ES.1803 Problem Section 7, Spring 2024 Solutions

Problem 13.1. Compute the following by thinking of matrix multiplication as a linear combination of the columns of the matrix.

Solution: Picks out second column

- ımn 5
- **(b)** $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} -2 \\ 4 \\ -2 \end{bmatrix}$
- **Solution:** Linear combination: $-2\begin{bmatrix}1\\4\\7\end{bmatrix} + 4\begin{bmatrix}2\\5\\8\end{bmatrix} 2\begin{bmatrix}3\\6\\9\end{bmatrix} = \begin{bmatrix}0\\0\\0\end{bmatrix}.$

Problem 13.2. Is it a vector space? For all of these you just have to check that they are closed under addition and scalar multiplication, i.e. closed under linear combinations.

(a) The set of functions f(x) such that f(5) = 0.

Solution: Yes: If f(5) = 0 and g(5) = 0, then clearly $c_1 f(5) + c_2 g(5) = 0$.

(b) The set of functions f(x) such that f(5) = 2.

Solution: No: If f(5) = 2 and g(5) = 2, then f(5) + g(5) = 4. So the set is not closed under addition.

(c) The set of vectors (x, y) in the plane, such that 2x + 3y = 0.

Solution: Yes. Graph this, it's a line through the origin. Or, algebraically, if (x_1, y_1) and (x_2, y_2) are in the set, then so is $c_1(x_1, y_1) + c_2(x_2, y_2) = (c_1x_1 + c_2x_2, c_1y_1 + c_2y_2)$. This is easy to check:

$$2(c_1x_1 + c_2x_2) + 3(c_1y_1 + c_2y_2) = c_1\underbrace{(2x_1 + 3y_1)}_{\text{equals }0} + c_2\underbrace{(2x_2 + 3y_2)}_{\text{equals }0} = 0$$

(d) The set of vectors (x, y) in the plane, such that 2x + 3y = 2.

Solution: No. Graph this, it's a line NOT through the origin, so it is not closed under scalar multiplication by 0.

Problem 13.3. Convert the following ODE to a companion system: $x''' + 2x'' + 3x' + 4x = \cos(5t)$.

Solution: Let y = x', z = x''. So, $z' + 2z + 3y + 4x = \cos(5t)$. We get $z' = -4x - 3y - 2z + \cos(5t)$. So,

$$\begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -4 & -3 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ \cos(5t) \end{bmatrix}$$

Problem 14.4. Let $A = \begin{bmatrix} 1 & 2 & 3 & 1 & 2 \\ 2 & 4 & 6 & 2 & 4 \\ 3 & 6 & 10 & 3 & 6 \end{bmatrix}$. Put A in row reduced echelon form. Find

the rank, a basis of the column space, a basis of the null space, and the dimension of each of the spaces.

Solution: Here are the row reduction steps:

$$A \xrightarrow{R_2 = R_2 - 2R_1}{R_3 = R_3 - 3R_1} \begin{bmatrix} 1 & 2 & 3 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix} \xrightarrow{\text{swap } R_2 \text{ and } R_3} \begin{bmatrix} 1 & 2 & 0 & 1 & 2 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = R$$

The pivot columns are Columns 1 and 3. These give a basis for the column space of A.

Basis:
$$\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} 3\\6\\10 \end{bmatrix} \right\}$$
 $\operatorname{Col}(A) = \left\{ x_1 \begin{bmatrix} 1\\2\\3 \end{bmatrix} + x_2 \begin{bmatrix} 3\\6\\10 \end{bmatrix} \right\}$

Note the semantic distinction: the basis set contains 2 vectors, the column space is a set with infinitely many vectors.

Rank(A) = # of pivots = dimension of column space = 2.

The null space of A has dimension 3 = # of free variables. Since A and R have the same null space, we work with R.

