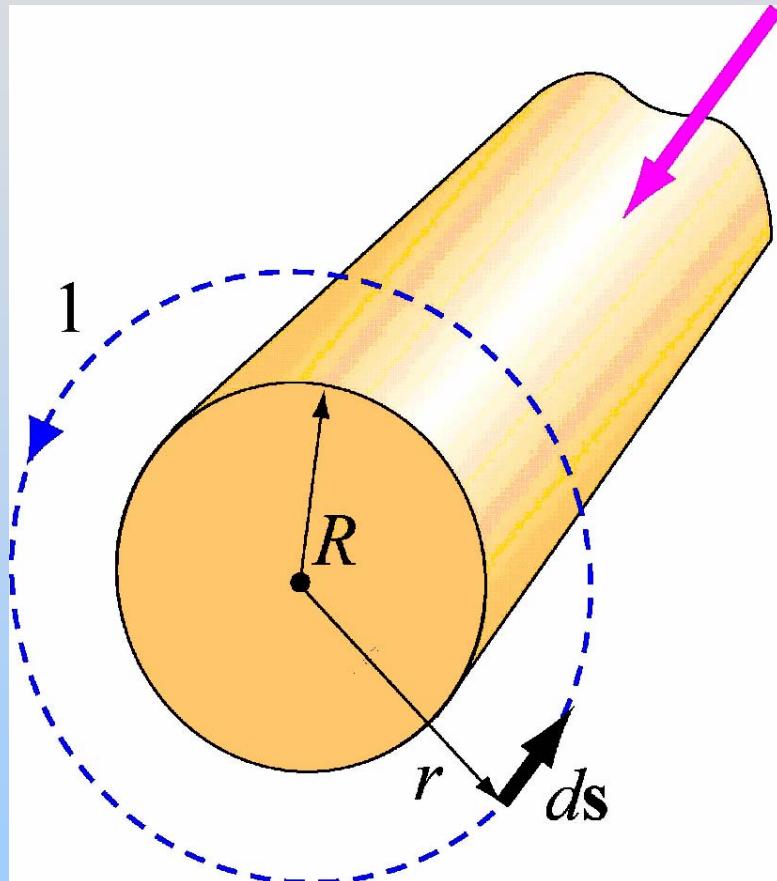
- (1) outside wire ($r \geq R$)
- (2) inside wire ($r < R$)

Ampere's Law Example: Infinite Wire



Amperian Loop:
B is Constant & Parallel
I Penetrates

Example: Wire of Radius R



Region 1: Outside wire ($r \geq R$)

