ABSTRACT INTEGRATION — I

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The material in these notes can be found in practically every textbook that includes basic measure theory, although the order with which various properties are proved can be somewhat different in different sources.

1 PRELIMINARIES

The objective of these notes is to define the integral \( \int g \, d\mu \) [sometimes also denoted \( \int g(\omega) \, d\mu(\omega) \)] of a measurable function \( g : \Omega \to \mathbb{R} \), defined on a measure space \((\Omega, \mathcal{F}, \mu)\). We remind that \( \mathbb{R} \) is the set of real values extended by \( \infty \) and \(-\infty\).

**Special cases:**

(a) If \((\Omega, \mathcal{F}, \mathbb{P})\) is a probability space and \( X : \Omega \to \mathbb{R} \) is measurable (i.e., an extended-valued random variable), the integral \( \int X \, d\mathbb{P} \) is also denoted \( \mathbb{E}[X] \), and is called the expectation of \( X \).

(b) If we are dealing with the measure space \((\mathbb{R}, \mathcal{B}, \lambda)\), where \( \mathcal{B} \) is the Borel \( \sigma \)-field and \( \lambda \) is the Lebesgue measure, the integral \( \int g \, d\lambda \) is often denoted as \( \int g(x) \, dx \), and is meant to be a generalization of the usual integral encountered in calculus.
**The program:** We will define the integral \( \int g \, d\mu \) for progressively general classes of measurable functions \( g \):

(a) Finite nonnegative functions \( g \) that take finitely many values ("simple functions"). In this case, the integral is just a suitably weighted sum of the values of \( g \). When \( g \) is in fact a random variable, the we recognize \( g \) as a discrete random variable since its range is finite.

(b) Nonnegative functions \( g \). Here, the integral will be defined by approximating \( g \) from below by a sequence of simple functions.

(c) General functions \( g \). This is done by decomposing \( g \) in the form \( g = g_+ - g_- \), where \( g_+ \) and \( g_- \) are nonnegative functions, and letting \( \int g \, d\mu = \int g_+ \, d\mu - \int g_- \, d\mu \).

We will be focusing on the integral over the entire set \( \Omega \). The integral over a (measurable) subset \( B \) of \( \Omega \) is defined by letting

\[
\int_B g \, d\mu = \int (1_B g) \, d\mu.
\]

Here \( 1_B \) is the indicator function of the set \( g \), so that

\[
(1_B g)(\omega) = \begin{cases} 
  g(\omega), & \text{if } \omega \in B, \\
  0, & \text{if } \omega \notin B.
\end{cases}
\]

Throughout, we will use the term “almost everywhere” to mean “for all \( \omega \) outside a zero-measure subset of \( \Omega \).” For the special case of probability measures, we will often use the alternative terminology “almost surely,” or “a.s.” for short. Thus, if \( X \) and \( Y \) are random variables, we have \( X = Y \), a.s., if and only if \( \mathbb{P}(X = Y) = \mathbb{P}\{\{\omega : X(\omega) \neq Y(\omega)\}\} = 0 \).

In the sequel, an inequality \( g \leq h \) between two functions will be interpreted as “\( g(\omega) \leq h(\omega) \), for all \( \omega \in \Omega \).” Similarly, “\( g \leq h \), a.e.” means that “\( g(\omega) \leq h(\omega) \), for all \( \omega \) outside a zero-measure set.” The notation “\( g_n \uparrow g \)” will mean that for every \( \omega \), the sequence \( g_n(\omega) \) is monotone nondecreasing and converges to \( g(\omega) \). Finally, “\( g_n \uparrow g \), a.e.,” will mean that the monotonic convergence of \( g_n(\omega) \) to \( g(\omega) \) holds for all \( \omega \) outside a zero-measure set.

### 2 THE MAIN RESULT

Once the construction is carried out, integrals of nonnegative functions will always be well-defined. For general functions, integrals will be left undefined only when an expression of the form \( \infty - \infty \) is encountered.
The following properties will turn out to be true, whenever the integrals or expectations involved are well-defined. On the left, we show the general version; on the right, we show the same property, specialized to the case of probability measures. In property 8, the convention $0 \cdot \infty = 0$ will be in effect.

