

ES.1803 Practice Solutions – Quiz 3, Spring 2024

Problem 1.

Consider the lightly damped second-order system $y'' + 2y' + 10y = \sin(\omega t)$.

For this problem, consider $\sin(\omega t)$ to be the input to the system.

(a) What is the natural frequency of this system?

Solution: The natural frequency is the frequency of the undamped, unforced harmonic oscillator $y'' + 10y = 0$. This has (angular) natural frequency $\omega_0 = \sqrt{10}$.

(b) If the damping is removed, what integer frequency ω_{int} will make the amplitude of $y_p(t)$ relatively large?

Solution: Without damping, a second order system has resonance at its natural frequency. Since $\omega_0 = \sqrt{10} \approx 3$, $\boxed{\omega_{\text{int}} = 3}$.

Alternatively, we can compute the solution to $y'' + 10y = \sin(\omega t)$:

The SRF gives $y_p(t) = \frac{\sin(\omega t - \phi(\omega))}{|P(i\omega)|} = \frac{\sin(\omega t - \phi(\omega))}{|10 - \omega^2|}$.

The amplitude of the response is $\frac{1}{|10 - \omega^2|}$. This is big when the denominator is small.

Therefore, the integer frequency that gives the biggest amplitude is $\boxed{\omega_{\text{int}} = 3}$.

(c) Find any practical resonant frequencies for the damped system.

Solution: With the damping included, the gain is

$$g(\omega) = \frac{1}{|P(i\omega)|} = \frac{1}{\sqrt{(10 - \omega^2)^2 + 4\omega^2}}.$$

Resonant frequencies are those positive ω that give relative maxima for $g(\omega)$. To find the maximum, we solve $g'(\omega) = 0$.

$$g(\omega) = ((10 - \omega^2)^2 + 4\omega^2)^{-1/2} \quad \Rightarrow \quad g'(\omega) = -\frac{1}{2} (-4\omega(10 - \omega^2) + 8\omega) ((10 - \omega^2)^2 + 4\omega^2)^{-3/2}.$$

$$\text{Now, } g'(\omega) = 0 \quad \Rightarrow \quad -4(\omega(10 - \omega^2) + 8\omega) = 0 \quad \Rightarrow \quad \omega = \sqrt{8} \text{ or } \omega = 0.$$

You can check by calculus or graphing that the $\sqrt{8}$ is a maximum (and not a minimum). (We never consider $\omega = 0$ as a resonant frequency.)

Problem 2.

Consider the DE $x'' + bx' + 5x = \cos(\omega t)$. Assume, for this system, that $\cos(\omega t)$ is the input.

(a) For what b is it possible for this system to undergo pure resonance?

Solution: Only when $b = 0$, i.e., when there is no damping.

(b) For all values of b in your answer to Part (a), give the corresponding resonant frequency.

Solution: For the undamped oscillator the resonant frequency equals the natural frequency $\omega_0 = \sqrt{5}$.

(c) For each of the b values in the answer to Part (a), solve the DE with ω equal to the resonant frequency.

Solution: From Part (a) the only value of b is $b = 0$. From Part (b) $\omega_0 = \sqrt{5}$ so our equation is

$$x'' + 5x = \cos(\omega_0 t).$$

(We'll write ω_0 so we won't have to write $\sqrt{5}$ repeatedly.)

Method 1: Use the SRF: We have $P(r) = r^2 + 5$, so $P(i\omega_0) = 0$. Then we have $P'(r) = 2r$, so $P'(i\omega_0) = 2i\omega_0 = 2\omega_0 e^{i\pi/2}$. The extended SRF gives (with $\phi = \text{Arg}(P'(i\omega_0)) = \pi/2$)

$$x_p(t) = \frac{t \cos(\omega_0 t - \phi)}{|P'(i\omega_0)|} = \frac{t \cos(\omega_0 t - \pi/2)}{2\omega_0} = \frac{t \sin(\omega_0 t)}{2\omega_0}.$$

