

8.03 Lecture 12

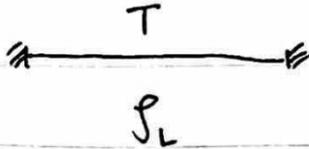
Systems we have learned:

Wave equation:

$$\frac{\partial^2 \psi}{\partial t^2} = v_p^2 \frac{\partial^2 \psi}{\partial x^2}$$

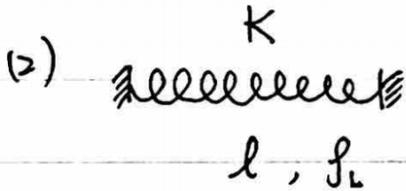
There are three different kinds of systems discussed in the lecture:

(1)



(1) String with constant tension and mass per unit length ρ_L

$$v_p = \sqrt{\frac{T}{\rho_L}}$$



(2) Spring with spring constant k , length l , and mass per unit length ρ_L

$$v_p = \sqrt{\frac{kl}{\rho_L}}$$

(3)



(3) Organ pipe with room pressure P_0 and air density ρ

$$v_p = \sqrt{\frac{\gamma P_0}{\rho}}$$

$$p \propto V^{-\gamma}$$

This time, we are doing EM (electromagnetic) waves!

$$\begin{aligned}
\vec{\nabla} \cdot \vec{E} &= \frac{\rho}{\epsilon_0} && \Rightarrow \text{Gauss' Law} \\
\vec{\nabla} \cdot \vec{B} &= 0 && \Rightarrow \text{Gauss' Law for magnetism} \\
\vec{\nabla} \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} && \Rightarrow \text{Faraday's Law} \\
\vec{\nabla} \times \vec{B} &= \mu_0 \left(\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) && \Rightarrow \text{Ampere's Law}
\end{aligned}$$

In the vacuum: $\rho = 0$ and $\vec{J} = 0$ and we get:

$$\begin{aligned}
\vec{\nabla} \cdot \vec{E} &= 0 \\
\vec{\nabla} \cdot \vec{B} &= 0 \\
\vec{\nabla} \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \\
\vec{\nabla} \times \vec{B} &= \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}
\end{aligned}$$

Where in the last two equations we see a changing magnetic field generates an electric field and a changing electric field generates a magnetic field. Can you see the EM wave solution from these equations? Maxwell saw it!

We need to use this identity:

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - (\vec{\nabla} \cdot \vec{\nabla})\vec{A}$$

Where $\vec{\nabla} \cdot \vec{\nabla} \equiv \vec{\nabla}^2$ is the Laplacian operator. In the vacuum:

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) \overset{-\partial \vec{B} / \partial t}{=} \vec{\nabla}(\vec{\nabla} \cdot \vec{E}) \overset{0}{=} -(\vec{\nabla}^2)\vec{E}$$

Where we have made replacements based on the vacuum Maxwell equations above. Let's first examine the left hand side:

$$\begin{aligned}
\vec{\nabla} \times \left(-\frac{\partial \vec{B}}{\partial t} \right) &= -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B}) \\
&= -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} \\
&= -\vec{\nabla}^2 \vec{E} \\
\Rightarrow \vec{\nabla}^2 \vec{E} &= \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}
\end{aligned}$$

Recall

$$\nabla^2 \equiv \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right)$$

And so we have a wave equation!!

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

This equation changed the world! Maxwell is the first one who recognized it because of the term he put in. It was a wave equation with speed equal to the speed of light:

$$v_p = c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} \approx 3 \cdot 10^8 \text{ m/s}$$

What about the \vec{B} field? We can do the same exercise:

$$\vec{\nabla}^2 B = \mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2}$$

It is very important that the associated magnetic field also satisfies the wave equation. From the Maxwell equation \vec{E} creates \vec{B} and \vec{B} creates \vec{E} , therefore they can not exist without each other.

1638 Galileo: speed of light is large

1676 Romer: $2.2 \times 10^8 \text{ m/s}$

1729 James Bradley: $3.01 \times 10^8 \text{ m/s}$

This means that in vacuum you can excite EM waves! What is oscillating? The field!

Before we tackle EM waves, let's review divergence and curl briefly.

*Field:

Scalar field: every position in the space gets a number. Temperature is an example.