1. $\int 1_B \, d\mu = \mu(B)$ \quad $\mathbb{E}[1_B] = \mathbb{P}(B)$
2. $g \geq 0 \implies \int g \, d\mu \geq 0$ \quad $X \geq 0 \implies \mathbb{E}[X] \geq 0$
3. $g = 0$, a.e. $\implies \int g \, d\mu = 0$ \quad $X = 0$, a.s. $\implies \mathbb{E}[X] = 0$
4. $g \leq h \implies \int g \, d\mu \leq \int h \, d\mu$ \quad $X \leq Y \implies \mathbb{E}[X] \leq \mathbb{E}[Y]$

(assuming both $\int g$ and $\int h$ exist)

4'. $g \leq h$, a.e. $\implies \int g \, d\mu \leq \int h \, d\mu$ \quad $X \leq Y$, a.s. $\implies \mathbb{E}[X] \leq \mathbb{E}[Y]$
5. $g = h$, a.e. $\implies \int g \, d\mu = \int h \, d\mu$ \quad $X = Y$, a.s. $\implies \mathbb{E}[X] = \mathbb{E}[Y]$

and both $\int f$ exist or do not exist simultaneously

6. $[g \geq 0$, a.e., and $\int g \, d\mu = 0] \implies g = 0$, a.e. \quad $[X \geq 0$, a.s., and $\mathbb{E}[X] = 0] \implies X = 0$, a.s.

7. $\int (g + h) \, d\mu = \int g \, d\mu + \int h \, d\mu$ \quad $\mathbb{E}[X + Y] = \mathbb{E}[X] + \mathbb{E}[Y]$

(assuming RHS is well-defined)

8. $\int (ag) \, d\mu = a \int g \, d\mu$ \quad $\mathbb{E}[aX] = a\mathbb{E}[X]$
9. $0 \leq g_n \uparrow g \implies \int g_n \, d\mu \uparrow \int g \, d\mu$ \quad $0 \leq X_n \uparrow X, \implies \mathbb{E}[X_n] \uparrow \mathbb{E}[X]$
9'. $0 \leq g_n \uparrow g$, a.e. $\implies \int g_n \, d\mu \uparrow \int g \, d\mu$ \quad $0 \leq X_n \uparrow X$, a.s. $\implies \mathbb{E}[X_n] \uparrow \mathbb{E}[X]$
10. $g \geq 0 \implies \nu(B) = \int_B g \, d\mu$ is a measure \quad $[f \geq 0 \text{ and } \int f \, d\mathbb{P} = 1]$

$\implies \nu(B) = \int_B f \, d\mathbb{P}$ is a probability measure

Property 7, the linearity of expectations is central. Also, Property 9, and its generalization, property 9', is known as the Monotone Convergence Theorem (MCT), and is a cornerstone of integration theory.

3 THE LIMITATIONS OF THE RIEMANN INTEGRAL

Before proceeding, it is worth understanding why the traditional integral encountered in calculus is not adequate for our purposes. Let us recall the definition of the (Riemann) integral $\int_a^b g(x) \, dx$. We subdivide the interval $[a, b]$ using a finite sequence $\sigma = (x_1, x_2, \ldots, x_n)$ of points that satisfy $a = x_1 < x_2 < \ldots < x_n = b$. The integral is then approximated by a sum of areas of rectangles, with heights given by the values of $g(x)$ at the points of subdivision. However, this approach has limitations:

- It requires the function to be continuous on a closed interval.
- It cannot handle discontinuities or oscillations.
- It is difficult to extend to functions defined on more general domains.

These limitations motivate the development of more general forms of integration, such as the Lebesgue integral, which we will introduce in later sections.

The Riemann integral is defined for a function $f$ on an interval $[a, b]$ if it satisfies the following conditions:

1. $f$ is bounded on $[a, b]$.
2. $f$ is integrable on every subinterval of $[a, b]$.
3. The set of discontinuities of $f$ has measure zero.

The Riemann integral of $f$ over $[a, b]$ is then defined as:

$$\int_a^b f(x) \, dx = \lim_{n \to \infty} \sum_{i=1}^n f(x_i^*) \Delta x_i$$

where $x_i^*$ is any point in the $i$th subinterval $[x_{i-1}, x_i]$ and $\Delta x_i = x_i - x_{i-1}$ is the width of the $i$th subinterval.

This definition is the basis for the more general Lebesgue integral, which allows for a broader class of functions to be integrated and provides a more robust framework for integration theory.