Cylindrical symmetry →

Amperian Circle

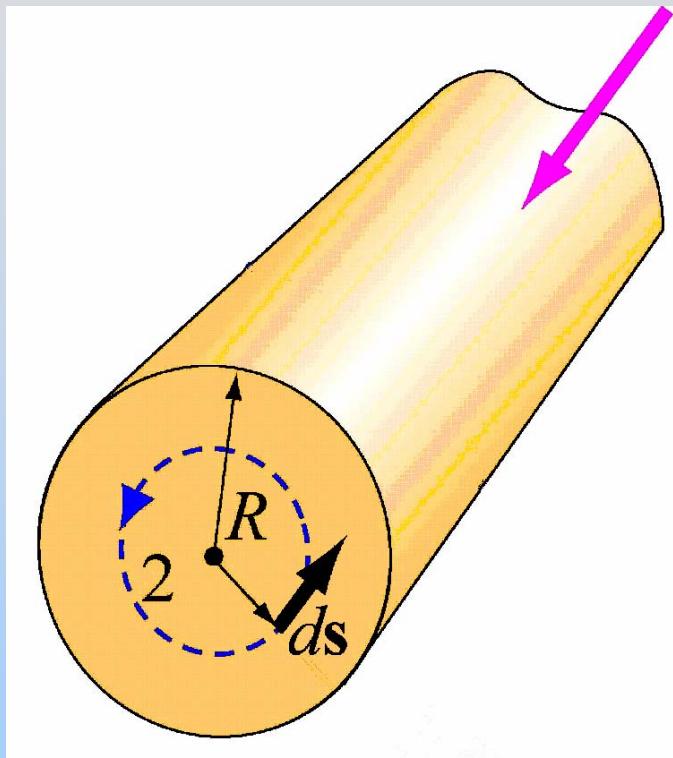
B-field counterclockwise

$$\oint \vec{B} \cdot d\vec{s} = B \oint d\vec{s} = B(2\pi r)$$

$$= \mu_0 I_{enc} = \mu_0 I$$

$$\vec{B} = \frac{\mu_0 I}{2\pi r} \text{ counterclockwise}$$

Example: Wire of Radius R



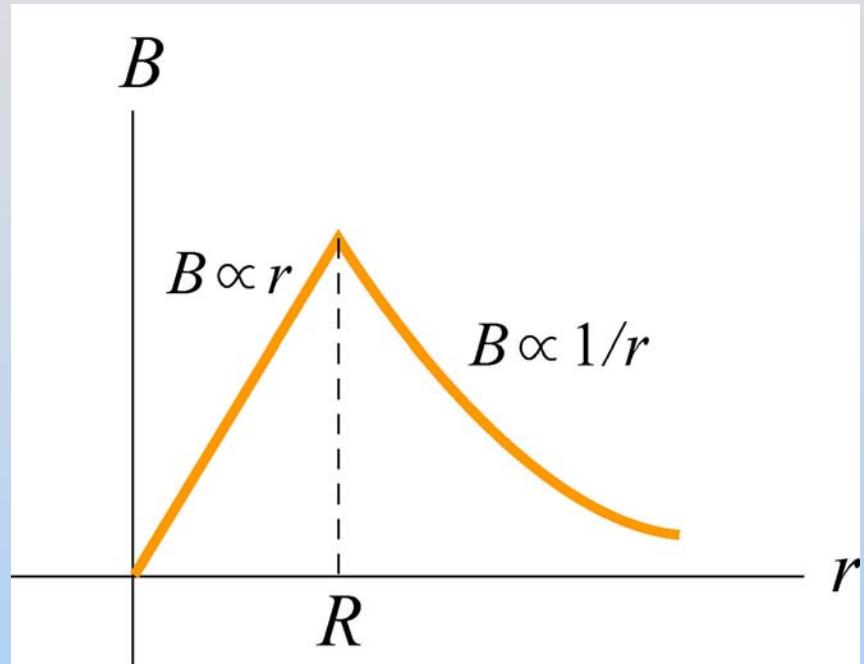
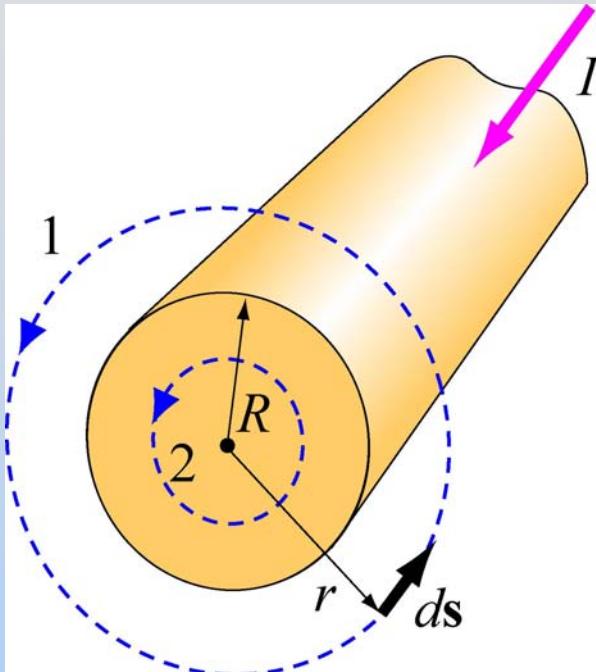
Region 2: Inside wire ($r < R$)

$$\oint \vec{B} \cdot d\vec{s} = B \oint d\vec{s} = B(2\pi r) \\ = \mu_0 I_{enc} = \mu_0 I \left(\frac{\pi r^2}{\pi R^2} \right)$$

$$\vec{B} = \frac{\mu_0 I r}{2\pi R^2} \text{ counterclockwise}$$

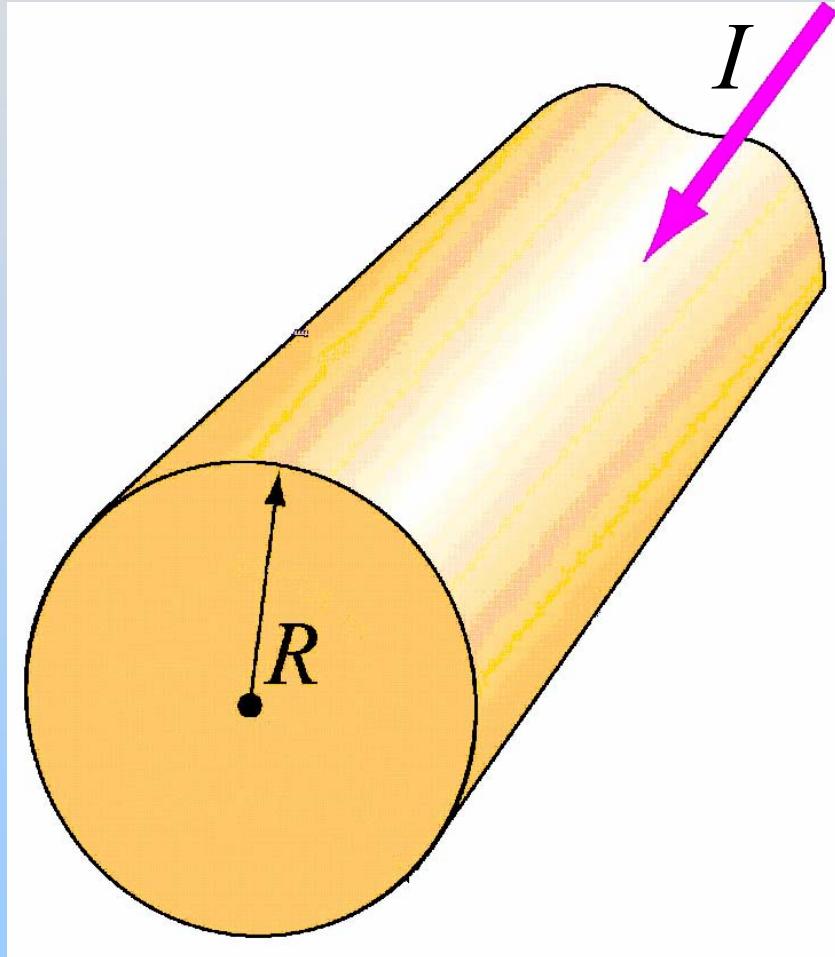
Could also say: $J = \frac{I}{A} = \frac{I}{\pi R^2}; I_{enc} = J A_{enc} = \frac{I}{\pi R^2} (\pi r^2)$