Vector field: Instead of a number or scalar, every point gets a vector.

$$\vec{A}(x, y, z) = A_x \hat{x} + A_y \hat{y} + A_z \hat{z}$$

The electric and magnetic fields are vector fields, e.g.:

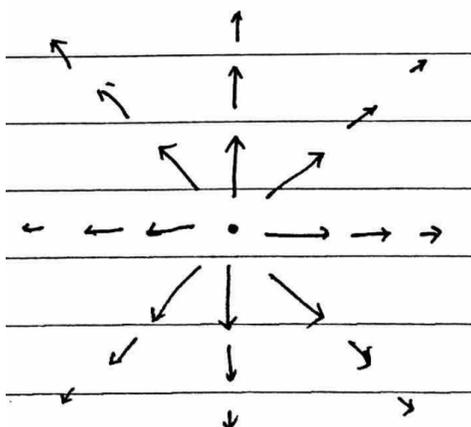
$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

To understand the structure of vector fields:

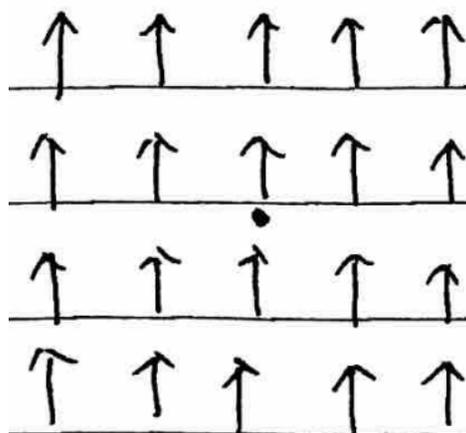
Divergence (using our definition of $\vec{\nabla}$ from above):

$$\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

The divergence is a measure of how much the vector v spreads out (*diverges*) from a point:



The divergence of this vector field is positive.

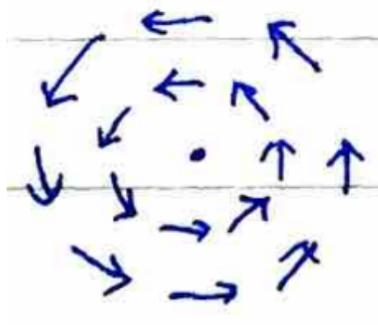


The divergence of this vector field is zero.

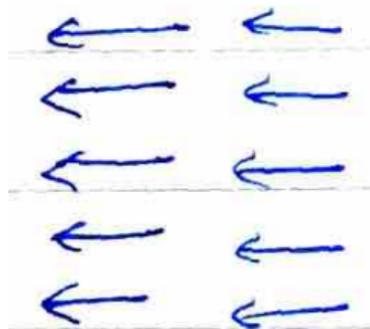
Curl:

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \hat{x} + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \hat{y} + \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{z}$$

What exactly does curl mean? It is a measure of how much the vector \vec{A} “curls around” a point.



This vector field has a large curl.



This vector field has no curl.

Gauss' Theorem (or the Divergence Theorem):

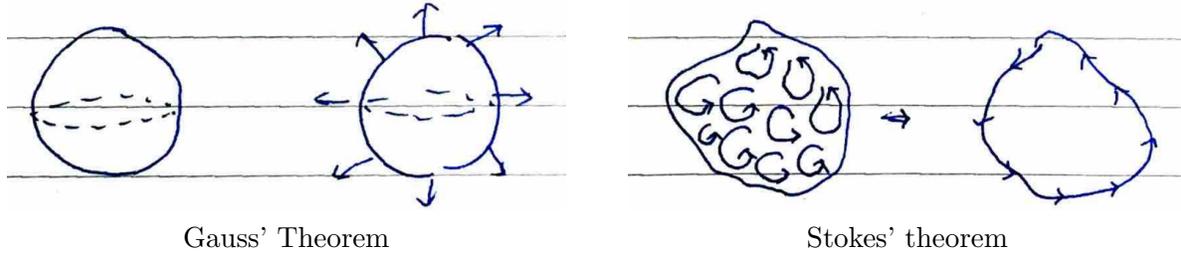
$$\iiint_V (\vec{\nabla} \cdot \vec{A}) d\tau = \oint_S \vec{A} \cdot \vec{da}$$

Which allows us to relate the integral of the divergence over the whole volume (RHS) to a 2-D surface integral (LHS).