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This definition is the basis for the more general Lebesgue integral, which allows for a broader class of functions to be integrated and provides a more robust framework for integration theory.
\[ \cdots < x_n = b, \text{ and define} \]
\[ U(\sigma) = \sum_{i=1}^{n-1} \left( \max_{x_i \leq x < x_{i+1}} g(x) \right) \cdot (x_{i+1} - x_i), \]
\[ L(\sigma) = \sum_{i=1}^{n-1} \left( \min_{x_i \leq x < x_{i+1}} g(x) \right) \cdot (x_{i+1} - x_i). \]

Thus, \( U(\sigma) \) and \( L(\sigma) \) are approximations of the “area under the curve \( g \),” from above and from below, respectively. We say that the integral \( \int_a^b g(x) \, dx \) is well-defined, and equal to a number \( c \), if
\[ \limsup_{\sigma} L(\sigma) = \liminf_{\sigma} U(\sigma) = c, \]
where \( \limsup \) and \( \liminf \) are taken with respect to sequences of partitions \( \sigma = (x_1, x_2, \ldots, x_n) \) whose resolution \( \max_{0 \leq i \leq n-1} (x_{i+1} - x_i) \) converges to zero.

In this case, we also say that \( g \) is Riemann-integrable over \([a, b]\). Intuitively, we want the upper and lower approximants \( U(\sigma) \) and \( L(\sigma) \) to agree, in the limit of very fine subdivisions of the interval \([a, b]\).

It is known that if \( g : \mathbb{R} \to \mathbb{R} \) is Riemann-integrable over every interval \([a, b]\), then \( g \) is continuous almost everywhere (i.e., there exists a set \( S \) of Lebesgue measure zero, such that \( g \) is continuous at every \( x \notin S \)). This is a severe limitation on the class of Riemann-integrable functions.

**Example.** Let \( Q \) be the set of rational numbers in \([0, 1]\). Let \( g = 1_Q \). For any \( \sigma = (x_1, x_2, \ldots, x_n) \), and every \( i \), the interval \([x_i, x_{i+1}]\) contains a rational number, and also an irrational number. Thus, \( \max_{x_i \leq x < x_{i+1}} g(x) = 1 \) and \( \min_{x_i \leq x < x_{i+1}} g(x) = 0 \). It follows that \( U(\sigma) = 1 \) and \( L(\sigma) = 0 \), for all \( \sigma \), and \( \sup_{\sigma} L(\sigma) \neq \inf_{\sigma} U(\sigma) \). Therefore \( 1_Q \) is not Riemann integrable. On the other hand if we consider a uniform distribution over \([0, 1]\), and the binary random variable \( 1_Q \), we have \( \mathbb{P}(1_Q = 1) = 0 \), and we would like to be able to say that \( \mathbb{E}[X] = \int_{[0, 1]} 1_Q(x) \, dx = 0 \). This indicates that a different definition is in order.

### 4 THE INTEGRAL OF A NONNEGATIVE SIMPLE FUNCTION

A function \( g : \Omega \to \mathbb{R} \) is called **simple** if it is measurable, finite- and takes only finitely many different values. In particular, a simple function can be written as
\[ g(\omega) = \sum_{i=1}^k a_i 1_{A_i}(\omega), \quad \forall \omega \in \Omega, \quad (1) \]
where \( k \) is a (finite) nonnegative integer, the coefficients \( a_i \in \mathbb{R} \) are real values and the \( A_i \) are measurable sets.

Note that a simple function can have several representations of the form (1). For example, \( 1_{[0,2]} \) and \( 1_{[0,1]} + 1_{[1,2]} \) are two representations of the same function. For another example, note that \( 1_{[0,2]} + 1_{[1,2]} = 1_{[0,1]} + 2 \cdot 1_{[1,2]} \). On the other hand, if we require the \( a_i \) to be distinct and the sets \( A_i \) to form a partition of \( \Omega \), it is not hard to see that there is only one possible representation, which we will call the canonical representation. More concretely, in the canonical representation, we let \( \{a_1, \ldots, a_k\} \) be the range of \( g \), where the \( a_i \) are distinct, and \( A_i = \{\omega \mid g(\omega) = a_i\} \).

**Definition 1.** If \( g \) is a simple function, of the form (1), its integral is defined by

\[
\int g \, d\mu = \sum_{i=1}^{k} a_i \mu(A_i).
\]

(If \( a_i = 0 \) and \( \mu(A_i) = \infty \), we assume \( a_i \mu(A_i) = 0 \).)

Before continuing, we need to make sure that Definition 1 is sound, in the following sense. If we consider two alternative representations of the same simple function, we need to ensure that the resulting value of \( \int g \, d\mu \) is the same. Technically, we need to show the following:

\[
\text{if } \sum_{i=1}^{k} a_i 1_{A_i} = \sum_{i=1}^{m} b_i 1_{B_i}, \text{ then } \sum_{i=1}^{k} a_i \mu(A_i) = \sum_{i=1}^{m} b_i \mu(B_i).
\]

This is left as an exercise for the reader.