Example: Wire of Radius R



$$B_{in} = \frac{\mu_0 I r}{2\pi R^2} \quad B_{out} = \frac{\mu_0 I}{2\pi r}$$

Group Problem: Non-Uniform Cylindrical Wire



A cylindrical conductor has radius R and a non-uniform current density with total current:

$$\vec{\mathbf{J}} = J_0 \frac{R}{r}$$

Find \mathbf{B} everywhere

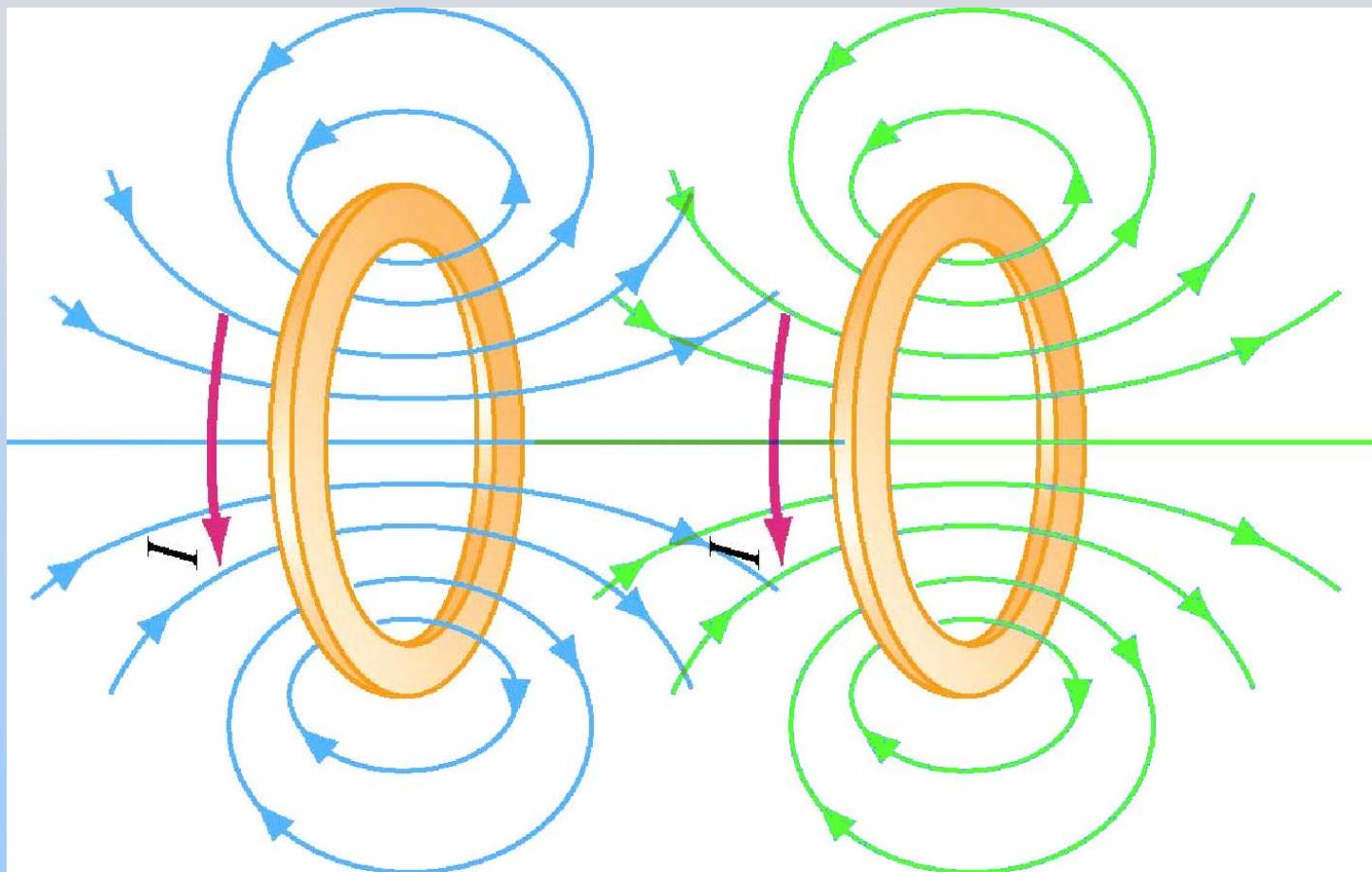
Applying Ampere's Law

In Choosing Amperian Loop:

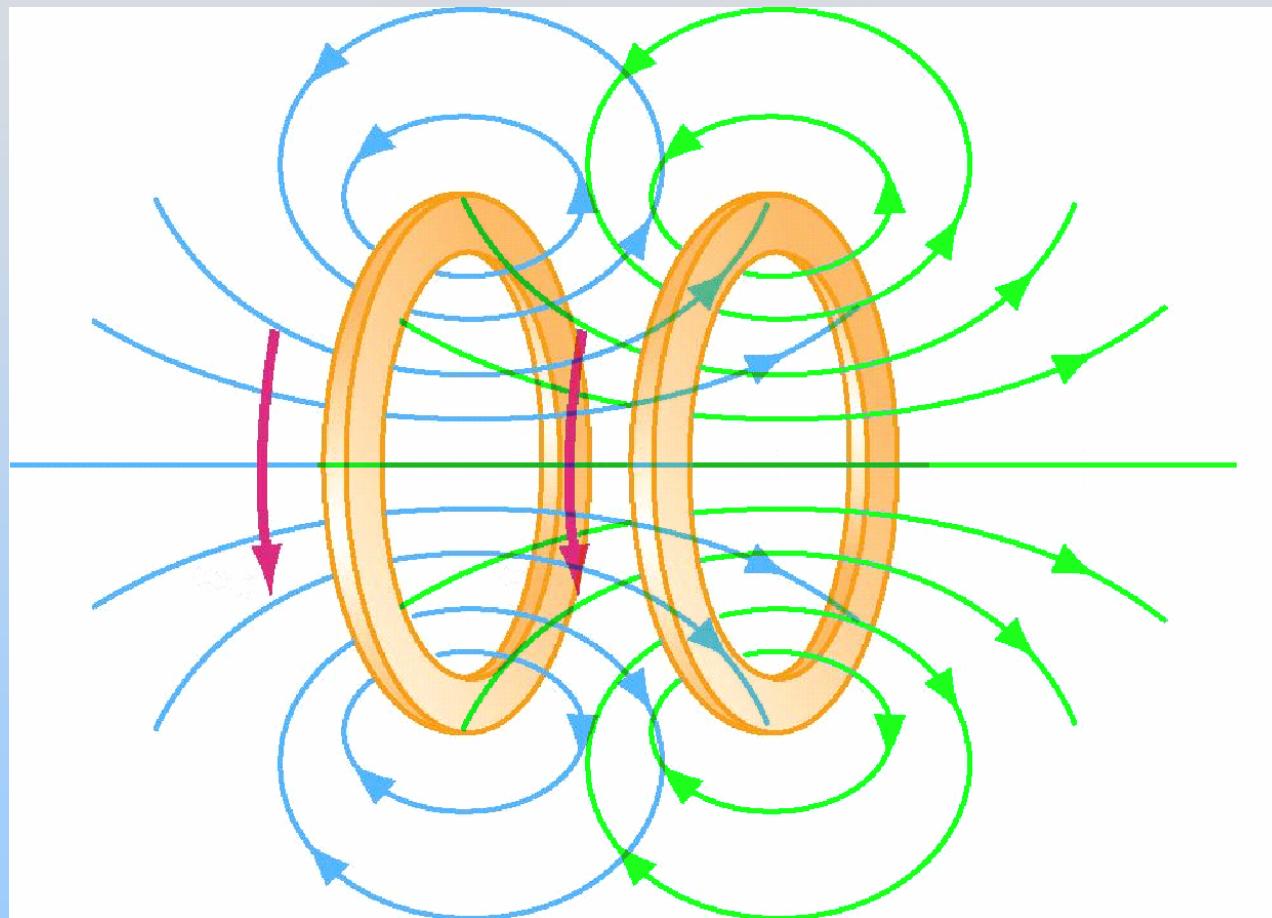
- Study & Follow Symmetry
- Determine Field Directions First
- Think About Where Field is Zero
- Loop Must
 - Be Parallel to (Constant) Desired Field
 - Be Perpendicular to Unknown Fields
 - Or Be Located in Zero Field