Stokes' Theorem:

$$\iint_S (\vec{\nabla} \times \vec{A}) \cdot \vec{da} = \oint_P \vec{A} \times \vec{dl}$$

Which allows us to relate the surface integral over the curl (LHS) to a line integral over a closed path (RHS).



*Consider a “plane wave” solution:

$$\begin{aligned}\vec{E} &= \text{Re} \left[E_0 e^{i(kz - \omega t)} \hat{x} \right] \quad \text{Only in the } \hat{x} \text{ direction.} \\ &= \{ E_0 \cos(kz - \omega t), 0, 0 \}\end{aligned}$$

Check if it satisfies

$$\begin{aligned}\vec{\nabla}^2 E &= \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} \\ \Rightarrow \frac{\partial^2 E_x}{\partial z^2} \hat{x} &= \mu_0 \epsilon_0 \frac{\partial^2 E_x}{\partial t^2} \hat{x}\end{aligned}$$

In \hat{x} direction: $-E_0 k^2 \cos(kz - \omega t) = -\mu_0 \epsilon_0 \omega^2 E_0 \cos(kz - \omega t)$

$$\frac{\omega}{k} = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = c \Rightarrow \text{Condition needed to satisfy the wave equation.}$$

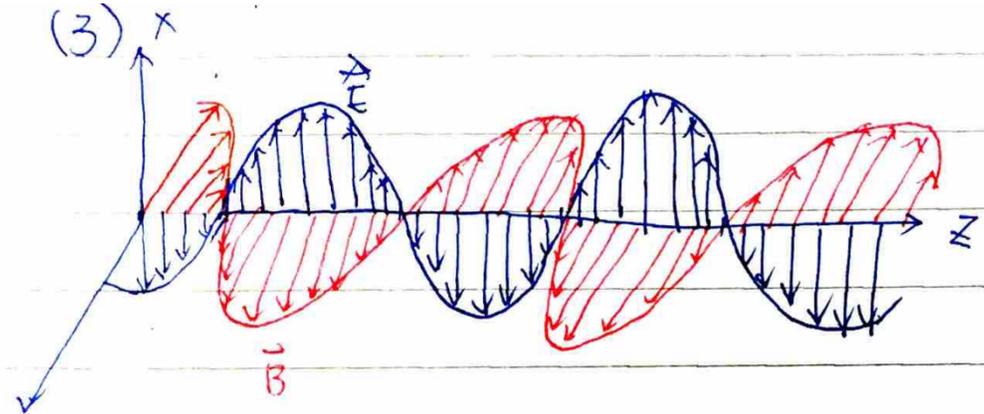
*What about \vec{B} ?

$$\begin{aligned}\vec{\nabla} \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \\ &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & 0 & 0 \end{vmatrix} = \frac{\partial E_x}{\partial z} \hat{y} - \frac{\partial E_x}{\partial y} \hat{z} \\ &= -k E_0 \sin(kz - \omega t) \hat{y} \\ \Rightarrow \vec{B} &= \frac{k}{\omega} E_0 \cos(kz - \omega t) \hat{y} = \frac{E_0}{c} \cos(kz - \omega t) \hat{y}\end{aligned}$$

What did we learn from this exercise?

1. \vec{E} must come with \vec{B} . In vacuum: the two fields are perpendicular and they are in phase. If \vec{k} is the direction of propagation then $\vec{B} = \frac{1}{c} \hat{k} \times \vec{E}$. The amplitude of the magnetic field is equal to the amplitude of the electric field divided by the speed of light.
2. The EM wave is non-dispersive, meaning that the speed of the wave c is independent of the wave number k : $\frac{\omega}{k} = c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$

3. The direction of the propagating EM wave is $\vec{E} \times \vec{B}$



In general a propagating EM wave can be written as:

$$\vec{E}(r, t) = \text{Re} \left[\vec{E}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t + \phi)} \right]$$

Where $\vec{E}_0 \equiv E_{0x} \hat{x} + E_{0y} \hat{y} + E_{0z} \hat{z}$, $\vec{r} \equiv x \hat{x} + y \hat{y} + z \hat{z}$ and $\omega \equiv ck$

