Problem Set 1, Part b

Due: Thursday, September 24, 2009

Reading:

Sections 3.6, 4.1-4.5 of Distributed Algorithms

Reading for next week: Section 5.1, Chapter 6
Aguilera, Toueg paper, listed in Handout 3
(Optional) Keidar, Rajsbaum paper

Problems:

1. In this problem, consider comparison-based algorithms in bidirectional rings with UIDs.
   (a) Design an algorithm for the Counting Problem, in which each process is required to output the correct total number \( n \) of processes in the ring. Prove an upper bound on the number of messages used in your algorithm. Try to get the smallest value you can for this measure.
   (b) Prove the best lower bound you can on the number of messages required to solve the Counting Problem in the worst case.
   (c) In the same setting, prove upper and lower bounds for the problem of determining the parity of the ring size \( n \) (i.e., whether \( n \) is odd or even).

2. Exercise 4.10.

3. Consider a variation of the Shortest Paths problem described in Section 4.3 of the textbook with the following requirements:
   A. Processes are not required to halt. We require only that eventually a shortest paths tree over the processes exists and does not change.
   B. Each process’s state contains a Boolean constant, \( \text{source} \), which is set to \( \text{true} \) for \( i_0 \) and \( \text{false} \) for every process \( i \neq i_0 \).
   C. Except for \( \text{source} \) and edge \( \text{weight} \) constants (which are assumed to be \( > 0 \)), the initial state of each process is arbitrary: each non-source, non-weight state variable \( v \) of a process, (including any rounds or status variables), is initially set to an arbitrary value from \( \text{type}(v) \).

Note that these conditions mean that different processes might think they are in different rounds, and processes can’t tell if they are just starting an algorithm execution or are in the middle of an execution.
   (a) Explain informally why the BellmanFord algorithm described on p. 62 of the textbook does not solve this new version of the Shortest Paths problem.
   (b) Describe informally a modified version of BellmanFord that solves the Shortest Paths problem under these conditions.
   (c) Give pseudocode in the style in the book for your new algorithm.
   (d) Extra Credit: State an invariant which holds for your algorithm and when proved by induction implies its correctness (i.e. that it terminates and produces the correct output).
4. Recall that SynchGHS proceeds in phases, each of which consists of a fixed number of rounds upon which processes agree ahead of time. We argued that this fixed number can be $O(n)$, where $n$ is the number of nodes in the network graph. Determine constants $a$ and $b$ such that every phase can be $an + b$ rounds (i.e., no phase requires more than $an + b$ rounds), and argue that $an + b$ rounds are sufficient for any phase. Try to find the smallest possible value for $a$ and $b$, particularly $a$. (Do not try to improve SynchGHS; just analyze the version described in the book.)