We find a basis two ways. First, we solve $R\mathbf{x} = \mathbf{0}$ by writing matrix multiplication as a linear combination of columns.

$$R\mathbf{x} = \begin{bmatrix} 1 & 2 & 0 & 1 & 2 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} x_1 + 2x_2 + x_4 + 2x_5 \\ x_3 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

Solving for the pivot variables, these equations show, $x_1 = -2x_2 - x_4 - 2x_5$ and $x_3 = 0$. So the general solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -2x_2 - x_4 - 2x_5 \\ x_2 \\ 0 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -2 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} .$$

This gives us 3 basis vectors:

$$\mathbf{v_1} = \begin{bmatrix} -2\\1\\0\\0\\0 \end{bmatrix}, \quad \mathbf{v_2} = \begin{bmatrix} -1\\0\\0\\1\\0 \end{bmatrix}, \quad \mathbf{v_3} = \begin{bmatrix} -2\\0\\0\\0\\1 \end{bmatrix}$$

So,

$$\operatorname{Null}(A) = \operatorname{span} \operatorname{of} \left\{ \mathbf{v_1}, \mathbf{v_2}, \mathbf{v_3} \right\} = \left\{ c_1 \begin{bmatrix} -2\\1\\0\\0\\0\\0 \end{bmatrix} + c_2 \begin{bmatrix} -1\\0\\0\\1\\0 \end{bmatrix} + c_3 \begin{bmatrix} -2\\0\\0\\1\\0 \end{bmatrix} \right\}$$

A faster method, is to set, in turn, each free variable to 1 and the others to 0 and then solve for the pivot variables. We do the computation by putting the values below the RREF matrix R.

Γ1	2	0	1	ך 2
0	0	1	0	0
LΟ	0	0	0	0
x_1	x_2	x_3	x_4	x_5
0	-1	0	~	~
-2	1	0	0	0
$-2 \\ -1$	$\frac{1}{0}$	$\begin{array}{c} 0\\ 0\end{array}$	$\begin{array}{c} 0 \\ 1 \end{array}$	$\begin{array}{c} 0\\ 0\end{array}$

This gives the same basis we found with our first method.

Problem 14.5. Let $R = \begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$. Suppose R is the row reduced echelon form for

A.

(a) What is the rank of A?

Solution: A and R have the same rank. Two pivots in R implies rank = 2.

(b) Find a basis for the null space of A.

Solution: A and R have the same null space. The second and fourth variables are free. We find a basis by setting them to 1 and 0 in turn and then solving for the pivot variables.

Note, I find this computation easiest to do if I think of matrix multiplication as a combination of the columns

$$\begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{vmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{vmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} = \mathbf{0}$$

We show the computation by putting the variables below the matrix. Each row below the matrix shows one solution to $R\mathbf{x} = \mathbf{0}$, found by setting one free variable to 1, the other free variables to 0 and solving for the pivot variables.

So a basis of Null(A) contains the two vectors

$$\begin{bmatrix} -2\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} -3\\0\\-1\\1 \end{bmatrix}.$$

There are, of course, many other bases. Our standard algorithm produces the one given.

(c) Suppose the column space of A has basis $\begin{bmatrix} 1\\1\\0\\1\end{bmatrix}$, $\begin{bmatrix} 3\\1\\1\\1\end{bmatrix}$. Find a possible matrix for A. That

is, give a matrix A with RREF R and the given column space.

Solution: Looking at R the Columns 1 and 3 are pivot columns. We put the given basis in those columns:

$$A = \begin{bmatrix} 1 & * & 3 & * \\ 1 & * & 1 & * \\ 0 & * & 1 & * \end{bmatrix}$$

The free columns of R are linear combinations of the pivot columns and those of A are the same linear combinations. In R it is clear that

$$\operatorname{Col}_2 = 2 \times \operatorname{Col}_1$$
 and $\operatorname{Col}_4 = 3 \times \operatorname{Col}_1 + \operatorname{Col}_3$.

So,

$$A = \begin{bmatrix} 1 & 2 & 3 & 6 \\ 1 & 2 & 1 & 4 \\ 0 & 0 & 1 & 1 \end{bmatrix}.$$

(d) Find a matrix with the same row reduced echelon form, but such that $\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$ and $\begin{bmatrix} 1\\2\\3 \end{bmatrix}$ are

in its column space.