Other Geometries

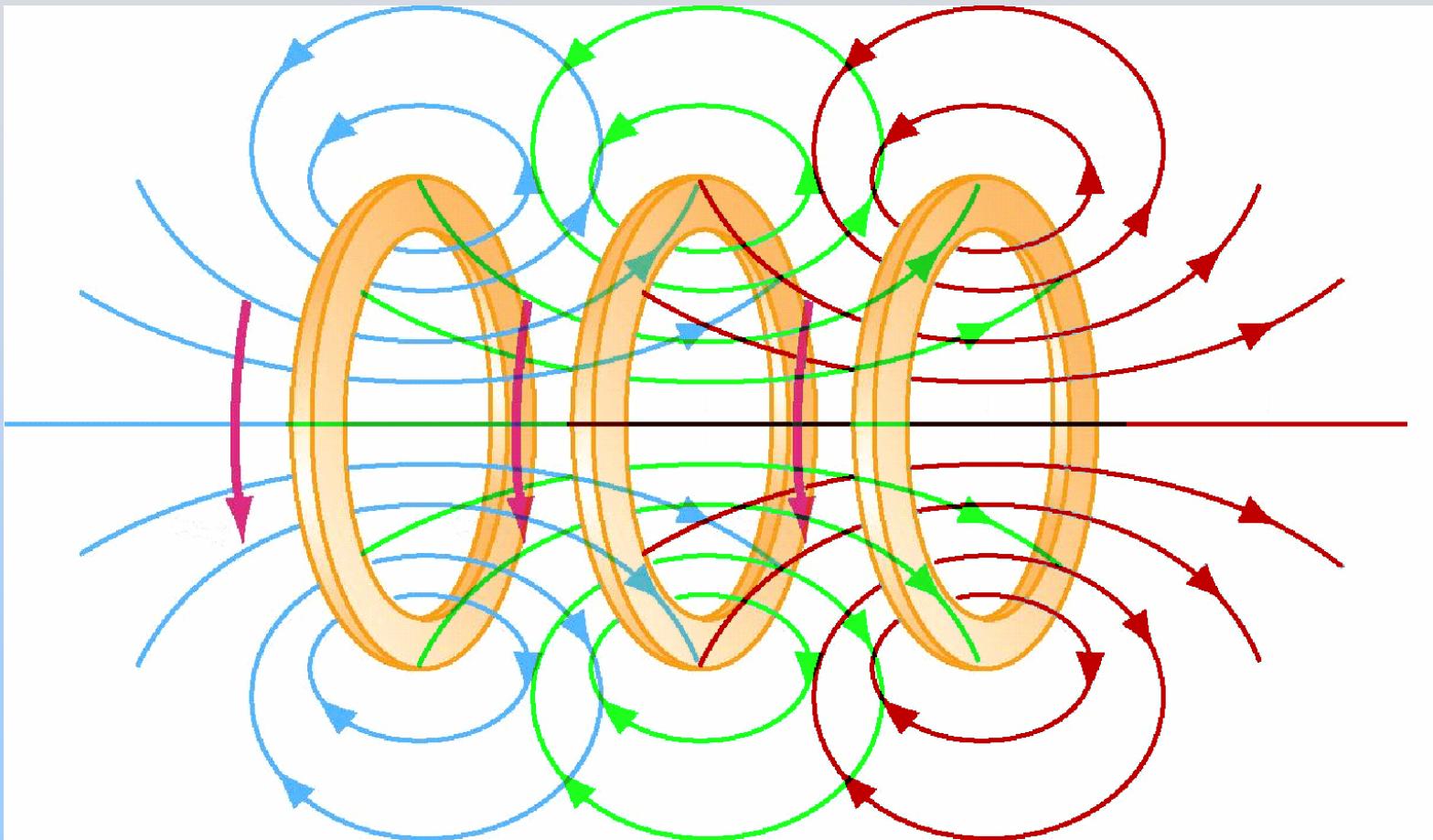
Helmholtz Coil



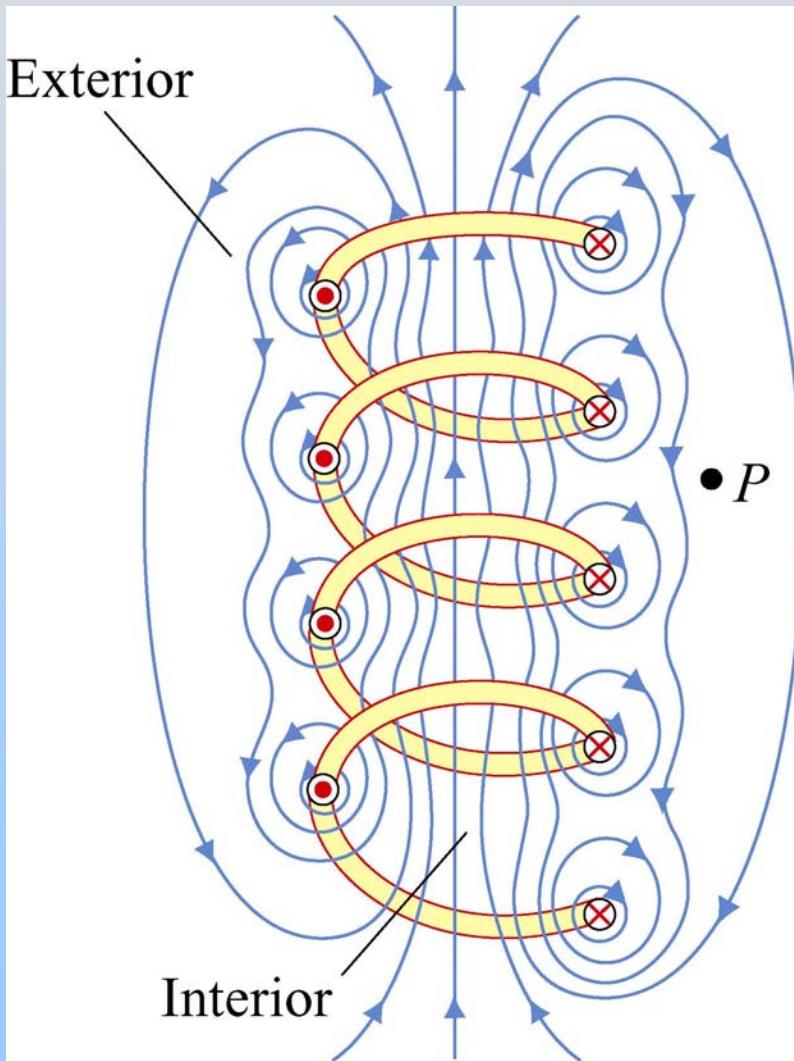
Closer than Helmholtz Coil



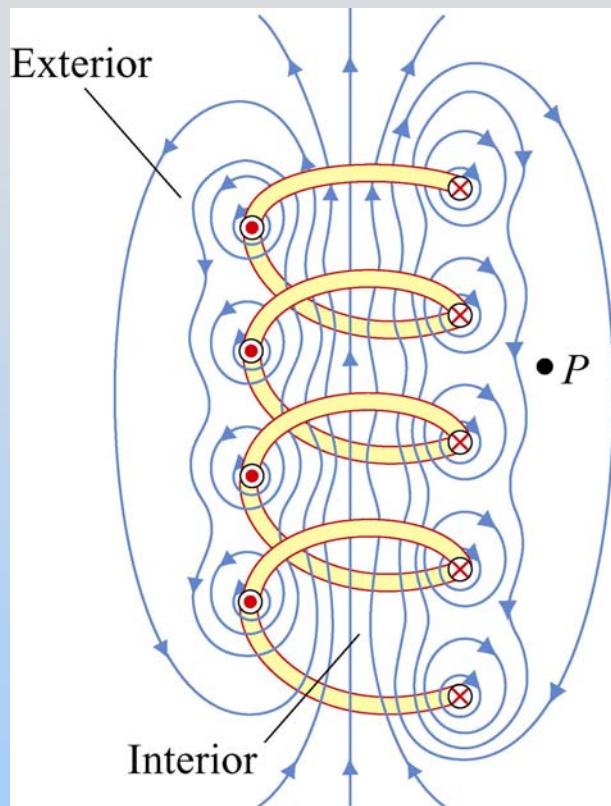
Multiple Wire Loops



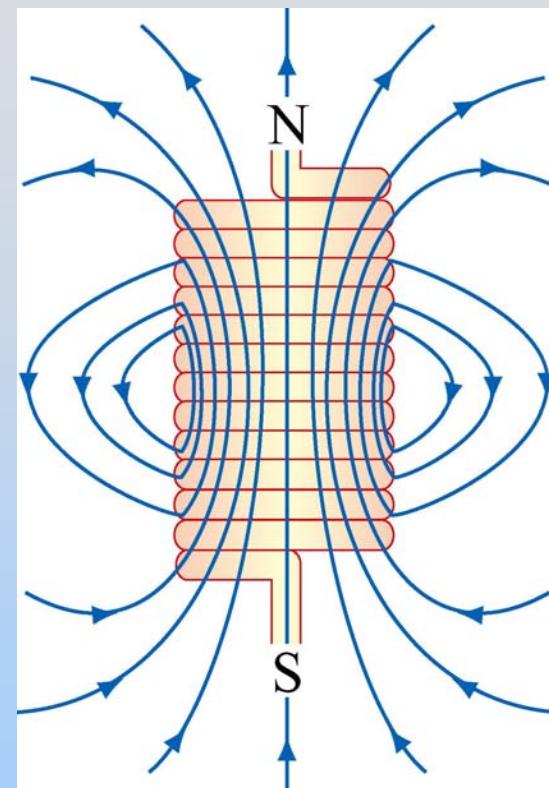
Multiple Wire Loops – Solenoid



Magnetic Field of Solenoid



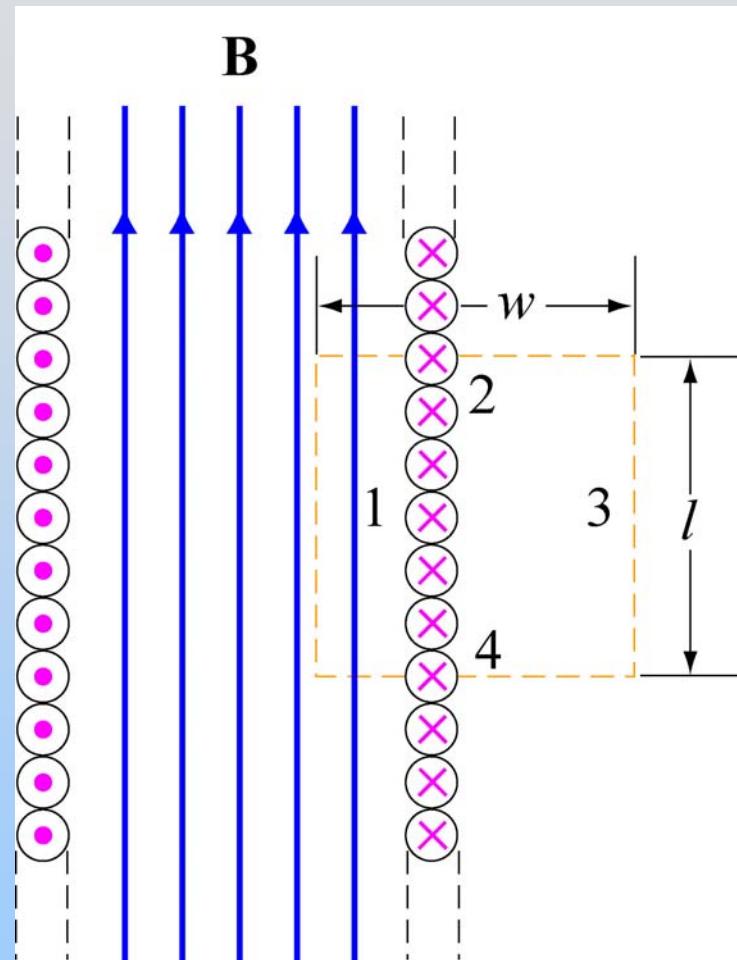
loosely wound



tightly wound

For ideal solenoid, B is uniform inside & zero outside

Magnetic Field of Ideal Solenoid