Method 2: Complexify the DE and use the ERF:

$$z'' + 5z = e^{i\omega_0 t}, \quad x = \text{Re}(z).$$

As in Method 1, we need the extended version and $P'(i\omega_0) = 2i\omega_0$.

$$z_p(t) = \frac{t e^{i\omega_0 t}}{P'(i\omega_0)} = \frac{t e^{i\omega_0 t}}{2i\omega_0} = \frac{t e^{i\omega_0 t}}{2e^{i\pi/2}\omega_0} = \frac{t e^{i(\omega_0 t - \pi/2)}}{2\omega_0}.$$

Taking the real part we get $x_p(t) = \frac{t \cos(\omega_0 t - \pi/2)}{2\omega_0} = \frac{t \sin(\omega_0 t)}{2\omega_0}$.

Including the homogeneous solution, the general solution to the DE is

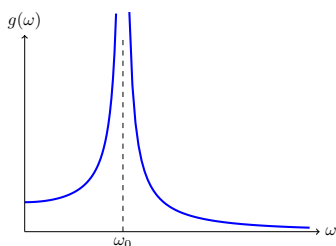
$$x(t) = x_p(t) + c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t).$$

(d) Graph the amplitude response of each of the systems that can undergo resonance.

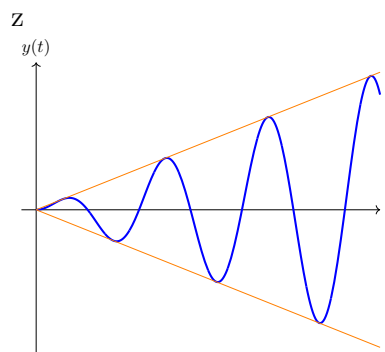
Solution: See the answer to Part (e).

(e) Graph one nicely chosen solution from Part (c).

Solution: We graph $x_p(t) = \frac{t \sin(\omega_0 t)}{2\omega_0}$.



(d) Undamped amplitude response



(e) Resonance response

(f) (Unrelated to the DE above.) Assume we have a (possibly frictionless) physical system modeled by a second-order constant coefficient linear DE with positive coefficients. What criteria must the roots satisfy if this system can undergo pure resonance?

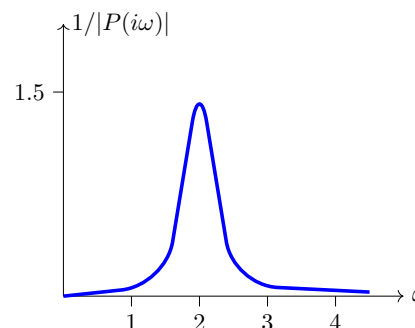
Solution: For a second-order with positive coefficients, we know that no root has a positive real part. If it can experience pure resonance, then at least one of the roots must have 0 real part.

This is noncontroversial when the root $i\beta \neq 0$. If the root is identically 0, then the response of the system to a constant input will go to infinity, just like resonance. But, perhaps we shouldn't call this resonance. An example is the velocity of a mass falling under constant gravity.

Problem 3.
 Suppose that $P(r)$ is a polynomial and consider the DE

$$P(D)x = \cos t + \cos 2t + \cos 3t.$$

The graph of $\frac{1}{|P(i\omega)|}$ is shown. On the axes provided give a rough sketch of the periodic solution $x_p(t)$ to the DE. Give a brief explanation of your reasoning.