Solution: We found the relationships between the columns in Part (c). So we put the given columns as pivot columns and construct the free columns from these relationships: $\begin{bmatrix} 1 & 2 & 1 & 4 \end{bmatrix}$

 $\begin{bmatrix} 1 & 2 & 2 & 5 \\ 1 & 2 & 3 & 6 \end{bmatrix}$

Note: you could put any other basis for the subspace generated by $\begin{bmatrix} 1\\1\\1 \end{bmatrix}$ and $\begin{bmatrix} 1\\2\\3 \end{bmatrix}$ in the pivot columns and adjust the free columns accordingly.

Extra problems if time.

Problem 14.6. Suppose we want to solve $A\mathbf{x} = \mathbf{b}$, where $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}$.

(a) When is this possible? Answer this in the form: "b must be a linear combination of the two vectors ..."

Solution: The equation can be solved exactly when **b** is a linear combination of the columns of A, i.e., when **b** is in $\operatorname{Col}(A)$. We can find a basis of $\operatorname{Col}(A)$ by finding the RREF. The RREF is

$$R = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}.$$

The first two columns are pivot columns and the last one is free. Thus, the column space of A is spanned by the first two columns of A. Since, **b** must be in Col(A), we can answer the question as follows:

b must be a linear combination of the first two columns of A, i.e., $\mathbf{b} = c_1 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$

Note. Since there are lots of other possible bases for the column space, this is just one of many possible answers.

(b) $A\mathbf{x} = \mathbf{b}$ is certainly solvable for $\mathbf{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$. (What is the obvious particular solution?) Describe the general solution to this equation, as $\mathbf{x} = \mathbf{x}_{\mathbf{p}} + \mathbf{x}_{\mathbf{h}}$.

Solution: $\mathbf{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ is the first column of A, so the obvious solution is $\mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. We can take this (or any other solution!) as $\mathbf{x}_{\mathbf{p}}$. To get the general solution, we must add the general homogeneous solution.

The homogeneous solution is the same as the null space of A or R. We can find that by setting the free variable $x_3 = 1$ and solving for $x_1 = 1$ and $x_2 = -2$. So, $\mathbf{x_h} = c \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$, and

$$\mathbf{x} = \mathbf{x}_{\mathbf{p}} + \mathbf{x}_{\mathbf{h}} = \begin{bmatrix} 1\\0\\0 \end{bmatrix} + c \begin{bmatrix} 1\\-2\\1 \end{bmatrix} = \begin{bmatrix} 1+c\\-2c\\c \end{bmatrix}.$$

Problem 14.7. Suppose that the row reduced echelon form of the 4×6 matrix B is

$$R = \begin{bmatrix} 0 & 1 & 2 & 3 & 0 & 5 \\ 0 & 0 & 0 & 1 & 0 & 7 \\ 0 & 0 & 0 & 0 & 1 & 9 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

(a) Find a linearly independent set of vectors of which every vector in the null space of B is a linear combination.

Solution: This is just another way of asking for a basis of Null(B). The null space of B is the same as the null space of its row-echelon form.

The free variables are: x_1 , x_3 and x_6 . As usual, we set them to 1 in turn.

ΓO	1	3	0	0	$5 \cdot$
0	0	0	1	0	7
0	0	0	0	1	9
LΟ	0	0	0	0	0.
x_1	x_2	r_{\circ}	x_4	x_5	x_6
x_1	x_2	x_3	ω_4	~5	~ 0
$\frac{x_1}{1}$	$\begin{array}{c} x_2 \\ 0 \end{array}$	0		0^{ω_5}	0^{ω_0}
-					
1	0	0	0	0	0

Thus a basis of Null(B) is

ſ	ר1]		[0]		[0])	
	0		-3		-5		
J	0		1		0		
Ì	0	,	0	,	-7		Ì
	0		0		-9		
l	$\lfloor 0 \rfloor$		0		1	J	

(b) Write the columns of B as $\mathbf{b_1}, \mathbf{b_2}, \dots, \mathbf{b_6}$. What is $\mathbf{b_1}$? What can we say about $\mathbf{b_2}$? Which of these vectors are linearly independent of the preceding ones? Express the ones which are not independent as explicit linear combinations of the previous ones. Describe a linearly independent set of vectors of which every vector in the column space of B is a linear combination.

