

LECTURE SUMMARY

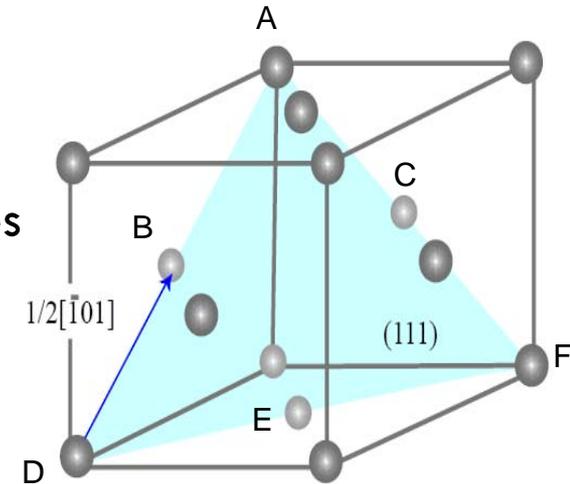
September 30th 2009

Key Lecture Topics

- **Crystal Structures in Relation to Slip Systems**
- **Resolved Shear Stress**
- **Using a Stereographic Projection to Determine the Active Slip System**

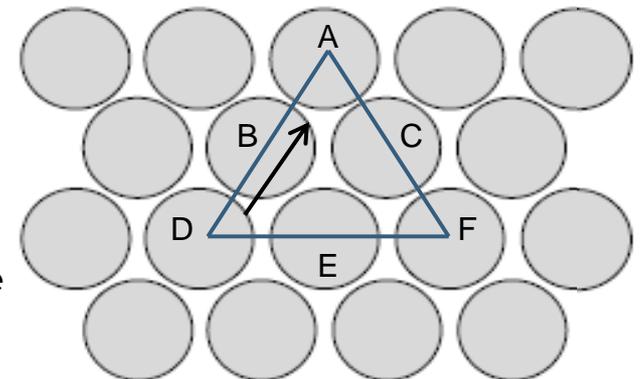
Slip Planes and Slip Directions

- *Slip Planes*
 - ▣ Highest Planar Density
 - Corresponds to most widely spaced planes
- *Slip Directions*
 - ▣ Highest Linear Density
- *Slip System*
 - ▣ Slip Plane + Slip Direction



Slip Plane: $\{111\}$

Figures by MIT OpenCourseWare.



The FCC unit cell has a slip system consisting of the $\{111\}$ plane and the $\langle 110 \rangle$ directions.

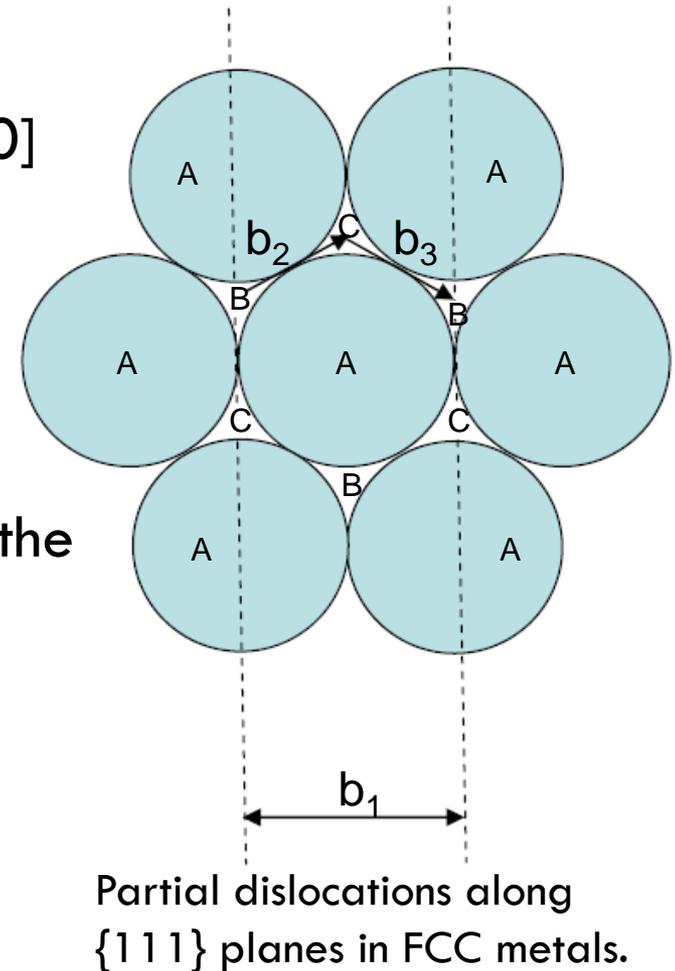
Face Centered Cubic Slip Systems

Figure by MIT OpenCourseWare.