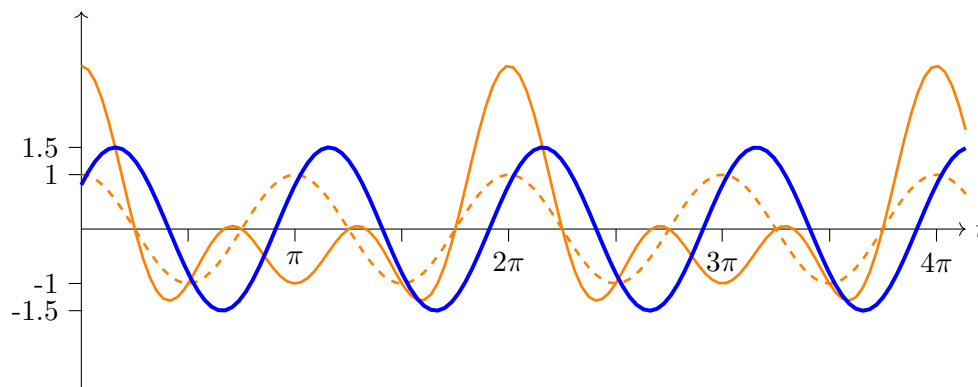
Solution: Using the sinusoidal response formula and superposition, the periodic solution to the DE is of the form $x_p(t) = \frac{\cos(t - \phi_1)}{|P(i)|} + \frac{\cos(2t - \phi_2)}{|P(2i)|} + \frac{\cos(3t - \phi_3)}{|P(3i)|}$.

The graph of $1/|P(i\omega)|$ shows $1/|P(2i)| = 1.5$ and $1/|P(i)|$ and $1/|P(3i)|$ are small. Thus the system 'filters out' the frequencies 1 and 3 and the second term in x_p is by far the biggest, so

$$x_p(t) \approx \cos(2t - \phi_2)/|P(2i)| = 1.5 \cos(t - \phi_2).$$

Since we don't know ϕ_2 we draw the graph with an arbitrary phase lag, but amplitude 1.5 and angular frequency 2.

The input is shown in orange, the part of the input with frequency 2 is shown as a dashed line, the output is shown in blue.



Problem 4.
 The differential operator for this problem is $P(D) = D^2 + 4D + 13I$.
 (a) (12) Find the general real-valued solution to $P(D)x = 2 \cos(\omega t)$.

Solution: Homogeneous equation: $P(D)x = 0$.
 Characteristic equation: $P(r) = r^2 + 4r + 13 = 0$.

Characteristic roots: $r = \frac{-4 \pm \sqrt{16 - 52}}{2} = -2 \pm 3i$.

Homogeneous solution: $x_h(t) = c_1 e^{-2t} \cos(3t) + c_2 e^{-2t} \sin(3t)$.

Particular solution using the SRF:

Preparation: $P(i\omega) = 13 - \omega^2 + 4i\omega$. So,

$|P(i\omega)| = \sqrt{(13 - \omega^2)^2 + 16\omega^2}$; $\phi(\omega) = \text{Arg}(P(i\omega)) = \tan^{-1}(4\omega/(13 - \omega^2))$, in Q1 or Q2.

So,

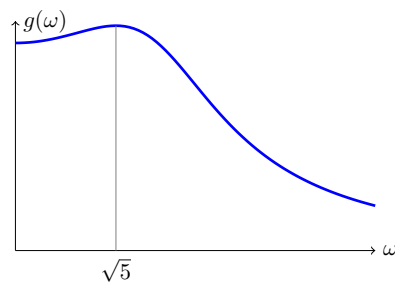
$$x_p(t) = \frac{2 \cos(\omega t - \phi(\omega))}{|P(i\omega)|} = \frac{2 \cos(\omega t - \phi(\omega))}{\sqrt{(13 - \omega^2)^2 + 16\omega^2}}$$

General real-valued solution: $x(t) = x_p(t) + x_h(t)$.

(b) (5) Assume that $\cos(\omega t)$ is the input to the system in Part (a). Give the amplitude response (as a function of ω).

We'll help you by saying that there is exactly one (practical) resonant frequency, which is at $\omega = \sqrt{5}$. Use this to help sketch a graph of the amplitude response. Be sure to label your axes.

Solution: From Part (a): $g(\omega) = 2/\sqrt{(13 - \omega^2)^2 + 16\omega^2}$. So we have $g(0) = 2/13$. The graph must increase from there to its only peak at $\omega = \sqrt{5}$. From there it must decrease asymptotically to 0 as $\omega \rightarrow \infty$.



