### 8.323 Problem Set 5 Solutions

March 14, 2023

Question 1: A Useful Formula, and the Path Integral in Phase Space (20 points) (a) Derive the following equations:

$$
\begin{aligned}
\left\langle x_{i+1}\right| e^{-i \frac{\hat{p}^{2}}{2 m} \Delta t} e^{-i \Delta t V(\hat{x})}\left|x_{i}\right\rangle & =\int む p_{i} \exp \left[-i \Delta t \frac{p_{i}^{2}}{2 m}-i \Delta t V\left(x_{i}\right)+i p_{i}\left(x_{i+1}-x_{i}\right)\right] \\
& =\sqrt{\frac{m}{2 \pi i \Delta t}} \exp \left[\frac{i m \Delta t}{2}\left(\frac{x_{i+1}-x_{i}}{\Delta t}\right)^{2}-i \Delta t V\left(x_{i}\right)\right]
\end{aligned}
$$

We start by deriving the first equation:

$$
\begin{aligned}
\left\langle x_{i+1}\right| e^{-i \frac{\hat{p}^{2}}{2 m} \Delta t} e^{-i \Delta t V(\hat{x})}\left|x_{i}\right\rangle & =\int d p_{i}\left\langle x_{i+1}\right| e^{-i \frac{\hat{p}^{2}}{2 m} \Delta t}\left|p_{i}\right\rangle\left\langle p_{i}\right| e^{-i \Delta t V(\hat{x})}\left|x_{i}\right\rangle \\
& =\int d p_{i} e^{-i \frac{p_{i}^{2}}{2 m} \Delta t} e^{-i \Delta t V\left(x_{i}\right)}\left\langle x_{i+1} \mid p_{i}\right\rangle\left\langle p_{i} \mid x_{i}\right\rangle \\
& =\int d p_{i} e^{-i \frac{p_{i}^{2}}{2 m} \Delta t} e^{-i \Delta t V\left(x_{i}\right)} e^{i p_{i} x_{i+1}} e^{-i p_{i} x_{i}} \\
& =\int む p_{i} \exp \left[-i \Delta t \frac{p_{i}^{2}}{2 m}-i \Delta t V\left(x_{i}\right)+i p_{i}\left(x_{i+1}-x_{i}\right)\right]
\end{aligned}
$$

To get the second equation from this, we complete the square and compute the Gaussian integral, or equivalently use the identity $\int d x e^{-a x^{2}+b x}=\sqrt{\frac{\pi}{a}} e^{b^{2} / 4 a}$. Hence,

$$
\begin{aligned}
\left\langle x_{i+1}\right| e^{-i \frac{\hat{p}^{2}}{2 m} \Delta t} e^{-i \Delta t V(\hat{x})}\left|x_{i}\right\rangle & =\frac{1}{2 \pi} \sqrt{\frac{2 \pi m}{i \Delta t}} \exp \left[-\frac{\left(x_{i+1}-x_{i}\right)^{2}}{2 i \Delta t / m}\right] e^{-i \Delta t V\left(x_{i}\right)} \\
& =\sqrt{\frac{m}{2 \pi i \Delta t}} \exp \left[\frac{i m \Delta t}{2}\left(\frac{x_{i+1}-x_{i}}{\Delta t}\right)^{2}-i \Delta t V\left(x_{i}\right)\right]
\end{aligned}
$$

(b) Use the first equation in (a) to derive the following:

$$
\left\langle x_{a}, t_{a} \mid x_{b}, t_{b}\right\rangle=\int_{x\left(t_{b}\right)=x_{b}}^{x\left(t_{a}\right)=x_{a}} D x(t) D p(t) \exp \left[i \int_{t^{\prime}}^{t} d t(p \dot{x}-H)\right]
$$

The integration in this expression should be understood as

$$
\int_{x\left(t_{b}\right)=x_{b}}^{x\left(t_{a}\right)=x_{a}} D x(t) D p(t)=\lim _{N \rightarrow \infty} \int \frac{d p_{0}}{2 \pi} \int \frac{d x_{1} d p_{1}}{2 \pi} \cdots \int \frac{d x_{N-1} d p_{N-1}}{2 \pi}
$$

where we again divide the interval $\left[t_{b}, t_{a}\right]$ into $N$ segments, with $t_{0}=t_{b}, t_{N}=t_{a}$.

