1 The Weak definition of a harmonic function

It is sometimes useful to weaken the notion of a harmonic function somewhat. One way of doing this is with the notion of a weakly harmonic function. Let \( u \) be a differentiable function on some set \( \Omega \). We say that \( u \) is weakly harmonic on \( \Omega \) if

\[
\int_{\Omega} \nabla \phi \cdot \nabla u = 0
\]

for all differentiable functions \( \phi \) with \( \phi = 0 \) on \( \partial \Omega \). One nice thing about this definition is that we don’t need \( u \) to be as smooth as we did for the old definition, so this really is a weaker condition.

The two definitions of harmonic are linked by Stokes’ theorem. If we take \( u \) to be harmonic then

\[
\int_{\Omega} \phi \Delta u = 0
\]

and

\[
\int_{\partial \Omega} \phi \nabla u \cdot dS = 0.
\]

Applying Stokes’ theorem to this we recover the weak definition

\[
\int_{\Omega} \nabla \phi \cdot \nabla u = 0,
\]

and it easy to run this argument backwards for \( C^2 \) functions.

2 Generalizations of the Laplacian

Over the last few lectures we have proved some results about the laplacian and harmonic functions. Now we will try to generalise some of these. We will consider operators of the form

\[
Lu = \sum_{i,j} \frac{\partial}{\partial x_i} \left( a_{ij} \frac{\partial u}{\partial x_j} \right),
\]

1
where $A$ is a symmetric $n \times n$ matrix with entries $a_{ij}$ (not necessarily constant). An operator written like this is said to be in divergence form since $Lu = \text{div}(A \nabla u)$. Note that if $A$ is the identity matrix then $L$ is simply the laplacian. We will often be interested in functions satisfying $Lu = 0$. Such functions are called $L$-harmonic. There is also the concept of a weakly $L$-harmonic function, where

$$\int_{\Omega} \nabla \phi \cdot (A \nabla u) = 0.$$  \hspace{1cm} (6)

by a similar argument to section 1 any $L$-harmonic function is weakly $L$-harmonic.

### 2.1 Uniformly Elliptic Operators

Operators where the matrix $A$ satisfies

$$\lambda |v|^2 \leq \langle A v, v \rangle \leq \Lambda |v|^2$$

for some real $0 < \lambda \leq \Lambda$ and for all vectors $v$ are of particular interest. These operators are said to be uniformly elliptic. If there is a lower bound but not an upper bound the operator is simply said to be elliptic. We can extend many of the results we proved for harmonic functions to functions solving any uniformly elliptic operator.

### 2.2 The Cacciopoli Inequality for uniformly elliptic operators

The first result that we will generalise is the Cacciopoli inequality. This is almost exactly the same inequality as for harmonic functions.

**Theorem 2.1** If $L$ is uniformly elliptic with $\lambda |v|^2 \leq \langle A v, v \rangle \leq \Lambda |v|^2$ and $u$ satisfies $uLu \geq 0$ on $B_{2r}$ then

$$\int_{B_r} |\nabla u|^2 \leq \frac{4\Lambda^2}{\lambda^{2/2}} \int_{B_{2r} \setminus B_r} u^2.$$  

**Proof** Again we start off by introducing a test function $\phi$ with $\phi \geq 0$ and $\phi = 0$ on the boundary of $B_{2r}$. Calculate

$$0 \leq \int_{B_{2r}} \phi^2 uLu$$

$$\leq \int_{B_{2r}} \phi^2 u(\nabla \cdot A \nabla u)$$

$$\leq -\int_{B_{2r}} \langle \nabla (\phi^2 u), A \nabla u \rangle$$

$$\leq -2 \int_{B_{2r}} \phi u < \nabla \phi, A \nabla u > - \int_{B_{2r}} \phi^2 < \nabla u, A \nabla u >$$
by Stokes' theorem. Therefore

$$\lambda \int_{B_{2r}} \phi^2 < \nabla u, \nabla u > \leq -2 \int_{B_{2r}} \phi u < \nabla \phi, A \nabla u >$$

(7)

by uniform ellipticity. Now work on the right hand side;

$$\lambda \int_{B_{2r}} \phi^2 < \nabla u, \nabla u > \leq -2 \int_{B_{2r}} \phi u < \nabla \phi, A \nabla u >$$

$$\leq -2 \int_{B_{2r}} < u \nabla \phi, \phi A \nabla u >$$

$$\leq |2 \int_{B_{2r}} < u \nabla \phi, \phi A \nabla u > |$$

At each point $A$ is a real symmetric matrix with positive eigenvalues, so it defines a good norm. Therefore we can apply Cauchy-Schwarz twice to the last line to get

$$\lambda \int_{B_{2r}} \phi^2 < \nabla u, \nabla u > \leq 2 \int_{B_{2r}} ( < u \nabla \phi, u A \nabla \phi > < \phi \nabla u, \phi A \nabla u > )^{1/2}$$

(8)

$$\leq 2 \left( \int_{B_{2r}} < u \nabla \phi, u A \nabla \phi > \right)^{1/2} \left( \int_{B_{2r}} < \phi \nabla u, \phi A \nabla u > \right)^{1/2}$$

(9)

Applying uniform ellipticity and rearranging gives

$$\lambda \int_{B_{2r}} \phi^2 < \nabla u, \nabla u > \leq 2 \lambda \left( \int_{B_{2r}} u^2 < \nabla \phi, \nabla \phi > \right)^{1/2} \left( \int_{B_{2r}} \phi^2 < \nabla u, \nabla u > \right)^{1/2}.$$  

(10)

Divide and square to get

$$\lambda^2 \int_{B_{2r}} \phi^2 |\nabla u|^2 \leq 4 \lambda^2 \int_{B_{2r}} u^2 |\nabla \phi|^2.$$  

(11)

Now pick $\phi$ and proceed exactly as we did for the previous Cacciopoli Inequality i.e. let

$$\phi(x) = \begin{cases} 
1 & \text{if } |x| \leq r; \\
\frac{2r-|x|}{r} & \text{if } r < x \leq 2r.
\end{cases}$$

Then

$$\int_{B_r} |\nabla u|^2 \leq \int_{B_{2r}} \phi^2 |\nabla u|^2$$

$$\leq 4 \frac{\lambda^2}{\lambda^2} \int_{B_{2r}} u^2 |\nabla \phi|^2$$

$$\leq 4 \frac{4 \lambda^2}{\lambda^2 r^2} \int_{B_{2r} \setminus B_r} u^2$$

as required.  

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