**Example.** We have \( 1_{[0,2]} + 1_{[1,2]} = 1_{[0,1]} + 2 \cdot 1_{[1,2]} \). The first representation leads to \( \mu([0, 2]) + \mu([1, 2]) \), the second to \( \mu([0, 1]) + 2 \mu([1, 2]) \). Using the fact \( \mu([0, 2]) = \mu([0, 1]) + \mu([1, 2]) \) (finite additivity), we see that the two values are indeed equal.

For the case where the underlying measure is a probability measure \( \mathbb{P} \), a simple function \( X : \Omega \to \mathbb{R} \) is called a simple random variable, and its integral \( \int X \, d\mathbb{P} \) is also denoted as \( \mathbb{E}[X] \). We then have

\[
\mathbb{E}[X] = \sum_{i=1}^{k} a_i \mathbb{P}(A_i).
\]

If the coefficients \( a_i \) are distinct and exhaust all the possible values of \( X \), then
by taking $A_i = \{\omega \mid X(\omega) = a_i\}$, we obtain

$$E[X] = \sum_{i=1}^{k} a_i P(\{\omega \mid X(\omega) = a_i\}) = \sum_{i=1}^{k} a_i P(X = a_i),$$

which agrees with the elementary definition of $E[X]$ for discrete random variables.

Note, for future reference, that the sum or difference of two simple functions is also simple.

### 4.1 Verification of various properties for the case of simple functions

For the various properties listed in Section 2, we will use the shorthand “property S-A” and “property N-A”, to refer to “property A for the special case of nonnegative simple functions” and “property A for nonnegative measurable functions,” respectively.

We note a few immediate consequences of the definition. For any $B \in \mathcal{F}$, the function $1_B$ is simple and $\int 1_B \, d\mu = \mu(B)$, which verifies property 1. In particular, when $Q$ is the set of rational numbers and $\mu$ is Lebesgue measure, we have $\int 1_Q \, d\mu = \mu(Q) = 0$, as desired. Note that a nonnegative simple function has a representation of the form (1) with all $a_i$ nonnegative. It follows that $\int g \, d\mu \geq 0$, which verifies property S-2.

Suppose now that a simple function satisfies $g = 0$, a.e. Then, it has a canonical representation of the form $g = \sum_{i=1}^{k} a_i 1_{A_i}$, where $\mu(A_i) = 0$, for every $i$ for which $a_i \neq 0$. Definition 1 implies that $\int g \, d\mu = 0$, which verifies property S-3.

Let us now verify the linearity property S-7. Let $g$ and $h$ be nonnegative simple functions. Using canonical representations, we can write

$$g = \sum_{i=1}^{k} a_i 1_{A_i}, \quad h = \sum_{j=1}^{m} b_j 1_{B_j},$$

where the disjoint sets $A_i$ or the sets $B_j$ form a partition of $\Omega$. Then, the sets $A_i \cap B_j$ are also disjoint, and form a partition of $\Omega$. We have

$$g + h = \sum_{i=1}^{k} \sum_{j=1}^{m} (a_i + b_j) 1_{A_i \cap B_j}.$$
Therefore,

\[ \int (g + h) \, d\mu = \sum_{i=1}^{k} \sum_{j=1}^{m} (a_i + b_j) \mu(A_i \cap B_j) \]

\[ = \sum_{i=1}^{k} a_i \sum_{j=1}^{m} \mu(A_i \cap B_j) + \sum_{j=1}^{m} b_j \sum_{i=1}^{k} \mu(A_i \cap B_j) \]

\[ = \sum_{i=1}^{k} a_i \mu(A_i) + \sum_{j=1}^{m} b_j \mu(B_j) \]

\[ = \int g \, d\mu + \int h \, d\mu. \]

(The first and fourth equalities follow from Definition 1. The third equality made use of finite additivity for \( \mu \). and the fact that the sets \( A_i \) or the sets \( B_j \) form a partition of \( \Omega \).)

**Property S-8** is an immediate consequence of Definition 1. We only need to be careful for the case where \( \int g \, d\mu = \infty \) and \( a = 0 \). We have \( ag = 0 \) and so \( \int (ag) \, d\mu = 0 \). On the other hand \( a \int g \, d\mu = 0 \cdot \infty \). We have agreed to assume that \( 0 \cdot \infty = 0 \) and under this convention the identity is verified.