$n = N/L$: # turns/unit length

Using Ampere's law: Think!

$$\begin{cases} \vec{\mathbf{B}} \perp d\vec{s} \text{ along sides 2 and 4} \\ \vec{\mathbf{B}} = 0 \text{ along side 3} \end{cases}$$

$$\oint \vec{\mathbf{B}} \cdot d\vec{s} = \int_1 \vec{\mathbf{B}} \cdot d\vec{s} + \int_2 \vec{\mathbf{B}} \cdot d\vec{s} + \int_3 \vec{\mathbf{B}} \cdot d\vec{s} + \int_4 \vec{\mathbf{B}} \cdot d\vec{s} \\ = Bl + 0 + 0 + 0$$

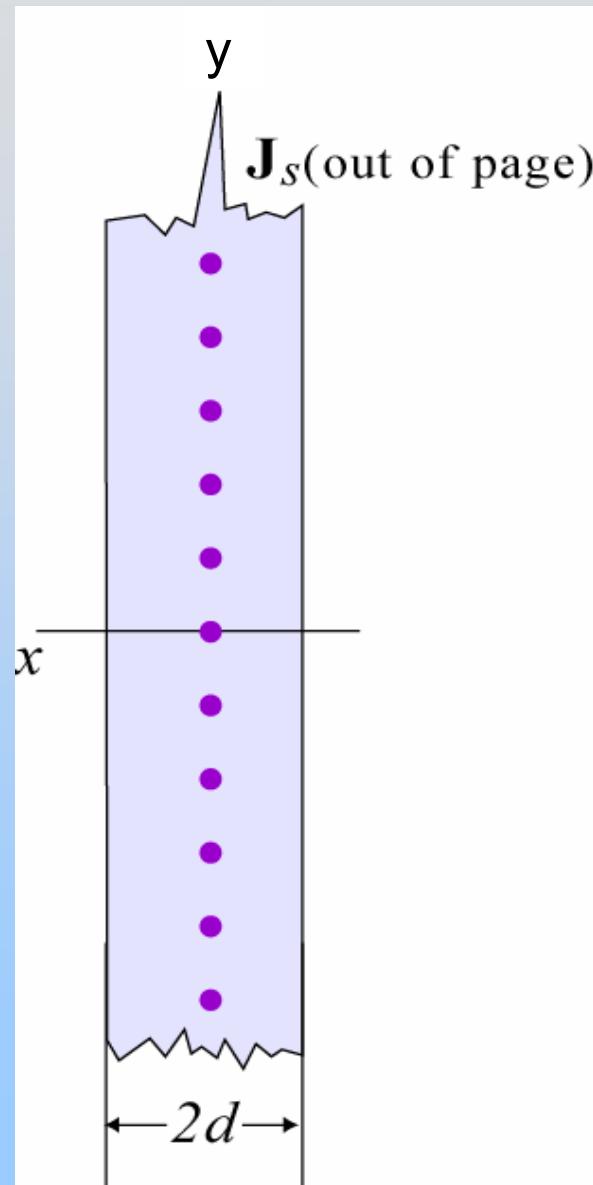
$$I_{enc} = nll \quad n: \text{turn density}$$