Solution: \mathbf{b}_1 must be $\mathbf{0}$, since applying row operations to it give $\mathbf{0}$, and row operations are reversible.

 $\mathbf{b_2} \neq \mathbf{0}$. This is all we can say.

The linear relations among the columns of B are the linear relations among the columns of R: so the columns of B corresponding to the pivot columns of R are independent of the previous columns: $\mathbf{b_2}$, $\mathbf{b_4}$, and $\mathbf{b_5}$.

For the linear relations, we just copy what we know for R: $\mathbf{b_1} = 0$; $\mathbf{b_3} = 3\mathbf{b_2}$; $\mathbf{b_6} = 5\mathbf{b_2} + 7\mathbf{b_4} + 9\mathbf{b_5}$.

By a 'linearly independent set of vectors of which every vector in the column space is a linear combination' we just mean a basis of $\operatorname{Col}(B)$, These are the pivot columns. That is, $\{\mathbf{b_2}, \mathbf{b_4}, \mathbf{b_5}\}$ is a basis for the column space of B.

Problem 14.8. Suppose we have a matrix equation

$$\begin{bmatrix} 1 & x & 2 \\ 3 & y & 4 \\ 5 & z & 6 \end{bmatrix} \mathbf{c} = \mathbf{0}$$

and all we know about the vector **c** is that $\mathbf{c} \neq \mathbf{0}$. What can we say about $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$?

Solution: To have a nontrivial null space the rank must be less than 3. Since the first and third columns are independent, the middle column must be a linear combination of them. Geometrically, the middle column is in the plane containing the origin and the other two columns.

Problem 14.9. For what values of y is it the case that the columns of $\begin{bmatrix} 1 & 1 & 2 \\ 3 & y & 4 \\ 5 & 1 & 6 \end{bmatrix}$ form a

linearly independent set?

Solution: The columns are linearly independent when the matrix has rank 3. We can find the rank by row reduction:

$$\begin{bmatrix} 1 & 1 & 2 \\ 3 & y & 4 \\ 5 & 1 & 6 \end{bmatrix} \xrightarrow{R_2 = R_2 - 3R_1} \begin{bmatrix} 1 & 1 & 2 \\ 0 & y - 3 & -2 \\ 0 & -4 & -4 \end{bmatrix} \xrightarrow{\text{swap } R_2 \text{ and } R_3} \begin{bmatrix} 1 & 1 & 2 \\ 0 & -4 & -4 \\ 0 & y - 3 & -2 \end{bmatrix}$$
$$\xrightarrow{R_2 = -R_2/4} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & y - 3 & -2 \end{bmatrix} \xrightarrow{R_3 = R_3 - (y - 3)R_2} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 - y \end{bmatrix}$$

If $1 - y \neq 0$, then we have 3 pivots. So the columns are linearly independent exactly when $y \neq 1$.

Problem 14.10. For the matrix $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}$:

(a) Find the row reduced echelon form of A; call it R.

Solution: Here are the row reduction steps:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix} \xrightarrow{R_2 = R_2 - 2R_1} \begin{bmatrix} 1 & 2 & 3 \\ 0 & -1 & -2 \\ 0 & -3 & -6 \end{bmatrix} \xrightarrow{R_2 = -R_2} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix} = R$$

(b) The last column of R should be a linear combination of the first columns in an obvious way. This is a linear relation among the columns of R. Find a vector \mathbf{x} , such that $R\mathbf{x} = \mathbf{0}$, which expresses this linear relationship.

Solution: This is just an awkward way of asking about null vectors. The first two columns are pivotal and the third is free. So the third is a combination of the other two. By inspection of R, we see that

 $\operatorname{Col}_3 = -\operatorname{Col}_1 + 2\operatorname{Col}_2 \quad \Rightarrow \operatorname{Col}_1 - 2\operatorname{Col}_2 + \operatorname{Col}_3 = \mathbf{0}.$ As a matrix equation this is $R \begin{bmatrix} 1\\ -2\\ 1 \end{bmatrix} = \begin{bmatrix} 0\\ 0\\ 0 \end{bmatrix}.$

(c) Verify that the same relationship holds among the columns of A.