By combining properties S-7 and S-8, with \( a = -1 \) we see that, for simple functions \( g \) and \( h \) we have

\[ (g - h) \, d\mu = g \, d\mu - h \, d\mu. \]

We now verify **property S-4’**, which also implies **property S-4** as a special case. Suppose that \( g \leq h \), a.e. We then have \( h = g + q \), for a simple function \( q \) such that \( q \geq 0 \), a.e. In particular, \( q = q_+ - q_- \), where \( q_+ \geq 0 \), \( q_- \geq 0 \), and \( q_-=0 \), a.e. Thus, \( h- = g + q_+ - q_- \). Note that \( q_+, q_- \) are all simple functions. Using the linearity property S-7, and then properties S-3, S-2, we obtain

\[ \int h \, d\mu = \int g \, d\mu + \int q_+ \, d\mu - \int q_- \, d\mu = \int g \, d\mu + \int q_+ \, d\mu \geq \int g \, d\mu. \]

We next verify **property S-5**. If \( g = h \), a.e., then we have both \( g \leq h \), a.e., and \( h \leq g \), a.e. Thus, \( \int g \, d\mu \leq \int h \, d\mu \), and \( \int g \, d\mu \geq \int h \, d\mu \), which implies that \( \int g \, d\mu = \int h \, d\mu \).

We finally verify **property S-6**. Suppose that \( g \geq 0 \), a.e., and \( \int g \, d\mu = 0 \). We write \( g = g_+ - g_- \), where \( g_+ \geq 0 \) and \( g_- \geq 0 \). Then, \( g_- = 0 \), a.e., and \( \int g_- \, d\mu = 0 \). Thus, using property S-7, \( \int g_+ \, d\mu = \int g \, d\mu + \int g_- \, d\mu = 0 \). Note that \( g_+ \) is simple. Hence, its canonical representation is of the form \( g_+ = \sum_{i=1}^{k} a_i 1_{A_i} \), with \( a_i \geq 0 \). Since \( \sum_{i=1}^{k} a_i \mu(A_i) = 0 \), it follows that \( \mu(A_i) = 0 \), for every \( i \) such that \( a_i > 0 \). From finite additivity, we conclude
that $\mu(\cup_i A_i) = 0$, where the union $\cup_i A_i$ is over $i$ such that $a_i > 0$. Therefore, $g_+ = 0$, a.e., and also $g = 0$, a.e.

5 THE INTEGRAL OF A NONNEGATIVE FUNCTION

The integral of a nonnegative function $g$ will be defined by approximating $g$ from below, using simple functions.

\textbf{Definition 2.} For a nonnegative (extended-valued) measurable function $g : \Omega \to [0, \infty]$, we let $S(g)$ be the set of all nonnegative simple (hence automatically measurable) functions $q$ that satisfy $0 \leq q \leq g$, and define

$$\int g \, d\mu = \sup_{q \in S(g)} \int q \, d\mu.$$ 

We will now verify that with this definition, properties N-2 to N-10 are all satisfied. This is easy for some (e.g., property N-2). Most of our effort will be devoted to establishing properties N-7 (linearity) and N-9 (monotone convergence theorem).

The arguments that follow will make occasional use of the following continuity property for monotonic sequences of measurable sets $B_i$: If $B_i \uparrow B$, then $\mu(B_i) \uparrow \mu(B)$. This property was established in the notes for Lecture 1, for the special case where $\mu$ is a probability measure, but the same proof applies to the general case.

5.1 Verification of some easy properties

Throughout this subsection, we assume that $g$ is measurable and nonnegative.

\textbf{Property N-2:} For every $q \in S(g)$, we have $\int q \, d\mu \geq 0$ (property S-2). Thus, $\int g \, d\mu = \sup_{q \in S(g)} \int q \, d\mu \geq 0$.

\textbf{Property N-3:} If $g = 0$, a.e, and $0 \leq q \leq g$, then $q = 0$, a.e. Therefore, $\int q \, d\mu = 0$ for every $q \in S(g)$ (by property S-3), which implies that $\int g \, d\mu = 0$.