We denote the left-hand side of the equation in (a) by $M_{i}$. Now we do the same trick from class to derive the path-integral:

$$
\begin{aligned}
\left\langle x_{a}, t_{a} \mid x_{b}, t_{b}\right\rangle & =\left\langle x_{a}\right| e^{-i \hat{H}\left(t_{a}-t_{b}\right)}\left|x_{b}\right\rangle=\left\langle x_{a}\right|\left(e^{-i \hat{H} \Delta t}\right)^{N}\left|x_{b}\right\rangle \\
& =\int d x_{1} \cdots d x_{N-1}\left\langle x_{a}\right| e^{-i \hat{H} \Delta t}\left|x_{N-1}\right\rangle\left\langle x_{N-1}\right| \cdots\left|x_{1}\right\rangle\left\langle x_{1}\right| e^{-i \hat{H} \Delta t}\left|x_{b}\right\rangle \\
& =\int d x_{1} \cdots d x_{N-1} M_{N-1} \cdots M_{0} \\
& =\int d x_{1} \cdots d x_{N-1} đ p_{0} \cdots d p_{N-1} \prod_{i=0}^{N-1} \exp \left[-i \Delta t \frac{p_{i}^{2}}{2 m}-i \Delta t V\left(x_{i}\right)+i p_{i}\left(x_{i+1}-x_{i}\right)\right] \\
& =\int_{x\left(t_{b}\right)=x_{b}}^{x\left(t_{a}\right)=x_{a}} D x(t) D p(t) \exp \left[i \sum_{i=0}^{N-1} \Delta t\left(p_{i} \frac{x_{i+1}-x_{i}}{\Delta t}-\frac{p_{i}^{2}}{2 m}-V\left(x_{i}\right)\right)\right] \\
& =\int_{x\left(t_{b}\right)=x_{b}}^{x\left(t_{a}\right)=x_{a}} D x(t) D p(t) \exp \left[i \int_{t_{b}}^{t_{a}} d t(p \dot{x}-H)\right]
\end{aligned}
$$

In the second line we insert the identity $N-1$ times, so that we can use the formula from (a) for each matrix element in the 4th line. In the 5th line the product of exponentials becomes a sum of exponents, which in the continuum case reduces to the integral in the last line.

## Question 2: The Schrödinger Equation, Rederived (20 points)

The wavefunction $\psi(t, x)$ for a system at time $t$ can be obtained from that at time $t^{\prime}$ by

$$
\psi(t, x)=\int d x^{\prime} K\left(x, t ; x^{\prime}, t^{\prime}\right) \psi\left(x^{\prime}, t^{\prime}\right)
$$

for the propagator given by

$$
K\left(x, t ; x^{\prime}, t^{\prime}\right)=\left\langle x, t \mid x^{\prime}, t^{\prime}\right\rangle=\int_{x\left(t_{b}\right)=x_{b}}^{x\left(t_{a}\right)=x_{a}} D x(t) \exp \left[i \int_{t^{\prime}}^{t} d t L(\dot{x}, x)\right]
$$

Show that $\psi(t, x)$ satisfies the Schrödinger equation,

$$
i \partial_{t} \psi(t, x)=-\frac{1}{2 m} \partial_{x}^{2} \psi(t, x)+V(x) \psi(t, x)
$$