Given this electric field, we can get the magnetic field:

$$\vec{B}(r, t) = \frac{1}{c} \hat{k} \times \vec{E}$$

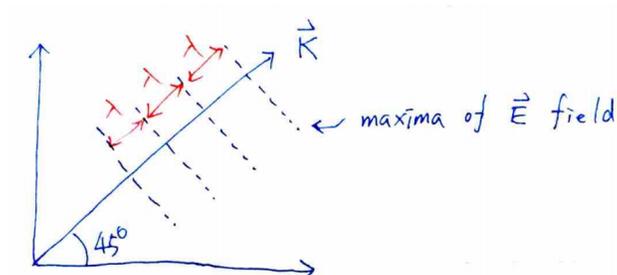
Example:

$$\vec{k} = \frac{2\pi}{\lambda} \left\{ \frac{\hat{x}}{\sqrt{2}} + \frac{\hat{y}}{\sqrt{2}} \right\}$$

$$\vec{E}_0 = -\frac{E_0}{\sqrt{2}} \hat{x} + \frac{E_0}{\sqrt{2}} \hat{y}$$

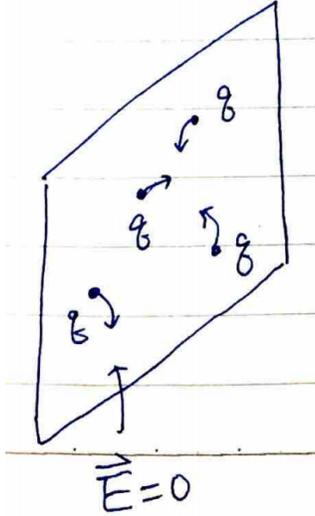
$$\vec{k} \cdot \vec{r} = \frac{2\pi}{\sqrt{2}\lambda} (x + y)$$

$$\Rightarrow \vec{E}(x, y, z) = E_0 \left(-\frac{\hat{x}}{\sqrt{2}} + \frac{\hat{y}}{\sqrt{2}} \right) \cos \left(\frac{\sqrt{2}\pi}{\lambda} (x + y) - \omega t \right)$$



$$\vec{B} = \frac{1}{c} \hat{k} \times \vec{E} \Rightarrow \vec{B}(x, y, z) = \frac{E_0}{c} \hat{z} \cos\left(\frac{\sqrt{2}\pi}{\lambda}(x+y) - \omega t\right)$$

If there is no other material, this EM wave will travel forever...
 Now let's put something into the game: A "perfect conductor"



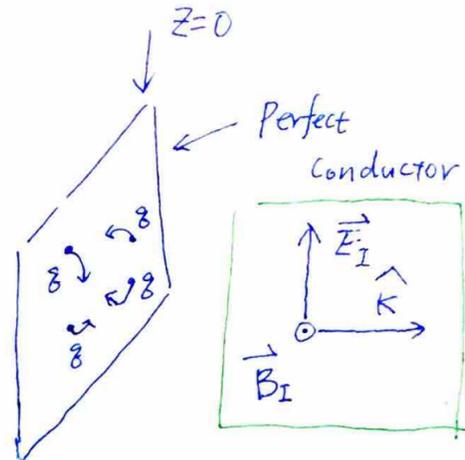
A busy world inside this system! All the little charges are moving around without cost of energy (there is no dissipation).

Incident wave:

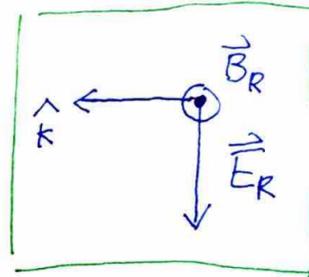
$$\begin{cases} \vec{E}_I = \frac{E_0}{2} \cos(kz - \omega t) \hat{x} \\ \vec{B}_I = \frac{E_0}{2c} \cos(kz - \omega t) \hat{y} \end{cases}$$

To satisfy the boundary conditions $\vec{E} = 0$ at $z = 0$ we need a reflected wave!