\textbf{Property N-4:} Suppose that $0 \leq g \leq h$. Then, $S(g) \subset S(h)$, which implies that

$$\int g \, d\mu = \sup_{q \in S(g)} \int q \, d\mu \leq \sup_{q \in S(h)} \int q \, d\mu = \int h \, d\mu.$$ 

\textbf{Property N-5:} Suppose that $g = h$, a.e. Let $A = \{\omega \mid g(\omega) = h(\omega)\}$, and note that the complement of $A$ has zero measure, so that $q = 1_A q$, a.e., for any
function \( q \). Then,

\[
\int g \, d\mu = \sup_{q \in S(g)} \int q \, d\mu = \sup_{q \in S(g)} \int 1_{A} q \, d\mu \leq \sup_{q \in S(1_{A} g)} \int q \, d\mu \\
\leq \sup_{q \in S(h)} \int q \, d\mu = \int h \, d\mu.
\]

A symmetrical argument yields \( \int h \, d\mu \leq \int g \, d\mu \).

**Exercise:** Justify the above sequence of equalities and inequalities.

**Property N-4′:** Suppose that \( g \leq h \), a.e. Then, there exists a function \( g' \) such that \( g' \leq h \) and \( g = g' \), a.e. Property N-5 yields \( \int g \, d\mu = \int g' \, d\mu \). Property N-4 yields \( \int g' \, d\mu \leq \int h \, d\mu \). These imply that \( \int g \, d\mu \leq \int h \, d\mu \).

**Property N-6:** Suppose that \( g \geq 0 \) but the relation \( g = 0 \), a.e., is not true. We will show that \( \int g \, d\mu > 0 \). Let \( B = \{ \omega \mid g(\omega) > 0 \} \). Then, \( \mu(B) > 0 \). Let \( B_n = \{ \omega \mid g(\omega) > 1/n \} \). Then, \( B_n \uparrow B \) and, therefore, \( \mu(B_n) \uparrow \mu(B) > 0 \). This shows that for some \( n \) we have \( \mu(B_n) > 0 \). Note that \( g \geq (1/n)1_{B_n} \).

Then, properties S-4, S-8, and 1 yield

\[
\int g \, d\mu \geq \int 1/n \cdot 1_{B_n} \, d\mu = \frac{1}{n} \int 1_{B_n} \, d\mu = \frac{1}{n} \mu(B_n) > 0.
\]

**Property N-8, when \( a \geq 0 \):** If \( a = 0 \), the result is immediate. Assume that \( a > 0 \). It is not hard to see that \( q \in S(g) \) if and only if \( aq \in S(ag) \). Thus,

\[
\int (aq) \, d\mu = \sup_{q \in S(ag)} \int q \, d\mu = \sup_{aq \in S(ag)} \int (aq) \, d\mu = \sup_{q \in S(g)} \int (aq) \, d\mu = a \int q \, d\mu.
\]

### 5.2 Proof of the Monotone Convergence Theorem

We first provide the proof of **property N-9**, for the special case where \( g \) is equal to a simple function \( q \), and then generalize.

Let \( q \) be a nonnegative simple function, represented in the form \( q = \sum_{i=1}^{k} a_i 1_{A_i} \), where the \( a_i \) are finite nonnegative numbers, and where the measurable sets \( A_i \) form a partition of \( \Omega \). Let \( g_n \) be a sequence of nonnegative measurable (not necessarily simple) functions such that \( g_n \uparrow q \). The limit \( \lim_n \int g_n \, d\mu \) exists by monotonicity. We need to show that this limit is \( \int q \, d\mu \). We distinguish between two different cases, depending on whether \( \int q \, d\mu \) is finite or infinite.
(i) Suppose that \( \int q \, d\mu = \infty \). This implies that there exists some \( i \) for which \( a_i > 0 \) and \( \mu(A_i) = \infty \). Fix such an \( i \), and let
\[
B_n = \{ \omega \in A_i \mid g_n(\omega) > a_i/2 \}.
\]
For every \( \omega \in A_i \), there exists some \( n \) such that \( g_n(\omega) > a_i/2 \). Therefore, \( B_n \uparrow A_i \). From the continuity of measures, we obtain \( \mu(B_n) \uparrow \infty \). Now, note that \( g_n \geq (a_i/2)1_{B_n} \). Then, using property N-4, we have
\[
\int g_n \, d\mu \geq \frac{a_i}{2} \mu(B_n) \uparrow \infty = \int q \, d\mu.
\]

(ii) Suppose now that \( \int q \, d\mu < \infty \). Then, \( \mu(A_i) < \infty \), for all \( i \in S \) for which \( a_i > 0 \). Let
\[
\mathcal{A}_i = \{ A_i \} \setminus \{ i \mid a_i > 0 \}\] By finite additivity, we have \( \mu(\mathcal{A}) < \infty \). Let us fix a positive integer \( r \) such that \( 1/r < a_i \) for every \( i \) such that \( a_i > 0 \). Let
\[
B_n = \{ \omega \in \mathcal{A} \mid g_n(\omega) \geq q(\omega) - (1/r) \}.
\]
We observe that \( B_n \uparrow A \) and, by continuity, \( \mu(B_n) \uparrow \mu(A) \). Since \( \mu(A) = \mu(B_n) + \mu(A \setminus B_n) \), and \( \mu(A) < \infty \), this also yields \( \mu(A \setminus B_n) \downarrow 0 \).

