Problem Wk.5.4.1: System behavior

Part 1: Stable?

We say that a system is **stable** if, for a bounded, transient input, its output converges to zero as n goes to infinity.

The systems below are specified either as a difference equation or as a system function.

Enter the **magnitude** of the dominant pole for each system and then enter whether the system is stable (type **yes** or **no**) and whether its response is oscillatory (type **yes** or **no**).

Note that strictly alternating signal corresponds to an oscillation of period 2.

Hint: use the **SystemFunction class** from lab. But, be careful about integer division when defining the coefficients, use 5.0/6, not 5/6.

1. \( y[n] = \frac{5}{6}y[n-1] + y[n-2] + x[n] \)

   dominant pole magnitude: 
   stable?: 
   oscillatory?: 

2. \( \frac{1}{1 + \frac{5}{4}R + \frac{3}{8}R^2} \)

   dominant pole magnitude: 
   stable?: 
   oscillatory?: 

3. \( y[n] = -\frac{3}{2}y[n-1] - \frac{9}{8}y[n-2] + x[n] \)

   dominant pole magnitude: 
   stable?: 
   oscillatory?: 

4. \( \frac{1}{1 + R + \frac{1}{2}R^2} \)

   dominant pole magnitude: 
   stable?: 
Part 2: DiffEq Behavior

For the four sequences given in the following four plots, which difference equation (A, B, C, or D) could have generated the sequence (given a unit sample input). Hint: Think about the poles of the corresponding systems.

Assume the input \( x[n] = 0 \) for \( n > 1 \).

A. \( y[n] = \frac{13}{8} y[n-1] - \frac{42}{64} y[n-2] + x[n] \)

B. \( y[n] = -\frac{13}{8} y[n-1] - \frac{42}{64} y[n-2] + x[n] \)

C. \( y[n] = -\frac{16}{8} y[n-1] - \frac{63}{64} y[n-2] + x[n] \)

D. \( y[n] = \frac{2}{8} y[n-1] + \frac{63}{64} y[n-2] + x[n] \)

1.

![Graph 1]

2.