$$\oint \vec{\mathbf{B}} \cdot d\vec{s} = Bl = \mu_0 nll$$

$$B = \frac{\mu_0 nll}{l} = \mu_0 nI$$

Demonstration: Long Solenoid

Group Problem: Current Sheet

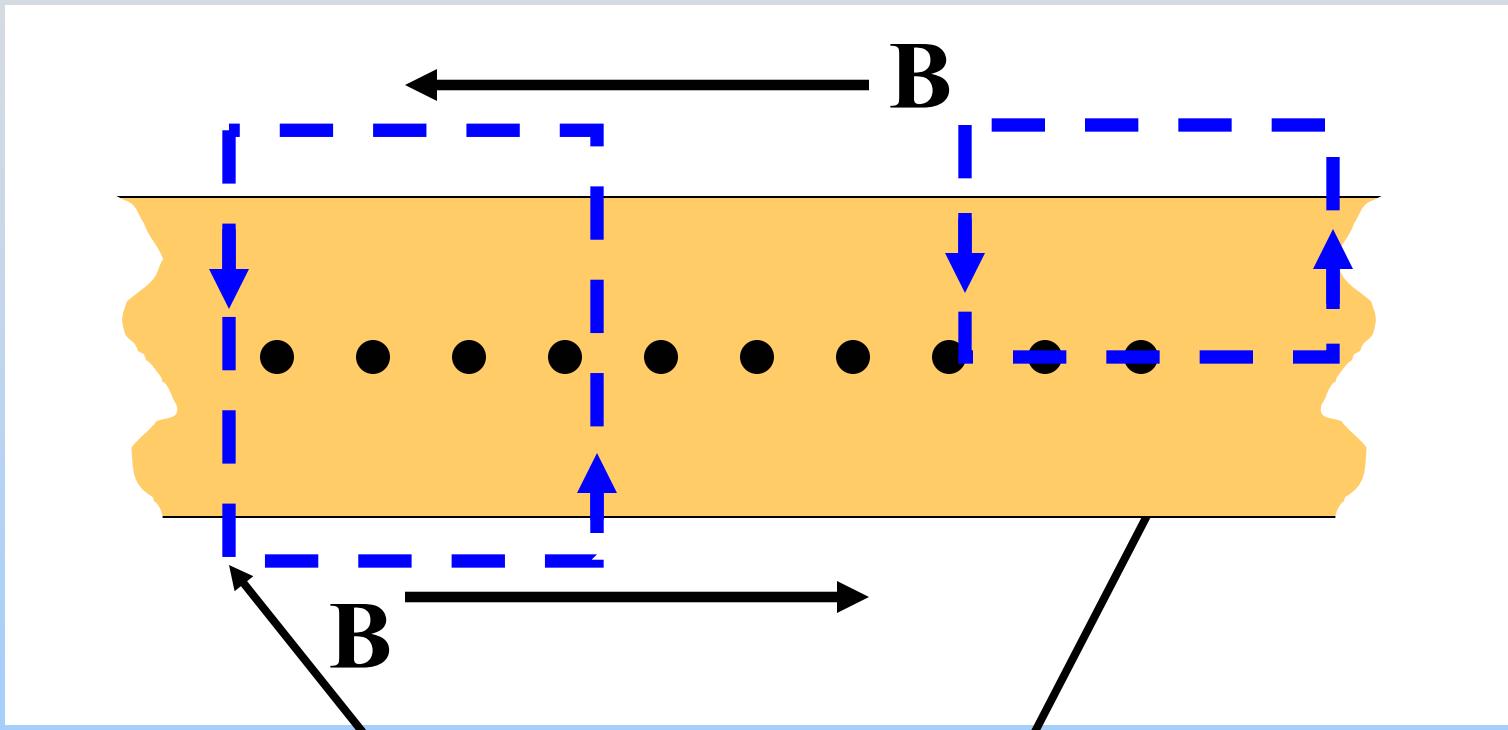


A sheet of current (infinite in the y & z directions, of thickness $2d$ in the x direction) carries a uniform current density:

$$\vec{\mathbf{J}}_s = J \hat{\mathbf{k}}$$

Find \mathbf{B} everywhere

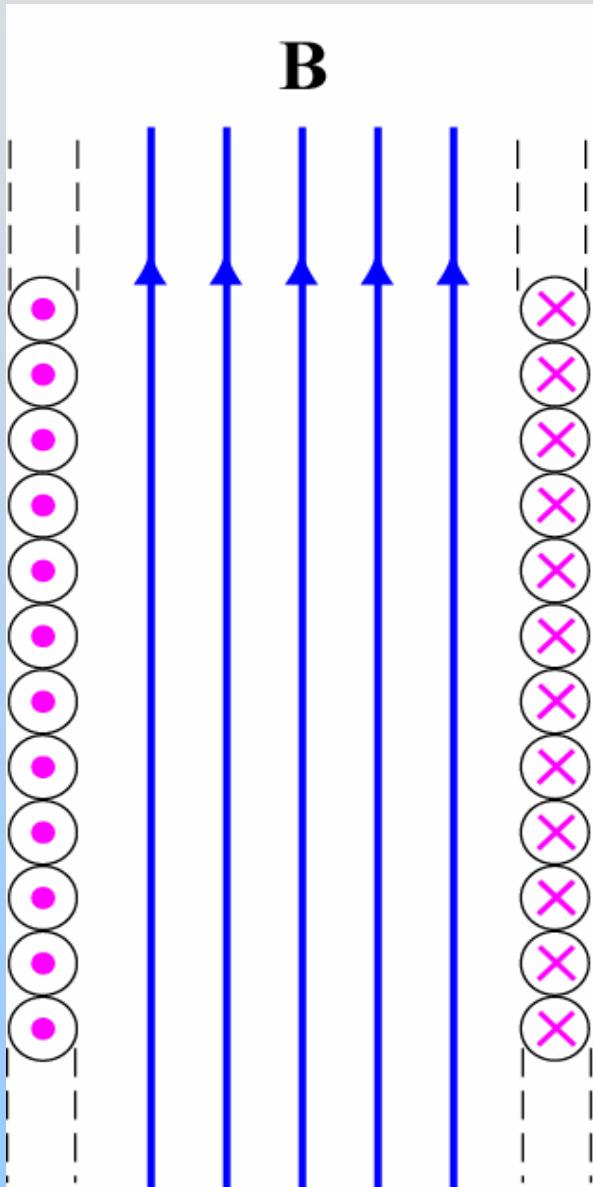
Ampere's Law: Infinite Current Sheet



Amperian Loops:

B is Constant & Parallel OR Perpendicular OR Zero
I Penetrates

Solenoid is Two Current Sheets



Field outside current sheet
should be half of solenoid,
with the substitution:

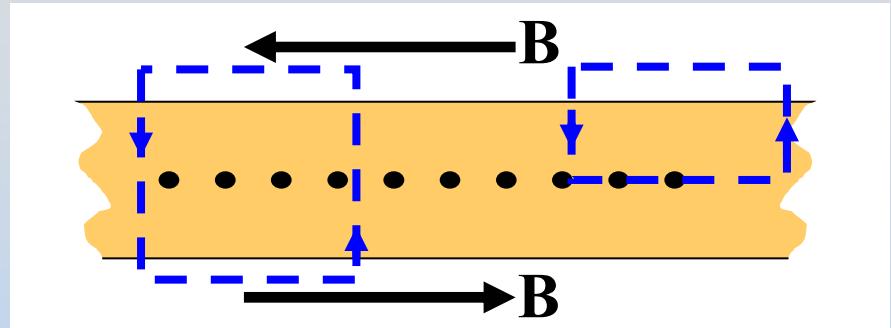
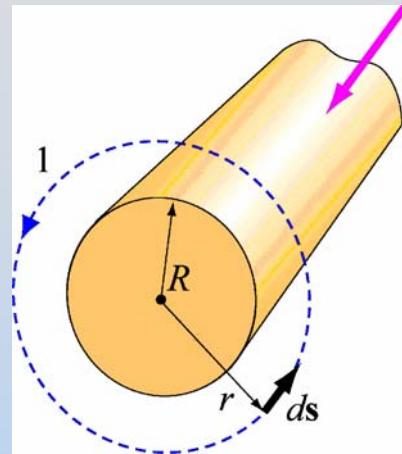
$$nI = 2dJ$$

This is current per unit length
(equivalent of λ , but we don't
have a symbol for it)

Ampere's Law:

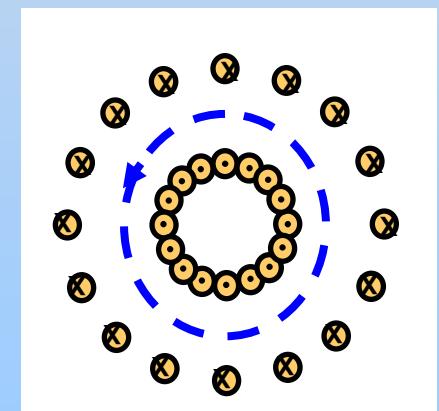
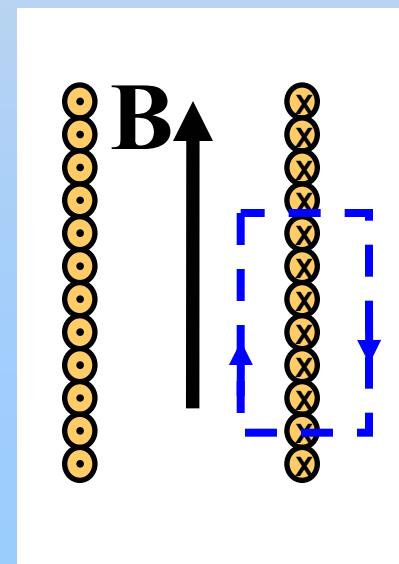
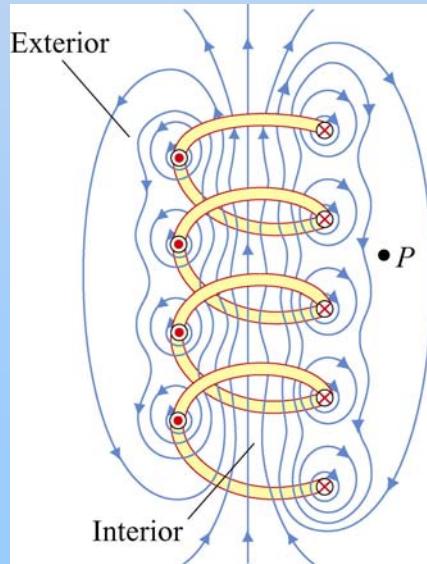
$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$

Long
Circular
Symmetry



(Infinite) Current Sheet

Solenoid
=
2 Current
Sheets



Torus

Brief Review Thus Far...

Maxwell's Equations (So Far)

Gauss's Law:

$$\iint_S \vec{E} \cdot d\vec{A} = \frac{Q_{in}}{\epsilon_0}$$

Electric charges make diverging Electric Fields

Magnetic Gauss's Law: $\iint_S \vec{B} \cdot d\vec{A} = 0$

No Magnetic Monopoles! (No diverging B Fields)

Ampere's Law:

$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$

Currents make curling Magnetic Fields