Note that \( 1_A q = q \), a.e. Using properties, S-5 and S-7, we have
\[
\int q \, d\mu = \int 1_A q \, d\mu = \int 1_{B_n} q \, d\mu + \int 1_{A \setminus B_n} q \, d\mu.
\] (2)
For \( \omega \in B_n \), we have \( g_n(\omega) + (1/r) \geq q(\omega) \). Thus, \( g_n + (1/r)1_{B_n} \geq 1_{B_n} q \). Using properties N-4 and S-7, together with Eq. (2), we have
\[
\int g_n \, d\mu + \int \frac{1}{r} 1_{B_n} \, d\mu \geq \int 1_{B_n} q \, d\mu = \int q \, d\mu - \int 1_{A \setminus B_n} q \, d\mu \geq \int q \, d\mu - a\mu(\mathcal{A} \setminus B_n),
\]
where \( a = \max_i a_i \). By taking the limit as \( n \to \infty \), we obtain
\[
\lim_{n \to \infty} \int g_n \, d\mu + \frac{1}{r} \mu(\mathcal{A}) \geq \int q \, d\mu.
\]
Since this is true for every \( r > 1/(\min_i a_i) \), we must have
\[
\lim_{n \to \infty} \int g_n \, d\mu \geq \int q \, d\mu.
\]
On the other hand, we have \( g_n \leq q \), so that \( \int g_n \, d\mu \leq \int q \, d\mu \), and \( \lim_{n \to \infty} \int g_n \, d\mu \leq \int q \, d\mu \).
We now turn to the general case. We assume that $0 \leq g_n \uparrow g$. Suppose that $q \in S(g)$, so that $0 \leq q \leq g$. We have

$$0 \leq \min\{g_n, q\} \uparrow \min\{g, q\} = q.$$ 

Therefore,

$$\lim_{n \to \infty} \int g_n \, d\mu \geq \lim_{n \to \infty} \int \min\{g_n, q\} \, d\mu = \int q \, d\mu.$$ 

(The inequality above uses property N-4; the equality relies on the fact that we already proved the MCT for the case where the limit function is simple.) By taking the supremum over $q \in S(g)$, we obtain

$$\lim_{n \to \infty} \int g_n \, d\mu \geq \sup_{q \in S(g)} \int q \, d\mu = \int g \, d\mu.$$ 

On the other hand, we have $g_n \leq g$, so that $\int g_n \, d\mu \leq \int g \, d\mu$. Therefore, $\lim_{n \to \infty} \int g_n \, d\mu \leq \int g \, d\mu$, which concludes the proof of property N-9.

To prove property 9', suppose that $g_n \uparrow g$, a.e. Then, there exist functions $g'_n$ and $g'$, such that $g_n = g'_n$, a.e., $g = g'$, a.e., and $g'_n \uparrow g'$. By combining properties N-5 and N-9, we obtain

$$\lim_{n \to \infty} \int g_n \, d\mu = \lim_{n \to \infty} \int g'_n \, d\mu = \int g' \, d\mu = \int g \, d\mu.$$ 

5.3 **Approximating $g$ from below using “special” simple functions**

Let $g$ be a nonnegative measurable function. From the definition of $\int g \, d\mu$, it follows that there exists a sequence $q_n \in S(g)$ such that $\int q_n \, d\mu \to \int q \, d\mu$. This does not provide us with much information on the sequence $q_n$. In contrast, the construction that follows provides us with a concrete way of approximating $\int g \, d\mu$.

For any positive integer $r$, we define a function $g_r : \Omega \to \mathbb{R}$ by letting

$$g_r(\omega) = \begin{cases} 
  r, & \text{if } g(\omega) \geq r \\
  \frac{i}{2^r}, & \text{if } \frac{i}{2^r} \leq g(\omega) < \frac{i + 1}{2^r}, \quad i = 0, 1, \ldots, r2^r - 1
\end{cases}$$ 

In words, the function $g_r$ is a quantized version of $g$. For every $\omega$, the value of $g(\omega)$ is first capped at $r$, and then rounded down to the nearest multiple of $2^{-r}$.