FCC (eg. Cu, Ag, Au, Al, and Ni)

Slip Planes $\{111\}$ **Slip Directions** $[110]$

- The shortest lattice vectors are $\frac{1}{2}[110]$ and $[001]$
- According to Frank's rule, the energy of a dislocation is proportional to the square of the burgers vector, b^2
- Compare energy
 - $\frac{1}{2}[110]$ dislocations have energy $2a^2/4$
 - $[001]$ dislocations have energy a^2
 - \rightarrow Slip Direction is $[110]$



More Slip Systems

<i>Metals</i>	<i>Slip Plane</i>	<i>Slip Direction</i>	<i>Number of Slip Systems</i>
Cu, Al, Ni, Ag, Au	FCC {111}	$\langle 1\bar{1}0 \rangle$	12
α -Fe, W, Mo	BCC {110}	$\langle \bar{1}11 \rangle$	12
α -Fe, W	{211}	$\langle \bar{1}11 \rangle$	12
α -Fe, K	{321}	$\langle \bar{1}11 \rangle$	24
Cd, Zn, Mg, Ti, Be	HCP {0001}	$\langle 11\bar{2}0 \rangle$	3
Ti, Mg, Zr	{10 $\bar{1}$ 0}	$\langle 11\bar{2}0 \rangle$	3
Ti, Mg	{10 $\bar{1}$ 1}	$\langle 11\bar{2}0 \rangle$	6

Resolved Shear Stress

□ What do we need to move dislocations?

□ A Shear Stress!

$$\sigma = F / A$$

$F \cos \lambda$ *Component of force in the slip direction*

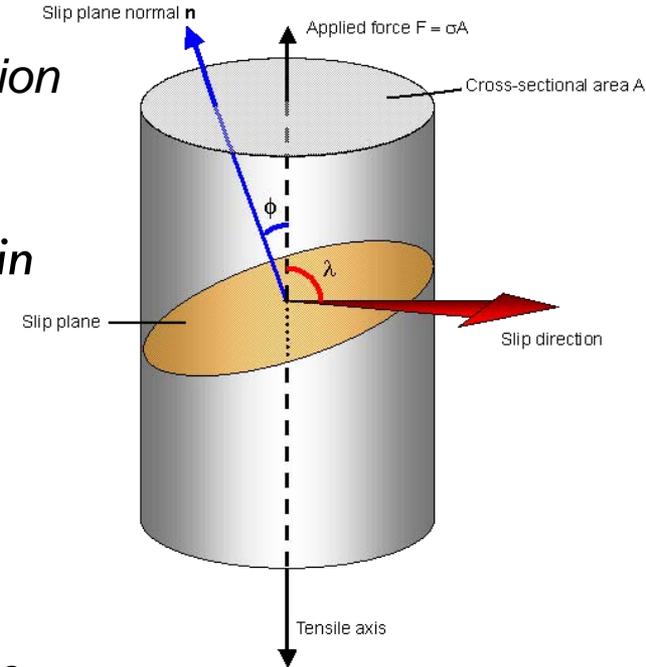
$A / \cos \phi$ *Area of slip surface*

□ Thus the shear stress τ , resolved on the slip plane in the slip direction

$$\tau = F / A \cos \phi \cos \lambda = \sigma \boxed{\cos \phi \cos \lambda}$$

**Schmid
Factor**

□ Note that $\phi + \lambda \neq 90$ degrees because the tensile axis, slip plane normal, and slip direction do not always lie in the same plane



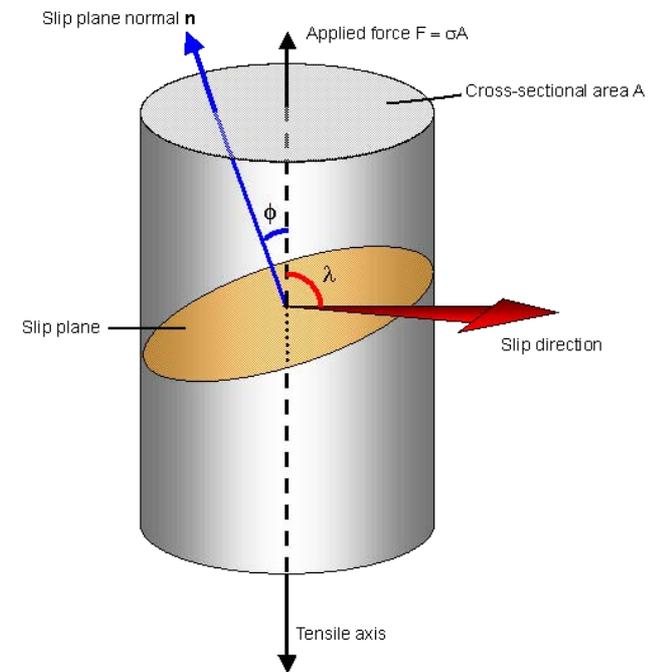
Courtesy of DoITPoMS, University of Cambridge. Used with permission.

Critical Resolved Shear Stress

- **Critical Resolved Shear Stress, τ_{CRSS}**
- the minimum shear stress required to begin plastic deformation or slip.
 - Temperature, strain rate, and material dependent
 - The system on which slip occurs has the largest Schmid factor

$$\tau = F / A \cos \phi \cos \lambda = \sigma \cos \phi \cos \lambda$$

- The minimum stress to begin yielding occurs when $\lambda = \phi = 45^\circ$
 - $\sigma = 2\tau_{CRSS}$



Courtesy of DoITPoMS, University of Cambridge. Used with permission.