4(b) Gain (Amplitude response)

Problem 5. Consider the forced undamped system: $x'' + 8x = \cos(\omega t)$.

(a) Why is this called a forced undamped system?

(b) Use the exponential response formula to find a solution.

(c) Consider the right-hand side of the DE to be the input and graph the amplitude response function.

(d) What is the resonant frequency of the system?

(e) Why is this called the natural frequency?

Solution: (a) No damping, input = force.

(b) (Model solution) We could use the SRF, but the instructions say to use the ERF, so we will complexify and use that.

Complexify: $z'' + 8z = e^{i\omega t}$, $x = \text{Re } z$.

Char. polynomial: $P(r) = r^2 + 8$. For use in the ERF and extended ERF we compute

$$P(i\omega) = 8 - \omega^2, |P(i\omega)| = |8 - \omega^2|, \text{Arg}(P(i\omega)) = \begin{cases} 0 & \text{if } \omega < \sqrt{8} \\ \pi & \text{if } \omega > \sqrt{8} \end{cases}$$

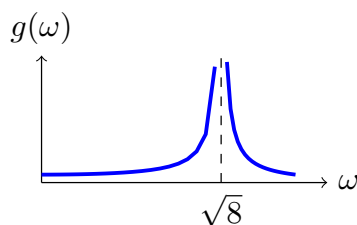
$$P'(i\omega) = 2i\omega, |P'(i\omega)| = 2\omega, \text{Arg}(P'(i\omega)) = \pi/2.$$

Exponential response formula:

$$\text{If } \omega \neq \sqrt{8}, \text{ then } z_p(t) = \frac{e^{i\omega t}}{P(i\omega)} = \frac{e^{i\omega t}}{8 - \omega^2} \Rightarrow x(t) = \text{Re } z = \begin{cases} \frac{\cos(\omega t)}{|8 - \omega^2|} & \text{if } \omega < \sqrt{8} \\ \frac{\cos(\omega t - \pi)}{|8 - \omega^2|} & \text{if } \omega > \sqrt{8} \end{cases}$$

$$\text{If } \omega = \sqrt{8}, \text{ then } z_p(t) = \frac{te^{i\omega t}}{P'(i\omega)} = \frac{te^{i\omega t}}{2i\omega} = \frac{te^{i\omega t}}{2\omega e^{i\pi/2}} \Rightarrow x(t) = \text{Re } z = \frac{t \cos(\omega t - \pi/2)}{2\omega}.$$

(c) $g(\omega) = 1/|8 - \omega^2|$. The graph of g vs. ω has a vertical asymptote at $\omega = \sqrt{8}$.



(d) The resonant frequency is at $\omega = \sqrt{8}$.

(e) Because the unforced, undamped system will naturally oscillate at this frequency

Problem 6.

Consider the forced damped second-order system: $x'' + 2x' + 9x = \cos(\omega t)$.

(a) What is the natural frequency of the system?

(b) Find the response of the system in amplitude-phase form.

(c) Consider the right-hand side of the DE to be the input. What is the amplitude response of the system?

(d) What is the practical resonant frequency?

(e) When $\omega = \sqrt{7}$, by how many radians does the output peak lag behind the input peak?

(f) For the forced undamped system $x'' + 9x = \cos(\omega t)$, give a detailed description of the phase lag for different input frequencies?

Solution: (a) Natural frequency = frequency of unforced, undamped system = $\sqrt{9} = 3$.