We note a few properties of $g_r$ that are direct consequences of its definition.

(a) For every $r$, the function $g_r$ is simple (and, in particular, measurable).
(b) We have $0 \leq g_r \uparrow g$; that is, for every $\omega$, we have $g_r(\omega) \uparrow g(\omega)$.

(c) If $g$ is bounded above by $c$ and $r \geq c$, then $|g_r(\omega) - g(\omega)| \leq 1/2^r$, for every $\omega$.

Statement (b) above gives us a transparent characterization of the set of measurable functions. Namely, a nonnegative function is measurable if and only if it is the monotonic and pointwise limit of simple functions. Indeed, we have established in earlier lectures that pointwise limits of measurable functions are measurable. On the other hand, we just showed that every measurable function is a pointwise monotone limit of simple functions. (While the discussion above was about non-negative functions, see how you can extend it to the general case). Furthermore, the MCT indicates that $\int g_r \, d\mu \uparrow \int g \, d\mu$, for this particular choice of simple functions $g_r$. (In an alternative line of development of the subject, some texts start by defining $\int g \, d\mu$ as the limit of $\int g_r \, d\mu$.)

5.4 Linearity

We now prove linearity (property N-7). Let $g_r$ and $h_r$ be the approximants of $g$ and $h$, respectively, defined in Section 5.3. Since $g_r \uparrow g$ and $h_r \uparrow h$, we have $(g_r + h_r) \uparrow (g + h)$. Therefore, using the MCT and property S-7 (linearity for simple functions),

$$\int (g + h) \, d\mu = \lim_{r \to \infty} \int (g_r + h_r) \, d\mu$$

$$= \lim_{r \to \infty} \left( \int g_r \, d\mu + \int h_r \, d\mu \right)$$

$$= \lim_{r \to \infty} \int g_r \, d\mu + \lim_{r \to \infty} \int h_r \, d\mu$$

$$= \int g \, d\mu + \int h \, d\mu.$$ 

5.5 Using an integral to define a measure

In order to prove the last property (property N-10) one uses countable additivity for the measure $\mu$, a limiting argument based on the approximation of $g$ by simple functions, and the MCT. The detailed proof is left as an exercise for the reader.
6 THE GENERAL CASE

Consider now a measurable function $g : \Omega \to \mathbb{R}$. Let $A_+ = \{ \omega \mid g(\omega) > 0 \}$ and $A_- = \{ \omega \mid g(\omega) < 0 \}$; note that these are measurable sets. Let $g_+ = g \cdot 1_{A_+}$ and $g_- = -1_{A_-}g$; note that these are nonnegative (possibly extended-valued) measurable functions. We then have $g = g_+ - g_-$, and we define

$$\int g \, d\mu = \int g_+ \, d\mu - \int g_- \, d\mu. $$

The integral $\int g \, d\mu$ is well-defined, as long as we do not have both $\int g_+ \, d\mu$ and $\int g_- \, d\mu$ equal to infinity.

With this definition, verifying properties 3-6 and 8 is not too difficult, and there are no surprises. We decompose the functions $g$ and $h$ into negative and positive parts, and apply the properties already proved for the nonnegative case. The details are left as an exercise. The only extra work is needed for property 7. It is clear, however, that establishing property 7 is equivalent to property N-7 and the following statement:

$$g \geq 0, h \geq 0 \Rightarrow \int (g - h) \, d\mu = \int g \, d\mu - \int h \, d\mu \quad (3)$$

In the special case $g \geq h$ property (3) is just a consequence of property N-7:

$$g \geq h \geq 0 \Rightarrow \int g \, d\mu = \int (g - h + h) \, d\mu = \int (g - h) \, d\mu + \int h \, d\mu. \quad (4)$$

The general case of (3) can be shown via the following argument:

$$\int (g - h) \, d\mu = \int (g - h)1\{g > h\} \, d\mu - \int (h - g)1\{g \leq h\} \, d\mu \quad (5)$$

$$= \int g1\{g > h\} \, d\mu - \int h1\{g > h\} \, d\mu$$

$$+ \int g1\{g \leq h\} \, d\mu - \int h1\{g \leq h\} \, d\mu \quad (6)$$

$$= \int g \, d\mu - \int h \, d\mu, \quad (7)$$

where (6) is from (4) and (7) is from

$$\int g1\{g > h\} \, d\mu + \int g1\{g \leq h\} \, d\mu = \int g \, d\mu$$

by property N-7.