Lab 5

Your code goes here!

rosbags

Images

feature_tracking

Feature Tracks

Feature Match Statistics
Where we’re headed

Unity Simulator
- Sensors + Networking

Images
- tesse_ros_bridge
- feature_tracking (lab 5)

Completed
- Controller_pkg (lab 3)

In Progress
- motion_estimation (lab 6)
- place_recognition (lab 8)

Sim/Real Drone

To Do (lab 4)

SLAM
(labs 7,9)
Example: SIFT Features

Where do you find the most? What types of image regions get the most detections?
Example: Feature Matching
Example: Feature Tracking
https://mit-spark.github.io/VNAV2020-handouts/lab5/