(b) (Model solution)

Using the sinusoidal response formula: $P(r) = r^2 + 2r + 9 \Rightarrow P(i\omega) = 9 - \omega^2 + 2i\omega$. So,

$$|P(i\omega)| = \sqrt{(9 - \omega^2)^2 + 4\omega^2} \text{ and } \phi(\omega) = \text{Arg}(P(i\omega)) = \tan^{-1}\left(\frac{2\omega}{9 - \omega^2}\right) \text{ in Q1 or Q2.}$$

Thus,

$$x_p(t) = \frac{1}{|P(i\omega)|} \cos(\omega t - \phi(\omega)) = \frac{\cos(\omega t - \phi(\omega))}{\sqrt{(9 - \omega^2)^2 + 4\omega^2}}.$$

Alternatively (you should know how to do this):

Complexify: $z'' + 2z' + 9z = e^{i\omega t}$, $x = \operatorname{Re} z$.

Char. polynomial: $P(r) = r^2 + 2r + 9 \Rightarrow P(i\omega) = 9 - \omega^2 + 2i\omega$.

$$\text{ERF: } z_p(t) = \frac{e^{i\omega t}}{P(i\omega)} = \frac{e^{i\omega t}}{9 - \omega^2 + 2i\omega}$$

Polar form: $9 - \omega^2 + 2i\omega = \sqrt{(9 - \omega^2)^2 + 4\omega^2} e^{i\phi(\omega)}$, where $\phi(\omega) = \tan^{-1}(2\omega/(9 - \omega^2))$, in Q1 or Q2.

$$\Rightarrow z_p(t) = \frac{1}{\sqrt{(9 - \omega^2)^2 + 4\omega^2}} e^{i(\omega t - \phi(\omega))} \Rightarrow x(t) = \frac{1}{\sqrt{(9 - \omega^2)^2 + 4\omega^2}} \cos(\omega t - \phi(\omega)).$$

(c) Amplitude response = $g(\omega) = \frac{1}{\sqrt{(9 - \omega^2)^2 + 4\omega^2}}$.

(d) Practical resonance occurs if $g(\omega)$ has a local maximum. Simple calculus shows it has a maximum at $\omega = \sqrt{7}$.

(e) $\omega = \sqrt{7} \Rightarrow \phi(\omega) = \tan^{-1}\left(\frac{2\sqrt{7}}{9 - 7}\right) = \tan^{-1}\sqrt{7} \approx 1.2$ radians. The output lags behind the input by approximately 1.2 radians. (You should graph input and response on same axes.)

(f) The phase lag at ω is given by $\operatorname{Arg}(P(i\omega))$. We have

$$P(i\omega) = 9 - \omega^2 + 2i\omega \Rightarrow \phi(\omega) = \operatorname{Arg}(P(i\omega)) = \begin{cases} 0 & \text{if } \omega < 3 \\ \pi & \text{if } \omega > 3. \end{cases}$$

Since there is no sinusoidal response when $\omega = 3$, there is no official phase lag, but the solution $x_p(t) = t \cos(3t - \pi/2)/6$ suggests that $\pi/2$ might be a reasonable unofficial choice.

Problem 7. Consider the driven first-order system: $x' + kx = kF_0 \cos(\omega t)$.

Consider the input to be $F_0 \cos(\omega t)$. Solve the DE and find the amplitude response. Show there is never practical resonance.

Solution: Use the sinusoidal response formula: $x_p(t) = \frac{kF_0 \cos(\omega t - \phi(\omega))}{|P(i\omega)|}$.

Char. polynomial: $P(r) = r + k$. So, $P(i\omega) = i\omega + k$.

Polar form: $P(i\omega) = k + i\omega \Rightarrow |P(i\omega)| = \sqrt{k^2 + \omega^2}$, and $\phi(\omega) = \operatorname{Arg}(P(i\omega)) = \tan^{-1}(\omega/k)$, in Q1. So,

$$x_p(t) = \frac{kF_0}{\sqrt{k^2 + \omega^2}} \cos(\omega t - \phi(\omega))$$

Amplitude response = $g(\omega) = \frac{k}{\sqrt{k^2 + \omega^2}}$. This is a decreasing function in ω , so there is no positive local maximum and no practical resonance.

End of practice quiz solutions

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ES.1803 Differential Equations

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