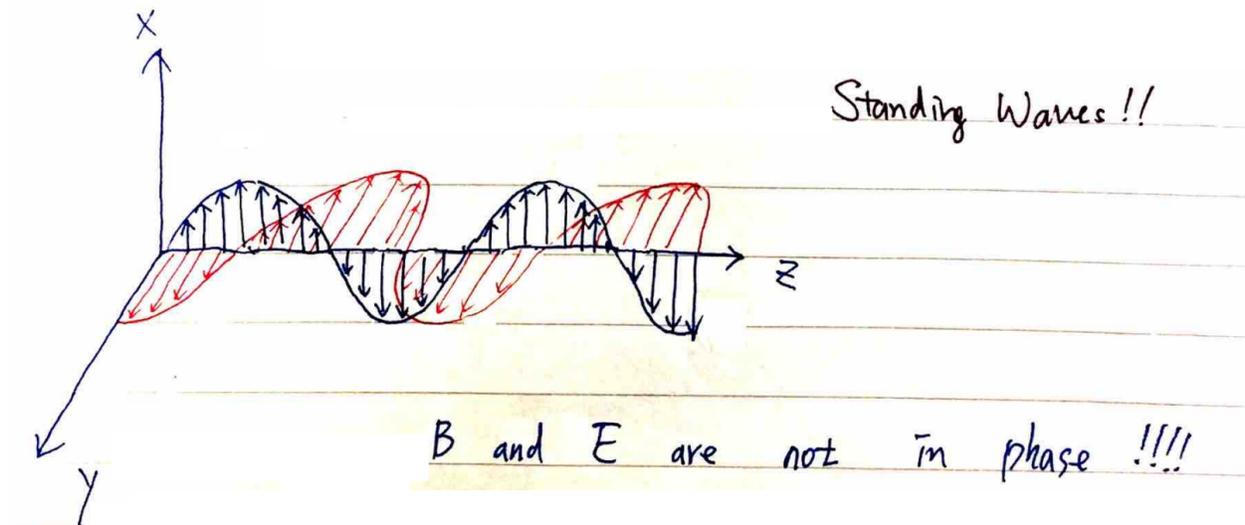
$$\begin{aligned} \vec{E}_R &= -\frac{E_0}{2} \cos(-kz - \omega t) \hat{x} \\ \vec{B}_R &= \frac{E_0}{2c} \cos(-kz - \omega t) \hat{y} \end{aligned}$$



$$\vec{B}_R = \frac{1}{c} \hat{k} \times \vec{E}_R$$



$$\begin{aligned}\vec{E} &= \vec{E}_I + \vec{E}_R = \frac{E_0}{2} (\cos(kz - \omega t) - \cos(-kz - \omega t)) \hat{x} \\ &= E_0 \sin(\omega t) \sin(kz) \hat{x} \\ \vec{B} &= \vec{B}_I + \vec{B}_R = \frac{E_0}{2c} (\cos(kz - \omega t) + \cos(-kz - \omega t)) \hat{y} \\ &= \frac{E_0}{c} \cos(\omega t) \cos(kz) \hat{y}\end{aligned}$$



Energy density?

$$\begin{aligned}U_E &= \frac{1}{2} \epsilon_0 E^2 = \frac{\epsilon_0}{2} E_0^2 \sin^2 \omega t \sin^2 kz \\ U_B &= \frac{1}{2\mu_0} B^2 = \frac{\epsilon_0}{2} E_0^2 \cos^2 \omega t \cos^2 kz\end{aligned}$$

Poynting vector: directional energy flux, or the rate of energy transfer per unit area:

$$\begin{aligned}\vec{S} &= \frac{\vec{E} \times \vec{B}}{\mu_0} = \frac{1}{\mu_0} E_x B_y \hat{z} \\ &= \frac{E_0^2}{\mu_0 c} \sin \omega t \cos \omega t \sin kz \cos kz \hat{z} \\ &= \frac{E_0^2}{4\mu_0 c} \sin(2\omega t) \sin(2kz) \hat{z}\end{aligned}$$

This is how a microwave oven works!

*The EM waves are bounced around inside the oven

*EM waves increase the vibration of the molecules in the oven and increase the temperature of the food.

MIT OpenCourseWare
<https://ocw.mit.edu>

8.03SC Physics III: Vibrations and Waves
Fall 2016

For information about citing these materials or our Terms of Use, visit: <https://ocw.mit.edu/terms>.