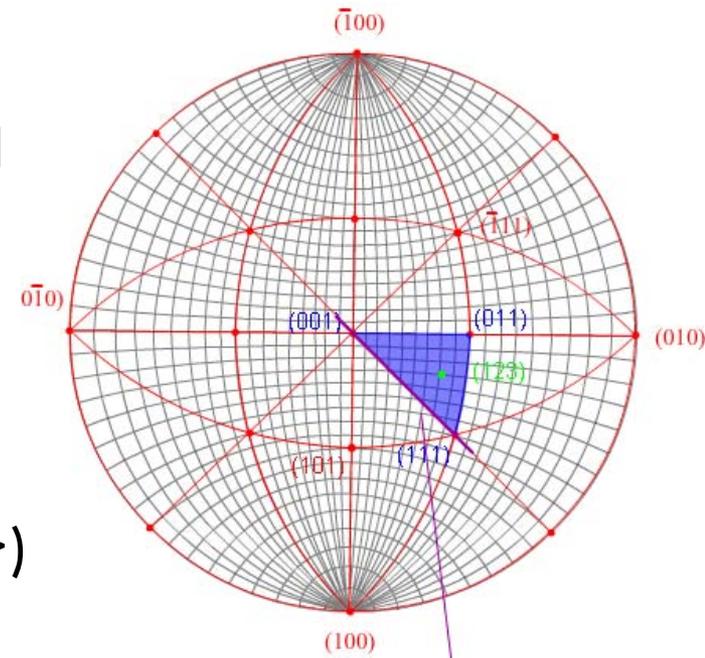
Determining Active Slip System

- There are two methods to determine which slip system is active
 - ▣ *Brute Force Method*- Calculate angles for each slip system for a given load and determine the maximum Schmid Factor
 - ▣ *Elegant Method*- Use stereographic projection to determine the active slip system graphically

Stereographic Projection Method

- 1 **Identify the triangle** containing the tensile axis
- 2 **Determine the slip plane** by taking the pole of the triangle that is in the family of the slip planes (i.e. for FCC this would be $\{111\}$) and reflecting it off the opposite side of the specified triangle
- 3 **Determine the slip direction** by taking the pole of the triangle that is in the family of directions (i.e. for FCC this would be $\langle 1-10 \rangle$) and reflecting it off the opposite side of the specified triangle

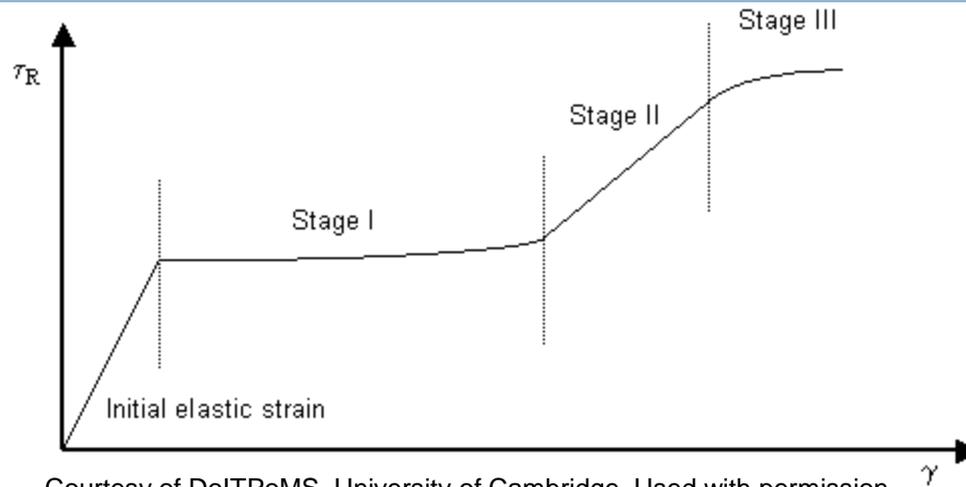
Courtesy of DoITPoMS, University of Cambridge.



Rotation of Crystal Lattice Under an Applied Load

- With increasing load, the slip plane and slip direction align parallel to the tensile stress axis
- This movement may be traced on the stereographic projection
- The tensile axis rotates toward the slip direction eventually reaching the edge of the triangle
 - ▣ Note that during compression the slip direction rotates away from the compressive axis
- At the edge of the triangle a second slip system is activated because it has an equivalent Schmid factor

More Physical Examples



Courtesy of DoITPoMS, University of Cambridge. Used with permission.

- **Initial Elastic Strain**- results from bond stretching (obeys Hooke's Law)
- **Stage I (easy glide)**- results from slip on one slip system
- **Stage II**- Multiple slip systems are active. A second slip system becomes active when its Schmid factor increases to the value of the primary slip system
- In some extreme orientations of HCP crystals, the material fractures rather than deforms plastically

Questions



MIT OpenCourseWare
<http://ocw.mit.edu>

3.40J / 22.71J / 3.14 Physical Metallurgy
Fall 2009

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.