We therefore consider the wavefunction after an infinitesimal time step $\delta t$ :

$$
\psi(t+\delta t, x)=\int d y K(t+\delta t, x ; t, y) \psi(t, y)
$$

Equating both sides of this equation to order $\delta$ will lead to the Schrödinger equation.
The left hand side is simple:

$$
\mathrm{LHS}=\psi(t+\delta t, x)=\psi(t, x)+\delta t \partial_{t} \psi(t, x)+\mathcal{O}\left(\delta t^{2}\right)
$$

To expand the right hand side, note for an infinitesimal $\delta t$ that the propagator $K(t+\delta t, x ; t, y)$ can be written as a single infinitesimal time step:

$$
K(t+\delta t, x ; t, y)=\left(\frac{m}{2 \pi i \delta t}\right)^{1 / 2} \exp \left[i \delta t\left(\frac{m}{2}\left(\frac{x-y}{\delta t}\right)^{2}-V(y)\right)\right]
$$

Therefore we expand:

$$
\begin{aligned}
\text { RHS } & =\int d y K(t+\delta t, x ; t, y) \psi(t, y) \\
& =\left(\frac{m}{2 \pi i \delta t}\right)^{1 / 2} \int d y e^{i \delta t\left(\frac{m}{2}\left(\frac{x-y}{\delta t}\right)^{2}-V(y)\right)} \psi(t, y) \\
& =\left(\frac{m}{2 \pi i}\right)^{1 / 2} \int d u e^{i\left(\frac{m}{2} u^{2}-\delta t V(x+u \sqrt{\delta t})\right.} \psi(t, x+u \sqrt{\delta t}) \\
& =\left(\frac{m}{2 \pi i}\right)^{1 / 2} \int d u e^{i \frac{m}{2} u^{2}}(1-\delta t V(x))\left(\psi(t, x)+\sqrt{\delta t} \partial_{x} \psi(t, x) u+\frac{\delta t}{2} \partial^{2} x \psi(t, u) u^{2}\right)+\mathcal{O}\left(\delta t^{2}\right) \\
& =\psi(t, x)+\delta t\left(-i V(x) \psi(t, x)+\frac{i}{2 m} \partial_{x}^{2} \psi(t, x)\right)+\mathcal{O}\left(\delta t^{2}\right)
\end{aligned}
$$

In the third line we have made the substitution $u \sqrt{\delta t}=y-x$, and in the 4th line we expand each term to order $\delta t$, neglecting higher order terms. In the subsequent line we perform the Gaussian integrals over $u$, noting that the order $(\delta t)^{1 / 2}$ term becauyse the integral is odd.

Setting the 2 sides equal, we have the Schrödinger equation as desired:

$$
i \partial_{t} \psi(t, x)=\left(-\frac{1}{2 m} \partial_{x}^{2}+V(x)\right) \psi(t, x)
$$

## Question 3: The Free Particle (20 points)

For a free particle, i.e. $V(x)=0$, perform explicitly the integrals over $x_{i}, i=1, \ldots, N-1$ to show that

$$
K\left(x_{a}, t_{a} ; x_{b}, t_{b}\right)=\left(\frac{m}{2 \pi i\left(t_{a}-t_{b}\right)}\right)^{1 / 2} \exp \left[\frac{i m\left(x_{a}-x_{b}\right)^{2}}{2\left(t_{a}-t_{b}\right)}\right]
$$

We evaluate the integrals in order, starting with the one over $x_{1}$. We denote $x_{0}=x_{b}$ and $x_{N}=x_{a}$.