Solution: The third column is indeed minus the first plus twice the second. As a matrix equation,

$$A\begin{bmatrix}1\\-2\\1\end{bmatrix} = \begin{bmatrix}1 & 2 & 3\\2 & 3 & 4\\3 & 4 & 5\end{bmatrix} \begin{bmatrix}1\\-2\\1\end{bmatrix} = \begin{bmatrix}0\\0\\0\end{bmatrix}$$

(d) Explain why the linear relations among the columns of R are the same as the linear relations among the columns of A. In fact, explain why, if A and B are related by row transformations, the linear relations among the columns of A are the same as the linear relations among the columns of B.

Solution: Row transformations do the same thing to the entries of all columns.

This is the same as saying that if A and B are related by row-operations, then their null spaces coincide. Their column spaces usually do not.

Problem 14.11. Consider the following system of equations:

$$x + y + z = 5$$
$$x + 2y + 3z = 7$$
$$x + 3y + 6z = 11$$

(a) Write this system of equations as a matrix equation.

Solution:

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \\ 11 \end{bmatrix}$$

(b) Use row reduction to get to row echelon form. What is the solution set?

Solution: Set up the augmented matrix:

$$\begin{bmatrix} 1 & 1 & 1 & 5 \\ 1 & 2 & 3 & 7 \\ 1 & 3 & 6 & 11 \end{bmatrix}$$

Do row reduction to RREF

The solution is x = 5, y = -2, z = 2. You can check this by substituting it into the original equations.

Problem 14.12. (a) Suppose we have a matrix equation

$$\begin{bmatrix} \bullet \\ \bullet \end{bmatrix} \begin{bmatrix} \bullet & \bullet \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & x \end{bmatrix}$$

Can you specify x? For any value of x you think is allowable, find such an equation. Can any of the \bullet 's be 0?

Solution: Each column of the product is a multiple of the column vector in the first factor. The 1s show that they are the same multiple. So x must be 2.

Alternatively, each row of the product is a multiple of the row vector. The first column of the product shows that the second row must be twice the first row. So x must be 2.

One equation that works for x = 2 is $\begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$.

None of the \bullet 's can be 0, since that would make the corresponding row or column in the product **0**.

(b) Suppose we have a matrix equation

$$\begin{bmatrix} \bullet & 3\\ \bullet & 4\\ \bullet & 5 \end{bmatrix} \begin{bmatrix} 1\\ 2 \end{bmatrix} = \begin{bmatrix} 0\\ 0\\ 0 \end{bmatrix}$$

Can you specify the \bullet 's?

Solution: The matrix equation says: the first column plus twice the second column is zero.

So the first column must be $\begin{bmatrix} -6\\ -8\\ -10 \end{bmatrix}$.

(c) Suppose we have a matrix equation

$$\begin{bmatrix} x & 3 \\ y & 4 \\ z & 5 \end{bmatrix} \mathbf{c} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

and all we know about the vector **c** is that $\mathbf{c} \neq \mathbf{0}$. What can we say about $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$?

Solution: The equation says that the columns of the matrix form a linearly dependent set. That is: one is a multiple of the other. Since the second column is nonzero, we can be sure

that the first is a multiple of the second: $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = t \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$ for some t.

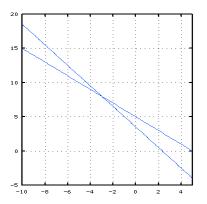
Problem 14.13. Solve this system of linear equations. How many methods can you think of to solve this system?

$$\begin{aligned} x + y &= 5\\ 3x + 2y &= 7 \end{aligned}$$

Solution: Some ideas:

- (1) Graphically with interesecting lines.
- (2) Elimination.
- (3) Row reduce the augmented matrix.
- (4) Matrix inverse.

(1) y = -x + 5 and $y = \frac{7}{2} - \frac{3}{2}x$ are two straight lines of different slopes; so they meet at a single point. To find where, we could eyeball the picture—maybe (-3, 8)? That satisfies both equations!