$$
\begin{aligned}
K\left(x_{a}, t_{a} ; x_{b}, t_{b}\right) & =\lim _{N \rightarrow \infty}\left(\frac{m}{2 \pi i \Delta t}\right)^{N / 2} \int d x_{1} \cdots d x_{N-1} e^{i \frac{m}{2 \Delta t}\left(\left(x_{N}-x_{N-1}\right)^{2}+\cdots+\left(x_{2}-x_{1}\right)^{2}+\left(x_{1}-x_{0}\right)^{2}\right)} \\
& =\lim _{N \rightarrow \infty}\left(\frac{m}{2 \pi i \Delta t}\right)^{N / 2}\left(\frac{i \pi \Delta t}{m}\right)^{1 / 2} \int d x_{2} \cdots d x_{N-1} e^{i \frac{m}{2 \Delta t}\left(\left(x_{N}-x_{N-1}\right)^{2}+\cdots+\left(x_{3}-x_{2}\right)^{2}+\frac{1}{2}\left(x_{2}-x_{0}\right)^{2}\right)} \\
& =\lim _{N \rightarrow \infty}\left(\frac{m}{2 \pi i \Delta t}\right)^{\frac{N-1}{2}} \frac{1}{\sqrt{2}} \int d x_{2} \cdots d x_{N-1} e^{i \frac{m}{2 \Delta t}\left(\left(x_{N}-x_{N-1}\right)^{2}+\cdots+\left(x_{3}-x_{2}\right)^{2}+\frac{1}{2}\left(x_{2}-x_{0}\right)^{2}\right)} \\
& =\lim _{N \rightarrow \infty}\left(\frac{m}{2 \pi i \Delta t}\right)^{\frac{N-1}{2}} \frac{2}{\sqrt{2}}\left(\frac{i \pi \Delta t}{3 m}\right)^{1 / 2} \int d x_{3} \cdots d x_{N-1} e^{i \frac{m}{2 \Delta t}\left(\left(x_{N}-x_{N-1}\right)^{2}+\cdots+\frac{1}{3}\left(x_{3}-x_{0}\right)^{2}\right)} \\
& =\lim _{N \rightarrow \infty}\left(\frac{m}{2 \pi i \Delta t}\right)^{\frac{N-2}{2}} \frac{1}{\sqrt{3}} \int d x_{3} \cdots d x_{N-1} e^{i \frac{m}{2 \Delta t}\left(\left(x_{N}-x_{N-1}\right)^{2}+\cdots+\left(x_{4}-x_{3}\right)^{2}+\frac{1}{3}\left(x_{3}-x_{0}\right)^{2}\right)} \\
& =\cdots=\lim _{N \rightarrow \infty}\left(\frac{m}{2 \pi i N \Delta t}\right)^{1 / 2} e^{i \frac{m}{2 N \Delta t}\left(x_{a}-x_{b}\right)^{2}} \\
& =\sqrt{\frac{m}{2 \pi i N\left(t_{a}-t_{b}\right)}} e^{i \frac{m}{2} \frac{\left(x_{a}-x_{b}\right)^{2}}{t_{a}-t_{b}}}
\end{aligned}
$$

## Question 4: The Path Integral for a Free Particle, Revisited (20 points)

In this problem we evaluate the path integral for a free particle using a different method than Problem 3. For simplicity, take $x_{a}=x_{b}=0, t_{b}=0, t_{a}=T$. As discussed in class, $K$ is a Gaussian path-integral of form:

$$
K(0, T ; 0,0)=\int_{x(0)=0}^{x(T)=0} D x(t) \exp \left[\frac{i}{2} \int d t d t^{\prime} x(t) A\left(t, t^{\prime}\right) x\left(t^{\prime}\right)\right]
$$

for some differential operator $A$.
(a) Write down the explicit expression for $A$.