(2) We can use elimination: Subtract 3 times the first equation from the second. Retaining the first equation as well, we get

$$\begin{aligned} x + y &= 5\\ 0 - y &= -8 \end{aligned}$$

and then the first equation gives x = -3. In fact, as a second step, we could add the new second equation to the first one:

$$x + 0 = -3$$
$$0 - y = -8$$

Thus (x, y) = (-3, 8) is the solution.

(3) Matrix methods: The system is $\begin{bmatrix} 1 & 1 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \end{bmatrix}$. So,

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 3 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 5 \\ 7 \end{bmatrix} = -\begin{bmatrix} 2 & -1 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 7 \end{bmatrix} = \begin{bmatrix} -3 \\ 8 \end{bmatrix}$$

Again (x, y) = (-3, 8) is the solution.

Problem 14.14. Solve the following equation using row reduction:

$$\begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

(a) At the end of the row-reduction process, was the last column pivotal or free? Is this related to the absence of solutions?

Solution: The augmented matrix is $\begin{bmatrix} 1 & 2 & | \\ 3 & 6 & | \\ 0 \end{bmatrix}$.

Do row reduction:

$$\begin{bmatrix} 1 & 2 & | & 1 \\ 3 & 6 & | & 0 \end{bmatrix} \xrightarrow{\operatorname{Row}_2 = \operatorname{Row}_2 - 3\operatorname{Row}_3} \begin{bmatrix} 1 & 2 & | & 1 \\ 0 & 0 & | & -3 \end{bmatrix} \xrightarrow{\operatorname{Row}_2 = -\operatorname{Row}_2/3} \begin{bmatrix} 1 & 2 & | & 1 \\ 0 & 0 & | & 1 \end{bmatrix}$$

The last equation now reads 0x + 0y = 1, which is rather hard to satisfy.

(We could already see this problem after the first reduction step.)

The last column was pivotal. This implies there is a row in the augmented RREF matrix with all zeros except for a 1 in the last column. This row corresponds to the equation 0x + 0y = 1, which explains why there are no solutions.

(b) Find a new vector $\mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ such that $\begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ has a solution.

Solution: Well, we could always take $\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, because the equation is then obviously solved by $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$.

To be more general, we can take **b** in the column space of the coefficient matrix. The row reduced echelon form shows that Column 1 is the only pivot column. So the column space has basis $\begin{bmatrix} 1\\3 \end{bmatrix}$.

Thus, the vectors $c \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ are exactly the vectors for which the equation admits a solution.

Problem 14.15. Show that the matrix $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ corresponds to counter-clockwise rotation about the origin by 90 degrees, by computing the effect of this matrix on the vectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} -3 \\ 4 \end{bmatrix}$ and drawing \mathbf{v}_1 , \mathbf{v}_2 , $A\mathbf{v}_1$, $A\mathbf{v}_2$ on the plane.

Solution: It's easy to compute:

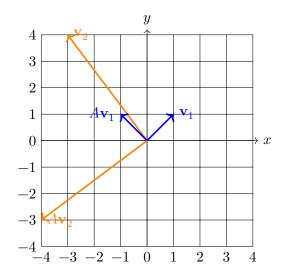
$$A\mathbf{v}_1 = \begin{bmatrix} 0 & -1\\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1\\ 1 \end{bmatrix} = \begin{bmatrix} -1\\ 1 \end{bmatrix}$$
 and $A\mathbf{v}_2 = \begin{bmatrix} -4\\ -3 \end{bmatrix}$

Using the dot product we can check that \mathbf{v}_1 is orthogonal to $A\mathbf{v}_1$:

$$\mathbf{v}_1 \cdot A\mathbf{v}_1 = \begin{bmatrix} 1\\1 \end{bmatrix} \cdot \begin{bmatrix} -1\\1 \end{bmatrix} = 0.$$

Similarly $\mathbf{v}_2 \cdot A\mathbf{v}_2 = 0$.

This shows hat tA has rotated each of the vectors \mathbf{v}_1 and \mathbf{v}_2 by 90°. The figure shows the rotation is counter-clockwise.



Problem 13.16. Make up a block matrix problem: Multiply a 4×4 matrix made up of four 2×2 blocks (two blocks of 0s, one block = identity, one block something else) times a 4×2 matrix with (i.e., two 2×2 blocks)

Solution: You do this!

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