The action for a free particle is given by

$$
\begin{aligned}
S[x(t)] & =\int d t \frac{m}{2} \partial_{t} x \partial_{t} x=-\frac{m}{2} \int d t x \partial_{t}^{2} x=-\frac{m}{2} \int d t d t^{\prime} x\left(t^{\prime}\right) \delta\left(t-t^{\prime}\right) \partial_{t}^{2} x(t) \\
& =\frac{1}{2} \int d t d t^{\prime} x\left(t^{\prime}\right) A\left(t^{\prime}, t\right) x(t), \quad A\left(t^{\prime}, t\right)=-m \delta\left(t-t^{\prime}\right) \partial_{t}^{2}
\end{aligned}
$$

Then, we write the propagator as

$$
K(0, T ; 0,0)=\int_{x(0)=0}^{x(T)=0} D x e^{i S}=\int_{x(0)=0}^{x(T)=0} D x \exp \left[\frac{i}{2} \int_{0}^{T} d t d t^{\prime} x\left(t^{\prime}\right) A\left(t^{\prime}, t\right) x(t)\right]
$$

for the differential operator $A\left(t^{\prime}, t\right)=-m \delta(t-t) \partial_{t}^{2}$.
(b) Find all the eigenvalues of $A$. Show that the determinant of $A$ can be written as

$$
\operatorname{det} A=\prod_{n=1}^{\infty} m \frac{n^{2} \pi^{2}}{T^{2}}
$$

The eigenvectors of a second order derivative operator are precisely exponentials, $x(t)=f_{\lambda}(t)=e^{i \lambda t}$. We further need our eigenvectors to satisfy the boundary conditions $x(0)=x(T)=0$, since the endpoints of our trajectory are fixed. Hence, a complete set of eigenvectors are given by sine functions, with momenta integer multiples of $\pi / T$. Without loss of generality we can restrict to $n>0$.

$$
f_{\lambda_{n}}(t)=\sqrt{\frac{2}{T}} \sin \left(\frac{n \pi t}{T}\right)
$$

Furthermore,

$$
\int d t A\left(t^{\prime}, t\right) f_{\lambda_{n}}(t)=-m \int d t \delta\left(t-t^{\prime}\right) \sqrt{\frac{2}{T}} \partial_{t}^{2} \sin \left(\frac{n \pi t}{T}\right)=m \frac{n^{2} \pi^{2}}{T^{2}} \sqrt{\frac{2}{T}} \sin \left(\frac{n \pi t}{T}\right)=\lambda_{n} f_{\lambda_{n}}(t)
$$

for the eigenvalue $\lambda_{n}=m \frac{n^{2} \pi^{2}}{T^{2}}$. In this basis $A$ is diagonal: $A_{m n}=m \frac{n^{2} \pi^{2}}{T^{2}} \delta_{n m}$. Finally, the determinant of an operator is obtained by multiplying all of its eigenvalues, giving us the desired expression:

$$
\operatorname{det} A=\prod_{n=1}^{\infty} m \frac{n^{2} \pi^{2}}{T^{2}}
$$

(c) Since our propagator is Gaussian, it can be evaluated as

$$
K(0, T ; 0,0)=\frac{C}{\sqrt{\operatorname{det} A}}
$$

where $C$ is some constant. By comparing this equation with the solution to Problem 3, show that the consistency of the 2 approaches requires

$$
\frac{C}{\sqrt{\operatorname{det} A}}=\left(\frac{m}{2 \pi i T}\right)^{1 / 2}
$$

We substitute $x_{a}=x_{b}=0, t_{a}=T, t_{b}=0$ into the result in Problem 3:

$$
K(0, T ; 0,0)=\left(\frac{m}{2 \pi i T}\right)^{1 / 2} \exp \left[\frac{i m 0^{2}}{2 T}\right]=\left(\frac{m}{2 \pi i T}\right)^{1 / 2}
$$

It therefore follows immediately from our work in (b) that

$$
K(0, T ; 0,0)=\left(\frac{m}{2 \pi i T}\right)^{1 / 2}=\frac{C}{\sqrt{\operatorname{det} A}}=\frac{C T}{\pi \sqrt{m}} \prod_{n=1}^{\infty} \frac{1}{n}
$$

MIT OpenCourseWare
https://ocw.mit.edu

### 8.323 Relativistic Quantum Field Theory I

Spring 2023

For information about citing these materials or our Terms of Use, visit: https://ocw.mit.edu/terms.

